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# CUSP UCSL Summer 2016: Introduction to Linear Algebra

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@fedhere

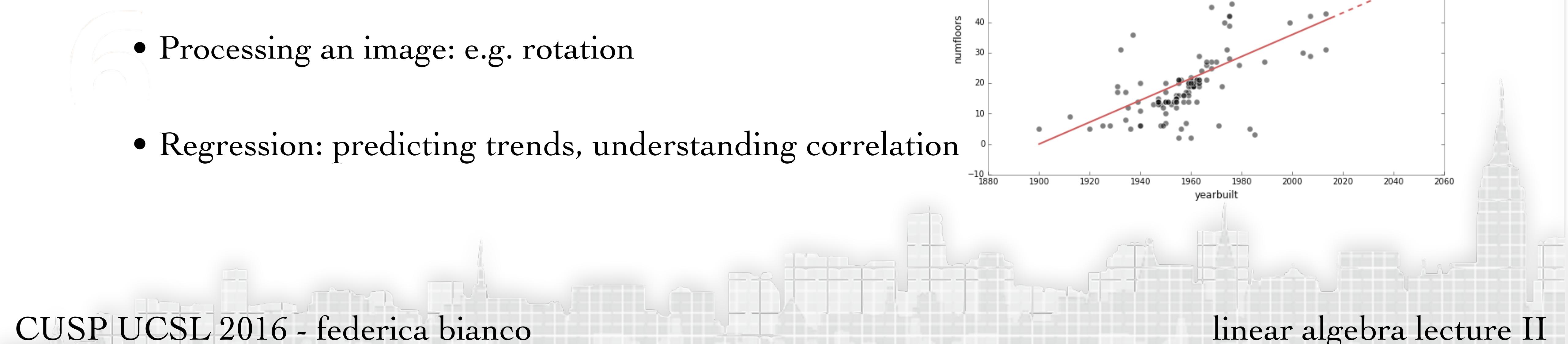
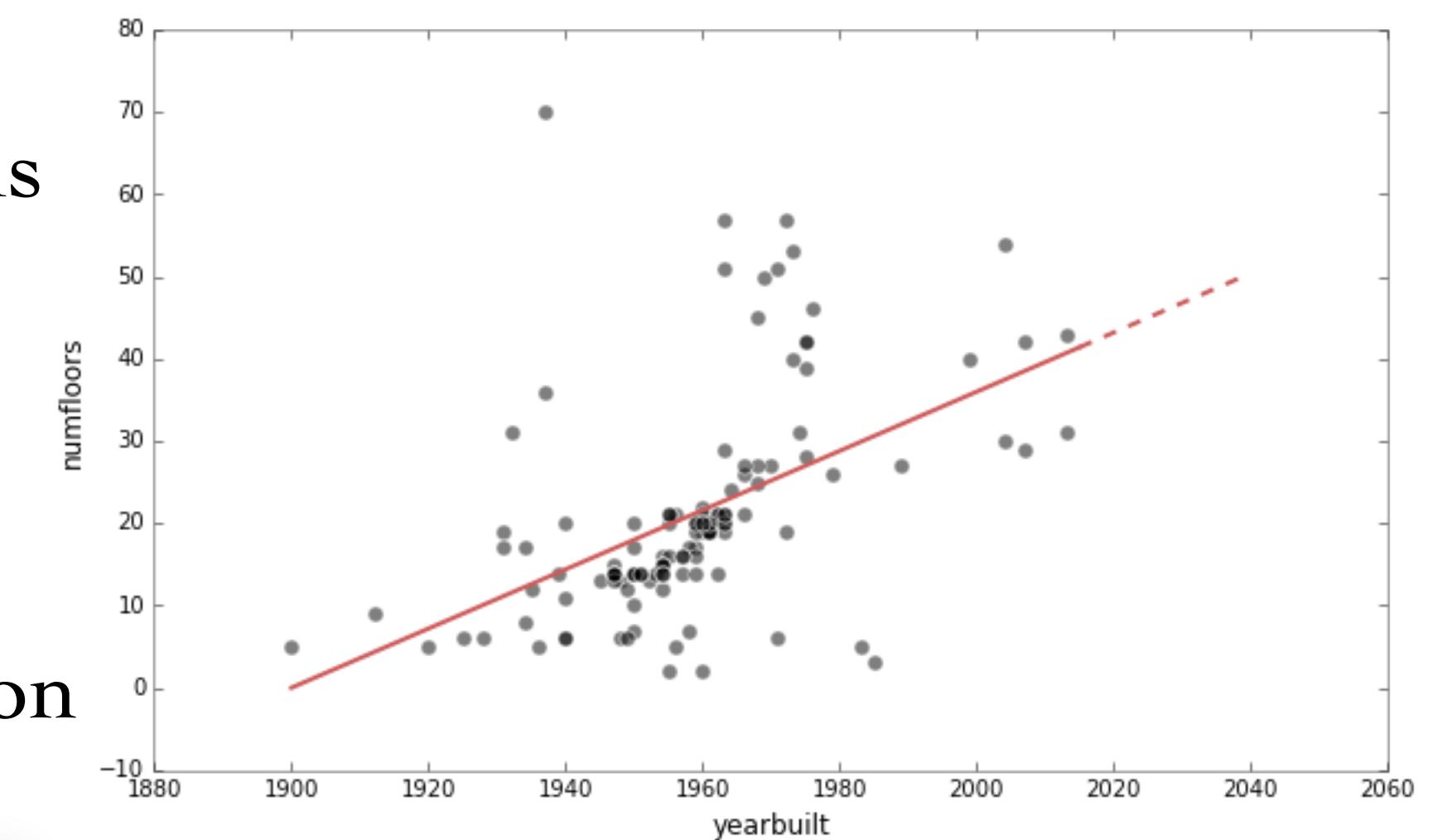
Material related to this lecture  
can be found at

[https://github.com/fedhere/  
UInotebooks/tree/master/UCSL2016](https://github.com/fedhere/UInotebooks/tree/master/UCSL2016)

## why do we bother with linear algebra?

LINEAR ALGEBRA ALLOWS US TO SOLVE COMPLEX SYSTEMS OF EQUATIONS EFFICIENTLY. Most Data Science and Computational problems can be described by sets of linear equations.

- Finding similarity patterns in data: e.g. network analysis
- Processing an image: e.g. rotation
- Regression: predicting trends, understanding correlation



