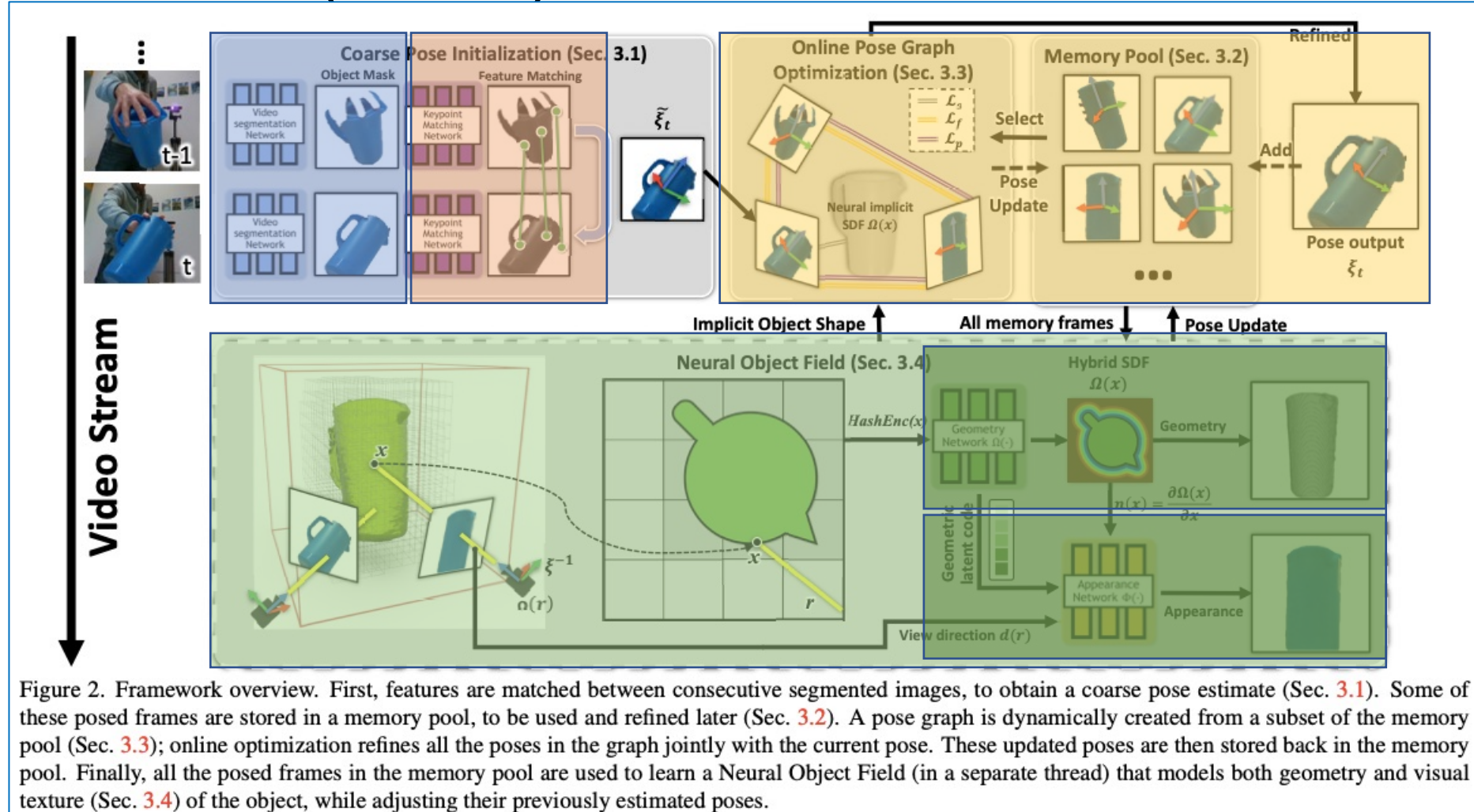


BundleSDF (2023)



BundleSDF (2023)

- Code runs!
- Milk film: **CUDA out of memory**
 - 7.79 GB total capacity; 2.63 GB already allocated; 219 MB free; 3.31 GB reserved in total by PyTorch
- HO3D dataset: **Unable to find a valid cuDNN algorithm to run convolution**

BundleSDF (2023)

- Code runs!

