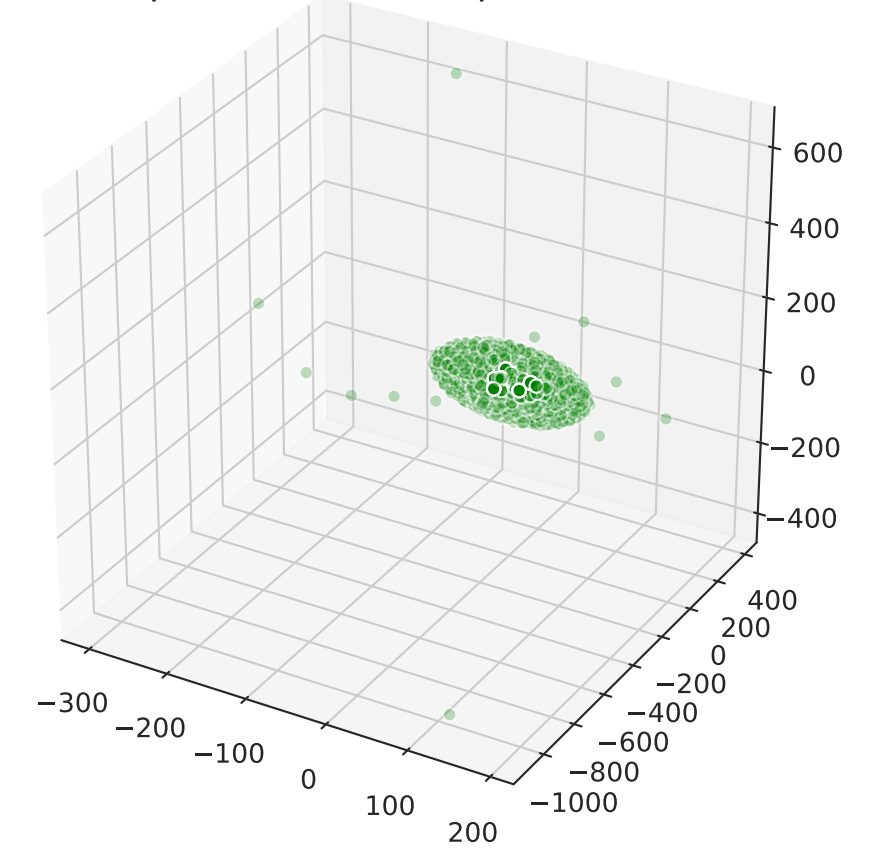
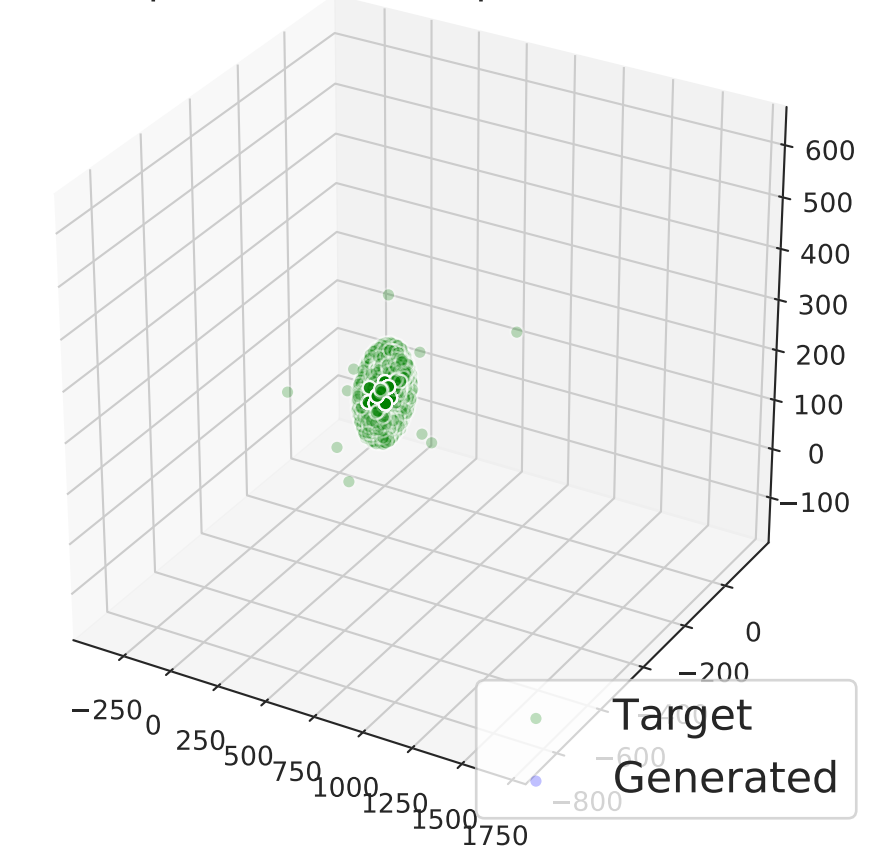