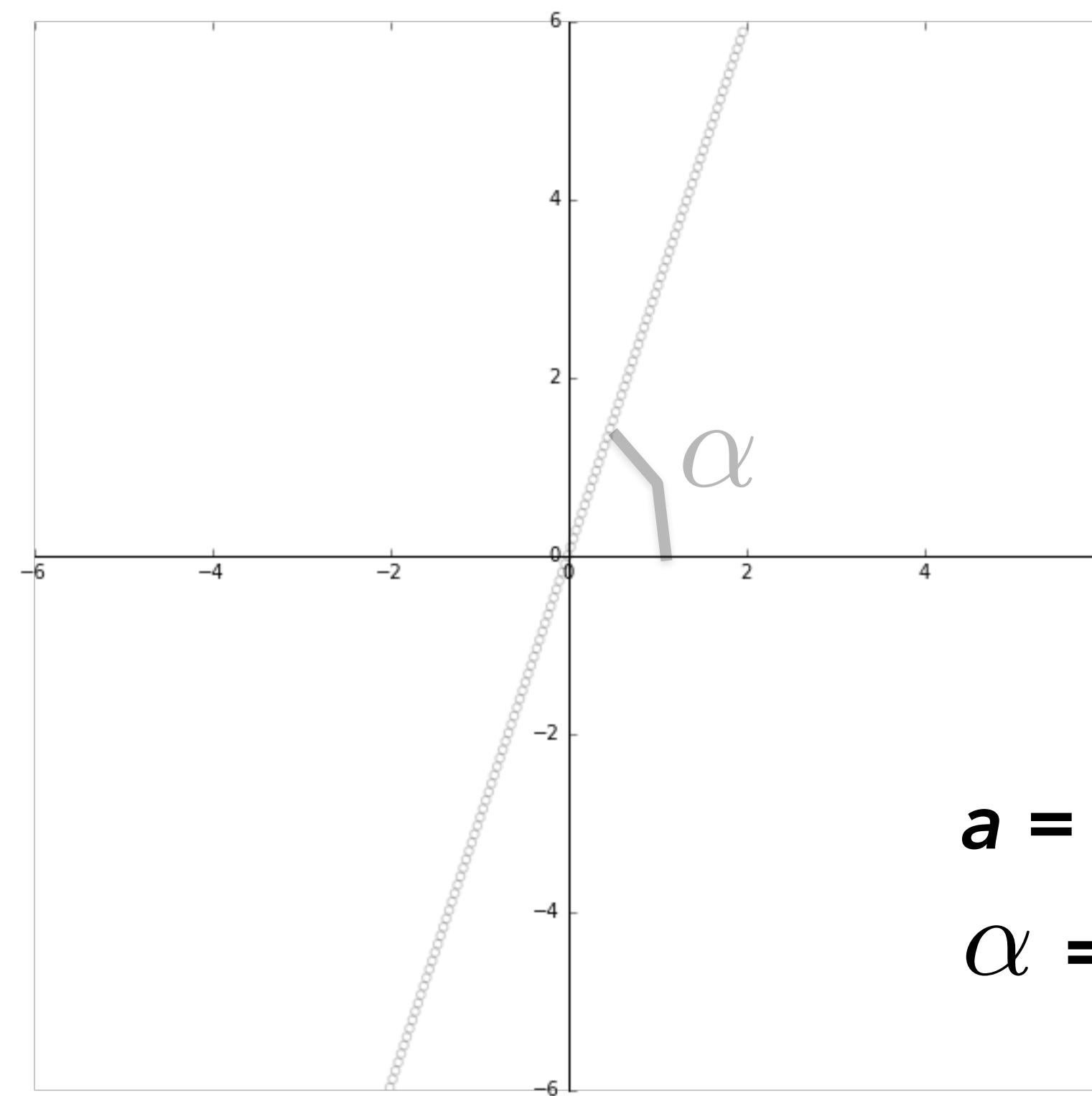
## outline:

- What is a vector
- What is a matrix
- vector & matrix transformations
- Solving systems of linear equations
- Eigenvectors/Eigenvalues



