RA - B Design and Construction
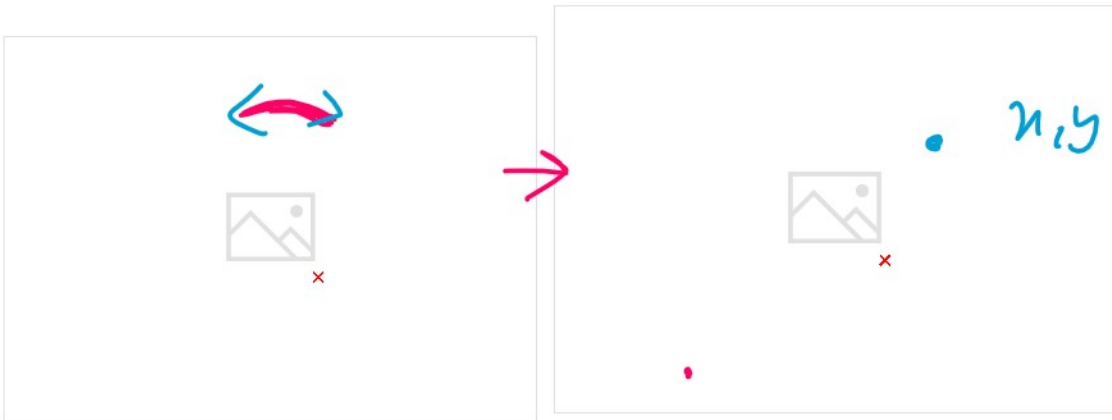
Jargons

Chain Manupilator
Serial

Task Space

Workspace

n, y

https://www.mathworks.com/help/fuzzy/modeling-inverse-kinematics-in-a-robotic-arm.html

Basic Design

11cm

10.4 cm

10.7 cm

z y

n