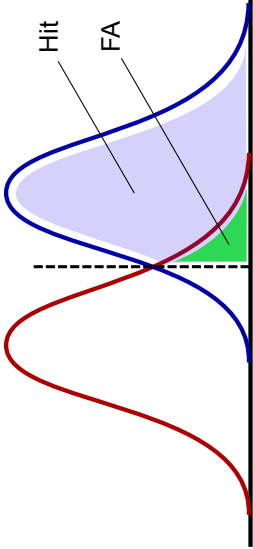


$P(e|noise)$

$P(e|signal)$



evidence (e)