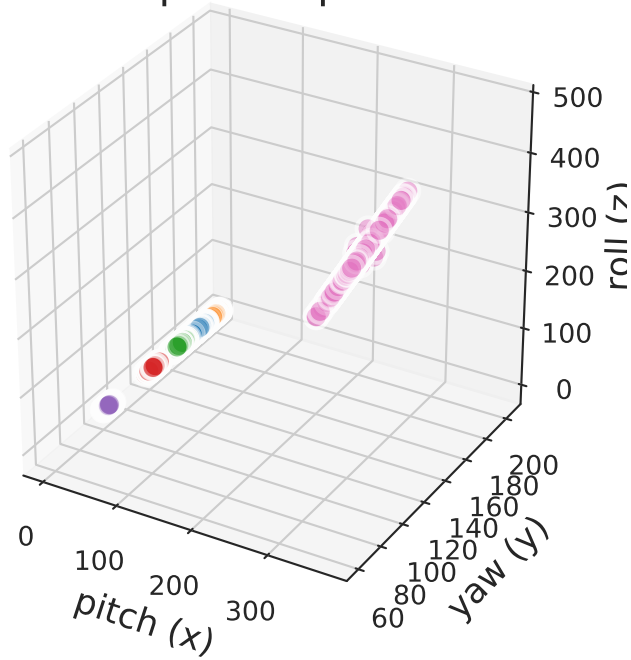
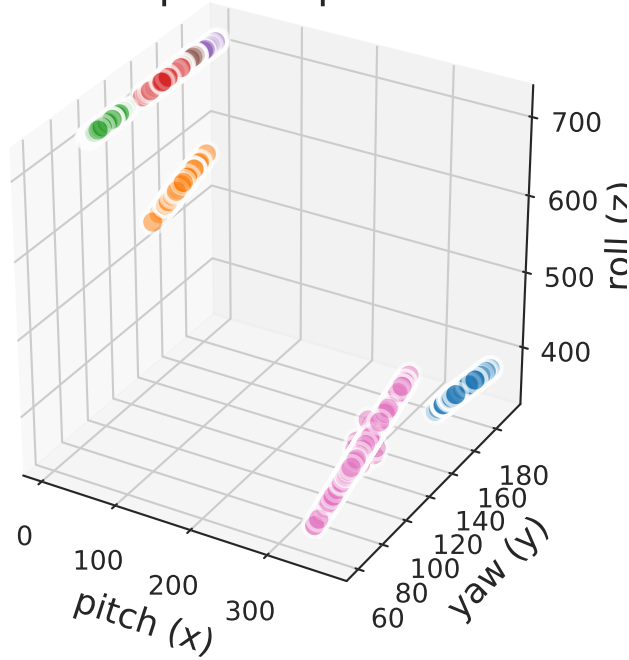


# Generated object pose distributions vs. target object pose distribution

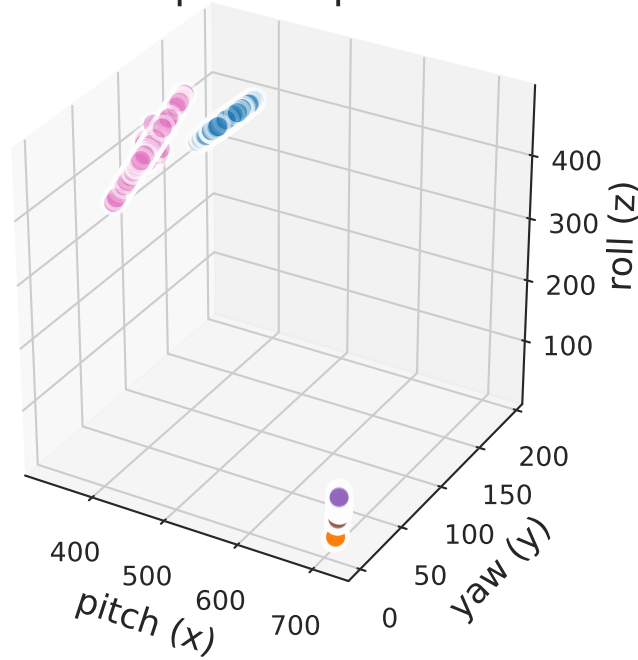
50 pretr. epochs



75 pretr. epochs



100 pretr. epochs



- epoch 0
- epoch 2
- epoch 4
- epoch 6
- epoch 8
- epoch 10
- Target dist.