## Scalar multiplication

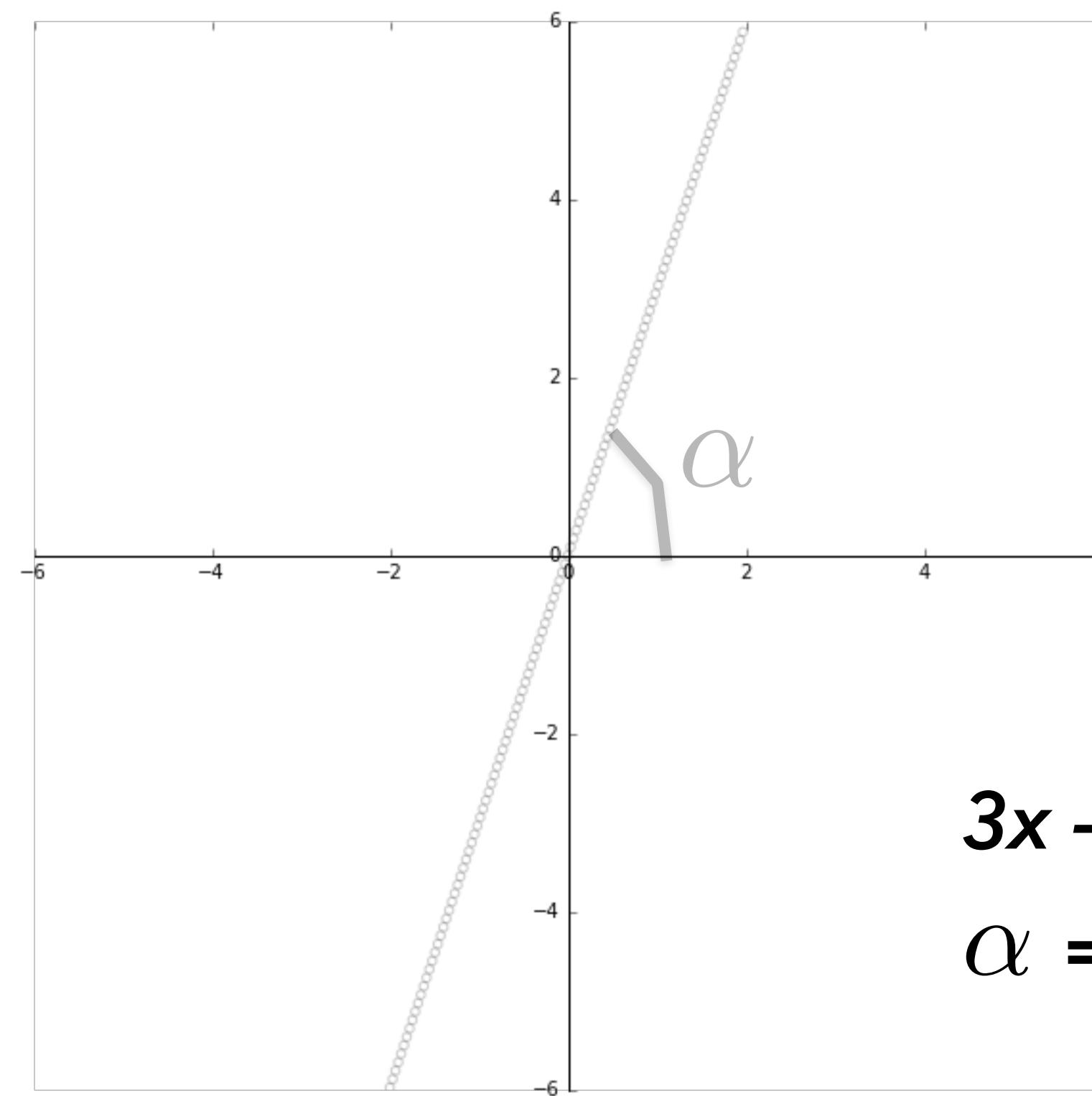
equation of a line



***constant direction : constant y/x***

## Scalar multiplication

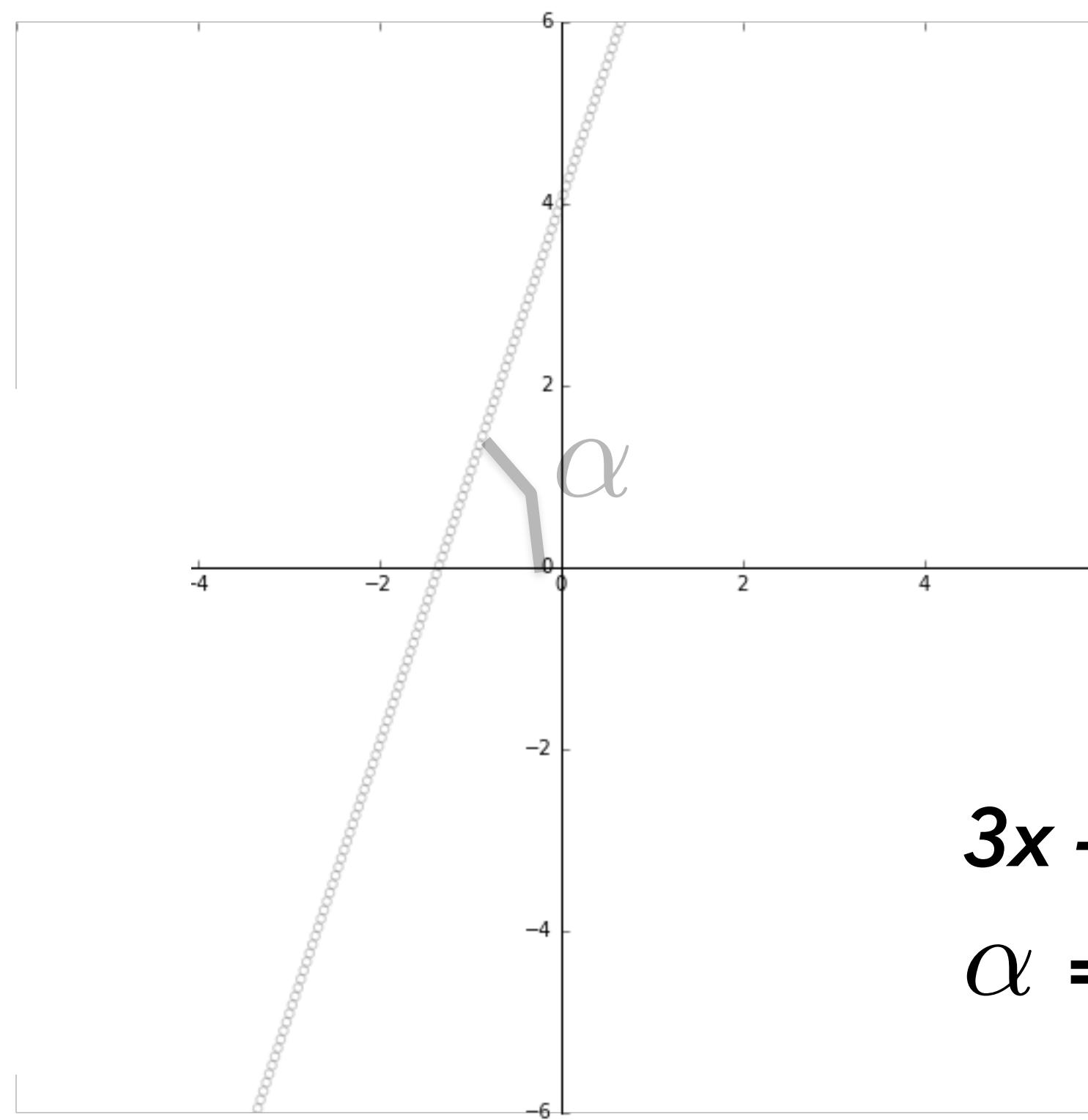
equation of a line



***constant direction : constant y/x***

## Scalar multiplication

equation of a line



***constant direction : constant y/x***

$$3x - y = -6$$
$$\alpha = \tan^{-1}(y/x)$$

## Systems of linear equations

$$\begin{aligned}2x - 3y &= 34 \\4x + y &= 12\end{aligned}$$



## Systems of **linear** equations

$$\begin{aligned}2x - 3y &= 34 \\4x + y &= 12\end{aligned}$$



# Systems of **linear** equations

the unknowns ( $x, y$ ) only appear in linear format  
(power of 1, no squares, square root, exponent...)

$$\begin{aligned}2x - 3y &= 34 \\4x + y &= 12\end{aligned}$$



## Systems of linear equations

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$N_{\text{eq}}$  equations,  
 $N_{\text{un}} > N_{\text{eq}}$  unknowns }  $> 1$  solution

$$\begin{aligned} 2x - 3y &= 34 \\ 4x + y &= 12 \end{aligned}$$



## Systems of linear equations

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$N_{eq}$  equations,  
 $N_{un} < N_{eq}$  unknowns } overconstrained

$$\begin{aligned} 2x - 3y &= 34 \\ 4x + y &= 12 \end{aligned}$$



# Systems of linear equations

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$N_{un} = N_{eq}$  1 solution

$$\begin{aligned}2x - 3y &= 34 \\4x + y &= 12\end{aligned}$$

# Systems of linear equations

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solving by substitution

$$\begin{aligned}2x - 3y &= 34 \\4x + y &= 12\end{aligned}$$

$$\begin{aligned}2x - 3y &= 34 \\y &= 12 - 4x\end{aligned}$$

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solving by substitution

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$$\begin{aligned}x &= 5 \\y &= 12 - 20\end{aligned}$$

# Systems of linear equations

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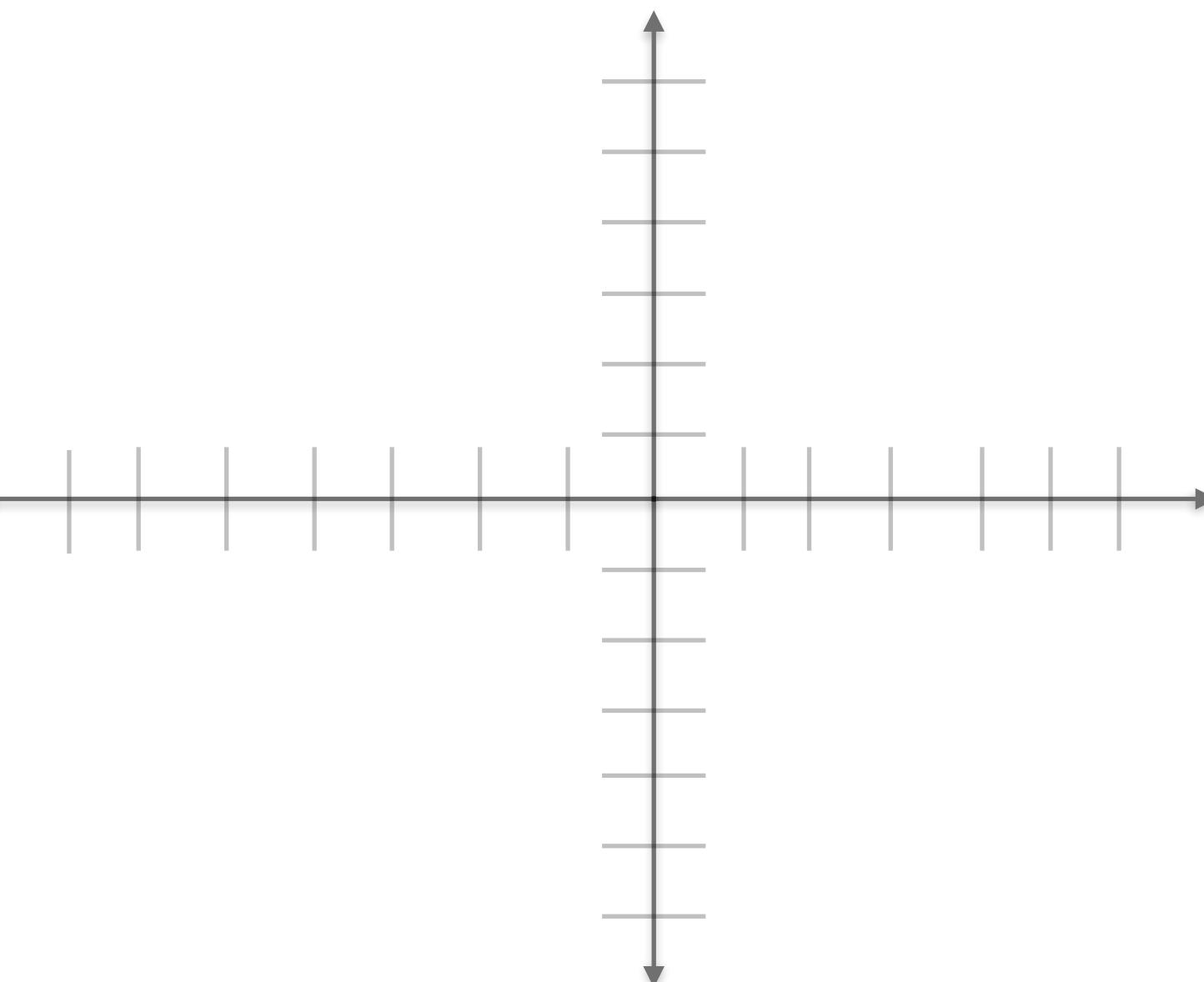
$$\begin{aligned}x &= 5 \\y &= -8\end{aligned}$$

