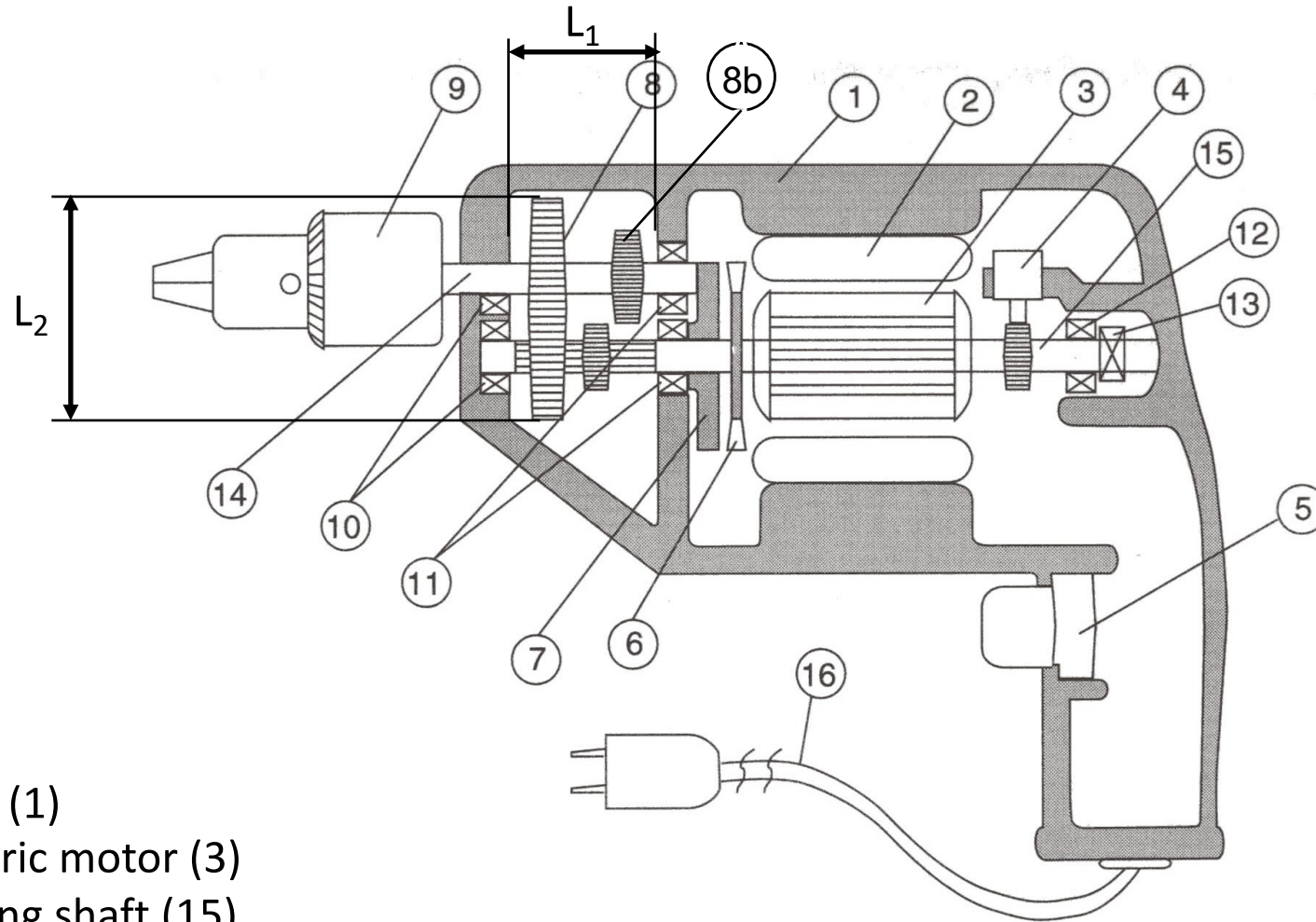


Course of Mechanical Design and Machine Elements

Homework 2, part A: Design and verification of the driven shaft of an electric drill



Legend:

- Case (1)
- Electric motor (3)
- Driving shaft (15)
- Driven shaft (14)
- Chuck (9)
- Spur gearset (8), (8b)
- Ball bearings (10)
- Roller bearings (11)
- Cam drive (7)

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The figure illustrates the schematic layout of an electric hammer drill. The main shaft is driven by an electric motor and the rotary motion is transmitted to a driven shaft through one of two spur gearsets. The chuck carrying the drill bit is mounted on the driven shaft through a tapered press fit. The impact loading is provided by a cam drive imparting an oscillatory axial motion to the driven shaft. The two gearsets are used to permit the drill to function at two distinct angular speeds (slow and fast speed). A spline is used on the main shaft to switch from one speed to the other. The outer ring of the ball bearing is hosted in a seat with axial clearance adequate to permit the oscillatory impact motion. The present project is focussed on the driven shaft and its machine elements only. In particular, it is requested to:

- 1) design the two pairs of spur gears
- 2) design the constraining system of the driven shaft (included the axial clearance) and select the rolling bearings
- 3) design the keys for gear/shaft couplings
- 4) design the driven shaft for strength (safe life) and stiffness
- 5) design the tapered press fit between chuck and shaft
- 6) prepare a detailed drawing of the shafts, including indications about tolerances, surface finish, material and heat treatment

Feel free to select material, surface finish, quality index, lubricant and non-specified dimensions.

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Data:

Nominal power of the electric motor: $W_{\text{motor}}=800 \text{ W}$

Angular speed of the electric motor: $n_{\text{motor}}= 1400 \text{ rev/min}$

Impact energy: $E_k = 1.6 \text{ J}$

Impact rate: $n_{\text{impact}}= 5600 \text{ impacts/min}$

Oscillating mass: $m_{\text{osc}} = 600 \text{ g}$

Service factor: $K_s=1.6$

Transmission ratio of the fast gearset: $\tau_{\text{fast}}=0.64$

Transmission ratio of the slow gearset: $\tau_{\text{slow}}=0.3$

Maximum internal distance between supports: $L_1= 60 \text{ mm}$

Maximum diametrical envelope of the gearsets: $L_2 = 120 \text{ mm}$

Maximum contact pressure on the tapered press fit: $p_{\text{all}} = 150 \text{ MPa}$

Service life: 1,000 h Reliability 99%

If the fatigue SN curve of the shaft material is not available, take:

$$\sigma_{\text{lim}} = \sigma_{2 \cdot 10^6} = 0.45 \sigma_R$$

$$\sigma_{10^4} = 0.75 \sigma_R$$

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Homework 2, part A: Design and verification of the driven shaft of an electric drill

Hints:

In general stiffness requirements are more demanding than strength requirements. Try to design first for stiffness and then verify the strength (safe life)

Slope and deflections can be calculated analytically or using a 2D beam software (remember to combine vectorially deflections and slopes estimated on the two transversal planes). See for instance:

- Beam 2D Stress Analysis, Orand Systems, Inc., available from the web
- FrameDesign, LetsConstruct, available from Google store

Usual stiffness requirements:

$$f_{\max} \leq \frac{l}{3000} \quad f_{\max} : \text{maximum deflection} \quad l : \text{shaft length}$$

$$\theta / l \leq 0.044 / 1000 \quad \text{rad} / \text{mm} \quad \text{maximum torsional deformation}$$

Maximum slope tolerated by bearings depend on the bearing type (see catalogues)

module	Max gear deflection
$m > 6 \text{ mm}$	0.25 mm
$3 < m < 6$	0.125 mm
$1 < m < 3 \text{ mm}$	0.075 mm

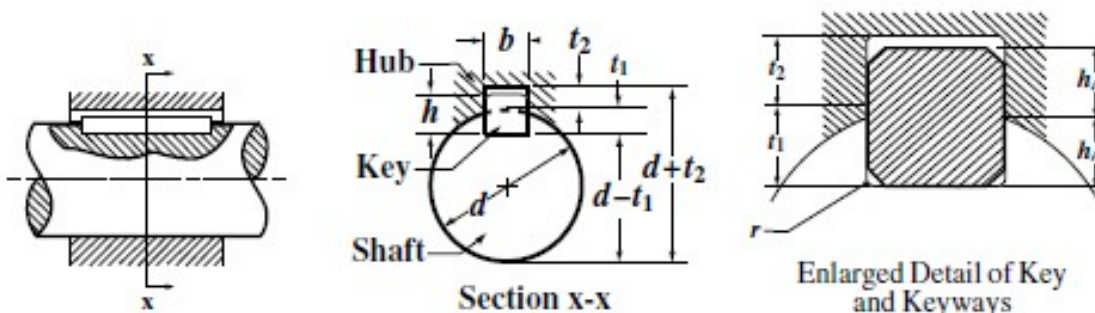
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Homework 2, part A: Design and verification of the driven shaft of an electric drill

Hints:

- Make sure that both gearsets have the same centre distance
- Assume the cam drive to impart a sinusoidal trajectory to the driven shaft
- Determine the amplitude of the sinusoidal motion from the impact energy
- The range of the motion plus a reasonable clearance determines the axial length of the seat of the outer ring of the ball bearing
- Verify the shaft for both speed regimes independently
- Neglect the effect of the axial (impact) load on the shaft strength
- Select a shaft material of adequate toughness

