COMP2521 19T0 lec13 cs2521@ jashankj@

COMP2521 19T0 Week 7, Thursday: Tropical Paradise

Jashank Jeremy
jashank.jeremy@unsw.edu.au

exotic trees

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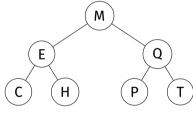
Balanced Trees

Complex Approaches Splay

Balanced Trees

Splay

Four choices to consider for a double-rotation:



1: LL 2: LR

3: RL 4: RR



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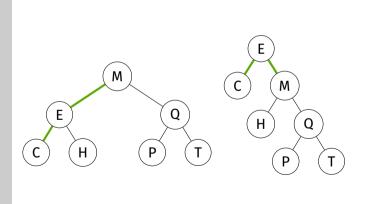
ees omplex Appro

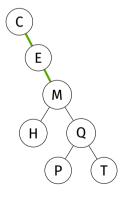
Splay

Splay Rotations

Double-Rotation: Left, Left

ROTATER au_{M} ROTATER au_{E}





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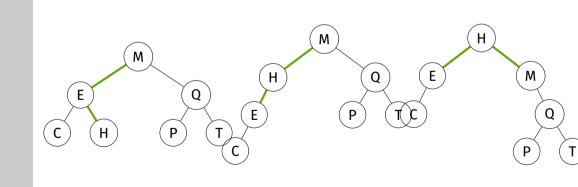
mplex Approach

Splay 2-3-4

Splay Rotations

Double-Rotation: Left, Right

ROTATEL τ_{E} ROTATER τ_{M}



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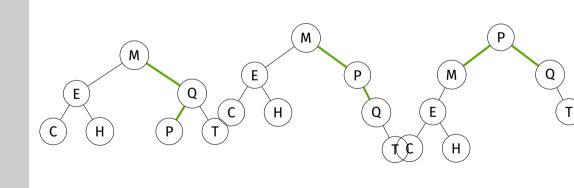
rees

Splay 2-3-4

Splay Rotations

Double-Rotation: Right, Left

ROTATER τ_{Q} ROTATEL τ_{M}





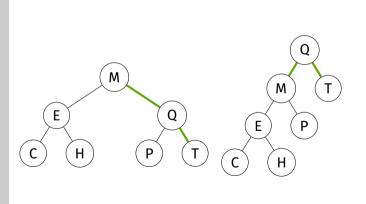
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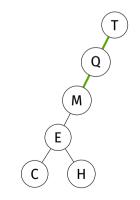
Splay

Splay Rotations

Double-Rotation: Right, Right

ROTATEL au_{M} ROTATEL τ_0





Balanced Trees Complex Approach

Splay

Some implementations do rotation-on-search, which has a similar effect to periodic rotations; increases search cost by doing more work, decreases search cost by moving likely keys closer to root.

Even on a degenerate tree, splay search massively improves the balance of the tree.

```
Complex App
Splay
```

```
btree node *btree insert splay (btree node *tree, Item it)
    if (tree == NULL) return btree node new (it, NULL, NULL);
    int diff = item cmp (it, tree->value);
    if (diff < 0) {</pre>
        if (tree->left == NULL) {
            tree->left = btree node new (it, NULL, NULL);
            return tree:
        int ldiff = item cmp (it. tree->left->value);
        if (ldiff < 0) {</pre>
            // Case 1: left-left
            tree->left->left = btree_insert_splay (tree->left->left, it);
            tree = btree_rotate_right (tree);
        } else {
            // Case 2: left-right
            tree->left->right = btree_insert_splay (tree->left->right, it);
            tree->left = btree rotate left (tree->left):
        return btree_rotate_right (tree);
```

```
Splay
```

```
// ... btree_insert_splay continues ...
   } else if (diff > 0) {
        int rdiff = item cmp (it, tree->right->value);
        if (rdiff < 0) {</pre>
            // Case 3: right-left
            tree->right->left = btree_insert_splay (tree->right->left, it);
            tree->right = btree_rotate_right (tree->right);
        } else {
            // Case 4: right-right
            tree->right->right = btree insert splay (tree->right->right, it);
            tree = btree rotate left (tree):
        return btree_rotate_left (tree);
    } else
        tree->value = it:
    return tree;
```

without insertion-specific code, we might call this btree splay

Balanced Trees Complex Approach

```
Splay
```

```
btree_node *btree_search_splay (btree_node **root, Item it)
{
    assert (root != NULL);
    if (*root == NULL) return NULL;
    *root = btree_splay (*root, it);
    if (item_cmp ((*root)->value, it) == 0)
        return *root;
    else
        return NULL;
}
```

Splay 2-3-4

Splay Trees: Why Bother?

Insertion Time Complexity

worst case (for work): item inserted at the end of a degenerate tree. $O\left(n\right)$ steps necessary here... but overall tree height now halved

worst case (from resulting tree): item inserted at root of degenerate tree. $O\left(1\right)$ steps necessary. surprise!

even in the worst case, not possible to *repeatedly* have O(n) steps to insert

Overall Time Complexity

alanced ees omplex Approach

Splay

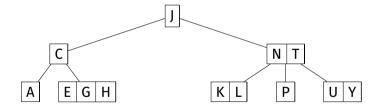
Assuming we do splay operations on insert and search, assuming we have N nodes and M inserts/searches: average $O\left((N+M)\log_2\left(N+M\right)\right)$

A good (amortised) cost overall ... but no guarantees of improved individual operations: some may still be $O\left(N\right)$.