- Milk film: C

- 7.79 GB
reserve

- HO3D dat

convolutio

No more out of memory issues!

- Batch size from 64 to 1
- Training iteration steps from 500 to 300
- Reduce number of keyframes
 - Coinflip to take or discard keyframe
 - Change the minimal required rotation from precedent keyframes from 5° to 10°

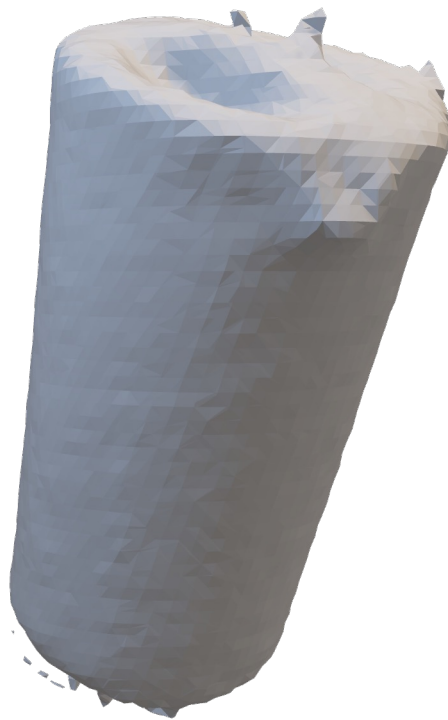
1 GB

n

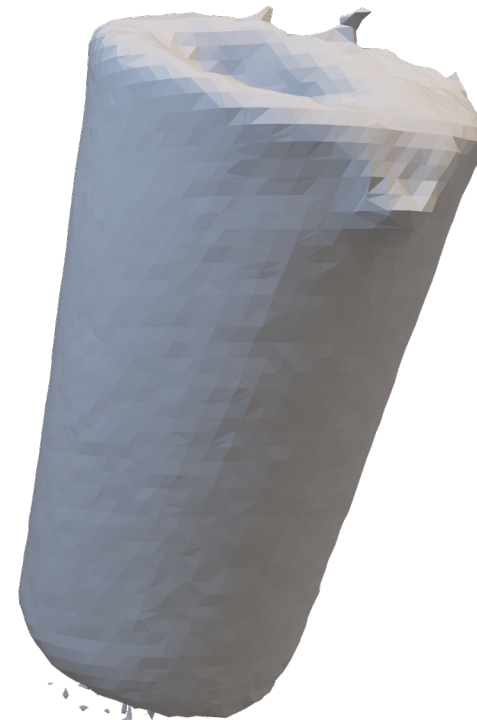
BundleSDF (2023)



Default
190 keyframes

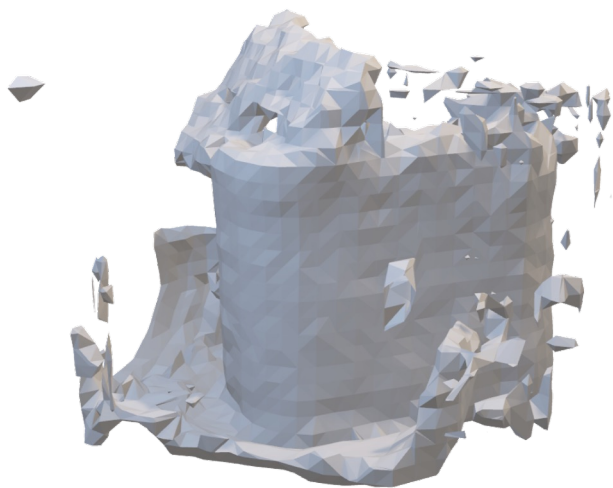


10°deg
90 keyframes



10°deg + cutoff
76 keyframes

BundleSDF (2023)



