## 1 Numerical integration on the Lorenz system

1. Integrate numerically the system

$$\begin{cases} \dot{x} = \sigma(y - x) \\ \dot{y} = rx - xz - y \\ \dot{z} = xy - bz \end{cases}$$
 (1)

up to t=60, with a time step dt = 0.005 using the Euler forward method, with the following sets of values for the parameters

- Set A:  $\sigma, b, r = (10, 8/3, 28)$
- Set B:  $\sigma, b, r = (10, 8/3, 9)$

and the initial condition  $L_0 \equiv (x_0, y_0, z_0) = (9, 10, 20)$ . Plot trajectories  $L(t, L_0)$  in the (x, z) space and describe the result (max 100 words).

- 2. Repeat 1. with  $L'_0 = (x'_0, y'_0, z'_0) = (9 + \epsilon, 10, 20)$  with  $\epsilon = 1 \times 10^{-10}$ . Plot x(t) for the two solutions  $L(t, L_0)$  and  $L(t, L'_0)$  and their difference. Describe the result (max 100 words).
- 3. For the set of parameters A, treat  $L(t, L_0)$  as an observed state and call it  $L_{true} = (x_{true}, y_{true}, z_{true})$  and  $L(t, L'_0) = (x', y', z')$  as an integration affected by an error  $\epsilon$  in the initial condition. Compute the root-mean-square error (RMSE)

$$R(t) = \sqrt{(x_{true}(t) - x'(t))^2 + (y_{true}(t) - y'(t))^2 + (z_{true}(t) - z'(t))^2}$$

as function of lead time and plot it on a linear and semilog scale. Describe the result (max 150 words). Repeat with  $\epsilon = 1 \times 10^{-5}$ ,  $\epsilon = 1 \times 10^{-3}$  and  $\epsilon = 10^{-1}$  and fill a table with the values of  $\epsilon$  and the first time  $t_a$  such that R(t) > a with a = 0.5. What can we say about the predictability time and how it varies with the error  $\epsilon$ ? Discuss in no more than 200 words.

4. Generate an ensemble of initial conditions by perturbing the initial condition  $L_0$  with a random perturbation  $E_k \equiv (\epsilon_k, 0, 0)$  for k = 1, ..., N and N=100. Suppose for simplicity that  $\epsilon_k$  is uniformly distributed between -0.75 and 0.75. Note that numpy.random.random() generates a random real number between 0 and 1 sampling from a uniform distribution. For each member of the ensemble  $L'_k(t, L_0 + E_k)$  integrate the system up to t=4 and compute the root mean square error

$$R_k(t)$$

and the root mean square error of the average  $\langle L \rangle$ , where

$$\langle \dots \rangle = \frac{1}{N} \sum_{k=1}^{N} (\dots).$$

Compare the latter with the average mean square error  $\langle R \rangle = \frac{1}{N} \sum_{k=1}^{N} R_k$  by plotting them as function of lead time. Describe and discuss the result.

5. (OPTIONAL) With the ensemble generated in 4, compute

$$S = \sqrt{\langle (x_k - \langle x_k \rangle)^2 \rangle}$$

Analyse S up to t=4 for different initial conditions and compare it with the RMSE of the ensemble mean. Discuss the interpretation of the result.

6. (OPTIONAL) Integrate numerically the system

$$\begin{cases} \dot{x} = \sigma(y - x) \\ \dot{y} = rx - xz - y + f(t) \\ \dot{z} = xy - bz \end{cases}$$
 (2)

up to t=500, with f(t)=0 and with an ensemble of 50 initial conditions with a uniform distribution of x between -20 and -20, y between -20 and 20, and z between 0 and 30. For each member k, consider subsets of the time series each 5000 time step long, from  $1+\tau$  to  $5000+\tau$  with  $\tau=1,2,...,M$  (choose the maximum M given the length of the time series). For each member, sample the probability  $p_x$  that x<0 as the number of time steps with x<0 divided by the total number of time steps and estimate it in chunks of 5000 time steps, compute this value for each  $\tau$  and assign it to an array  $P_k(\tau)$ . Plot  $P_k(\tau)$  for each member and plot the mean  $\langle P_k \rangle$ , all in the same panel (ax.plot(...,alpha=0.5,...) can be used to plot semi-transparent lines). Repeat all these tasks with  $f(t)=\frac{1}{3}\sqrt{t}$ . Plot also f(t). Describe the result and discuss what we can conclude about the interpretation of the response of a chaotic system to a forcing f (max 200 words).

7. Write a short report (max 4 pages), including a brief introduction, figures and text produced during the session (points 1-4 and 5-6 where applicable) and a conclusive comment.