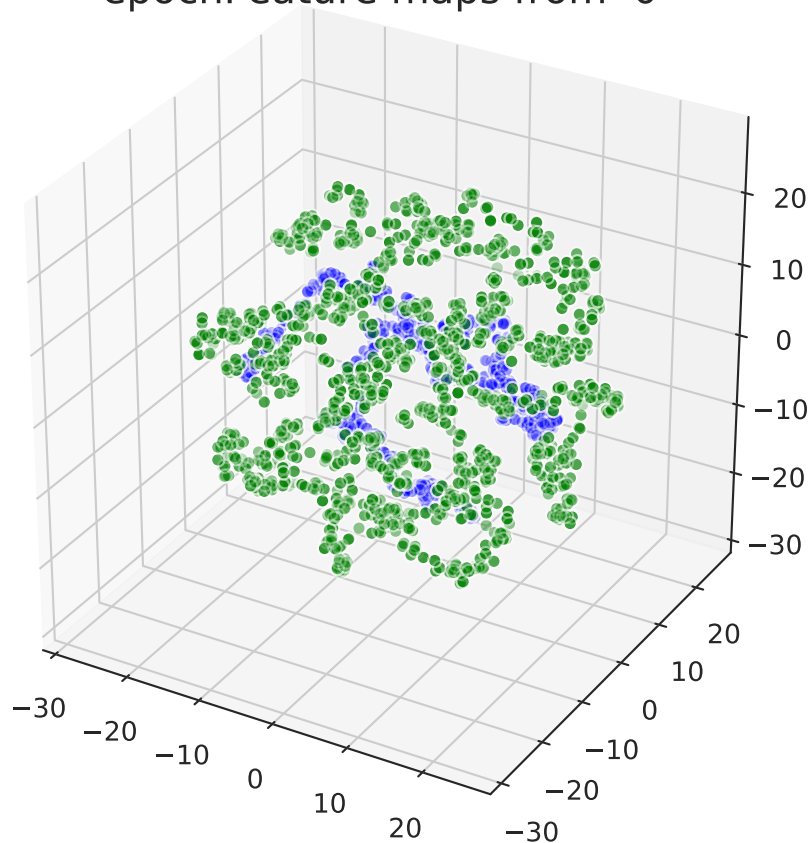


# Inception feature maps from Gaussian to Gaussian distribution

epochFeature maps from 0



epochFeature maps from 100