# Inception feature maps from Gaussian to Gaussian distribution

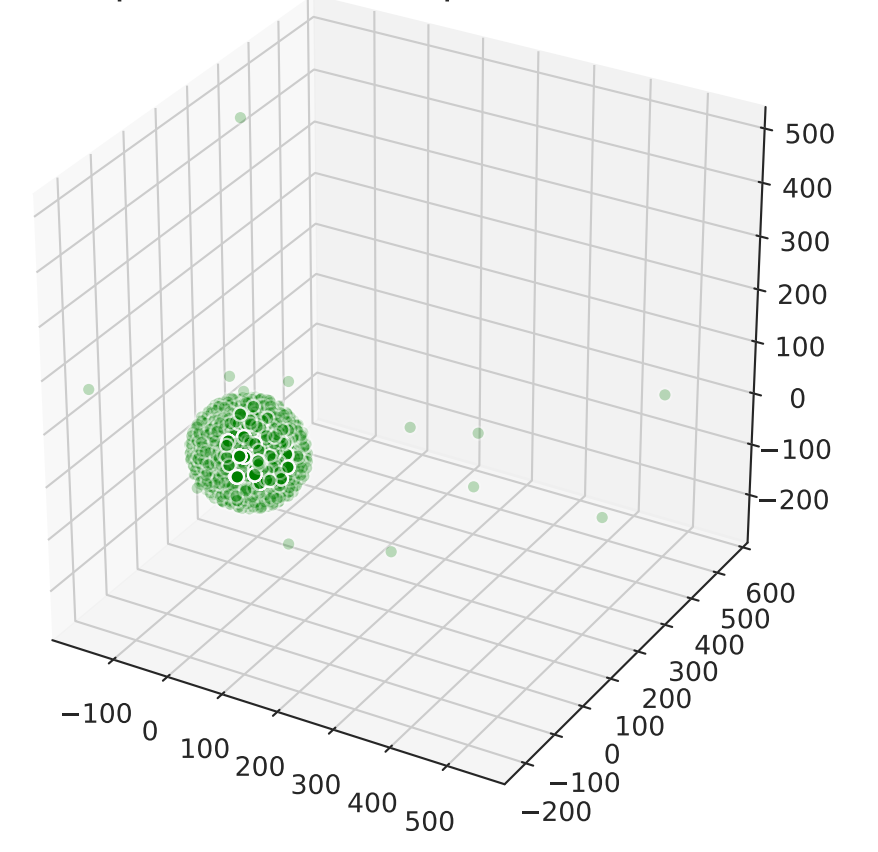
epochFeature maps from 0



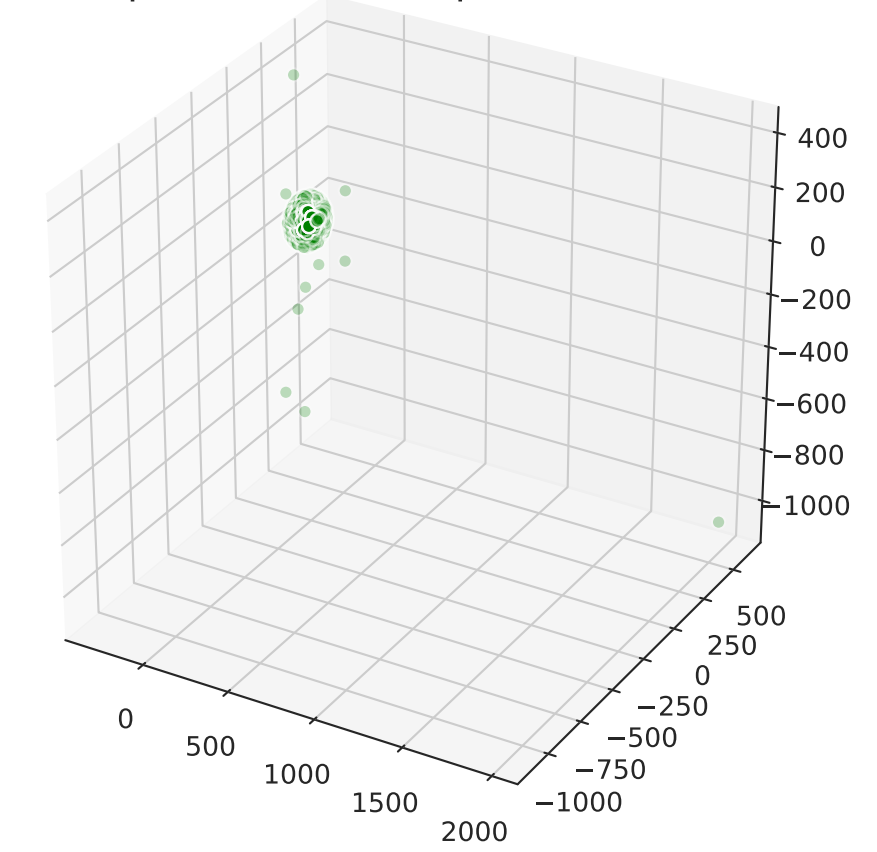
epochFeature maps from 75



