

# Linear Algebra

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G-04

## Week 12

### Quiz

Let  $A, B \in \mathbb{R}^{n \times n}$  and  $W \in \mathbb{R}^{m \times n}$ :

1. How is  $\det(A)$  related to  $\det(7A)$ ?  $\det(7A) = 7^n \det(A)$
2. The determinant is only defined for square matrices **TRUE**
3. If two rows or columns of  $A$  are identical,  $\det(A) = 0$  **TRUE**,  $A$  is not invertible
4. Applying elimination matrices on  $A$  doesn't change  $\det(A)$  **FALSE**  
→ may change sign and if we include multiplying row by scalar, also by scalar
5.  $\det(A) = -\det(A^T)$  **FALSE**,  $\det A = \det A^T$  (see next page)
6.  $\det(AB) = \det(B) \det(A)$  **TRUE** (see next page)
7.  $\det(A^2) = \det(A) \det(A)$  **TRUE** (6. applied on  $AB = A A$ )
8.  $\det(A^{-1}) = \frac{1}{\det(A)}$  **TRUE**  $1 = \det(I) = \det(AA^{-1}) = \det(A) \det(A^{-1})$   
 $\Rightarrow \det(A^{-1}) = \frac{1}{\det(A)}$
9.  $WW^+ = I$  or  $W^+W = I$  **FALSE**, only if full column or row rank  
→ see week 10,  $x = W^+b$  still has nice properties!
10. If  $W$  has full column rank,  $W^T W$  has full row rank and is surjective **TRUE**  
→ see week 10,  $W^T W$  has full rank and is invertible
11. If  $W$  has full row rank,  $m \geq n$  and  $W$  is surjective **FALSE**,  $m$  may be smaller than  $n$

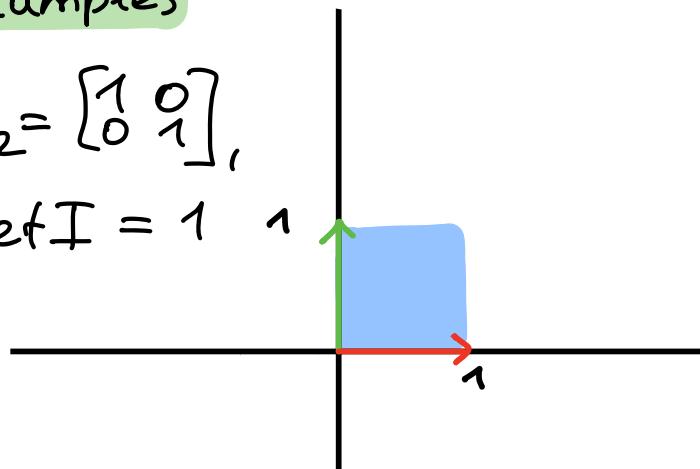
# The determinant

We consider  $\det A = D(a_1, \dots, a_n)$  where  $a_1, \dots, a_n \in \mathbb{R}^n$  are the columns of  $A \in \mathbb{R}^{n \times n}$  as a function  $\mathbb{R}^{n \times n} \rightarrow \mathbb{R}$  that gives us the oriented volume of the  $n$ -dimensional parallelogram spanned by  $a_1, \dots, a_n$ .

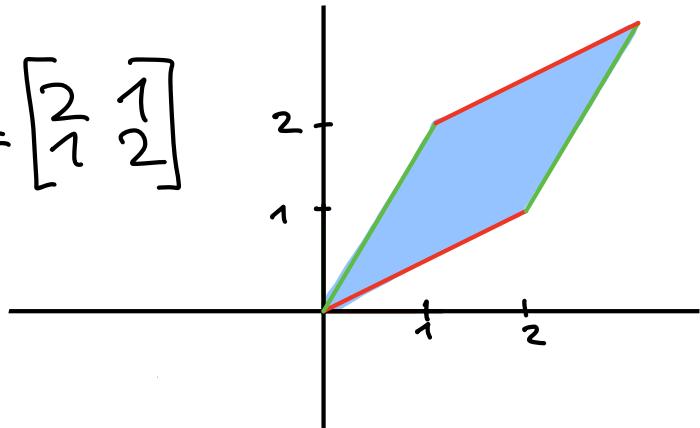
## Examples

$$I_2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix},$$

$$\det I = 1$$



$$A = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$



## Most important properties

- 1) Linear in each column/row
- 2) Swapping columns/rows changes sign
- 3)  $\det A$  doesn't change if we add multiple of one column (row) to another
- 4)  $\det A \neq 0 \iff A$  is invertible
- 5)  $\det A = \det A^T$
- 6)  $\det(AB) = \det(A) \det(B)$
- 7)  $\det(\alpha A) = \alpha^n \det(A) \rightarrow$  n times linearity per column/row
- 8) determinant of triangular matrix is product of diagonal entries in particular of diagonal matrix
- 9)  $\det \begin{pmatrix} A & B \\ 0 & D \end{pmatrix} = \det \begin{pmatrix} A & 0 \\ C & D \end{pmatrix} = \det A \det D$