solved in 6 operations

# Systems of linear equations

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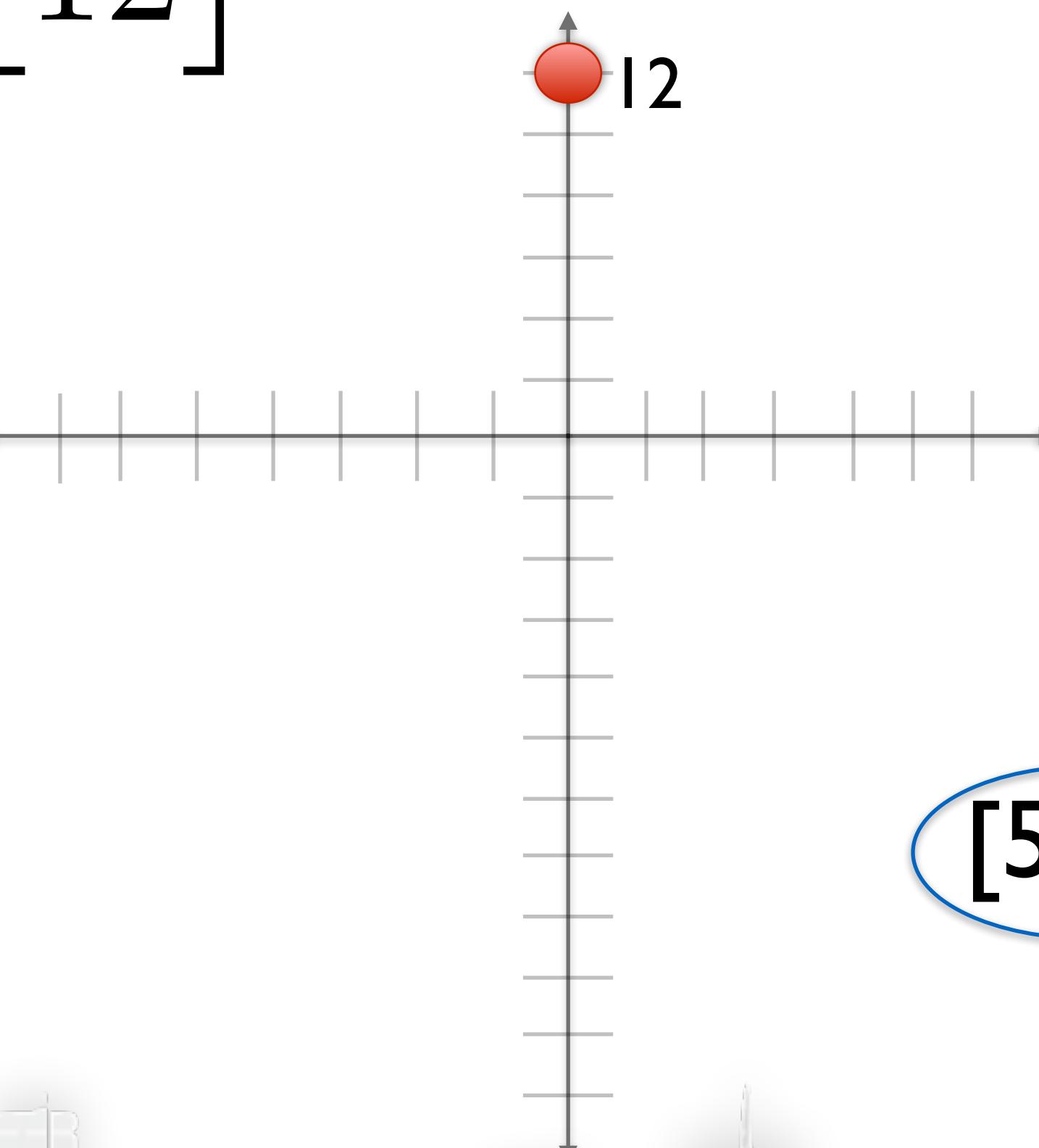
$$\begin{aligned}2x - 3y &= 34 \\4x + y &= 12\end{aligned}$$



## Systems of linear equations

$$\begin{bmatrix} 2 & -3 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 34 \\ 12 \end{bmatrix}$$

