

Periodic solutions of Euler-Lagrange equations in an anisotropic Orlicz-Sobolev space setting

Fernando D. Mazzone *

Dpto. de Matemática, Facultad de Ciencias Exactas, Físico-Químicas y Naturales
Universidad Nacional de Río Cuarto
(5800) Río Cuarto, Córdoba, Argentina,
`fmazzone@exa.unrc.edu.ar`

Sonia Acinas †

Dpto. de Matemática, Facultad de Ciencias Exactas y Naturales
Universidad Nacional de La Pampa
(L6300CLB) Santa Rosa, La Pampa, Argentina
`sonia.acinas@gmail.com`

Abstract

In this paper we consider the problem of finding periodic solutions of certain Euler-Lagrange equations, which include, among others, equations involving the p -Laplace and, more generality, the (p, q) -Laplace operator. We employ the direct method of the calculus of variations in the framework of anisotropic Orlicz-Sobolev spaces. These spaces appear to be useful in formulating a unified theory of existence for the type of problem considered.

1 Introduction

In this paper we obtain existence of solutions for systems of equations of the type:

$$\begin{cases} \frac{d}{dt} \nabla_y \mathcal{L}(t, u(t), u'(t)) = \nabla_x \mathcal{L}(t, u(t), u'(t)) & \text{a.e. } t \in (0, T), \\ u(0) - u(T) = u'(0) - u'(T) = 0, \end{cases} \quad (P)$$

where the function $\mathcal{L} : [0, T] \times \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}$, $d \geq 1$ (hereinafter called the *Lagrange function* or *lagrangian*) satisfying that it is measurable in t for each

*SECyT-UNRC, FCEyN-UNLPam and CONICET

†SECyT-UNRC and FCEyN-UNLPam

2010 AMS Subject Classification. Primary: 34C25. Secondary: 34B15.

Keywords and phrases. Periodic Solutions, Orlicz Spaces, Euler-Lagrange, Critical Points.

$(x, y) \in \mathbb{R}^d \times \mathbb{R}^d$ and continuously differentiable in (x, y) for almost every $t \in [0, T]$. The unknown function $u : [0, T] \rightarrow \mathbb{R}^d$ is assumed absolutely continuous.

Our approach involves the direct method of the calculus of variations in the framework of *anisotropic Orlicz-Sobolev spaces*. We suggest the article [18] for definitions and main results on anisotropic Orlicz spaces. These spaces allow us to unify and extend previous results on existence of solutions for systems like (P).

Through this article we say that a function $\Phi : \mathbb{R}^d \rightarrow [0, +\infty)$ is a N_∞ function if Φ is convex, $\Phi(0) = 0$, $\Phi(y) > 0$ if $y \neq 0$, $\Phi(-y) = \Phi(y)$, and

$$\lim_{|y| \rightarrow \infty} \frac{\Phi(y)}{|y|} = +\infty, \quad (1)$$

where $|\cdot|$ denotes the euclidean norm on \mathbb{R}^d . From [8, Cor. 2.35] a N_∞ function is continuous.

Associated to Φ we have the *complementary function* Φ^* which is defined in $\zeta \in \mathbb{R}^d$ as

$$\Phi^*(\zeta) = \sup_{y \in \mathbb{R}^d} y \cdot \zeta - \Phi(y) \quad (2)$$

From the continuity of Φ and (1), we have that $\Phi^* : \mathbb{R}^d \rightarrow [0, \infty)$. The complementary function Φ^* is a N_∞ function (see [13, Chapter 2] and [18, Th. 2.2]). The Moreau Theorem (see [8, Th. 4.21]) implies that $\Phi^{**} = \Phi$.

Some examples of N_∞ functions are the following.

Example 1.1. $\Phi_p(y) := |y|^p/p$, for $1 < p < \infty$. In this case $\Phi^*(\zeta) = |\zeta|^{p'}/p'$, $p' := p/(p-1)$.

Example 1.2. If $\Phi : \mathbb{R} \rightarrow [0, +\infty)$ is a N_∞ function on \mathbb{R} then $\bar{\Phi}(y) = \Phi(|y|)$ is a N_∞ function on \mathbb{R}^d . In this example, as in the previous one, the function Φ is *radial*, i.e. the value of $\Phi(y)$ depends only on the norm of y . These cases are not authentically anisotropic.

Example 1.3. An anisotropic function $\Phi(y)$ depends on the direction of y . For example, if $1 < p_1, p_2 < \infty$, we define $\Phi_{p_1, p_2} : \mathbb{R}^d \times \mathbb{R}^d \rightarrow [0, +\infty)$ by

$$\Phi_{p_1, p_2}(y_1, y_2) := \frac{|y_1|^{p_1}}{p_1} + \frac{|y_2|^{p_2}}{p_2}.$$

Then Φ_{p_1, p_2} is a N_∞ function. In this case the complementary function is the function $\Phi_{p'_1, p'_2}$.

More generally, if $\Phi_k : \mathbb{R}^d \rightarrow [0, +\infty)$, $k = 1, \dots, n$, are N_∞ functions, then $\Phi : \mathbb{R}^d \times \dots \times \mathbb{R}^d \rightarrow [0, +\infty)$ defined by $\Phi(y_1, \dots, y_n) = \Phi_1(y_1) + \dots + \Phi_n(y_n)$ is a N_∞ function.

Example 1.4. When Φ does not satisfy the Δ_2 condition (see (10) below), an anisotropic N_∞ function is not necessarily controlled by powers functions. For example $\Phi : \mathbb{R}^d \rightarrow [0, +\infty)$ defined by $\Phi(y) = \exp(|y|) - 1$ is N_∞ function.

Example 1.5. Let $(d_1, \dots, d_k) \in \mathbb{Z}_+^k$. Suppose that $\Phi_j : \mathbb{R}^{d_j} \rightarrow [0, +\infty)$, $j = 1, \dots, k$, are N_∞ functions and that $O_j \in L(\mathbb{R}^d, \mathbb{R}^{d_j})$ are bounded linear functions satisfying $\bigcap_{j=1}^k \ker O_j = \{0\}$. Then

$$\Phi(y) := \sum_{j=1}^k \Phi_j(O_j y)$$

is a N_∞ function.

Let us briefly show that Φ satisfies (1). Suppose $|y_n| \rightarrow \infty$ and $\Phi(y_n)/|y_n|$ bounded. If for some $j = 1, \dots, k$ there exists $\epsilon > 0$ and a subsequence n_s such that $|O_j(y_{n_s})| \geq \epsilon |y_{n_s}|$, then $\Phi_j(O_j y_{n_s})/|y_{n_s}| \rightarrow \infty$, contrary our assumption. Hence $O_j(y_n)/|y_n| \rightarrow 0$ when $n \rightarrow \infty$. Passing to a subsequence, we can assume that there exists $y \in \mathbb{R}^d$ with $y_n/|y_n| \rightarrow y$. Then $y \in \ker O_j$ and $y \neq 0$, which is a contradiction.

As a consequence the function $\Phi : \mathbb{R}^d \times \mathbb{R}^d \rightarrow [0, +\infty)$ defined by

$$\Phi(y_1, y_2) = e^{|y_1 - y_2|} - 1 + |y_2|^p,$$

with $1 < p < \infty$, is a N_∞ function.

We will find solutions of (P) for finding extreme points of the *action integral*

$$I(u) = I_{\mathcal{L}}(u) := \int_0^T \mathcal{L}(t, u(t), u'(t)) dt. \quad (IA)$$

In order that I is defined and be differentiable over certain Sobolev-Orlicz spaces (which we will define later) we need to introduce the following property.

Definition 1.1. *We say that a lagrangian \mathcal{L} satisfies the condition (S) if*

$$|\mathcal{L}| + |\nabla_x \mathcal{L}| + \Phi^* \left(\frac{\nabla_y \mathcal{L}}{\lambda} \right) \leq a(x) \left[b(t) + \Phi \left(\frac{y}{\Lambda} \right) \right], \quad (S)$$

for a.e. $t \in [0, T]$, where $a \in C(\mathbb{R}^d, [0, +\infty))$, $b \in L^1([0, T], [0, +\infty))$ and $\Lambda, \lambda > 0$.

An important example of lagrangian is giving by:

$$\mathcal{L}_{\Phi, F}(t, x, y) := \Phi(y) + F(t, x). \quad (3)$$

Here Φ is assumed differentiable and $F(t, x)$, which is often referred to potential, is differentiable with respect to x for a.e. $t \in [0, T]$. Moreover, it is usually assumed that F satisfies the following conditions:

(C) F and its gradient $\nabla_x F$, with respect to $x \in \mathbb{R}^d$, are Carathéodory functions, i.e. they are measurable functions with respect to $t \in [0, T]$, for every $x \in \mathbb{R}^d$, and they are continuous functions with respect to $x \in \mathbb{R}^d$ for a.e. $t \in [0, T]$.