default

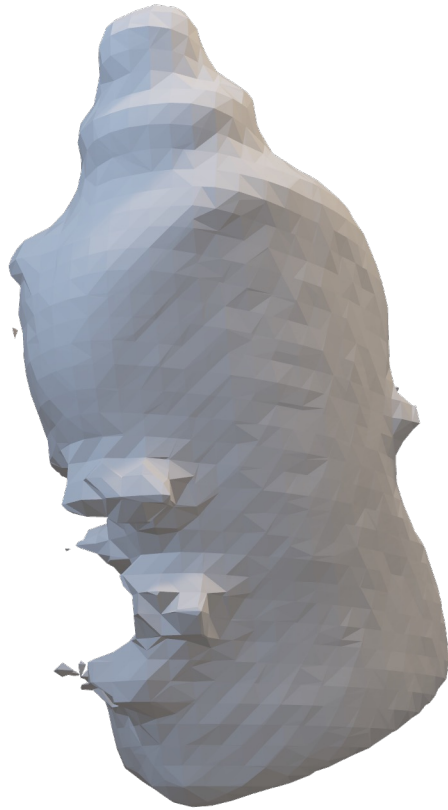


10°deg

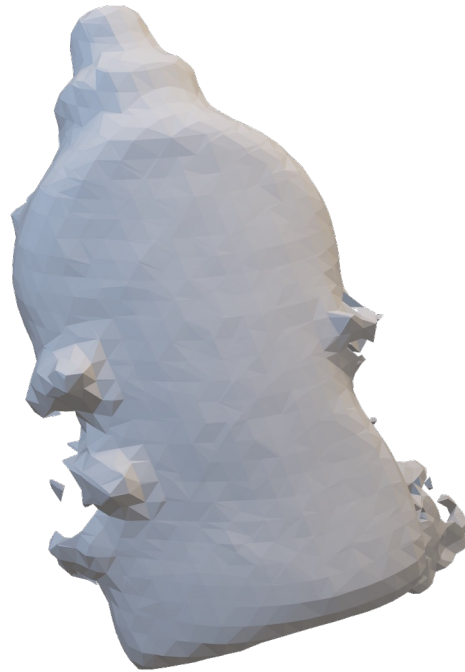


10°deg + cutoff

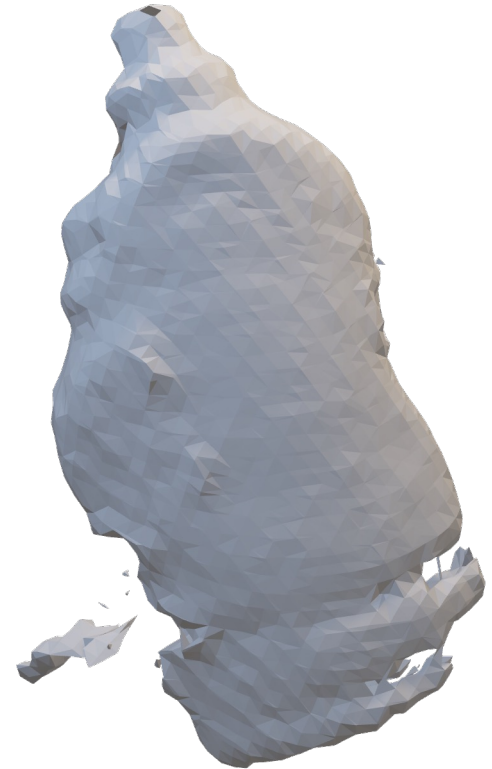
BundleSDF (2023)



default



10°deg



10°deg + cutoff

BundleSDF (2023)