$$\begin{aligned} 2x - 3y &= 34 \\ 4x + y &= 12 \end{aligned}$$



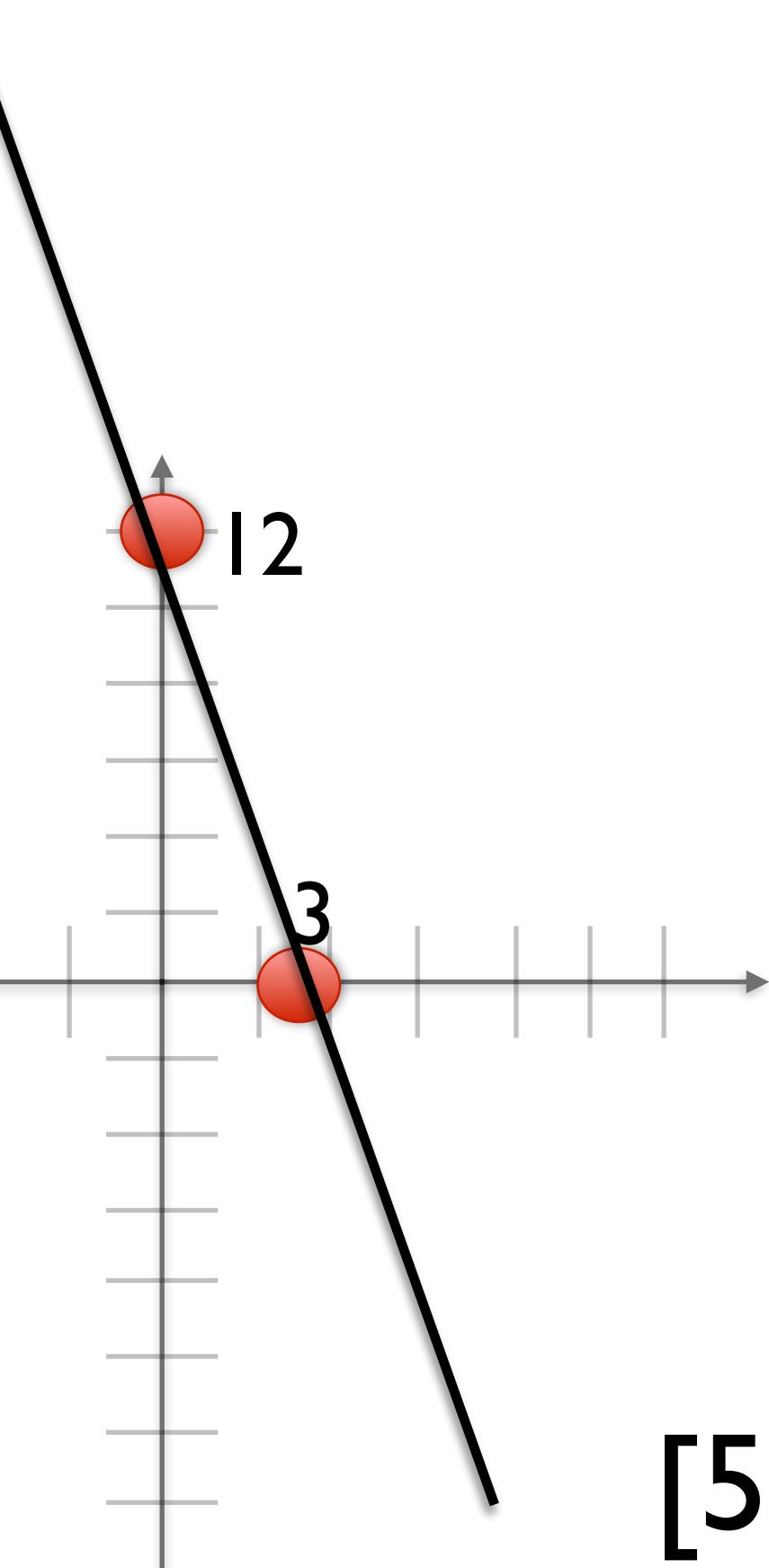
[5 -8]  
solution



## Systems of linear equations

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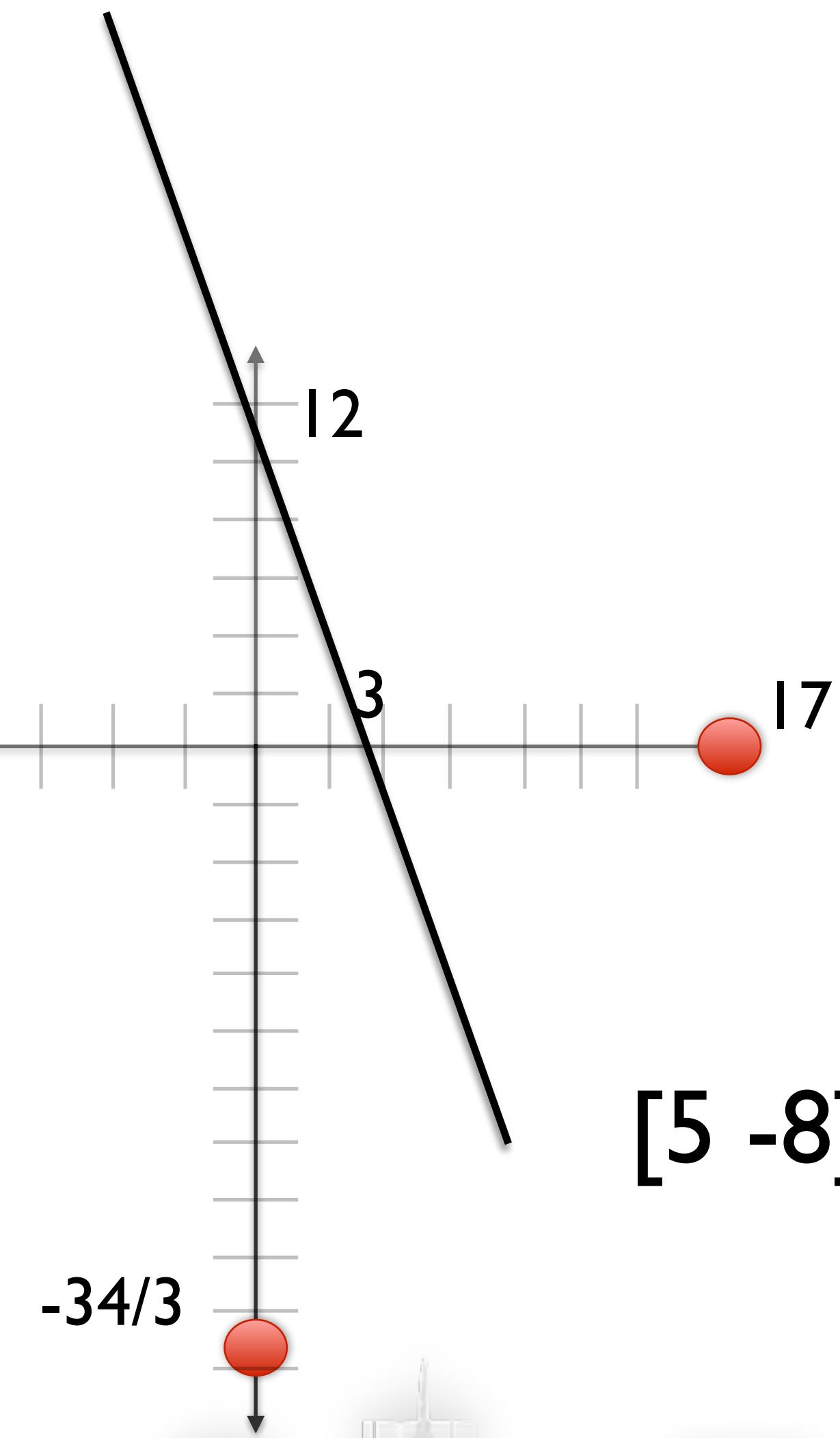
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## Systems of linear equations

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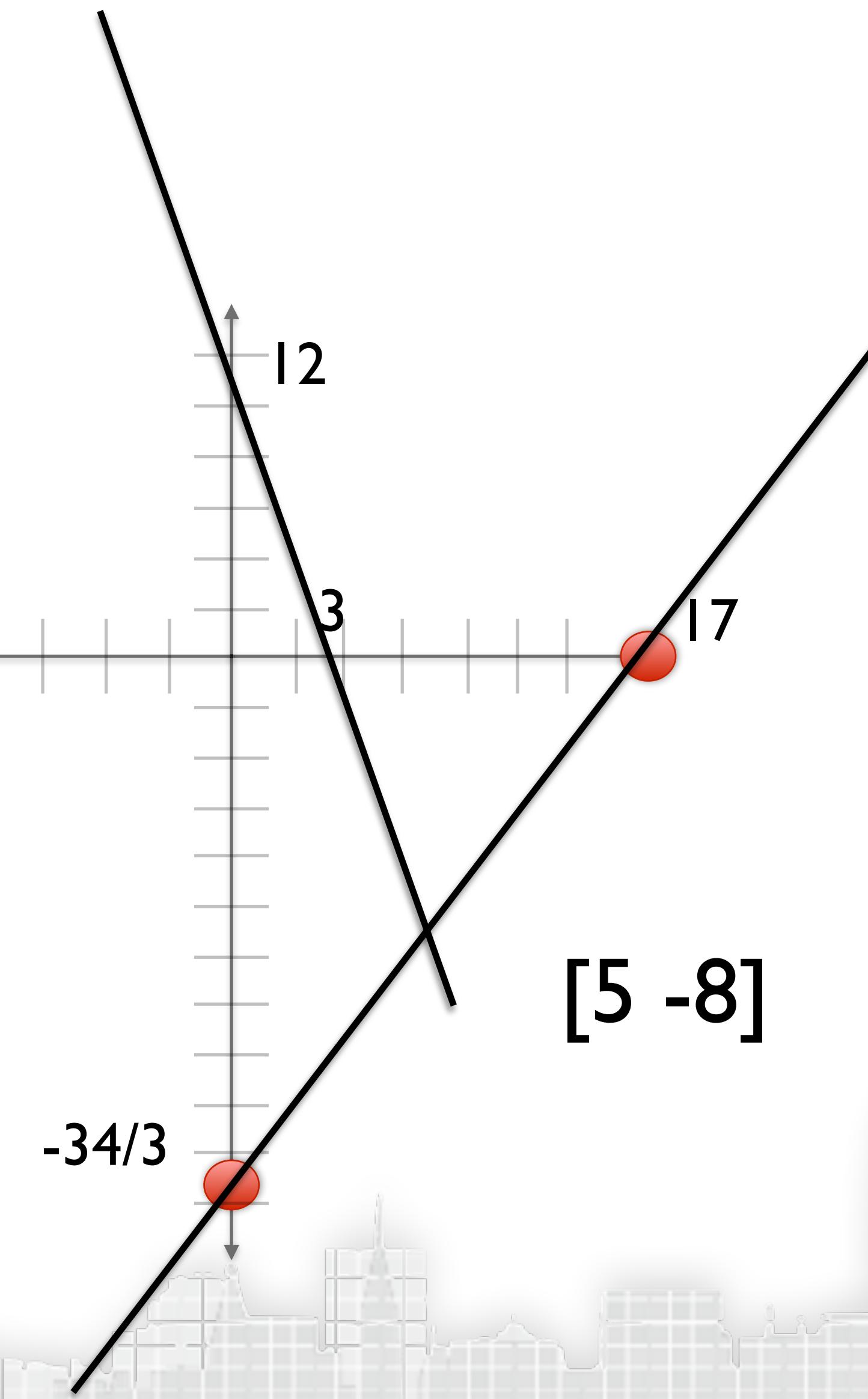
[5 -8]