(A) For a.e. $t \in [0, T]$, it holds that

$$|F(t, x)| + |\nabla_x F(t, x)| \leq a(x)b(t). \quad (4)$$

where $a \in C(\mathbb{R}^d, [0, +\infty))$ and $0 \leq b \in L^1([0, T], \mathbb{R})$.

Remark 1. The lagrangian $\mathcal{L}_{\Phi,F}$ satisfies condition (S), for every $\Lambda < 1$. In order to prove this, the only non trivial fact that we should to establish is that $\Phi^*(\nabla_y \mathcal{L}) \leq a(x) \{b(t) + \Phi(y/\Lambda)\}$. But, from inequality (9) below, $\Phi^*(\nabla_y \mathcal{L}) = \Phi^*(\nabla \Phi(y)) \leq \Lambda(1 - \Lambda)^{-1} \Phi(y/\Lambda)$, for every $\Lambda < 1$.

The laplacian $\mathcal{L}_{\Phi,F}$ leads to the Φ -Laplacian system

$$\begin{cases} \frac{d}{dt} \nabla \Phi(u'(t)) = \nabla_x F(t, u(t)) & \text{a.e. } t \in (0, T), \\ u(0) - u(T) = u'(0) - u'(T) = 0, \end{cases} \quad (P_\Phi)$$

Problem (P_Φ) contains, as a particular case, many problems that are usually considered in the literature. For example, the classic book [13] deals mainly with problem (P_Φ) with $\Phi(x) = |x|^2/2$, through various methods: direct, dual, saddle points, minimax, etc. The results in [13] were extended and improved in several articles, see [20, 21, 22, 26, 29] to cite some examples. The case $\Phi(y) = |y|^p/p$, for arbitrary $1 < p < \infty$ were considered in [23, 24], among other papers. In this case (P_Φ) is reduced to the p -laplacian system

$$\begin{cases} \frac{d}{dt} (u'(t)|u'|^{p-2}) = \nabla_x F(t, u(t)) & \text{a.e. } t \in (0, T) \\ u(0) - u(T) = u'(0) - u'(T) = 0. \end{cases} \quad (P_p)$$

If Φ is as in Example 1.3 and $F : [0, T] \times \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}$ is a Carathéodory function, then (P_Φ) becomes

$$\begin{cases} \frac{d}{dt} (|u'_1|^{p_1-2} u'_1) = F_{x_1}(t, u) & \text{a.e. } t \in (0, T) \\ \frac{d}{dt} (|u'_2|^{p_2-2} u'_2) = F_{x_2}(t, u) & \text{a.e. } t \in (0, T) \\ u(0) - u(T) = u'(0) - u'(T) = 0, \end{cases} \quad (P_{p_1, p_2})$$

where $x = (x_1, x_2) \in \mathbb{R}^d \times \mathbb{R}^d$ and $u(t) = (u_1(t), u_2(t)) \in \mathbb{R}^d \times \mathbb{R}^d$. In the literature, these equations are known as (p_1, p_2) -Laplacian system, see [12, 14, 15, 16, 17, 27, 28].

Our condition (S) includes structure conditions that have previously been considered in the literature in the case of p -laplacian and p_1, p_2 -laplacian systems. For example, it is easy to see that, when $\Phi(x)$ is as in Example 1.1, then the condition (S) is equivalent to the structure condition in [13, Th. 1.4]. If Φ is a radial N_∞ function such that Φ^* satisfies that Δ_2 function then (S) is related to conditions [1, Eq. (2)-(4)]. If Φ is as in Example 1.3 and $\mathcal{L} = \mathcal{L}(t, x_1, x_2, y_1, y_2)$ is a lagrangian with $\mathcal{L} : [0, T] \times \mathbb{R}^d \times \mathbb{R}^d \times \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}$ then inequality (S) is related to estructure conditions like [24, Lemma 3.1, Eq. (3.1)]. As can be seen, condition (S) is a more compact expression than [24, Lemma 3.1, Eq. (3.1)] and moreover weaker, because (S) does not imply a control of $|D_{y_1} L|$ independent of y_2 .

In conclusion, the problems (P) and (P_Φ) with conditions (S) contains several problems that have been considered by many authors in the past. Moreover, our results still improve some results on (p_1, p_2) -Laplacian since our structure conditions are less restrictive even in that particular case. For all this, we believe that Sobolev-Orlicz's anisotropic spaces can provide a suitable framework for

unifying many known results and extending them to, for example, non-power-controlled Lagrangians. Another benefit of the present approach is that many properties on Lagrangians are expressed in a more compact way.

The paper is organized as follows. In section 2 we summarize some results, mainly known, about Orlicz and Orlicz-Sobolev spaces. In Theorem 3.1 of section 3 we establish conditions for the continuous differentiability of action integrals. In order to obtain existence of minimizers of action integrals it is necessary that the functional $I_{\mathcal{L}}$ be coercive. In the past, several conditions on F have been useful to obtain coercivity of $I_{\mathcal{L}}$. In section 4 we will study the condition that in the literature was called sublinearity (see [20, 26, 29] for the laplacian, [11, 23] for the p -laplacian and [12, 14, 15, 28] for (p, q) -laplacian). We contextualize the sublinearity within our framework (see (B) below) and we establish results of existence of minimizers of (IA) (Theorem 4.2) and of existence of solutions of (P_{Φ}) (Theorem 4.3).

2 Anisotropic Orlicz and Orlicz-Sobolev spaces

In this section, we give a short introduction to Orlicz and Orlicz-Sobolev spaces of vector valued functions associated to anisotropic N_{∞} functions $\Phi : \mathbb{R}^d \rightarrow [0, +\infty)$. References for these topics are [4, 5, 7, 9, 10, 18, 19, 25]. For the theory of convex functions in general we suggest [8]. Note that, unlike in [10], we do not require that N_{∞} functions be superlinear near from 0, i.e. $\Phi(x)/|x| \rightarrow 0$ when $|x| \rightarrow 0$. However, most of the results proved in [10] do not depend on this property.

If Φ is a N_{∞} function then from convexity and since $\Phi(0) = 0$ we obtain that

$$\Phi(\lambda x) \leq \lambda \Phi(x), \quad \lambda \in [0, 1], x \in \mathbb{R}^d. \quad (5)$$

One of the greatest difficulties when dealing with anisotropic Orlicz spaces is the lack of monotony with respect to the Euclidean norm, i.e. $|x| \leq |y|$ does not imply $\Phi(x) \leq \Phi(y)$. From (5) and since $\Phi(x) = \Phi(-x)$, we see that N_{∞} functions have the following form of radial monotony:

$$0 < |\lambda_1| \leq |\lambda_2|, x \in \mathbb{R}^d \Rightarrow \Phi(\lambda_1 x) \leq \Phi(\lambda_2 x). \quad (6)$$

The mutually complementary N_{∞} functions Φ and Φ^* satisfy the following important relations (see [8]): for any $x, y \in \mathbb{R}^d$

$$x \cdot y \leq \Phi(x) + \Phi^*(y) \quad (7)$$

$$x \cdot \nabla \Phi(x) = \Phi(x) + \Phi^*(\nabla \Phi(x)) \quad (8)$$

In (8) we assume Φ differentiable. More generality (8) holds when $\nabla \Phi(y)$ is replaced by elements in the subdifferential $\partial \Phi(y)$ of Φ (see [8, Ex. 4.27]).

To avoid complications arising from considering non-differentiable functions Φ , from now on we will assume Φ differentiable.

The following inequality will be useful, it is consequence of (8) and of that $(d/dt)\Phi(tx) = \nabla\Phi(tx) \cdot x$ is an non decreasing function of t . Let $\Lambda > 1$. Then

$$\Phi^*(\nabla\Phi(x)) \leq x \cdot \nabla\Phi(x) \leq \frac{1}{\Lambda-1} \int_1^\Lambda \frac{d}{dt}\Phi(tx)dt \leq \frac{1}{\Lambda-1}\Phi(\Lambda x). \quad (9)$$

We say that $\Phi : \mathbb{R}^d \rightarrow [0, +\infty)$ satisfies the Δ_2^∞ -condition, it is denoted by $\Phi \in \Delta_2^\infty$, if there exists a constant $C > 0$ such that

$$\Phi(2x) \leq C\Phi(x) + 1, \quad (10)$$

for every x .

Throughout this article, we denote by $C = C(\lambda_1, \dots, \lambda_n)$ a positive constant that may depend on T and Φ , or other N_∞ functions, and the parameters $\lambda_1, \dots, \lambda_n$. We assume that the value that C represents may change in different occurrences in the same chain of inequalities.

