

# Financial Modeling Analysis

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# Contents

<b>1</b>	<b>TEST</b>	<b>2</b>
<b>2</b>	<b>Single Period Model</b>	<b>3</b>
2.1	Simple Example . . . . .	3
2.2	State price . . . . .	3
2.3	Optimality and Asset Pricing . . . . .	6
2.4	Discrete Martingale . . . . .	8

# Chapter 1

## TEST

SSS

# Chapter 2

## Single Period Model

### 2.1 Simple Example

Suppose one buy a call option  $C$  which payoff  $V_1 = (S_1 - K)^+$  at time 1,  $S_1$  can be  $uS_0 > K$  or  $dS_0 < K$  determined in probability space  $(\{H, T\}, 2^{\{H, T\}}, \mathbb{P})$ . To replicate such option, we construct our portfolio by buying  $\Delta_0$  stock and investing remaining in risk-free asset at return  $r$ :

$$(V_0 - \Delta_0 S_0)(1 + r) + \Delta_0 S_1 = (S_1 - K)^+$$

solve:

$$V_0 = \frac{pV_1(H) + qV_1(T)}{1 + r}, \Delta_0 = \frac{V_1(H) - V_1(T)}{S_1(H) - S_1(T)}$$

where  $p = \frac{1+r-d}{u-d}$ ,  $q = 1 - p$ .

$p$  and  $q$  can be then seen as probability assigned to  $\mathbb{P}\{H\}$  and  $\mathbb{P}\{T\}$ . Then  $V_0$  is just the discounted of expected value of such option, such measure  $\mathbb{P}$  is called **risk-neutral**.

### 2.2 State price

Suppose  $\mathbf{S}_0 \in \mathbb{R}^N$  is price of  $N$  stocks at time 0, and  $\mathbf{D} \in \mathbb{R}^{N \times n}$  is their price at time  $t$  for  $n$  states. For any portfolio  $\boldsymbol{\theta} \in \mathbb{R}^N$ , it cost  $\mathbf{S}_0' \boldsymbol{\theta}$  and its value is  $\mathbf{D}' \boldsymbol{\theta} \in \mathbb{R}^n$  for all  $n$  states.

An arbitrage is then defined as a portfolio  $\boldsymbol{\theta}$ , *s.t.*  $\mathbf{S}_0' \boldsymbol{\theta}$  have different sign with  $\mathbf{D}' \boldsymbol{\theta}$ .

**Definition 2.1** (State price). A state price vector is  $\psi \in \mathbb{R}_{++}^n$  s.t.  $\mathbf{S}_0 = \mathbf{D}\psi$ .

To justify the name of state price, suppose we want to “bet” the state of market, i.e., we would like earning  $\mathbf{1}_{state=i}$ , then our portfolio supposed to be  $\mathbf{D}'\theta = \mathbf{e}_i$ , and it cost

$$\mathbf{S}_0'\theta = \psi'\mathbf{D}'\theta = \psi'\mathbf{e}_i = \psi_i$$

so the coordinate of  $\psi$  is the price of “betting” a state.

**Theorem 2.1.** *There is no arbitrage iff there is a state price vector.*

**Theorem 2.2** (Separating Hyperplane Theorem). *Suppose  $M$  and  $K$  are closed convex cones in  $\mathbb{R}^d$  that  $M \cap K = \{\mathbf{0}\}$ , if  $K$  isn't a linear space, then there is a nonzero linear  $f$  separated them, i.e.,  $f(x) < f(y)$  for any  $x \in M$  and  $y \in K - \{\mathbf{0}\}$ .*

**Theorem 2.3** (Riesz Representation Theorem). *Any continuous linear function  $f$  on Hilbert space  $\mathcal{H}$  can be written as  $f(x) = \langle x, v \rangle$  for some  $v \in \mathcal{H}$ .*

*Proof.* Let  $M = \{(-\mathbf{S}_0'\theta, \mathbf{D}'\theta) : \theta \in \mathbb{R}^N\}$  and  $K = \mathbb{R}_+ \times \mathbb{R}_+^n$ . Then there is no arbitrage iff  $K \cap M = \{\mathbf{0}\}$ .

$\Rightarrow$ , let  $f$  be the functional in theorem 2.2, note  $M$  is a linear space,  $f$  should be vanish on  $M$ , i.e.,  $f(x) = 0, \forall x \in M$ , otherwise, fix  $f(y) > 0$  for  $y \in K - \{\mathbf{0}\}$ , we can find  $\lambda \in \mathbb{R}$  s.t.  $\lambda f(x) = f(\lambda x) > f(y)$ .

