Generated distributions when increasing weight decay 0.05 weight decay 0.001 weight decay 0.01 weight decay 140 epoch 0 140 -140 -120 epoch 2 120 120 100 epoch 4 100 epoch 6 80 80 80 epoch 8 60 -60 epoch 10 60 40 -Target dist. 40 40 20 20 20 50 100 125 200 225 60 100 160 180 200 60 80 100 120 140 yaw yaw yaw