If $\Phi \in \Delta_2^\infty$ then Φ satisfies the following properties:

- *Quasi-subadditivity.* There exists $C > 0$ such that for every $x, y \in \mathbb{R}^d$

$$\Phi(x+y) \leq C(\Phi(x) + \Phi(y)) + 1. \quad (11)$$

- For any $\lambda > 1$ there exists $C : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ such that

$$\Phi(\lambda x) \leq C(\lambda)\Phi(x) + 1. \quad (12)$$

- Φ is bounded by powers functions (see [9, Proof Lemma 2.4] and [6, Prop. 1]), i.e. there exists $1 < p < \infty$, $C > 0$ such that

$$\Phi(x) \leq C|x|^p + 1.$$

We consider that one of the most important aspects in considering N_∞ functions is that it accounts for Lagrange functions with faster growth than powers function, for example an exponential growth. From this point of view, it important to avoid imposing the hypothesis that $\Phi \in \Delta_2$. However, for some results we will need that $\Phi^* \in \Delta_2$.

Let Φ_1 and Φ_2 be N_∞ functions. Following to [25] we write $\Phi_1 \rightarrow \Phi_2$ if there exists $k, C > 0$ such that

$$\Phi_1(x) \leq C + \Phi_2(kx), \quad x \in \mathbb{R}^d. \quad (13)$$

For example, if Φ is Δ_2 then there exist $p \in (1, +\infty)$ such that $\Phi \rightarrow |x|^p$. If for every $k > 0$ there exists $C = C(k) > 0$ such that (13) holds we write $\Phi_1 \ll \Phi_2$.

If $\Phi_1 \rightarrow \Phi_2$ then $\Phi_2^* \rightarrow \Phi_1^*$ as the following simple computation proves

$$\begin{aligned} \Phi_1^*(k\xi) &\geq \sup \{k\xi \cdot x - \Phi_2(kx) - C\} \\ &= \sup \{\xi \cdot x - \Phi_2(x)\} - C \\ &= \Phi_2^*(\xi) - C. \end{aligned}$$

As a consequence of the previous result, we obtain that if a Lagrange function \mathcal{L} satisfies structure condition (S) and $\Phi \rightarrow \Phi_0$ then \mathcal{L} satisfies (S) with Φ_0 instead to Φ and possibly with other functions b , a and constants Λ and λ .

If $\Phi^* \in \Delta_2^\infty$ then Φ satisfies that for every $0 < r < 1$ there exists $l = l(r) > 0$ and $C' = C'(r) > 0$

$$\Phi(x) \leq \frac{r}{l} \Phi(lx) + C', \quad x \in \mathbb{R}^d. \quad (14)$$

In fact, let $\lambda > 1$ and suppose $C(\lambda)$ satisfying (12). Then

$$\begin{aligned} \Phi(x) &= \sup_{y \in \mathbb{R}^d} \{x \cdot y - \Phi^*(y)\} \\ &= \sup_{y \in \mathbb{R}^d} \{\lambda x \cdot y - \Phi^*(\lambda y)\} \\ &\geq C(\lambda) \sup_{y \in \mathbb{R}^d} \left\{ \frac{\lambda}{C(\lambda)} x \cdot y - \Phi^*(y) \right\} - 1 \\ &= C(\lambda) \Phi\left(\frac{\lambda}{C(\lambda)} x\right) - 1. \end{aligned}$$

It is easy to prove that $1 < \lambda \leq C(\lambda)$. Now, writing $C' = 1/C$, $r = \lambda^{-1} < 1$, $l = C(\lambda)/\lambda \geq 1$ and $y = l^{-1}x$ we obtain (14).

We denote by $\mathcal{M} := \mathcal{M}([0, T], \mathbb{R}^d)$, with $d \geq 1$, the set of all measurable functions (i.e. functions which are limits of simple functions) defined on $[0, T]$ with values on \mathbb{R}^d and we write $u = (u_1, \dots, u_d)$ for $u \in \mathcal{M}$.

Given an N_∞ function Φ we define the *modular function* $\rho_\Phi : \mathcal{M} \rightarrow \mathbb{R}^+ \cup \{+\infty\}$ by

$$\rho_\Phi(u) := \int_0^T \Phi(u) \, dt.$$

Now, we introduce the *Orlicz class* $C^\Phi = C^\Phi([0, T], \mathbb{R}^d)$ by setting

$$C^\Phi := \{u \in \mathcal{M} \mid \rho_\Phi(u) < \infty\}. \quad (15)$$

The *Orlicz space* $L^\Phi = L^\Phi([0, T], \mathbb{R}^d)$ is the linear hull of C^Φ ; equivalently,

$$L^\Phi := \{u \in \mathcal{M} \mid \exists \lambda > 0 : \rho_\Phi(\lambda u) < \infty\}. \quad (16)$$

The Orlicz space L^Φ equipped with the *Luxemburg norm*

$$\|u\|_{L^\Phi} := \inf \left\{ \lambda \left| \rho_\Phi\left(\frac{u}{\lambda}\right) \leq 1 \right. \right\},$$

is a Banach space.

The subspace $E^\Phi = E^\Phi([0, T], \mathbb{R}^d)$ is defined as the closure in L^Φ of the subspace $L^\infty([0, T], \mathbb{R}^d)$ of all \mathbb{R}^d -valued essentially bounded functions. The equality $L^\Phi = E^\Phi$ is true if and only if $\Phi \in \Delta_2^\infty$ (see [18, Cor. 5.1]).

A generalized version of *Hölder's inequality* holds in Orlicz spaces (see [18, Thm. 7.2]). Namely, if $u \in L^\Phi$ and $v \in L^{\Phi^*}$ then $u \cdot v \in L^1$ and

$$\int_0^T v \cdot u \, dt \leq 2 \|u\|_{L^\Phi} \|v\|_{L^{\Phi^*}}. \quad (17)$$

By $u \cdot v$ we denote the usual dot product in \mathbb{R}^d between u and v .

We consider the subset $\Pi(E^\Phi, r)$ of L^Φ given by

$$\Pi(E^\Phi, r) := \{u \in L^\Phi \mid d(u, E^\Phi) < r\}.$$

This set is related to the Orlicz class C^Φ by the following inclusions

$$\Pi(E^\Phi, r) \subset rC^\Phi \subset \overline{\Pi(E^\Phi, r)} \quad (18)$$

for any positive r . This relation is a trivial generalization of [18, Thm. 5.6]. If $\Phi \in \Delta_2^\infty$, then the sets L^Φ , E^Φ , $\Pi(E^\Phi, r)$ and C^Φ are equal.

As usual, if $(X, \|\cdot\|_X)$ is a normed space and $(Y, \|\cdot\|_Y)$ is a linear subspace of X , we write $Y \hookrightarrow X$ and we say that Y is *embedded* in X when there exists $C > 0$ such that $\|y\|_X \leq C\|y\|_Y$ for any $y \in Y$. With this notation, Hölder's inequality states that $L^\Phi \hookrightarrow [L^{\Phi^*}]^*$, where a function $v \in L^\Phi$ is associated to $\xi_v \in [L^{\Phi^*}]^*$ given by

$$\langle \xi_v, u \rangle = \int_0^T v \cdot u \, dt, \quad (19)$$

We suppose $u \in L^\infty([0, T], \mathbb{R}^d)$. Since Φ is continuous, Φ is bounded on $\overline{B}_r(0) = \{x \in \mathbb{R}^n : |x| \leq r\}$. Let $M_r := \max_{\overline{B}_r(0)} \Phi(x)$. As $M_r \rightarrow 0$ when $r \rightarrow 0$, we can choose r such that $M_r T \leq 1$. Then

$$\int_0^T \Phi \left(\frac{ru}{\|u\|_{L^\infty}} \right) dt \leq M_r T \leq 1$$

and consequently $\|u\|_{L^\Phi} \leq r^{-1} \|u\|_{L^\infty}$, i.e. $L^\infty \hookrightarrow L^\Phi$. It is also easy to see that $L^\Phi \hookrightarrow L^1$ for any N_∞ function Φ .

Suppose $u \in L^\Phi([0, T], \mathbb{R}^d)$ and consider $K := \rho_\Phi(u) + 1 \geq 1$. Then from (5) we have $\rho_\Phi(K^{-1}u) \leq K^{-1} \rho_\Phi(u) \leq 1$. Therefore we conclude the inequality

$$\|u\|_{L^\Phi} \leq \rho_\Phi(u) + 1. \quad (20)$$

We highlight the following result (see [10, Th. 3.3]).

Proposition 2.1. $L^\Phi([0, T], \mathbb{R}^d) = [E^{\Phi^*}([0, T], \mathbb{R}^d)]^*$.

As a consequence of previous proposition, $L^\Phi([0, T], \mathbb{R}^d)$ can be equipped with the weak \star topology induced by $E^{\Phi^*}([0, T], \mathbb{R}^d)$.