Then by theorem 2.3, we have  $f(x) = x'v$  for some  $v$ , write  $v = (\alpha, \phi)$  where  $\alpha \in \mathbb{R}$  and  $\phi \in \mathbb{R}^n$ . Since  $f(x) > 0$  for nonzero  $x \in K$ ,  $\alpha$  and  $\phi$  should strictly positive, then

$$-\alpha\mathbf{S}_0'\theta + \phi'\mathbf{D}'\theta = 0$$

which implies  $-\alpha\mathbf{S}_0 + \mathbf{D}\phi = \mathbf{0}$  and thus  $\frac{\phi}{\alpha}$  is a state price vector as required.

$\Leftarrow$ , Suppose  $(-\mathbf{S}_0'\theta, \mathbf{D}'\theta) \in K$ , then,  $\psi'\mathbf{D}'\theta \leq 0$  and  $\mathbf{D}'\theta \geq 0$ , which contrast to  $\psi \gg 0$ . □

**Exercise 2.1.** 1

*Solution.* Given above.

**Exercise 2.2.** 2

*Solution.* Setup:

$$\mathbf{S}_0 = (1, S_0)', \mathbf{D} = \begin{bmatrix} 1+r & 1+r \\ uS_0 & dS_0 \end{bmatrix}$$

then the state price should be

$$\psi = \mathbf{D}^{-1}\mathbf{S}_0 = [(-u+1+r)S_0, (d-1-r)S_0]' \gg 0$$

then claim follows.

**Exercise 2.3.** 3

*Solution.* No. Let  $\psi = (\frac{1}{3}, \frac{1}{3})$ , it's a state price vector.

**Exercise 2.4.** 4

*Solution.* Note column space of  $D$  is just  $\{\lambda \cdot (1, 2, 3)' : \lambda \in \mathbb{R}\}$ , which excluded  $\bar{q}$ , therefore there is no state price vector and thus arbitrage exists.

### 2.2.1 Risk-neutral probability

If  $\mathbf{p} > 0$  and  $\mathbf{e}'\mathbf{p} = 1$ , we can view  $\mathbf{p} \in \mathbb{R}^n$  as a probability vector represent each state, as there is only  $n$  states, we can use it to represent probability measure. Then

$$\mathbb{E} S_T = \mathbf{D}\mathbf{p}$$

take  $\mathbf{p} = \frac{\psi}{\mathbf{e}'\psi}$ . Then

$$\mathbb{E} S_T = \frac{\mathbf{D}\psi}{\mathbf{e}'\psi} = \frac{\mathbf{S}_0}{\mathbf{e}'\psi}$$

where  $\mathbf{e}'\psi$  is the discount on riskless borrowing. To confirm this, suppose the market allow positive riskless borrowing and we replicate it by investing a portfolio  $\boldsymbol{\theta}$  for which

$$\mathbf{D}'\boldsymbol{\theta} = \mathbf{e}$$

and  $\boldsymbol{\theta}$  cost  $\mathbf{S}_0'\boldsymbol{\theta} = \psi'\mathbf{D}'\boldsymbol{\theta} = \mathbf{e}'\psi$ . That is  $\psi_0 = \mathbf{e}'\boldsymbol{\theta}$  is the riskless discount, i.e.  $\frac{1}{\psi_0} = e^{rT}$ .

If probability vector  $\mathbf{p}$  also let  $\mathbb{E} S_T$  have the same value, we said it's a risk-neutral probability measure.

A claim  $C \in \mathbb{R}^n$  and it's said to be attainable or can be hedged if there is a portfolio  $\boldsymbol{\theta}$  that  $\mathbf{D}'\boldsymbol{\theta} = C$ .

**Theorem 2.4.** *With absence of arbitrage, the price of an attainable claim  $C \in \mathbb{R}^n$  is  $\mathbf{e}'\psi \mathbb{E} C$  if  $\mathbf{S}_0 = \mathbf{e}'\psi \mathbb{E} S_T$  for some probability measure  $\psi$ .*

*Proof.* Suppose  $\mathbf{D}'\boldsymbol{\theta} = C$ , then its price should be  $\boldsymbol{\theta}'\mathbf{S}_0$

$$\mathbb{E} C = \mathbb{E} \mathbf{D}'\boldsymbol{\theta} = \frac{\boldsymbol{\theta}'\mathbf{D}\psi}{\mathbf{e}'\psi} = \boldsymbol{\theta}'\mathbf{S}_0$$

□

A market is said to be complete if every claim  $C$  is attainable.

**Theorem 2.5.** *The market in our setting is complete iff  $N \geq n$  and  $\mathbf{D}$  have full column rank.*

*Proof.* Completeness is precisely equivalent row space  $\mathcal{C}(\mathbf{D}') = \mathbb{R}^n$  and then claim follows. □

In complete market, risk-neutral measure is unique.