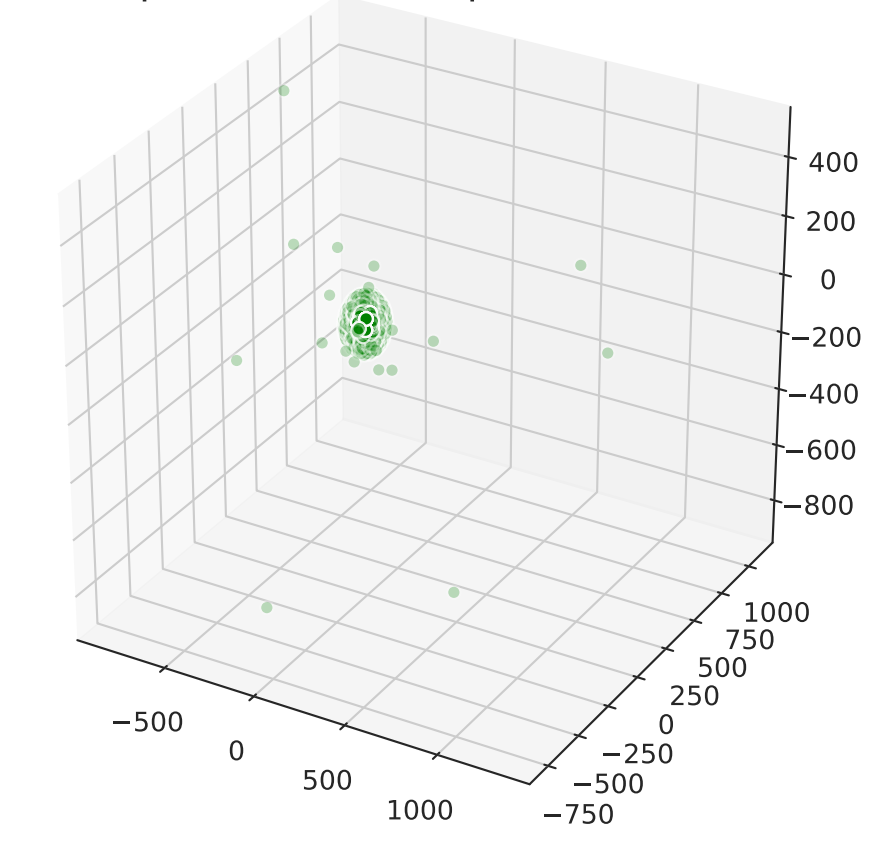
epochFeature maps from 150



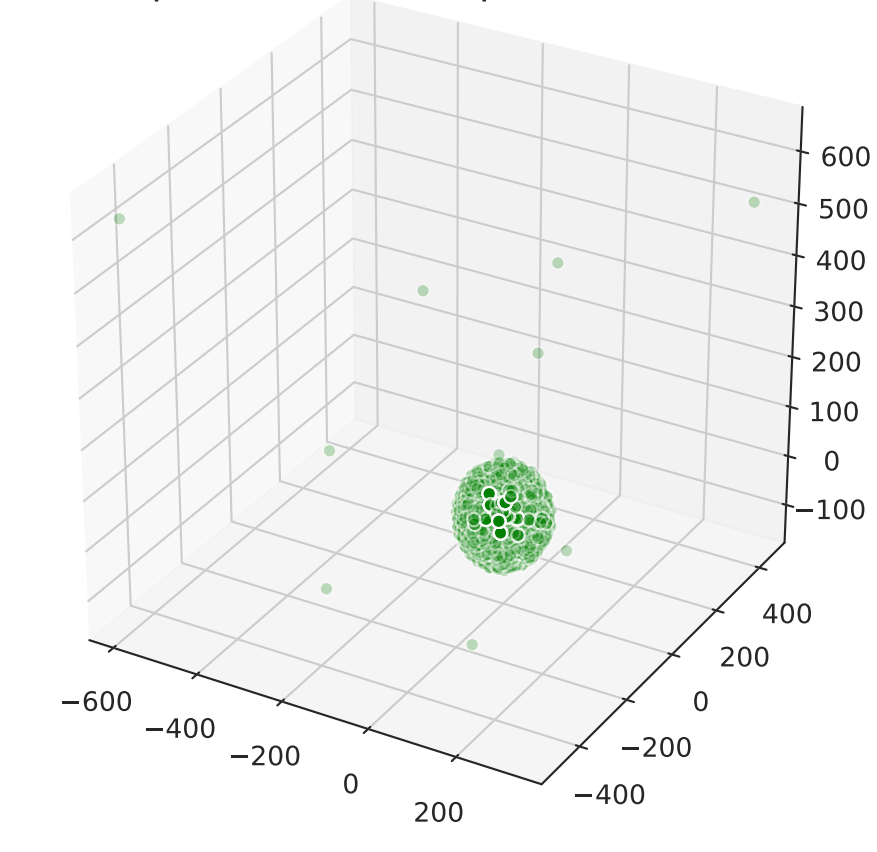
epochFeature maps from 225



epochFeature maps from 300



epochFeature maps from 375



epochFeature maps from 450

