

A polytope in  $\mathbb{R}^d$  is the  $n$ -dimensional analog of a polygon.

You can describe it in two ways:

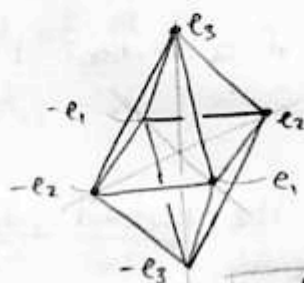
### ① Vertices

A polytope is the "convex hull" of a finite set of points  $V = \{v_1, \dots, v_n\}$  in  $\mathbb{R}^d$ .

$$P = \text{conv}(V) = \left\{ x = \sum_{i=1}^n a_i v_i \mid a_i \geq 0, \sum_{i=1}^n a_i = 1 \right\}$$

Think: Snap a rubber band (or rubber suit?) around  $V$ .

This is the smallest convex set containing  $P$ .



$\text{conv}(\pm e_1, \pm e_2, \pm e_3)$   
octahedron  
(6 vertices)

### ② Facets

A polytope is a bounded intersection of halfspaces defined by linear inequalities

$$P = \{ x \in \mathbb{R}^d \mid a_1 \cdot x \leq z_1, \dots, a_m \cdot x \leq z_m \}$$

octahedron:

$$x_1 + x_2 + x_3 \leq 1$$

$$x_1 - x_2 + x_3 \leq 1$$

$\vdots$

$$\pm x_1 \pm x_2 \pm x_3 \leq 1 \quad (8 \text{ facets})$$

### Theorem

A subset  $S \subseteq \mathbb{R}^d$  is a convex hull of a finite set of points  
iff it is a bounded intersection of halfspaces.

This is great because we can go from the  $V$ -description to the  $H$ -description freely; for example:

$$\circ (\text{polytope}) \cap (\text{polytope}) = \text{polytope} \quad H$$

$$\circ (\text{polytope}) \cap (\text{affine subspace}) = \text{polytope} \quad H$$

$$\circ (\text{projection of polytope}) = \text{polytope} \quad V$$

To define a face  $F$  of  $P$ , one "points in its direction"  $w$ :

$$F_w = \{x \in P \mid w \cdot x \text{ is maximum}\} \quad (\text{a polytope of smaller dimension})$$

Face of octahedron: 1 3-D, 8 2-D, 12 1-D, 6 0-D, 1 (-1)-D

Def The matroid polytope  $P_M$  of  $M$  (or matroid basis polytope)

is

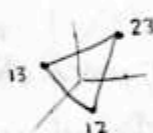
$$P_M = \text{conv}(\{e_{b_1} + \dots + e_{b_r} \mid \{b_1, \dots, b_r\} \text{ is a basis of } M\}) \text{ in } \mathbb{R}^E.$$

Ex  $|E|=3$

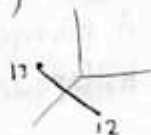
$$M = U_{1,3}$$



$$M = U_{2,3}$$



$$M(\begin{smallmatrix} 1 & 2 \\ 3 \end{smallmatrix})$$

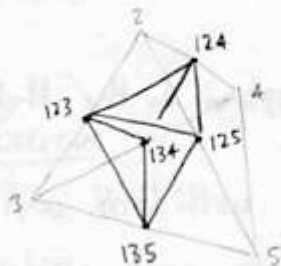


Ex  $M(\begin{smallmatrix} 1 & 2 & 3 & 4 & 5 & 6 \\ 5 & 3 & 1 & 6 \end{smallmatrix}) = \text{conv}(\begin{matrix} 111000, 110100, 110010, 101100, 101010 \\ \uparrow \quad \uparrow \quad \uparrow \quad \uparrow \quad \uparrow \\ 123 \quad 124 \quad 125 \quad 134 \quad 135 \end{matrix})$

This is in  $\mathbb{R}^6$ ! But:

- $x_1 + x_2 + x_3 + x_4 + x_5 + x_6 = 3$
- $x_1 = 1$
- $x_6 = 0$

$\rightarrow$  So 3-D



Q What is  $\dim(P_M)$ ?