# Deriving the formal definition

$$D(v_1, \dots, v_n)$$

$$A = \begin{bmatrix} 1 & & & 1 \\ v_1 & \dots & v_n \\ 1 & & & 1 \end{bmatrix}$$

$$= D\left(\sum_{j=1}^n a_{j,1} e_j, v_2, \dots, v_n\right) \quad (v_1 = \sum_{j=1}^n a_{j,1} e_j)$$

$$= \sum_{j=1}^n a_{j,1} D(e_j, v_2, \dots, v_n) \quad (\text{linearity in each column/row})$$

⋮ (repeating the step above for  $v_2, \dots, v_n$ )

$$= \sum_{j_1=1}^n \sum_{j_2=1}^n \dots \sum_{j_n=1}^n a_{j_1,1} a_{j_2,2} \dots a_{j_n,n} D(e_{j_1}, e_{j_2}, \dots, e_{j_n})$$

this sum is gigantic with  $n^n$  terms

BUT:  $D(e_{j_1}, \dots, e_{j_n}) = 0$  if two columns are identical, meaning two of the indices  $j_1, \dots, j_n$  are the same.

The only sequences of indices  $j_1, \dots, j_n$  that remain are rearrangements of  $\{1, \dots, n\}$ : so called permutations.

We consider one such permutation as a function

$$\sigma : \{1, \dots, n\} \rightarrow \{1, \dots, n\}$$

where  $\sigma(1), \dots, \sigma(n)$  is the new order/arrangement.

↓  
form group  
 $S_n$  of order  $n!$

We now have:

$$= \sum_{\sigma \in S_n} a_{\sigma(1),1} a_{\sigma(2),2} \dots a_{\sigma(n),n} \underbrace{D(e_{\sigma(1)}, \dots, e_{\sigma(n)})}_{= 1 \text{ or } -1 \text{ depending on number of row swaps (odd/even) from I}}$$

We define

$$\text{sign}(\sigma) = \begin{cases} 1 & \text{even } \# \text{ swaps required from } \{1, \dots, n\} \text{ to } \{\sigma(1), \dots, \sigma(n)\} \\ -1 & \text{odd } \_ \_ \_ \end{cases}$$

$$\text{to get } \det A = \sum_{\sigma \in S_n} \text{sign}(\sigma) \prod_{i=1}^n \sigma(i), i \xrightarrow{\text{order}} \sum_{\sigma \in S_n} \text{sign}(\sigma) \prod_{i=1}^n i, \sigma(i)$$

The above definition can be used to find formulas for the determinant of  $2 \times 2$  or  $3 \times 3$  matrices.

However: Don't use it directly for computations!

The following page has two methods for computing  $\det A$ .

**Example** There are two permutations of  $1, 2$ :

- $\sigma_1(1) = 1, \sigma_1(2) = 2 \Rightarrow \text{sign}(\sigma_1) = 1$
- $\sigma_2(1) = 2, \sigma_2(2) = 1 \Rightarrow \text{sign}(\sigma_2) = -1$

For a  $2 \times 2$  matrix this gives us:

$$\begin{aligned}\det A &= \text{sign}(\sigma_1) a_{1, \sigma_1(1)} a_{2, \sigma_1(2)} + \text{sign}(\sigma_2) a_{1, \sigma_2(1)} a_{2, \sigma_2(2)} \\ &= a_{11}a_{22} - a_{12}a_{21}\end{aligned}$$

# Computing the determinant

1) Laplace-Expansion  $\rightarrow$  benefits from rows/columns that have many zeros

expand

$$k^{\text{th}} \text{ row: } \det A = \sum_{j=1}^n (-1)^{k+j} a_{kj} \text{ oled } A[k, j]$$

$$l^{\text{th}} \text{ column: } \det A = \sum_{j=1}^n a_{jl} \underbrace{(-1)^{j+l} \det A[l, l]}_{\text{cofactor } jl, C_{jl}}$$

general formula for  $2 \times 2$  matrices:

$$\det \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} = a_{11}a_{22} - a_{12}a_{21}$$