## Systems of linear equations

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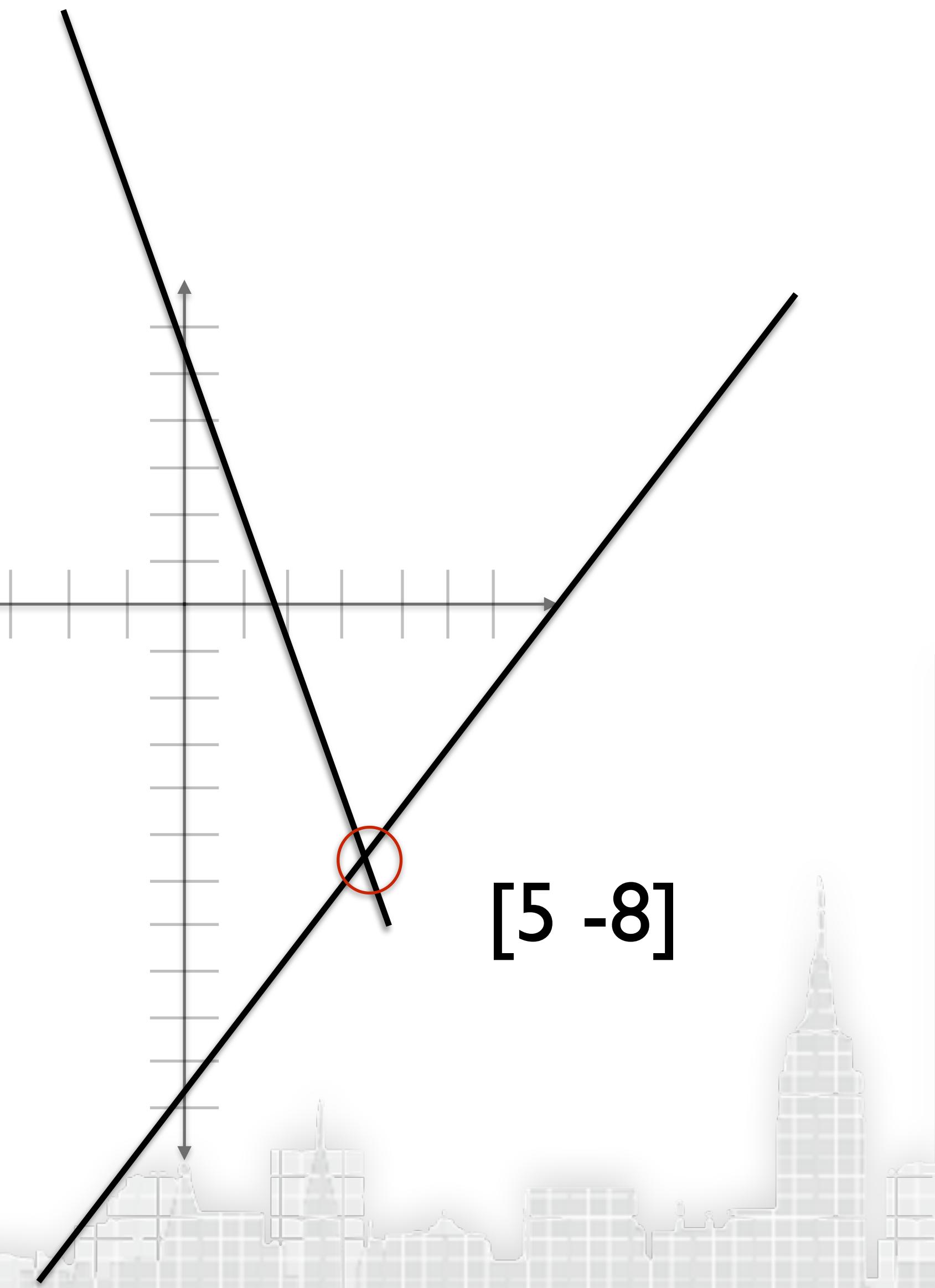
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$$\begin{bmatrix} 2 & -3 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 34 \\ 12 \end{bmatrix}$$

$$\begin{aligned} 2x - 3y &= 34 \\ 4x + y &= 12 \end{aligned}$$

corresponds to finding the point of  
intersection of vectors  
(lines in 2D, planes in 3D ....)  
N equations, N dimensions, N unknowns)



## outline:

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- What is a matrix
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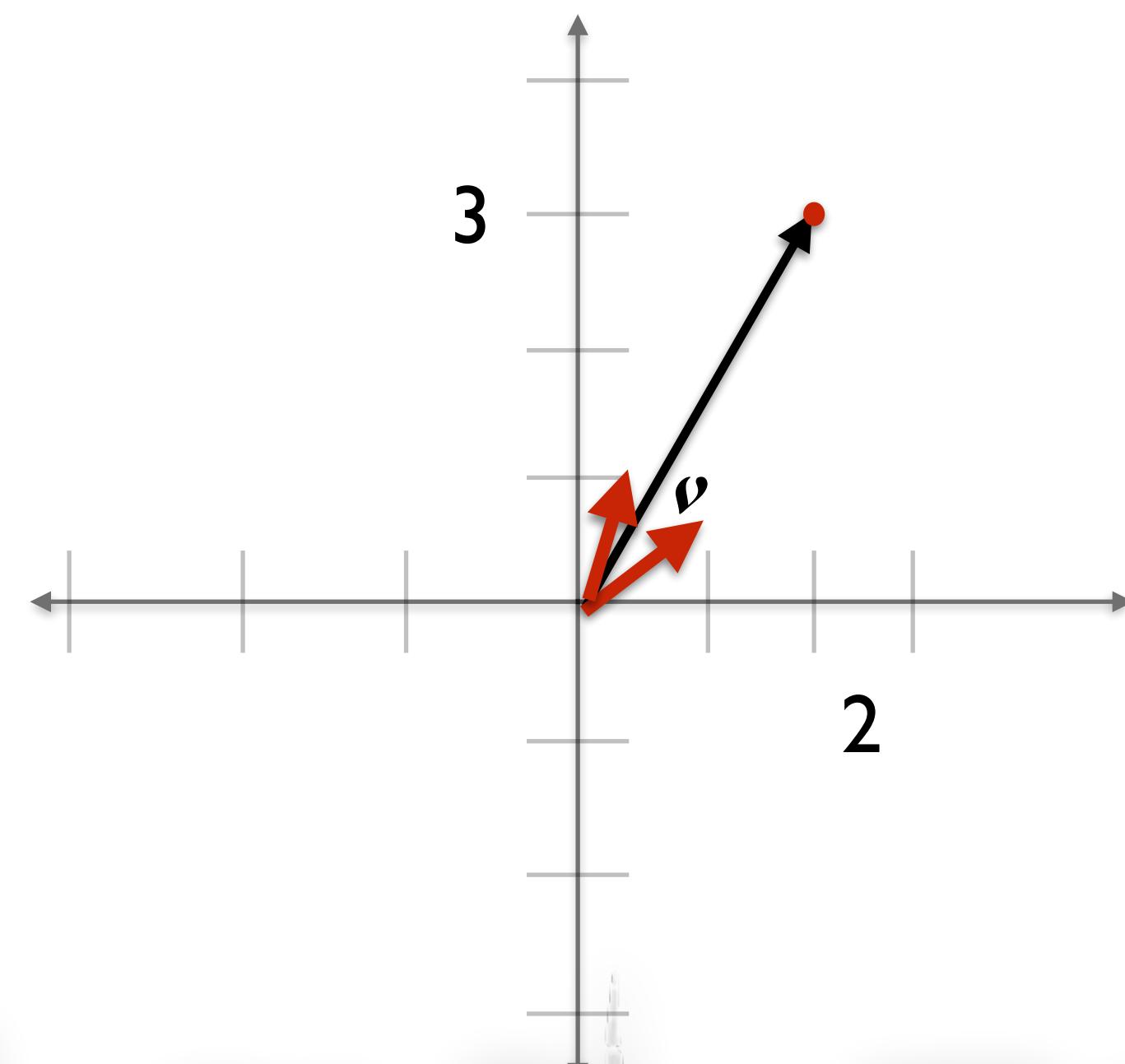


