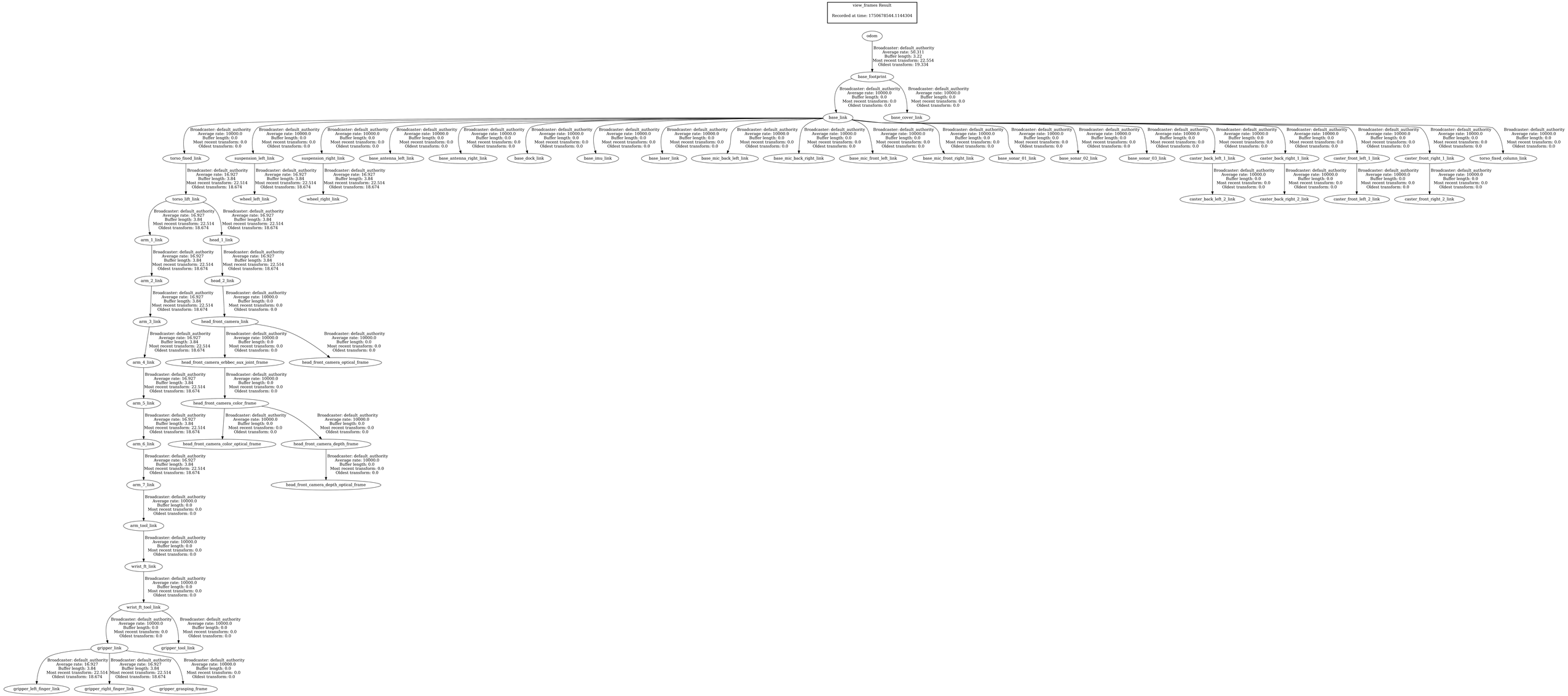
view_frames Result
Recorded at time: 1750678844.1144304
odom
Broadcaster: default_authority
Average rate: 50.311
Buffer length: 3.22
Most recent transform: 22.554
Oldest transform: 19.334
base_footprint
Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
base_link
base_cover_link
torso_fixed_link
suspension_left_link
suspension_right_link
base_antenna_left_link
base_antenna_right_link
base_dock_link
base_imu_link
base_laser_link
base_mic_back_left_link
base_mic_back_right_link
base_mic_front_left_link
base_mic_front_right_link
base_sonar_01_link
base_sonar_02_link
base_sonar_03_link
caster_back_left_1_link
caster_back_right_1_link
caster_front_left_1_link
caster_front_right_1_link
torso_fixed_column_link
caster_back_left_2_link
caster_back_right_2_link
caster_front_left_2_link
caster_front_right_2_link
torso_lift_link
Broadcaster: default_authority
Average rate: 16.927
Buffer length: 3.84
Most recent transform: 22.514
Oldest transform: 18.674
wheel_left_link
wheel_right_link
arm_1_link
head_1_link
arm_2_link
head_2_link
arm_3_link
head_front_camera_link
arm_4_link
head_front_camera_orbbec_aux_joint_frame
head_front_camera_optical_frame
arm_5_link
head_front_camera_color_frame
arm_6_link
head_front_camera_color_optical_frame
head_front_camera_depth_frame
arm_7_link
head_front_camera_depth_optical_frame
arm_tool_link
wrist_ft_link
wrist_ft_tool_link
gripper_link
gripper_tool_link
gripper_left_finger_link
gripper_right_finger_link
gripper_grasping_frame