Expansion along first row:

$$\det \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix} = a_{11} \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix} - a_{12} \begin{vmatrix} a_{21} & a_{23} \\ a_{31} & a_{33} \end{vmatrix} + a_{13} \begin{vmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{vmatrix}$$

2) Gauss-Elimination  $\rightarrow$  used in practice  $O(n^3)$

$$\det A = (-1)^{\sum_{i=1}^n \text{r}_{ii}} \prod_{\substack{\text{row} \\ \text{swaps}}} \text{P} \text{ Product of pivots in } \text{REF}(A)$$

• Note: don't multiply row by scalar! This might change  $\det A$ !

There are methods for computing  $A^{-1}$  and  $x = A^{-1}b$  using the determinant. You can find them in the script.

## Example

$$\det \begin{bmatrix} 0 & 1 & 1 \\ 1 & 2 & -5 \\ 6 & -4 & 3 \end{bmatrix} = 0 \cdot \det \begin{bmatrix} 2 & -5 \\ -4 & 3 \end{bmatrix} - 1 \cdot \det \begin{bmatrix} 1 & 1 \\ 4 & 3 \end{bmatrix} \\ + 6 \cdot \det \begin{bmatrix} 1 & 1 \\ 2 & -5 \end{bmatrix}$$
$$= -1(3+4) + 6 \cdot (-5-2)$$
$$= -7 + 6(-7) = -49$$

# Complex Numbers

Any  $z \in \mathbb{C}$  has the form  $z = a + bi$  where  $i^2 = -1$ .

$a$  is the real part of  $z$ :  $\operatorname{Re}(z) = a$

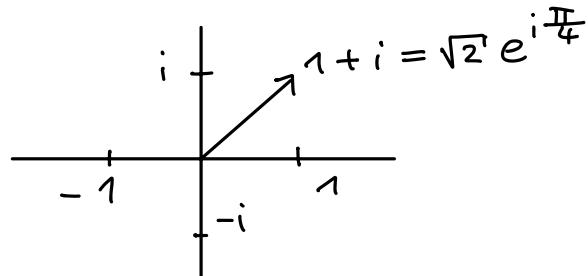
$b$  is the imaginary part of  $z$ :  $\operatorname{Im}(z) = b$

$\bar{z} = \overline{a+bi} = a - bi$  is the complex conjugate of  $z$

$|z| = \sqrt{a^2+b^2} = \sqrt{z \bar{z}}$  is the modulus of  $z$   $\curvearrowright$  corresponds to length in complex plane

We can see  $z$  as a vector in the complex plane

$\rightarrow$   $x$  axis is the real axis,  $y$  axis the imaginary axis



Any complex number  $z$  has polar form  $re^{i\theta}$ :

$$\bullet z = a + bi = r(\cos\theta + i\sin\theta) = re^{i\theta}$$

$$\rightarrow r = |z|$$

$$\rightarrow a = r\cos\theta$$

$$\rightarrow b = r\sin\theta$$

- Multiplying by  $re^{i\theta}$  has effect of stretching by  $r$  and rotating counterclockwise by  $\theta$  in the complex plane

example: multiply by  $i = e^{i\pi/2} \leftrightarrow$  rotate by 90 degrees (=  $\pi/2$  radians)

$A^* = \overline{A^T}$  is the conjugate transpose of  $A$   
(often also called hermitian transpose)

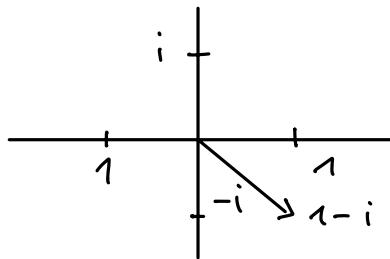
$\rightarrow$  Quickly estimate/compute values of  $\sin/\cos$  utilizing the unit circle