## 2.3 Optimality and Asset Pricing

Suppose the market  $(\mathbf{D}, \mathbf{S}_0)$  is given, an agent is defined by an utility function  $U : \mathbb{R}^n \rightarrow \mathbb{R}$  and an endowment  $\boldsymbol{\varepsilon} \in \mathbb{R}_+^n$ . Our optimal target is

$$\max_{\boldsymbol{\theta} \in A} U(\boldsymbol{\varepsilon} + \mathbf{D}'\boldsymbol{\theta})$$

where

$$A = \{\mathbf{S}'_0\boldsymbol{\theta} \leq 0, \boldsymbol{\varepsilon} + \mathbf{D}'\boldsymbol{\theta} \geq \mathbf{0}\}$$

and we assume there is  $\boldsymbol{\theta}_0$  s.t.  $\mathbf{D}'\boldsymbol{\theta}_0 > 0$ , that along with absence of arbitrage implies the optimal  $\boldsymbol{\theta}^*$  satisfy  $\mathbf{S}'_0\boldsymbol{\theta} = 0$ , otherwise we can invest some on  $\boldsymbol{\theta}_0$  and get a better portfolio.

Note  $A = \{\mathbf{S}'_0\boldsymbol{\theta} = 0, \boldsymbol{\varepsilon} + \mathbf{D}'\boldsymbol{\theta} \geq \mathbf{0}\}$  is closed and bounded if there is no arbitrage and assume  $U$  is continuous, we have

**Proposition 2.1.** *The optimal problem has solution iff there is no arbitrage.*

**Theorem 2.6.** *If in optimal solution  $\boldsymbol{\theta}^*$ ,  $\mathbf{c}^* = \boldsymbol{\varepsilon} + \mathbf{D}'\boldsymbol{\theta}^* \gg 0$ ,  $\nabla U \gg 0$  at  $\mathbf{c}^*$ , There exist  $\lambda > 0$  s.t.  $\lambda \nabla U(\mathbf{c}^*)$  is a state price vector.*

*Proof.* Suppose  $\boldsymbol{\theta}^*$  is solution, for any portfolio  $\boldsymbol{\theta}$  s.t.  $\mathbf{S}'_0\boldsymbol{\theta} = 0$ , if we combine  $\boldsymbol{\theta}^*$  and  $\boldsymbol{\theta}$ , utility will be

$$g(\alpha) = U[\boldsymbol{\varepsilon} + \mathbf{D}'(\boldsymbol{\theta}^* + \alpha\boldsymbol{\theta})] = U(\mathbf{c}^* + \alpha\mathbf{D}'\boldsymbol{\theta})$$

where  $\mathbf{c}^* = \boldsymbol{\varepsilon} + \mathbf{D}'\boldsymbol{\theta}^*$ . As  $\boldsymbol{\theta}^*$  is the solution, we have FOC on  $\alpha = 0$ :

$$g'(0) = [\nabla U(\mathbf{c}^*)]' \mathbf{D}'\boldsymbol{\theta} = [\mathbf{D}'\nabla U(\mathbf{c}^*)]' \boldsymbol{\theta} = 0$$

that implies  $\mathbf{D}'\nabla U(\mathbf{c}^*) = \mu \mathbf{S}_0$  for some  $\mu \in \mathbb{R}$ . It's remaining to show that  $\mu > 0$ . Take  $\boldsymbol{\theta}_0$  in assumption, we have

$$\mu \mathbf{S}'_0\boldsymbol{\theta}_0 = [\nabla U(\mathbf{c}^*)]' \mathbf{D}'\boldsymbol{\theta}_0 > 0$$

thus  $\mu > 0$  as required. □

Since convex function automatically satisfy SOC, we have

**Corollary 2.1.** *If  $U$  is concave and strictly increasing,  $\mathbf{c}^* \gg 0$ , then  $\boldsymbol{\theta}^*$  is the optimal solution iff  $\lambda \nabla U(\mathbf{c}^*)$  is a state price vector for some  $\lambda > 0$ .*

### 2.3.1 Expected Utility Function

Now we consider a special case of utility:

$$U(\mathbf{c}) = \mathbb{E} u(c) = \mathbf{p}'\mathbf{u}$$

where  $u : \mathbb{R}_+ \rightarrow \mathbb{R}$  is concave and increasing and  $\mathbf{u} = [u(c_1), u(c_2), \dots, u(c_n)]'$ .