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Balanced Trees Complex Approaches Splay 2-3-4

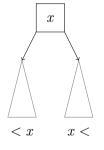
2-3-4 trees have three types of nodes: 2-nodes have one value and two children; 3-nodes have two values and three children; 4-nodes have three values and four children;

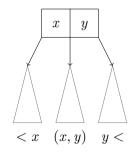


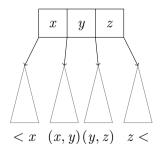
2-3-4 trees grow 'upwards' from the leaves, all of which are equidistant to the root.

2-3-4

A similar ordering to a conventional BST:







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Trees
Complex Approach
Splay
2-3-4

2–3–4 trees are always balanced; depth is $O(\log n)$

worst case for depth: all nodes are 2-nodes same case as for balanced BSTs, i.e. $d \simeq \log_2 n$

best case for depth: all nodes are 4-nodes balanced tree with branching factor 4, i.e. $d \simeq \log_4 n$

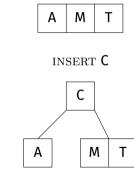
2-3-4

The Algorithm

- find leaf node where item belongs (via search)
- ② if node is not full (i.e., order < 4), insert item in this node, order++.
- 3 if node is full (i.e., contains 3 Items):
 - split into two 2-nodes as leaves
 - promote middle element to parent
 - insert item into appropriate leaf 2-node
 - if parent is a 4-node, continue split/promote upwards
 - if promote to root, and root is a 4-node, split root node and add new root

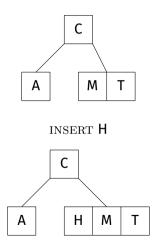
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Balanced Trees Complex Approach Splay 2-3-4

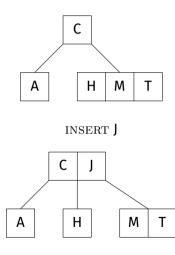


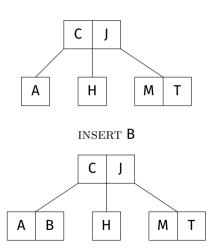
(II)

Balanced Trees Complex Approache Splay 2-3-4



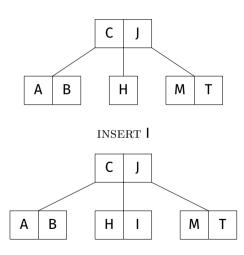
Balanced
Trees
Complex Approaches
Splay
2-3-4





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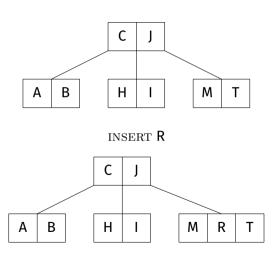
Balanced Trees Complex Approache Splay 2-3-4



(VI)

Balanced Trees Complex Approach

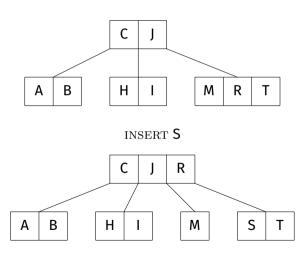
2-3-4



2-3-4

2–3–4 Tree Insertion

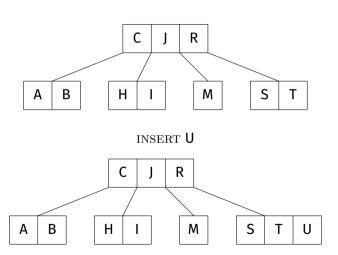
(VII)

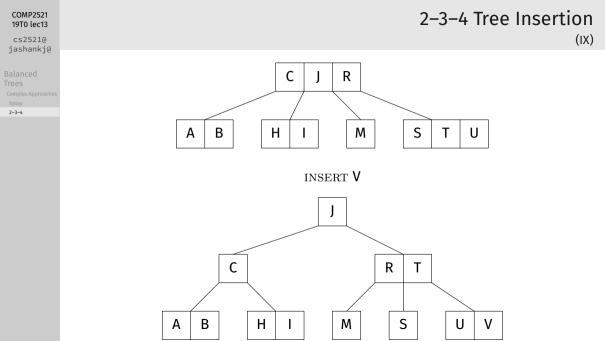


2-3-4

2–3–4 Tree Insertion

(VIII)





C Implementation: Node Structure

2-3-4

```
typedef struct t234_node t234_node;
struct t234_node {
   int order; // 2, 3, 4
   Item data[3]; // items in node
   t234_node *child[4]; // links to subtrees
};
```

```
Trees
Complex Approach
Splay
2-3-4
```

```
Item *t234 search (t234 node *tree, Item it)
    if (tree == NULL) return NULL;
    int i, diff = 0;
   for (i = 0; i < tree->order - 1; i++) {
       diff = item_cmp (it, tree->data[i]);
        if (diff <= 0) break:
   if (diff == 0) return &(t->data[i]);
   else return t234 search (t->child[i], k);
```

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Complex Approact

2-3-4

Why stop with just 2-, 3-, and 4-nodes? If we allow nodes to hold M/2 to M items, we have a B-tree.

commonly used in DBMS, FS, ... where a node represents a disk page.

2-3-4

2-3-4, unplugged (I)

red-black trees are a representation of 2-3-4 trees using only plain old BST nodes; each node needs one extra value to encode link type, but we no longer have to deal with different kinds of nodes.

plain old binary search tree search works, unmodified get benefits of 2–3–4 tree self-balancing on insert, delete ... with great complexity in insertion/deletion.



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Balanced Trees Complex Approaches

2-3-4

Red-Black Trees

2-3-4, unplugged (II)

red links combine nodes to represent 3- and 4-nodes; effectively, child along red link is a 2-3-4 neighbour. black links are analogous to 'ordinary' child links. some texts call these 'red nodes' and 'black nodes'

THE RULES:

each link is either red or black no two red links appear consecutively on any path all paths from root to leaf have same number of black links