We define the *Sobolev-Orlicz space* $W^1 L^\Phi([0, T], \mathbb{R}^d)$ by

$$W^1 L^\Phi([0, T], \mathbb{R}^d) := \{u \mid u \in AC([0, T], \mathbb{R}^d) \text{ and } u' \in L^\Phi([0, T], \mathbb{R}^d)\},$$

where $AC([0, T], \mathbb{R}^d)$ denotes the space of all \mathbb{R}^d valued absolutely continuous functions defined on $[0, T]$. The space $W^1 L^\Phi([0, T], \mathbb{R}^d)$ is a Banach space when equipped with the norm

$$\|u\|_{W^1 L^\Phi} = \|u\|_{L^\Phi} + \|u'\|_{L^\Phi}. \quad (21)$$

Anisotropic Sobolev-Orlicz spaces were treated in [4, 5, 7, 25]. Usually functions in Sobolev spaces are required to be weakly differentiable. In the particular and simplest case of functions of one variable, the weak differentiability implies absolute continuity. Hence we can assume, without losing generality, $u \in AC([0, T], \mathbb{R}^d)$ in the definition of $W^1 L^\Phi([0, T], \mathbb{R}^d)$.

As is well known, an active research topic in mathematical analysis are the Sobolev and Poincare inequalities. This topic have also been treated in the framework of anisotropic Orlicz-Sobolev, mainly in [5, 7, 25] for functions of several variables and in [4] for functions of one single variable and Φ and Φ^* functions of Δ_2^∞ class. We do not know a reference for the embedding of Sobolev-Orlicz anisotropic spaces in the space of continuous functions when Φ or Φ^* are not Δ_2^∞ .

We define the function $A_\Phi : \mathbb{R}^d \rightarrow [0, +\infty)$ as the greatest convex radial minorant of Φ , i.e.

$$A_\Phi(x) = \sup \{ \Psi(x) \}, \quad (22)$$

where the supremum is taken over all the convex, non negative and radial functions Ψ with $\Psi(x) \leq \Phi(x)$.

Proposition 2.2. *A_Φ is a radial and N_∞ function.*

Proof. The convexity and radially of A_Φ is a consequence of the fact that the supremum preserving these properties. It is only necessary to show that $A_\Phi(x) > 0$, when $x \neq 0$ and $A_\Phi(x)/|x| \rightarrow \infty$, when $|x| \rightarrow \infty$. We write, for $r \in \mathbb{R}$, $r^+ = \max\{r, 0\}$. Since Φ is N_∞ function, for every $k > 0$ there exists $r_0 > 0$ such that $\Phi(x) \geq k(|x| - r_0)^+$, for $|x| > r_0$. Since $k(|x| - r_0)^+$ is a non negative radial and convex function, it follows that $A_\Phi(x) \geq k(|x| - r_0)^+$. Therefore $\liminf_{|x| \rightarrow \infty} A_\Phi(x)/|x| \geq k$. This implies that $\lim_{|x| \rightarrow \infty} A_\Phi(x)/|x| = \infty$.

As Φ is a N_∞ and continuous function, for every $r > 0$ there exists $k(r) > 0$ such that $\Phi(x) \geq k(r)|x| \geq k(r)(|x| - r)^+$, when $|x| \geq r$. This fact implies that $A_\Phi(x) > 0$ for $x \neq 0$. \square

By abuse of notation, we sometime identify A_Φ with a (invertible) function defined on $[0, +\infty)$.

Corollary 2.3. $L^\Phi([0, T], \mathbb{R}^d) \hookrightarrow L^{A_\Phi}([0, T], \mathbb{R}^d)$.

As is customary, we will use the decomposition $u = \bar{u} + \tilde{u}$ for a function $u \in L^1([0, T])$ where $\bar{u} = \frac{1}{T} \int_0^T u(t) dt$ and $\tilde{u} = u - \bar{u}$.

Lemma 2.4. *Let $\Phi : \mathbb{R}^d \rightarrow [0, +\infty)$ be a N_∞ function and let $u \in W^1 L^\Phi([0, T], \mathbb{R}^d)$. Let $A_\Phi : \mathbb{R}^d \rightarrow [0, +\infty)$ be the isotropic function defined by (22). Then*

1. Morrey's inequality. For every $s, t \in [0, T]$, $s \neq t$

$$|u(t) - u(s)| \leq |s - t| A_{\Phi}^{-1} \left(\frac{1}{|s - t|} \right) \|u'\|_{L^{\Phi}} \quad (\text{M.I})$$

2. Sobolev's inequality.

$$\|u\|_{L^{\infty}} \leq A_{\Phi}^{-1} \left(\frac{1}{T} \right) \max\{1, T\} \|u\|_{W^1 L^{\Phi}} \quad (\text{S.I})$$

3. Poincaré-Wirtinger's inequality. We have $\tilde{u} \in L^{\infty}([0, T], \mathbb{R}^d)$ and

$$\|\tilde{u}\|_{L^{\infty}} \leq T A_{\Phi}^{-1} \left(\frac{1}{T} \right) \|u'\|_{L^{\Phi}} \quad (\text{P-W.I})$$

4. If Φ is N_{∞} then the space $W^1 L^{\Phi}([0, T], \mathbb{R}^d)$ is compactly embedded in the space of continuous functions $C([0, T], \mathbb{R}^d)$.

Proof. It is immediate consequence of Corollary 2.3 and [1, Lemma 2.1, Corollary 2.2]. \square

Lemma 2.4 gives us estimates of isotropic norms of u . In these type of inequalities some information is lost. The following result gives us an estimate that takes into account the anisotropic nature of the space $W^1 L^{\Phi}([0, T], \mathbb{R}^d)$. The proof is similar to the proof of [4, Th. 4.5].

Lemma 2.5 (Anisotropic Poincaré-Wirtinger's inequality). *Let $\Phi : \mathbb{R}^d \rightarrow [0, +\infty)$ be a N_{∞} function and let $u \in W^1 L^{\Phi}([0, T], \mathbb{R}^d)$. Then*

$$\Phi(\tilde{u}(t)) \leq \frac{1}{T} \int_0^T \Phi(Tu'(r)) dr. \quad (\text{A.P-W.I})$$

Proof. Applying Jensen's inequality two times, we get

$$\begin{aligned} \Phi(\tilde{u}(t)) &= \Phi \left(\frac{1}{T} \int_0^T (u(t) - u(s)) ds \right) \\ &\leq \frac{1}{T} \int_0^T \Phi(u(t) - u(s)) ds \\ &\leq \frac{1}{T} \int_0^T \Phi \left(\int_s^t |t - s| u'(r) \frac{dr}{|t - s|} \right) ds \\ &\leq \frac{1}{T} \int_0^T \frac{1}{|t - s|} \int_s^t \Phi(|t - s| u'(r)) dr ds \end{aligned}$$

From (5) we have that $\Phi(rx)/r$ is increasing with respect to $r > 0$ for $x \in \mathbb{R}^d$ fix. Therefore, previous inequality implies (A.P-W.I). \square

Remark 2. As consequence of Lemma 2.4 we obtain that

$$\|u\|'_{W^1 L^\Phi} = |\bar{u}| + \|u'\|_{L^\Phi},$$

define an equivalent norm to $\|\cdot\|_{W^1 L^\Phi}$ on $W^1 L^\Phi([0, T], \mathbb{R}^d)$. This affirmation is proved as follows. On the one hand, by Hölder inequality (17)

$$|\bar{u}| \leq \frac{2}{T} \|1\|_{L^{\Phi^*}} \|u\|_{L^\Phi}.$$

On the other hand, from the embedding $L^\infty \hookrightarrow L^\Phi$ and (P-W.I)

$$\|u\|_{L^\Phi} \leq C|\bar{u}| + C\|\tilde{u}\|_{L^\infty} \leq C\|u\|'_{W^1 L^\Phi}.$$

Corollary 2.6. *Every bounded sequence $\{u_n\}$ in $W^1 L^\Phi([0, T], \mathbb{R}^d)$ has an uniformly convergent subsequence.*

Given a function $a : \mathbb{R}^d \rightarrow \mathbb{R}$, we define the composition operator $\mathbf{a} : \mathcal{M} \rightarrow \mathcal{M}$ by $\mathbf{a}(u)(x) = a(u(x))$. We will often use the following result whose proof can be performed as that of Corollary 2.3 in [1].

Lemma 2.7. *If $a \in C(\mathbb{R}^d, \mathbb{R}^+)$ then $\mathbf{a} : W^1 L^\Phi \rightarrow L^\infty([0, T])$ is bounded. More concretely, there exists a non decreasing function $A : [0, +\infty) \rightarrow [0, +\infty)$ such that $\|\mathbf{a}(u)\|_{L^\infty([0, T])} \leq A(\|u\|_{W^1 L^\Phi})$.*

The following theorem will be used repeatedly. We adapted the proof of [1, Lemma 2.5] to the anisotropic case. For an alternative approach see [4].