Homework 2, part A: Design and verification of the driven shaft of an electric drill

														
Shaft		Key		Keyway										
Nominal Diameter d		Size, $b \times h$		Width, b					Depth				Radius r	
				Free Fit		Normal Fit		Close Fit	Shaft t_1		Hub t_2		Max.	Min.
				Shaft (H9)	Hub (D10)	Shaft (N9)	Hub (J _S 9) ^a	Shaft and Hub (P9)	Nominal	Tolerance	Nominal	Tolerance		
Over	Up to and Incl	Tolerances												
Keyways for Square Parallel Keys														
6	8	2 × 2	2	+0.025	+0.060	-0.004	+0.012	-0.006	1.2	+0.1 0	1	+0.1 0	0.16	0.08
8	10	3 × 3	3	0	+0.020	-0.029	-0.012	-0.031	1.8		1.4		0.16	0.08
10	12	4 × 4	4	+0.030 0	+0.078 +0.030	0 -0.030	+0.015 -0.015	-0.012 -0.042	2.5		1.8		0.16	0.08
12	17	5 × 5	5						3		2.3		0.25	0.16
17	22	6 × 6	6						3.5		2.8		0.25	0.16
Keyways for Rectangular Parallel Keys														
22	30	8 × 7	8	+0.036	+0.098	0	+0.018	-0.015	4	+0.2 0	3.3	+0.2 0	0.25	0.16
30	38	10 × 8	10	0	+0.040	-0.036	-0.018	-0.051	5		3.3		0.40	0.25
38	44	12 × 8	12	+0.043	+0.120 +0.050	0 -0.043	+0.021 -0.021	-0.018 -0.061	5		3.3		0.40	0.25
44	50	14 × 9	14						5.5		3.8		0.40	0.25
50	58	16 × 10	16						6		4.3		0.40	0.25
58	65	18 × 11	18						7		4.4		0.40	0.25
65	75	20 × 12	20	+0.052	+0.149 +0.065	0 -0.052	+0.026 -0.026	-0.022 -0.074	7.5		4.9		0.60	0.40
75	85	22 × 14	22						9		5.4		0.60	0.40
85	95	25 × 14	25						9		5.4		0.60	0.40
95	110	28 × 16	28						10		6.4		0.60	0.40
110	130	32 × 18	32	+0.062	+0.180 -0.080	0 -0.062	+0.031 -0.031	-0.026 -0.088	11	+0.3 0	7.4	+0.3 0	0.60	0.40
130	150	36 × 20	36						12		8.4		1.00	0.70
150	170	40 × 22	40						13		9.4		1.00	0.70
170	200	45 × 25	45						15		10.4		1.00	0.70
200	230	50 × 28	50						17		11.4		1.00	0.70
230	260	56 × 32	56						20		12.4		1.60	1.20
260	290	63 × 32	63	+0.074	+0.220 +0.100	0 -0.074	+0.037 -0.037	-0.032 -0.106	20		12.4		1.60	1.20
290	330	70 × 36	70						22		14.4		1.60	1.20
330	380	80 × 40	80						25		15.4		2.50	2.00
380	440	90 × 45	90						28		17.4		2.50	2.00
440	500	100 × 50	100	+0.087 0	+0.260 +0.120	0 -0.087	+0.043 -0.043	-0.037 -0.124	31		19.5		2.50	2.00

^a Tolerance limits J_S9 are quoted from BS 4500, "ISO Limits and Fits," to three significant figures.

All dimensions in millimeters.

Course of Mechanical Design and Machine Elements

Homework 2, part A: Design and verification of the driven shaft of an electric drill

- 1) Typical values of the notch fatigue factor introduced by the keyseat into the shaft are 3 in bending and 2 in torsion.
- 2) Typical key material is steel C45 ($p_{all} = 150 \text{ MPa}$, $\tau_{all} = 75 \text{ MPa}$).
- 3) Check if the selected bearings have width and fillet radii compatible with the shaft designed in part A and, if necessary, update the shaft layout to accommodate the bearings.
- 4) Prepare a constructive drawing that shows the mounting of bearings, in particular how inner and outer rings are fixed radially and axially.

For bearing selection, you can consult any manufacturer catalogue, for instance:

<http://www.skf.com/binary/77-121486/SKF-rolling-bearings-catalogue.pdf>

<http://www.skf.com/it/knowledge-centre/engineering-tools/skfbearingcalculator.html>

http://www.fag.de/content.fag.de/en/products_services/rotativ_products/index.jsp