## Eigenvalues and Eigenvectors

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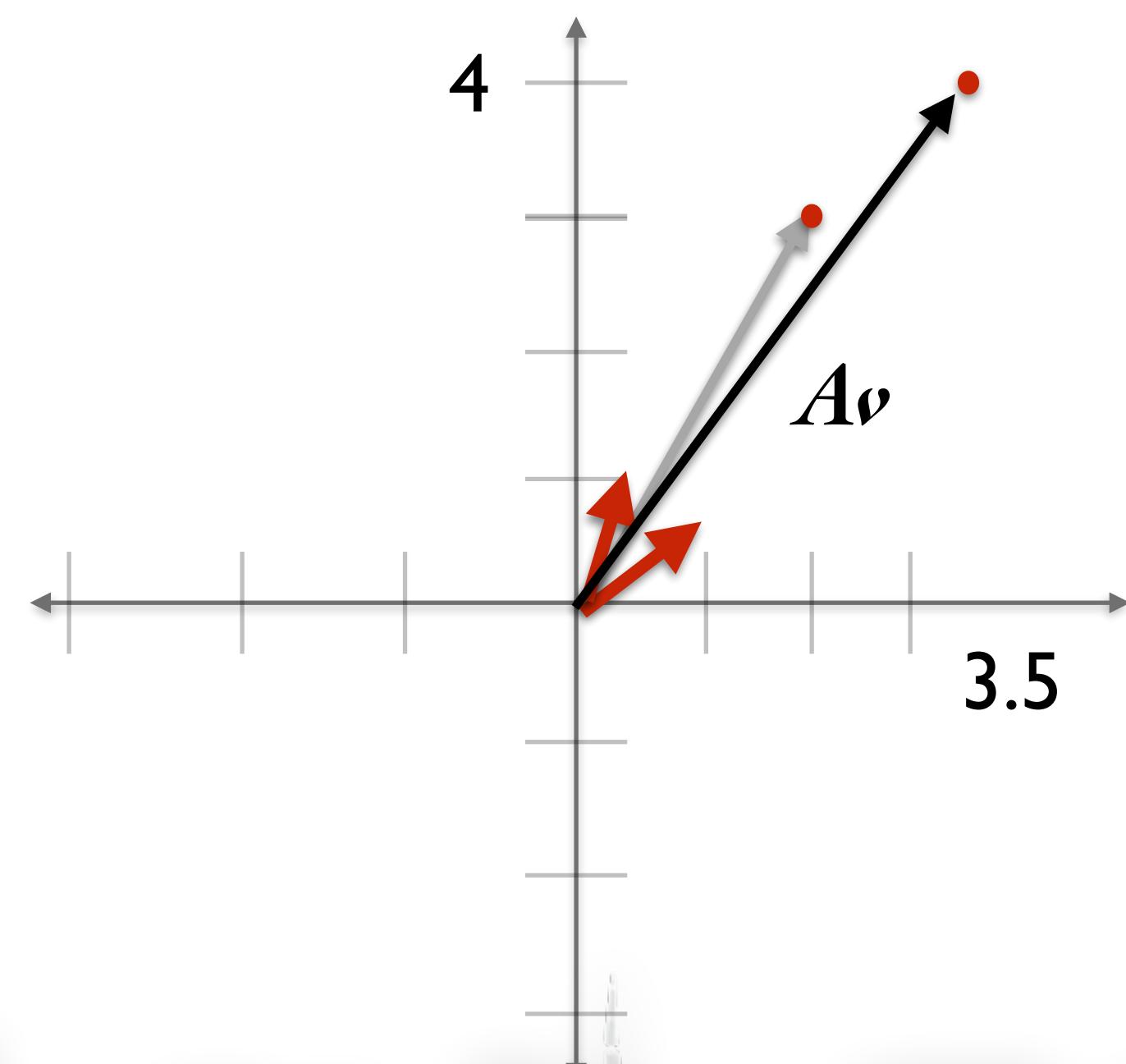
$$v = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 0.5 \\ 0.5 & 1 \end{bmatrix}$$



## Eigenvalues and Eigenvectors

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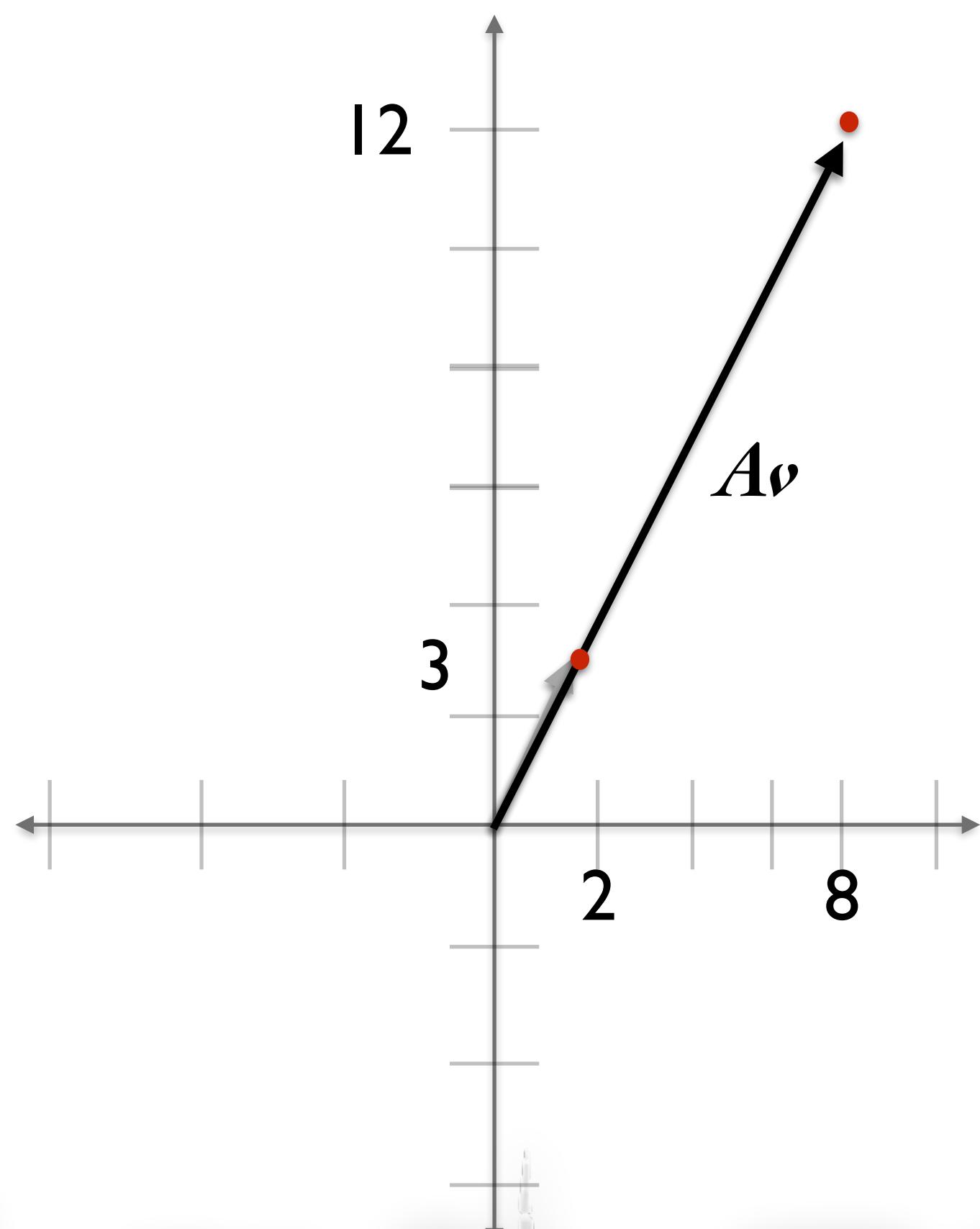
$$\mathbf{v} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 0.5 \\ 0.5 & 1 \end{bmatrix}$$