Lemma 2.8. *Let $\{u_n\}_{n \in \mathbb{N}}$ be a sequence of functions converging to $u \in \Pi(E^\Phi, \lambda)$ in the L^Φ -norm. Then, there exist a subsequence u_{n_k} and a real valued function $h \in L^1([0, T], \mathbb{R})$ such that $u_{n_k} \rightarrow u$ a.e. and $\Phi(u_{n_k}/\lambda) \leq h$ a.e.*

Proof. Since $d(u, E^\Phi) < \lambda$ and u_n converges to u , there exists a subsequence of u_n (again denoted u_n), $\bar{\lambda} \in (0, \lambda)$ and $u_0 \in E^\Phi$ such that $d(u_n, u_0) < \bar{\lambda}$, $n = 1, \dots$. Since $L^\Phi([0, T], \mathbb{R}^d) \hookrightarrow L^1([0, T], \mathbb{R}^d)$, the sequence u_n converges in measure to u . Therefore, we can extract a subsequence (denoted again u_n) such that $u_n \rightarrow u$ a.e. and

$$\lambda_n := \|u_n - u_{n-1}\|_{L^\Phi} < \frac{\lambda - \bar{\lambda}}{2^{n-1}}, \quad \text{for } n \geq 2.$$

We can assume $\lambda_n > 0$ for every $n = 1, \dots$. We write $\lambda_1 := \|u_1 - u_0\|_{L^\Phi}$ and $\lambda_0 := \lambda - \sum_{n=1}^{\infty} \lambda_n$ and define $h : [0, T] \rightarrow \mathbb{R}$ by

$$h(t) = \frac{\lambda_0}{\lambda} \Phi\left(\frac{u_0}{\lambda_0}\right) + \sum_{j=0}^{\infty} \frac{\lambda_{j+1}}{\lambda} \Phi\left(\frac{u_{j+1} - u_j}{\lambda_{j+1}}\right). \quad (23)$$

Since $\Phi(0) = 0$ and from the convexity of Φ we have for any $n = 1, \dots$

$$\begin{aligned}\Phi\left(\frac{u_n}{\lambda}\right) &= \Phi\left(\frac{u_0}{\lambda} + \sum_{j=0}^{n-1} \frac{u_{j+1} - u_j}{\lambda}\right) \\ &\leq \frac{\lambda_0}{\lambda} \Phi\left(\frac{u_0}{\lambda_0}\right) + \sum_{j=0}^{n-1} \frac{\lambda_{j+1}}{\lambda} \Phi\left(\frac{u_{j+1} - u_j}{\lambda_{j+1}}\right) \leq h\end{aligned}$$

Since $u_0 \in E^\Phi \subset C^\Phi$ and E^Φ is a subspace we have that $\Phi(u_0/\lambda_0) \in L^1([0, T], \mathbb{R})$. On the other hand $\|u_{j+1} - u_j\|_{L^\Phi} = \lambda_{j+1}$, therefore

$$\int_0^T \Phi\left(\frac{u_{j+1} - u_j}{\lambda_{j+1}}\right) dt \leq 1.$$

Then $h \in L^1([0, T], \mathbb{R})$. □

3 Differentiability Gateaux of action integrals in anisotropic Orlicz spaces

The proof of the following theorem follows the same lines as [1, Th. 3.2] but with some modifications by the lack of monotony of Φ with respect to the euclidean norm and the fact that the notion of absolutely continuous norm (used intensely in [1, Th. 3.2]) does not work very well in the framework of anisotropic Orlicz spaces.

Theorem 3.1. *Let \mathcal{L} be a differentiable Carathéodory function satisfying (S). Then the following statements hold:*

1. *The action integral given by (IA) is finitely defined on the set $\mathcal{E}_\Lambda^\Phi := W^1 L^\Phi \cap \{u|u' \in \Pi(E^\Phi, \Lambda)\}$.*
2. *The function I is Gateaux differentiable on \mathcal{E}_Λ^Φ and its derivative I' is demicontinuous from \mathcal{E}_Λ^Φ into $[W^1 L^\Phi]^*$, i.e. I' is continuous when \mathcal{E}_Λ^Φ is equipped with the strong topology and $[W^1 L^\Phi]^*$ with the weak* topology. Moreover, I' is given by the following expression*

$$\langle I'(u), v \rangle = \int_0^T [\nabla_x \mathcal{L}(t, u, u') \cdot v + \nabla_y \mathcal{L}(t, u, u') \cdot v'] dt. \quad (24)$$

3. *If $\Phi^* \in \Delta_2^\infty$ then I' is continuous from \mathcal{E}_Λ^Φ into $[W^1 L^\Phi]^*$ when both spaces are equipped with the strong topology.*

Proof. Let $u \in \mathcal{E}_\Lambda^\Phi$. From (18) we obtain $\Phi(u'(t)/\Lambda) \in L^1$. Now, from (S) and Lemma 2.7 we have

$$\begin{aligned}|\mathcal{L}(t, u(t), u'(t))| + |\nabla_x \mathcal{L}(t, u(t), u'(t))| + \Phi^*\left(\frac{\nabla_y \mathcal{L}(t, u, u')}{\lambda}\right) \\ \leq A(\|u\|_{W^1 L^\Phi}) \left[b(t) + \Phi\left(\frac{u'(t)}{\Lambda}\right) \right] \in L^1,\end{aligned} \quad (25)$$

Thus item (1) is proved integrating this inequality.

We split up the proof of item 2 into four steps.

Step 1. The non linear operator $u \mapsto \nabla_x \mathcal{L}(\cdot, u, u')$ is continuous from \mathcal{E}_Λ^Φ into $L^1([0, T])$ with the strong topology on both sets.

Let $\{u_n\}_{n \in \mathbb{N}}$ be a sequence of functions in \mathcal{E}_Λ^Φ and let $u \in \mathcal{E}_\Lambda^\Phi$ such that $u_n \rightarrow u$ in $W^1 L^\Phi$. By (S.I), $u_n \rightarrow u$ uniformly. As $u'_n \rightarrow u' \in \mathcal{E}_\Lambda^\Phi$, by Lemma 2.8, there exist a subsequence of u'_n (again denoted u'_n) and a function $h \in L^1([0, T], \mathbb{R})$ such that $u'_n \rightarrow u'$ a.e. and $\Phi(u'_n/\Lambda) \leq h$ a.e.

Since $u_n, n = 1, 2, \dots$, is a bounded sequence in $W^1 L^\Phi$, according to Lemma (2.7), there exists $M > 0$ such that $\|a(u_n)\|_{L^\infty} \leq M, n = 1, 2, \dots$. From the previous facts and (25), we get

$$|\nabla_x \mathcal{L}(\cdot, u_n, u'_n)| \leq a(u_n) \left[b + \Phi \left(\frac{u'_n}{\Lambda} \right) \right] \leq M(b + h) \in L^1.$$

On the other hand, by the continuous differentiability of \mathcal{L} , we have

$$\nabla_x \mathcal{L}(t, u_{n_k}(t), u'_{n_k}(t)) \rightarrow \nabla_x \mathcal{L}(t, u(t), u'(t)) \quad \text{for a.e. } t \in [0, T].$$

Applying the Dominated Convergence Theorem we conclude the proof of step 1.

Step 2. The non linear operator $u \mapsto \nabla_y \mathcal{L}(\cdot, u, u')$ is continuous from \mathcal{E}_Λ^Φ with the strong topology into $[L^\Phi]^$ with the weak* topology.*

Let $u \in \mathcal{E}_\Lambda^\Phi$. From (25) it follows that

$$\nabla_y \mathcal{L}(\cdot, u, u') \in \lambda C^{\Phi^*}([0, T], \mathbb{R}^d) \subset L^{\Phi^*}([0, T], \mathbb{R}^d) \subset [L^\Phi([0, T], \mathbb{R}^d)]^*. \quad (26)$$

Let $u_n, u \in \mathcal{E}_\Lambda^\Phi$ such that $u_n \rightarrow u$ in the norm of $W^1 L^\Phi$. We must prove that $\nabla_y \mathcal{L}(\cdot, u_n, u'_n) \xrightarrow{w^*} \nabla_y \mathcal{L}(\cdot, u, u')$. On the contrary, there exist $v \in L^\Phi, \epsilon > 0$ and a subsequence of $\{u_n\}$ (denoted $\{u_n\}$ for simplicity) such that

$$|\langle \nabla_y \mathcal{L}(\cdot, u_n, u'_n), v \rangle - \langle \nabla_y \mathcal{L}(\cdot, u, u'), v \rangle| \geq \epsilon. \quad (27)$$

We have $u_n \rightarrow u$ in L^Φ and $u'_n \rightarrow u' \in \Pi(E^\Phi, \Lambda)$. By Lemmas 2.6 and 2.8, there exist a subsequence of $\{u_n\}$ (again denoted $\{u_n\}$ for simplicity) and a function $h \in L^1([0, T], \mathbb{R})$ such that $u_n \rightarrow u$ uniformly, $u'_n \rightarrow u'$ a.e. and $\Phi(u'_n/\Lambda) \leq h$ a.e. As in the previous step, Lemma 2.7 implies that $a(u_n(t))$ is uniformly bounded by a certain constant $M > 0$. Therefore, from inequality (25) with u_n instead of u , we have

$$\Phi^* \left(\frac{\nabla_y \mathcal{L}(\cdot, u_n, u'_n)}{\lambda} \right) \leq M(b + h) =: h_1 \in L^1. \quad (28)$$

As $v \in L^\Phi$ there exists $\lambda_v > 0$ such that $\Phi(v/\lambda_v) \in L^1$. Now, by Young inequality and (28), we have

$$\begin{aligned} \nabla_y \mathcal{L}(\cdot, u_n, u'_n) \cdot v(t) &\leq \lambda \lambda_v \left[\Phi^* \left(\frac{\nabla_y \mathcal{L}(\cdot, u_n, u'_n)}{\lambda} \right) + \Phi \left(\frac{v}{\lambda_v} \right) \right] \\ &\leq \lambda \lambda_v M(b + h) + \lambda \lambda_v \Phi \left(\frac{v}{\lambda_v} \right) \in L^1 \end{aligned} \quad (29)$$

Finally, from the Lebesgue Dominated Convergence Theorem, we deduce

$$\int_0^T \nabla_y \mathcal{L}(t, u_n, u'_n) \cdot v dt \rightarrow \int_0^T \nabla_y \mathcal{L}(t, u, u') \cdot v dt \quad (30)$$

which contradicts the inequality (27). This completes the proof of step 2.

