view frames Result Recorded at time: 36.488 odom Broadcaster: /gazebo Average rate: 50.201 Buffer length: 4.98 Most recent transform: 36.47 Oldest transform: 31.49 base link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher | Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 50.806 Average rate:  $1000\overline{0}.0$ Average rate:  $1000\overline{0}.0$ Average rate:  $49.5\overline{9}7$ Average rate:  $49.5\overline{9}7$ Average rate:  $49.5\overline{9}7$ Average rate:  $49.5\overline{97}$ Buffer length: 4.96 Buffer length: 4.96 Buffer length: 4.96 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 4.96 Buffer length: 4.96 Most recent transform: 36.45 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 36.45 Most recent transform: 36.45 Most recent transform: 36.45 Most recent transform: 36.45 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 31.49 imu\_link laser\_link front\_left\_wheel front\_right\_wheel rear\_left\_wheel rear\_right\_wheel arm\_base Broadcaster: /robot\_state\_publisher Average rate:  $50.8\overline{0}6$ Buffer length: 4.96 Most recent transform: 36.45 Oldest transform: 31.49 bicep Broadcaster: /robot\_state\_publisher Average rate:  $50.8\overline{0}6$ Buffer length: 4.96 Most recent transform: 36.45 Oldest transform: 31.49 bottom\_wrist Broadcaster: /robot state publisher Average rate:  $50.8\overline{0}6$ Buffer length: 4.96 Most recent transform: 36.45 Oldest transform: 31.49 elbow Broadcaster: /robot\_state\_publisher Average rate:  $49.5\overline{9}7$ Buffer length: 4.96 Most recent transform: 36.45 Oldest transform: 31.49 top\_wrist