10°deg + cutoff version



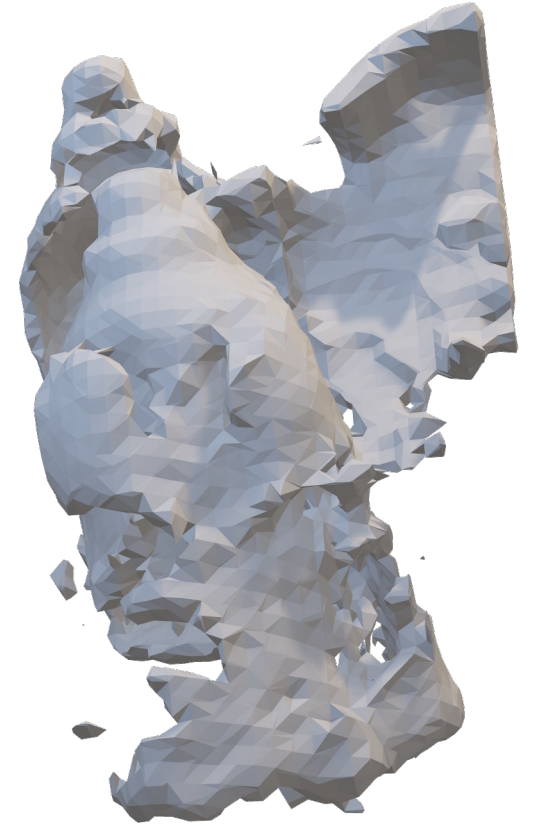
1st estimation, 5
keyframes



30 keyframes



55 keyframes



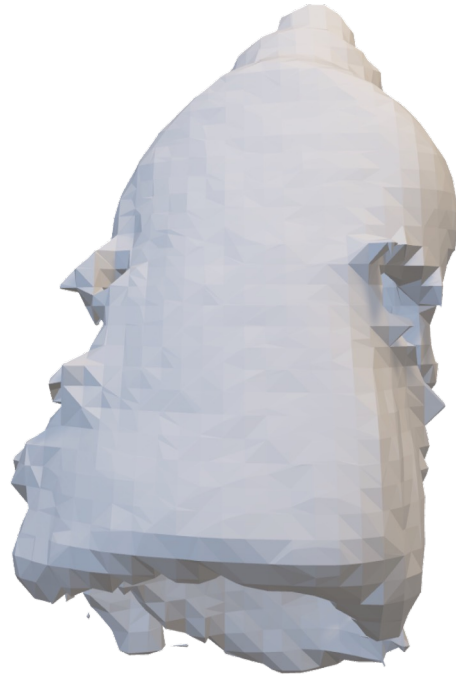
85 keyframes

BundleSDF (2023)

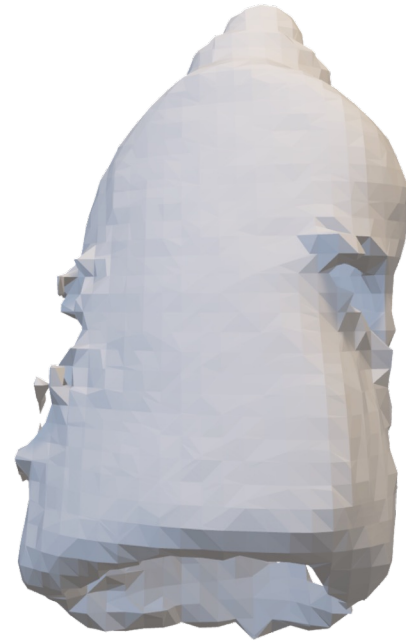
10°deg version



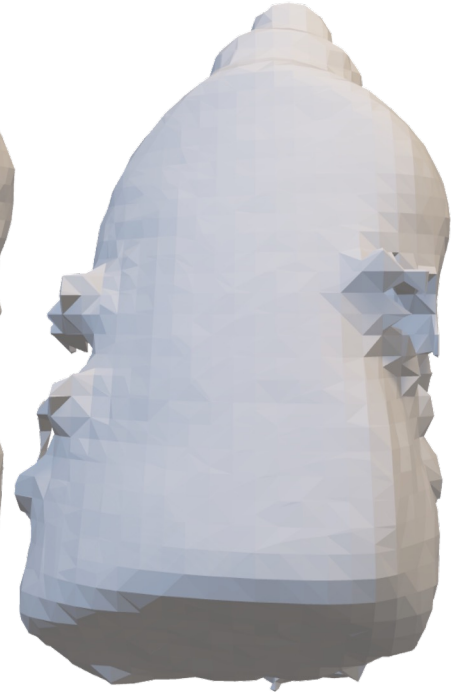
1st estimation, 5
keyframes



45 keyframes



85 keyframes



120 keyframes

DATASETS

Run on your own dataset

- Prepare your RGB and depth data [data here](#) for testing

```
root
├── rgb/      (PNG)
├── depth/    (PNG)
├── masks/
└── cam_K.txt (S)
```

No problem for both masks and camera geometry file

- BundleSDF does need only first mask frame, others can be generated when option turned on

Find an [example milk](#)

(background)

DATASETS

Run on your own dataset

- Prepare your RGB and depth data [data here](#) for testing

```
root
├── rgb/      (PNG)
├── depth/    (PNG)
├── masks/
└── cam_K.txt (
```

Find an [example milk](#)

Azure Kinect

- Computer does not see it
- ### Kinect SDK
- Only Windows + Ubuntu 16