Step 3. We will prove (24). Note that (25), (26) and the imbeddings $W^1 L^\Phi \hookrightarrow L^\infty$ and $L^{\Phi^*} \hookrightarrow [L^\Phi]^*$ imply that the second member of (24) defines an element of $[W^1 L^\Phi]^*$.

The proof follows similar lines as [13, Thm. 1.4]. For $u \in \mathcal{E}_\Lambda^\Phi$ and $0 \neq v \in W^1 L^\Phi$, we define the function

$$H(s, t) := \mathcal{L}(t, u(t) + sv(t), u'(t) + sv'(t)).$$

For $|s| \leq s_0 := (\Lambda - d(u', E^\Phi)) / \|v\|_{W^1 L^\Phi}$ we have that $u' + sv' \in \Pi(E^\Phi, \Lambda)$. This fact implies, in virtue of Theorem 3.1 item 1, that $I(u + sv)$ is well defined and finite for $|s| \leq s_0$.

We write $s_1 := \min\{s_0, 1 - d(u', E^\Phi)/\Lambda\}$. Let $\lambda_v > 0$ such that $\Phi(v'/\lambda_v) \in L^1$. As $u' \in \Pi(E^\Phi, \Lambda)$, then

$$d\left(\frac{u'}{(1-s_1)\Lambda}, E^\Phi\right) = \frac{1}{(1-s_1)\Lambda} d(u', E^\Phi) < 1$$

Consequently $(1-s_1)^{-1}\Lambda^{-1}u' \in C^\Phi$. Hence, if $v' \in L^\Phi$ and $|s| \leq s_1\Lambda\lambda_v^{-1}$, from the convexity of Φ and (6), we get

$$\begin{aligned} \Phi\left(\frac{u' + sv'}{\Lambda}\right) &\leq (1-s_1)\Phi\left(\frac{u'}{(1-s_1)\Lambda}\right) + s_1\Phi\left(\frac{s}{s_1\Lambda}v'\right) \\ &\leq (1-s_1)\Phi\left(\frac{u'}{(1-s_1)\Lambda}\right) + s_1\Phi\left(\frac{v'}{\lambda_v}\right) \\ &=: h(t) \in L^1 \end{aligned} \quad (31)$$

We also have $\|u + sv\|_{W^1 L^\Phi} \leq \|u\|_{W^1 L^\Phi} + s_0\|v\|_{W^1 L^\Phi}$; then, by Lemma 2.7, there exists $M > 0$, independent of s , such that $\|a(u + sv)\|_{L^\infty} \leq M$. Now, applying Young's Inequality, (25), the fact that $v \in L^\infty$, (31) and $\Phi(v'/\lambda_v) \in L^1$, we get

$$\begin{aligned} |D_s H(s, t)| &= |\nabla_x \mathcal{L}(t, u + sv, u' + sv') \cdot v + \nabla_y \mathcal{L}(t, u + sv, u' + sv') \cdot v'| \\ &\leq M \left[b(t) + \Phi\left(\frac{u' + sv'}{\Lambda}\right) \right] |v| \\ &\quad + \lambda \lambda_v \left[\Phi^*\left(\frac{\nabla_y \mathcal{L}(t, u + sv, u' + sv')}{\lambda}\right) + \Phi\left(\frac{v'}{\lambda_v}\right) \right] \\ &\leq M \left[b(t) + \Phi\left(\frac{u' + sv'}{\Lambda}\right) \right] (|v| + \lambda \lambda_v) + \lambda \lambda_v \Phi\left(\frac{v'}{\lambda_v}\right) \\ &\leq M (b(t) + h(t)) (|v| + \lambda \lambda_v) + \lambda \lambda_v \Phi\left(\frac{v'}{\lambda_v}\right) \in L^1. \end{aligned} \quad (32)$$

Consequently, I has a directional derivative and

$$\langle I'(u), v \rangle = \frac{d}{ds} I(u + sv) \Big|_{s=0} = \int_0^T [\nabla_x \mathcal{L}(t, u, u') \cdot v + \nabla_y \mathcal{L}(t, u, u') \cdot v'] dt.$$

Moreover, from the previous formula, (25), (26), and Lemma 2.4, we obtain

$$|\langle I'(u), v \rangle| \leq \|\nabla_x \mathcal{L}\|_{L^1} \|v\|_{L^\infty} + \|\nabla_y \mathcal{L}\|_{L^{\Phi^*}} \|v'\|_{L^\Phi} \leq C \|v\|_{W^1 L^\Phi}$$

with a appropriate constant C . This completes the proof of the Gâteaux differentiability of I . The previous steps imply the demicontinuity of the operator $I' : \mathcal{E}_\Lambda^\Phi \rightarrow [W^1 L_d^\Phi]^*$.

In order to prove item 3, it is necessary to see that the maps $u \mapsto \nabla_x \mathcal{L}(t, u, u')$ and $u \mapsto \nabla_y \mathcal{L}(t, u, u')$ are norm continuous from \mathcal{E}_Λ^Φ into L^1 and L^{Φ^*} , respectively. It remains to the continuity of the second map. To this purpose, we take $u_n, u \in \mathcal{E}_\Lambda^\Phi$, $n = 1, 2, \dots$, with $\|u_n - u\|_{W^1 L^\Phi} \rightarrow 0$. As before, we can deduce there exist a subsequence (denoted u'_n for simplicity) and $h_1 \in L^1$ such that (28) holds and $u_n \rightarrow u$ a.e. Since $\Phi^* \in \Delta_2$,

$$\Phi^*(\nabla_y \mathcal{L}(\cdot, u_n, u'_n)) \leq c(\lambda) \Phi^*\left(\frac{\nabla_y \mathcal{L}(\cdot, u_n, u'_n)}{\lambda}\right) + 1 \leq c(\lambda) h_1 + 1 =: h_2 \in L^1. \quad (33)$$

Then, from the quasi-subadditivity of Φ^* we have

$$\Phi^*(\nabla_y \mathcal{L}(\cdot, u_n, u'_n) - \nabla_y \mathcal{L}(\cdot, u, u')) \leq K(h_2 + \Phi^*(\nabla_y \mathcal{L}(\cdot, u, u'))) + 1.$$

Now, by Dominated Convergence Theorem, we obtain that $\nabla_y \mathcal{L}(\cdot, u_n, u'_n)$ is ρ_{Φ^*} modular convergent to $\nabla_y \mathcal{L}(\cdot, u, u')$, i.e. $\rho_{\Phi^*}(u_n - u) \rightarrow 0$. Since Φ^* is Δ_2^∞ , modular convergence implies norm convergence (see [19]). \square

4 Existence of minimizers

For simplicity, from now on we will consider Lagrangian functions of the form (3), i.e. $\mathcal{L} = \mathcal{L}_{\Phi, F}$. However, the results of this section extend without difficulty to any lagrangian \mathcal{L} with $\mathcal{L} \geq \mathcal{L}_{\Phi, F}$ (see [1]).

It is well known that an important ingredient in the direct method of calculus of variations is the coercivity of action integrals. To obtain coercivity for integral I defined in (IA) with $\mathcal{L} = \mathcal{L}_{\Phi, F}$, it is necessary to impose more restrictions on the potential F .

There are several restrictions that were explored in the past. The one we will study in this article is based on what is known in the literature as sublinearity (see [20, 26, 29] for the laplacian, [23, 11] for the p -laplacian and [28, 12, 14, 15] for (p, q) -laplacian). In this article we will use another denomination for the sublinearity.