$$A\mathbf{v} = \begin{bmatrix} 3.5 \\ 4 \end{bmatrix}$$

## Eigenvalues and Eigenvectors

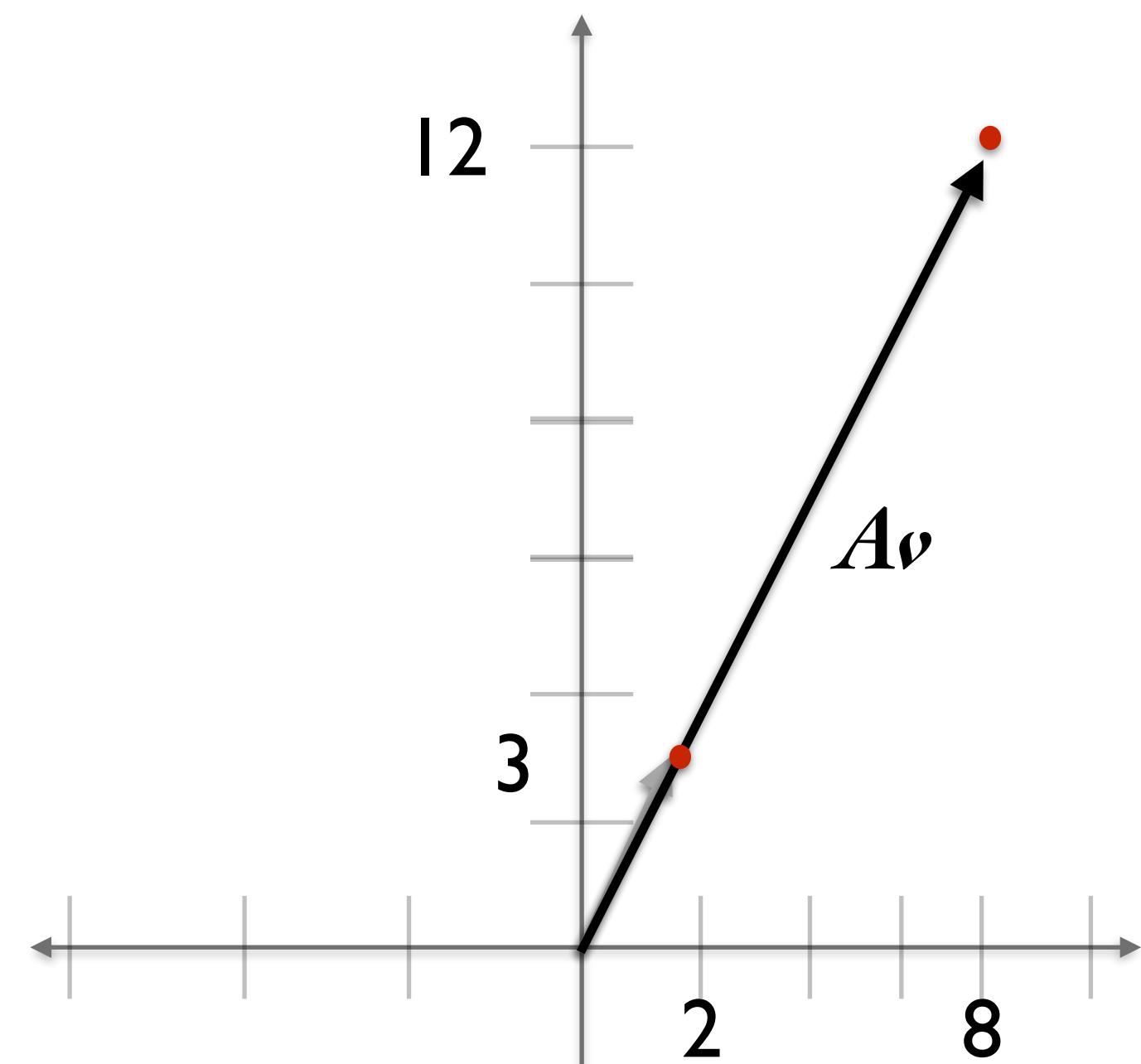
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$$v = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 2 \\ 6 & 0 \end{bmatrix}$$

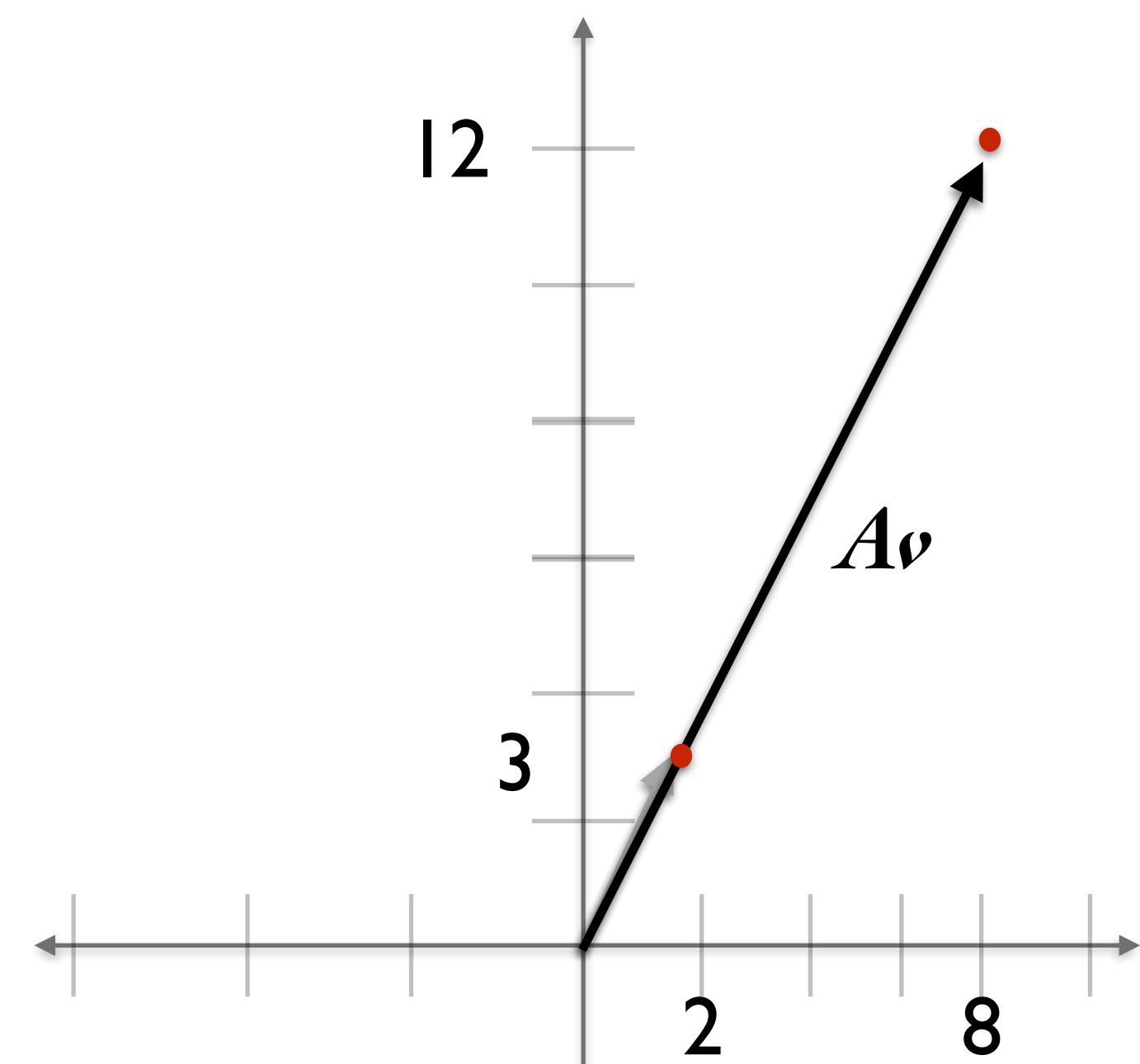
$$Av = \begin{bmatrix} 8 \\ 12 \end{bmatrix} = 4v$$



A vector  $v$  is an *eigenvector* of the matrix  $A$  if there exist a  $\lambda$  such that  
$$Av = \lambda v$$
and  $\lambda$  is then the eigenvalue of  $A$  associated to  $v$

i.e. if you can draw a line through the origin  $(0,0)$  that passes through  $v$  and  $Av$

i.e.:  $v$  is only scaled, and not rotated, by the transformation  $A$



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$$Av = \lambda v$$

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every point on the same line as an eigenvector is an eigenvector.  
The line is called the *eigenspace*.

# Eigenvalues and Eigenvectors

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Facial recognition: Eigenfaces



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