Then we have

$$\nabla U(\mathbf{c}) = \begin{bmatrix} p_1 u'(c_1) \\ p_2 u'(c_2) \\ \vdots \\ p_n u'(c_n) \end{bmatrix}$$

theorem 2.6 yields

$$\mathbf{S}_0 = \mathbf{D}\psi = \lambda \mathbf{D}\nabla U(\mathbf{c}^*) = \mathbb{E} [\lambda S_T \cdot u'(c)]$$

where

$$\psi = \lambda \begin{bmatrix} p_1 u'(c_1) \\ p_2 u'(c_2) \\ \vdots \\ p_n u'(c_n) \end{bmatrix}$$

thus we can define risk-neutral measure  $\mathbb{Q}$  by  $\psi, \mathbf{S}_0 = \psi_0 \mathbb{E}^{\mathbb{Q}} S_T$ .

Set  $\boldsymbol{\pi} = [\pi_i = \psi_i/p_i]$ , then  $\mathbb{E} \boldsymbol{\pi} = \psi_0$  and  $\mathbf{S}_0 = \mathbb{E} S_T \boldsymbol{\pi}$

*Remark.* We use boldface to refer the vector representation of a random variable.

In fact, for any attainable claim  $C$ , we have

**Theorem 2.7.** *The price of  $C$  is given by  $\mathbb{E} \boldsymbol{\pi} \mathbb{E}^{\mathbb{Q}} C$*

*Proof.* Suppose  $C$  can be attain by  $\theta$ , then

$$S'_0 \theta = [\mathbb{E} S_T \boldsymbol{\pi}]' \theta = \mathbb{E} \pi S'_T \theta = \mathbb{E} \pi C = \psi_0 \mathbb{E}^{\mathbb{Q}} C = \mathbb{E} \boldsymbol{\pi} \mathbb{E}^{\mathbb{Q}} C$$

□

### 2.3.2 Equilibrium

**Definition 2.2.** Equilibrium is a pair  $(\boldsymbol{\theta}_i)_{i \leq m}, q$ , where  $\boldsymbol{\theta}_i$  maximize each one's utility and  $\sum \boldsymbol{\theta}_i = \mathbf{0}$ .

If each person invest  $\boldsymbol{\theta}_i$ , then we allocate  $\mathbf{c}_i = \boldsymbol{\varepsilon}_i + \mathbf{S}'_{\mathbf{T}} \boldsymbol{\theta}_i$  for each one, and therefore we can define Pareto optimal etc.

**Theorem 2.8** (The First Welfare Theorem). *Under complete market, equilibrium is Pareto optimal.*



## 2.4 Discrete Martingale

Under risk-neutral measure, for each time  $k$ , we have

$$\psi_0 \mathbb{E}_k S_{k+1} = S_k$$

thus if we define the discounted stock price as  $\tilde{S}_k = \psi_0^k S_k$  (where each  $\psi_0$  can be vary by time so it should be  $\prod_{i=1}^k \psi_{0,i}$  but we abuse notation here), then  $\tilde{S}$  became a martingale. That implies the discounted claim  $\tilde{V}$  is also a martingale.

Now let  $(\varphi_n, \psi_n)$  be the amount of stock and bond at time  $n$ , the portfolio we holding value:

$$V_n = \varphi_n S_n + \psi_n B_n$$

since the portfolio is self-financing, the should equal to the value at the start of  $n+1$  (when the price is remain the same):

$$V_n = \varphi_{n+1} S_n + \psi_{n+1} B_n$$

Put them together and take discount, we have

$$\tilde{V}_n = \varphi_{n+1} \tilde{S}_n + \psi_{n+1} = \varphi_n \tilde{S}_n + \psi_n$$

we have

$$\tilde{V}_{n+1} - \tilde{V}_n = \varphi_{n+1} (\tilde{S}_{n+1} - \tilde{S}_n)$$

By induction we have

$$\tilde{V}_n = V_0 + \sum_{i=0}^{n-1} \varphi_{i+1} (\tilde{S}_{i+1} - \tilde{S}_i)$$

that is a martingale by invoking following lemma:

**Lemma 2.1.** Suppose process  $X = \{X_t\}_{t \in \mathbb{N}}$  is adapted to  $\mathbb{F} = \{\mathcal{F}_t\}_{t \in \mathbb{N}}$  and  $\{\varphi_i\}_{i \in \mathbb{N}^+}$  is  $\mathbb{F}$ -predictable. Then

$$\left\{ Z_n \triangleq Z_0 + \sum_{i=0}^{n-1} \varphi_{i+1} (X_{i+1} - X_i) \right\}_{n \in \mathbb{N}}$$

is a martingale if so is  $X$ .

Now we turn to stocks market consist  $N$  stocks, construct sample space as  $\Omega$  be all possible path  $(\mathbb{R}^N)^T$ . The absence of arbitrage give a risk-neutral measure for which

$$S_{t-1} = \psi_0 \mathbb{E}_{S_{t-1}} S_t$$

and as before, take discount  $\tilde{S}_t = \psi_0^t S_t$  we have a martingale. And we claim that absence of martingale is equivalent to existence of risk-neutral measure.