Definition 4.1. Let $F : [0, T] \times \mathbb{R}^d \rightarrow \mathbb{R}$ be a functions satisfying (C) and (A). We say that F satisfies condition (B) if there exist an N_∞ function Φ_0 , with $\Phi_0 \ll \Phi$, a function $d \in L^1([0, T], \mathbb{R})$, with $d \geq 1$, such that

$$\Phi^\star(d^{-1}(t)\nabla_x F) \leq \Phi_0(x) + 1 \quad (B)$$

The condition (B) encompasses the sublinearity condition. For example, in [12, Th. 1.1.] Li, Ou and Tang considered a potential $F : [0, T] \times \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}$ satisfying (C) and (A) and the following condition (we recall that $p' = p/(p-1)$).

(H) There exists $f_i, g_i, h_i \in L^1([0, T], \mathbb{R}_+)$, $\alpha_i \in [0, p_i/p'_i]$, $i = 1, 2$, $\beta_1 \in [0, p_2/p'_1]$ and $\beta_2 \in [0, p_1/p'_2]$ such that

$$|\nabla_{x_i} F(t, x_1, x_2)| \leq f_i(t)|x_1|^{\alpha_i} + g_i(t)|x_2|^{\beta_i} + h_i(t), \quad i = 1, 2$$

It is easy to prove that (H) \Rightarrow (B), with $\Phi_0(x_1, x_2) = \Phi_{\bar{p}_1, \bar{p}_2}(x_1, x_2) = |x_1|^{\bar{p}_1}/\bar{p}_1 + |x_2|^{\bar{p}_2}/\bar{p}_2$, where \bar{p}_i , $i = 1, 2$, are taken so that $\max\{\alpha_1 p'_1, \beta_2 p'_2\} \leq \bar{p}_1 < p_1$ and $\max\{\alpha_2 p'_2, \beta_1 p'_1\} \leq \bar{p}_2 < p_2$ and $d = C(1 + \sum_i \{f_i + g_i + h_i\}) \in L^1$, with $C > 0$ chosen large enough.

Theorem 4.2. *Let Φ be an N_∞ -function whose complementary function Φ^\star satisfies the Δ_2^∞ -condition. Let F be a potential that satisfies (C), (A), (B) and the following condition*

$$\lim_{|x| \rightarrow \infty} \frac{\int_0^T F(t, x) dt}{\Phi_0(2x)} = +\infty. \quad (34)$$

Let M be a weak \star closed subspace of L^Φ and let $V \subset C([0, T], \mathbb{R}^d)$ be closed in the $C([0, T], \mathbb{R}^d)$ -strong topology. Then I attains a minimum on $H = \{u \in W^1 L^\Phi | u \in V \text{ and } u' \in M\}$.

Proof. Step 1. The action integral is coercive.

Let λ be any positive number with $\lambda > 2 \max\{T, 1\}$. Since $\Phi_0 \ll \Phi$ there exists $C(\lambda) > 0$ such that

$$\Phi_0(x) \leq \Phi\left(\frac{x}{2\lambda}\right) + C(\lambda), \quad x \in \mathbb{R}^d. \quad (35)$$

By the decomposition $u = \bar{u} + \tilde{u}$, the absolute continuity of $F(t, x + sy)$ with respect to $s \in \mathbb{R}$, Young's inequality, (B), the convexity of Φ_0 , (6), (35),

(A.P-W.I) we obtain

$$\begin{aligned}
 J &:= \left| \int_0^T F(t, u) - F(t, \bar{u}) dt \right| \\
 &\leq \int_0^T \int_0^1 |\nabla_x F(t, \bar{u} + s\tilde{u}) \tilde{u}| ds dt \\
 &\leq \lambda \int_0^T d(t) \int_0^1 \Phi^* (d^{-1}(t) \nabla_x F(t, \bar{u} + s\tilde{u})) + \Phi \left(\frac{\tilde{u}}{\lambda} \right) ds dt \\
 &\leq \lambda \int_0^T d(t) \left[\int_0^1 \frac{1}{2} \Phi_0(2\bar{u}) + \frac{1}{2} \Phi_0(2\tilde{u}) ds + \Phi \left(\frac{\tilde{u}}{\lambda} \right) + 1 ds \right] dt \\
 &\leq \lambda \int_0^T d(t) \left[\int_0^1 \Phi_0(2\bar{u}) + 2\Phi \left(\frac{\tilde{u}}{\lambda} \right) + C(\lambda) ds \right] dt \\
 &\leq C_1 \Phi_0(2\bar{u}) + \lambda C_2 \int_0^T \Phi \left(\frac{Tu'(s)}{\lambda} \right) ds + C_1
 \end{aligned}$$

where $C_2 = C_2(\|d\|_{L^1})$ and $C_1 = C_1(\|d\|_{L^1}, \lambda)$. Since Φ^* is Δ_2^∞ we can choose λ large enough so that $l = \lambda T^{-1}$ satisfies (14) for $r = \frac{1}{2} \min\{(C_2 T)^{-1}, 1\}$. Thus we have

$$J \leq C_1 \Phi_0(2\bar{u}) + \frac{1}{2} \int_0^T \Phi(u'(s)) ds + C_1$$

Then

$$\begin{aligned}
 I(u) &= \int_0^T \Phi(u') + F(t, u) dt \\
 &= \int_0^T \{\Phi(u') + [F(t, u) - F(t, \bar{u})] + F(t, \bar{u})\} dt \\
 &\geq \frac{1}{2} \int_0^T \Phi(u') dt - C_1 \Phi_0(2\bar{u}) + \int_0^T F(t, \bar{u}) dt - C_1
 \end{aligned} \tag{36}$$

We take $u_n \in W^1 L^\Phi$ with $\|u_n\|_{W^1 L^\Phi} \rightarrow \infty$. From Remark 2, we can suppose that $\|u'_n\|_{L^\Phi} \rightarrow \infty$ or $|\bar{u}_n| \rightarrow \infty$. In the first case, we have from (20) that $\rho_\Phi(u_n) \rightarrow \infty$ and hence $I(u_n) \rightarrow \infty$. In the second case, $I(u_n) \rightarrow \infty$ as consequence of (34).

Step 2. Suppose that $u_n \rightarrow u$ uniformly and $u'_n \xrightarrow{} u'$ in $L^\Phi([0, T], \mathbb{R}^d)$ then $I(u) \leq \liminf_{n \rightarrow \infty} I(u_n)$.*

Without loss of generality, passing to subsequences, we may assume that the \liminf is really a \lim . The embedding $L^\Phi([0, T], \mathbb{R}^d) \hookrightarrow L^1([0, T], \mathbb{R}^d)$ implies that $u'_n \rightharpoonup u'$ in $L^1([0, T], \mathbb{R}^d)$. Now, applying [3, Th. 3.6] we obtain $I(u) \leq \lim_{n \rightarrow \infty} I(u_n)$.

Step 3. Final step. The proof of the theorem is concluded with a usual argument. We take a minimizing sequence $u_n \in H$ of I . From the coercivity of I we have that u_n is bounded in $W^1 L^\Phi([0, T], \mathbb{R}^d)$. By Corollary 2.6 (passing to

subsequences) we can suppose that u_n converges uniformly to a function $u \in V$. On the other hand, u'_n is bounded in $L^\Phi = [E^{\Phi^*}]^*$. Thus, since E^{Φ^*} is separable (see [18, Thm. 6.3]), it follows from [2, Cor. 3.30] there exist a subsequence of u'_n (we denote it u'_n again) and $v \in M$ such that $u'_n \xrightarrow{*} v$. From this fact and the uniform convergence of u_n to u , we obtain that

$$\int_0^T \varphi' \cdot u \, dt = \lim_{n \rightarrow \infty} \int_0^T \varphi' \cdot u_n \, dt = - \lim_{n \rightarrow \infty} \int_0^T \varphi \cdot u'_n \, dt = - \int_0^T \varphi \cdot v \, dt,$$

for every function $\varphi \in C^\infty([0, T], \mathbb{R}^d) \subset E^{\Phi^*}$ with $\varphi(0) = \varphi(T) = 0$. Thus u has a derivative in the weak sense in L^Φ . Taking account of $L^\Phi \hookrightarrow L^1$ and [3, Thms. 2.3 and 2.17], we obtain $u \in W^1 L^\Phi$ and $v = u'$ a.e. $t \in [0, T]$. Hence, $u \in H$.

Finally, the semicontinuity of I implies that u is a minimum of I . \square

The next step is to obtain variational solutions of (P_Φ) . For this purpose we define the $C([0, T], \mathbb{R}^d)$ -closed linear set $V := \{u \in C([0, T], \mathbb{R}^d) | u(0) = u(T)\}$, $M := L^\Phi([0, T], \mathbb{R}^d)$ and H as in Theorem 4.2.

