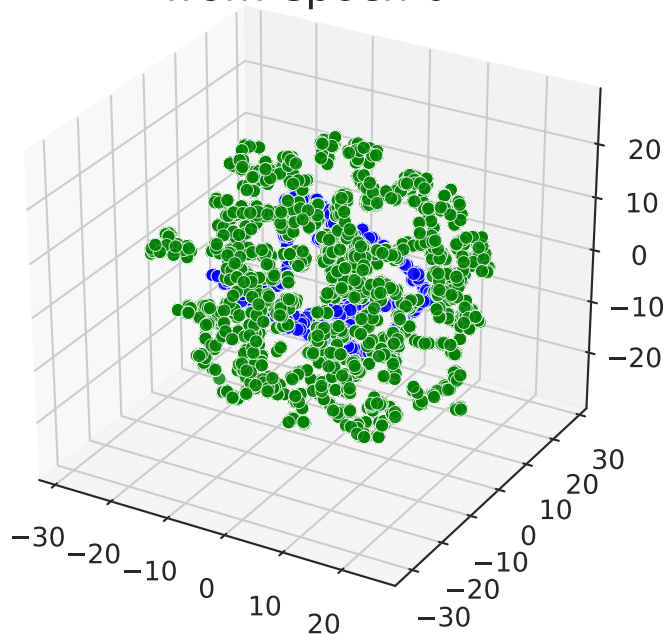
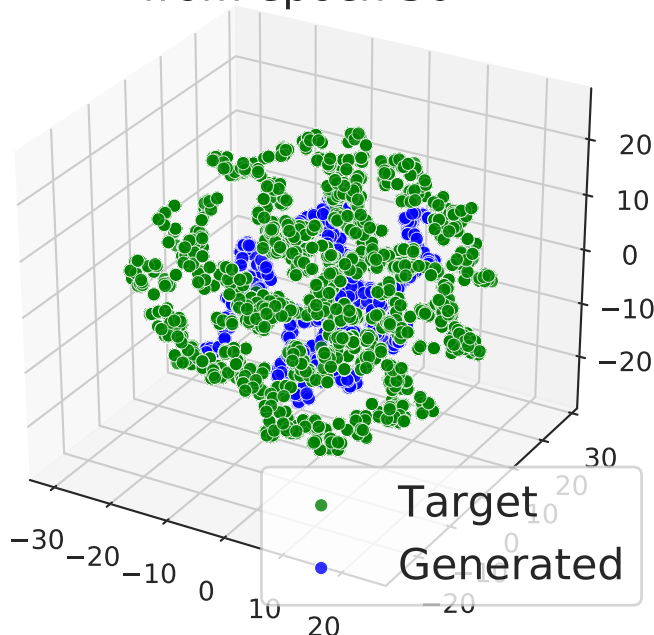


Inception feature maps from Gaussian to Gaussian distribution

Feature maps
from epoch 0



Feature maps
from epoch 50



Feature maps
from epoch 100

