MOT & Reconstruction W6

- Benchmarking metrics
- Linemod Test
- Kinect Works!
- Other

Benchmarking metrics for BSDF

- 6DF pose estimation
 - AUC (area under curve) percentage of ADD and ADD-S metrics?
- 3D shape reconstruction
 - Chamfer distance (CD) between reconstruction & ground truth

Benchmarking metrics

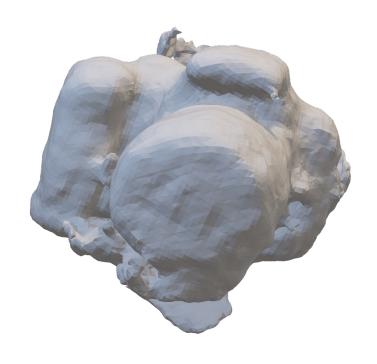
- 6DF pose estimation
 - HOTA, IDF1, AssA, DetA, MOTA
- 3D shape reconstruction
 - <u>CD</u>, EMD, IoU

- 6D Pose estimation dataset
- RGBD
- Occluded objects, subject is fixed in the middle of the table, rotate 90° every some frame

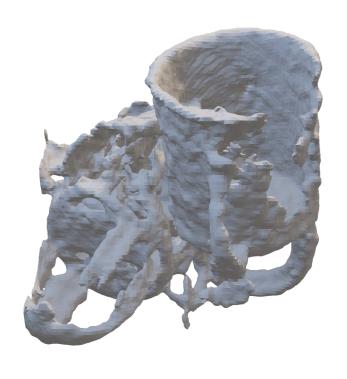


- Ran on 3 videos of the test folders in Linemod
 - Smaller videos, just to try

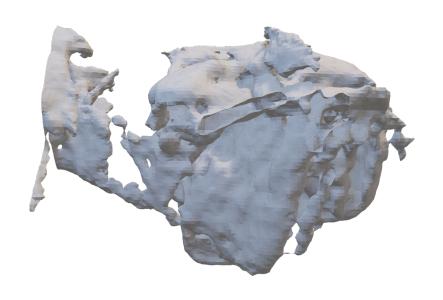














- Pose estimation fails
 - Error propagates to 3D shape reconstruction

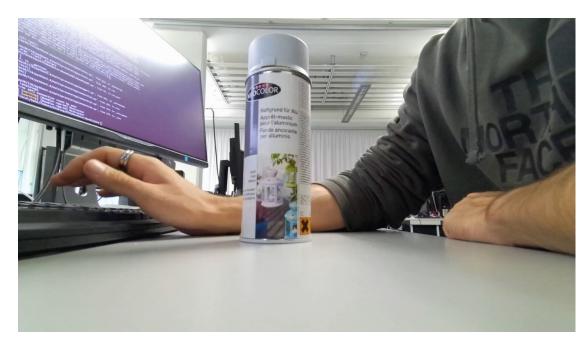
- Managed to making it run through the SDK on Ubuntu 20.04
 - SDK supported only on Ubuntu 16
- Somehow k4aviwer and k4arecorder can't work both at the same time?

- Camera calibration
 - /smidm/video2calibration

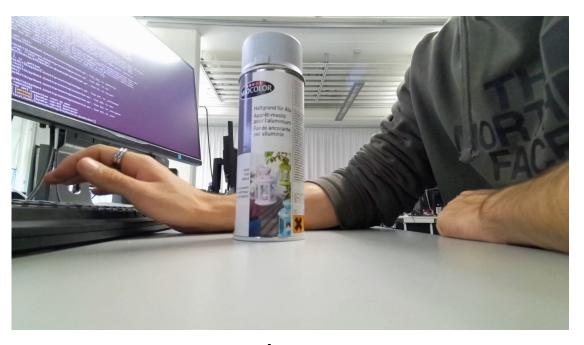


- RGB segmentation
 - BundleSDF uses XMem
 - GUI issues, does not run
 - MiVOS runs!
 - Cuda out of memory
 - Input images are 2 MB each
 - Ffmpeg has troubles converting Matroska files

- Created first dataset "spraypaintFEDONA"
 - Record RGBD with kinect
 - Select 1/10 of the frames to be able to use MiVOS
 - Ran MiVOS to get masks
 - Used cam_K file from camera calibration



Original video



Input video to BSDF









Final reconstruction

- Just a first try
 - Cannot compare this run with other datasets
 - Very few input images
 - High resolution inputs
 - BundleSDF is trained on other resolutions
 - Bad object?
 - Smooth, feature extraction might be harder

Other

- Next 3 weeks I won't be available
 - I will be working during weekends at the lab

 Matroska format, what converter could I be using instead of ffmpeg?