According to Remark 1 and Theorem 3.1, I is Gâteaux differentiable on $W^1 L^\Phi([0, T], \mathbb{R}^d) \cap \{u | d(u', E^\Phi) < 1\}$. Let u be a minimum and suppose that $d(u', E^\Phi) < 1$. By the Fermat's rule (see [8, Prop. 4.12]), $\langle I'(u), v \rangle = 0$, for every $v \in H$. Therefore

$$\int_0^T \nabla \Phi(u'(t)) \cdot v'(t) dt = - \int_0^T \nabla_x F(t, u(t)) \cdot v(t) dt. \quad (37)$$

From Theorem 3.1, $\nabla_x F(t, u(t)) \in L^1([0, T], \mathbb{R}^d)$ and $\nabla \Phi(u'(t)) \in L^{\Phi^*}([0, T], \mathbb{R}) \hookrightarrow L^1([0, T], \mathbb{R})$. Identity (37) holds for every $v \in C^\infty([0, T], \mathbb{R}^d)$ with $v(0) = v(T)$. Using the [13, Fundamental Lemma, p. 6] we get that $\nabla \Phi(u'(t))$ is absolutely continuous and $(d/dt)(\nabla \Phi(u'(t))) = \nabla_x F(t, u(t))$, a.e. on $[0, T]$. Moreover, $\nabla \Phi(u'(0)) = \nabla \Phi(u'(T))$. We can not move forward without assuming that Φ is *strictly convex*, i.e. $\Phi(\lambda x + (1 - \lambda)y) < \lambda \Phi(x) + (1 - \lambda)\Phi(y)$, when $\lambda \in (0, 1)$. It is well known that, in this case $\nabla \Phi : \mathbb{R}^d \rightarrow \mathbb{R}^d$ is a one-to-one map (see, e.g. [8, Ex. 4.17, p. 67]). Hence, we conclude that $u'(0) = u'(T)$. We have proved the following result.

Theorem 4.3. *Assume Φ , Φ_0 and F as in Theorem 4.2 and Φ is strictly convex. If u is a minimum of I on the set $H = \{u \in W^1 L^\Phi[0, T], \mathbb{R}^d | u(0) = u(T)\}$ and $d(u', E^\Phi) < 1$ then u is solution of (P_Φ) .*

Remark 3. If u is a minimum of I on H then $d(u', E^\Phi) \leq 1$. This follows of that $\rho_\Phi(u') < \infty$ and (18). Then, the possible minima of I that do not satisfy the hypotheses of Theorem 4.3 lie in a nowhere dense set of the domain of I .

Remark 4. The condition $d(u', E^\Phi) < 1$ is trivially satisfied when Φ is a Δ_2^∞ function, because, in this case, $E^\Phi([0, T], \mathbb{R}^d) = L^\Phi([0, T], \mathbb{R}^d)$. Therefore our Theorem 4.3 implies existence of solutions, among others, for the system (P_p) and more generally for the system (P_{p_1, p_2}) .

Remark 5. It seems that it is not possible to choose M otherwise than as in the proof of Theorem 4.3. The set M must contain the space $C^\infty([0, T], \mathbb{R}^d)$ so that we are able to infer (37). Thus, M must contain $E^\Phi([0, T], \mathbb{R}^d)$. But, it can be proved that $E^\Phi([0, T], \mathbb{R}^d)$ is weak \star dense in $L^\Phi([0, T], \mathbb{R}^d)$.

Acknowledgments

The authors are partially supported by UNRC and UNLPam grants. The second author is partially supported by a UNSL grant.

References

- [1] S. Acinas, L. Buri, G. Giubergia, F. Mazzone, and E. Schwindt. Some existence results on periodic solutions of Euler-Lagrange equations in an Orlicz-Sobolev space setting. *Nonlinear Analysis, TMA.*, 125:681 – 698, 2015.
- [2] H. Brezis. *Functional Analysis, Sobolev Spaces and Partial Differential Equations*. Universitext. Springer New York, 2010.
- [3] G. Buttazzo, M. Giaquinta, and S. Hildebrandt. *One-dimensional Variational Problems: An Introduction*. Oxford Lecture Series in Math. Clarendon Press, 1998.
- [4] M Chamra and J Maksymiuk. Anisotropic Orlicz-Sobolev spaces of vector valued functions and Lagrange equations. *arXiv preprint arXiv:1702.08683*, 2017.
- [5] A. Cianchi. A fully anisotropic Sobolev inequality. *Pacific J. Math.*, 196(2):283–295, 2000.
- [6] A. Cianchi. Local boundedness of minimizers of anisotropic functionals. *Ann. Inst. H. Poincaré Anal. Non Linéaire*, 17(2):147–168, 2000.
- [7] Andrea Cianchi. Optimal Orlicz-Sobolev embeddings. *Revista Matemática Iberoamericana*, 20(2):427–474, 2004.
- [8] F. Clarke. *Functional Analysis, Calculus of Variations and Optimal Control*. Graduate Texts in Mathematics. 2013.
- [9] W. Desch and R. Grimmer. On the well-posedness of constitutive laws involving dissipation potentials. *Trans. Amer. Math. Soc.*, (353):5095–5120, 2001.
- [10] Piotr Gwiazda, Piotr Minakowski, and Agnieszka Swierczewska-Gwiazda. On the anisotropic Orlicz spaces applied in the problems of continuum mechanics. *Discrete Contin. Dyn. Syst. Ser. S*, 6(5):1291–1306, 2013.

- [11] Chun Li, Ravi P Agarwal, and Chun-Lei Tang. Infinitely many periodic solutions for ordinary p -laplacian systems. *Adv. Nonlinear Anal.*, 4(4):251–261, 2015.
- [12] Chun Li, Zeng-Qi Ou, and Chun-Lei Tang. Periodic solutions for non-autonomous second-order differential systems with (q, p) -laplacian. *Electronic Journal of Differential Equations*, 2014(64):1–13, 2014.
- [13] J. Mawhin and M. Willem. *Critical point theory and Hamiltonian systems*. Springer-Verlag, New York, 1989.
- [14] Daniel Pasca. Periodic solutions of a class of nonautonomous second order differential systems with (q, p) -laplacian. *Bulletin of the Belgian Mathematical Society-Simon Stevin*, 17(5):841–851, 2010.
- [15] Daniel Paşca and Chun-Lei Tang. Some existence results on periodic solutions of nonautonomous second-order differential systems with (q, p) -laplacian. *Applied Mathematics Letters*, 23(3):246–251, 2010.
- [16] Daniel Pasca and Chun-Lei Tang. Some existence results on periodic solutions of ordinary (q, p) -laplacian systems. *Journal of Applied Mathematics & Informatics*, 29(1.2):39–48, 2011.
- [17] Daniel Pasca and Zhiyong Wang. On periodic solutions of nonautonomous second order hamiltonian systems with (q, p) -laplacian. *Electronic Journal of Qualitative Theory of Differential Equations*, 2016(106):1–9, 2016.
- [18] G. Schappacher. A notion of Orlicz spaces for vector valued functions. *Appl. Math.*, 50(4):355–386, 2005.
- [19] M. S. Skaff. Vector valued Orlicz spaces. II. *Pacific J. Math.*, 28(2):413–430, 1969.
- [20] C.-L. Tang. Periodic solutions for nonautonomous second order systems with sublinear nonlinearity. *Proc. Amer. Math. Soc.*, 126(11):3263–3270, 1998.
- [21] C. L. Tang and X.-P. Wu. Periodic solutions for second order systems with not uniformly coercive potential. *J. Math. Anal. Appl.*, 259(2):386–397, 2001.
- [22] Chun-Lei Tang. Periodic solutions of non-autonomous second-order systems with γ -quasisubadditive potential. *Journal of Mathematical Analysis and Applications*, 189(3):671–675, 1995.
- [23] X. Tang and X. Zhang. Periodic solutions for second-order Hamiltonian systems with a p -Laplacian. *Ann. Univ. Mariae Curie-Skłodowska Sect. A*, 64(1):93–113, 2010.
- [24] Y. Tian and W. Ge. Periodic solutions of non-autonomous second-order systems with a p -Laplacian. *Nonlinear Anal.*, 66(1):192–203, 2007.

References

- [25] Neil Trudinger. An imbedding theorem for $H^0(G, \Omega)$ -spaces. *Studia Mathematica*, 50(1):17–30, 1974.
- [26] X.-P. Wu and C.-L. Tang. Periodic solutions of a class of non-autonomous second-order systems. *J. Math. Anal. Appl.*, 236(2):227–235, 1999.
- [27] Xiaoxia Yang and Haibo Chen. Periodic solutions for a nonlinear (q, p) -Laplacian dynamical system with impulsive effects. *Journal of Applied Mathematics and Computing*, 40(1-2):607–625, 2012.
- [28] Xiaoxia Yang and Haibo Chen. Existence of periodic solutions for sublinear second order dynamical system with (q, p) -laplacian. *Mathematica Slovaca*, 63(4):799–816, 2013.
- [29] F. Zhao and X. Wu. Periodic solutions for a class of non-autonomous second order systems. *J. Math. Anal. Appl.*, 296(2):422–434, 2004.