Example For  $z = 1 - i$ , find  $\bar{z}$  and  $r = |z|, \theta$  such that

$$z = re^{i\theta}:$$

$$\bar{z} = \overline{(1-i)} = 1+i$$

$$r = |z| = \sqrt{1^2 + (-1)^2} = \sqrt{2}$$



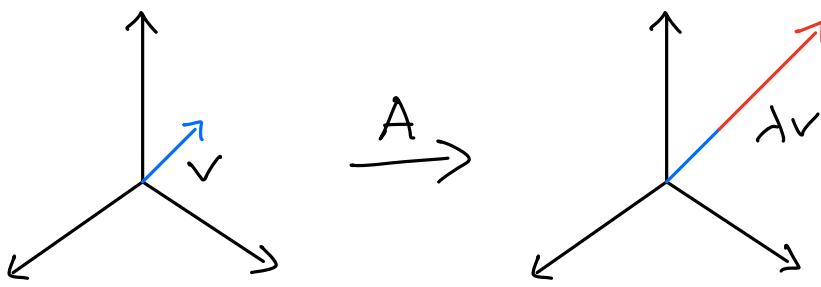
We see that this is a  $45^\circ$  rotation clockwise  
which is  $-\frac{\pi}{4} = 2\pi - \frac{\pi}{4} = \frac{7}{4}\pi$  radians  
(we could also use  $1-i = \sqrt{2}(\cos\theta + i\sin\theta)$ )

# Eigenvalues and eigenvectors

Let  $A \in \mathbb{R}^{n \times n}$ . We call nonzero  $v \in \mathbb{C}^n$  "eigenvector of  $A$  corresponding to the eigenvalue  $\lambda \in \mathbb{C}$ " if

$$Av = \lambda v$$

Geometrically,  $v$  is only stretched but did not change direction after applying  $A$ :



$$Av = \lambda v$$

$$\iff Av - \lambda v = 0$$

$$\iff (A - \lambda I)v = 0$$

$$\iff \det(A - \lambda I) = 0 \text{ and } v \in \underbrace{N(A - \lambda I)}_{\substack{\text{all eigenvectors corresponding} \\ \text{to } \lambda}}$$

characteristic polynomial  $\chi_A(\lambda) = \det(A - \lambda I)$

( $\hookrightarrow$  why is this a polynomial of degree  $n$ ?

$\rightarrow$  consider formal definition of determinant

algebraic multiplicity of  $\lambda$  . . . multiplicity of  $\lambda$  as root of  $\chi_A(\lambda)$

geometric multiplicity of  $\lambda$  . . .  $\dim N(A - \lambda I)$

$\downarrow$   
"how many dimensions of eigenvectors corresponding to  $\lambda$ "

$$\chi_A(\lambda) = (-\lambda)^n + \text{Tr}(A) (-\lambda)^{n-1} + \dots + \det A$$

Fundamental theorem of algebra:

$$\chi_A(\lambda) = (\lambda_1 - \lambda) \cdots (\lambda_n - \lambda) = (\lambda_1 - \lambda)^{p_1} \cdots (\lambda_k - \lambda)^{p_k}$$

$\lambda$  is eigenvalue with algebraic multiplicity  $p_1, \dots, p_k$

Algorithm for computing eigenvalues/eigen vectors

1. Find  $\chi_A(\lambda) = \det(A - \lambda I)$
2. Find solutions to  $\chi_A(\lambda) = 0$   
→ eigenvalues  $\lambda$
3. For every unique  $\lambda$ , find basis of  $N(A - \lambda I)$  with elimination  
→ eigenvectors  $v$

Example Find all eigenvalues and eigenvectors of

$$A = \begin{bmatrix} 4 & -5 \\ 2 & -3 \end{bmatrix}$$

$$1. \chi_A(\lambda) = \det \begin{bmatrix} 4-\lambda & -5 \\ 2 & -3-\lambda \end{bmatrix} = (4-\lambda)(-3-\lambda) + 10$$

$$= -12 - 4\lambda + 3\lambda + \lambda^2 + 10 = \lambda^2 - \lambda - 2 = (\lambda+1)(\lambda-2)$$

$$2. \chi_A(\lambda) = (\lambda+1)(\lambda-2) = 0 \iff \lambda = -1 \text{ or } \lambda = 2$$

3. (i)  $\lambda = -1$ , we solve  $(A + I)v = 0$  for  $v = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$ :

$$\begin{bmatrix} 5 & -5 \\ 2 & -2 \end{bmatrix} \sim \begin{bmatrix} 5 & -5 \\ 0 & 0 \end{bmatrix} \Rightarrow 5v_1 - 5v_2 = 0 \Rightarrow v_1 = v_2, v = \begin{bmatrix} v_2 \\ v_2 \end{bmatrix} = v_2 \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$v_2$  is free  
A basis for  $N(A + I)$  is given by  $\left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$

$$(ii) \lambda = 2$$

$$A - 2I = \begin{bmatrix} 2 & -5 \\ 2 & -5 \end{bmatrix} \sim \begin{bmatrix} 2 & -5 \\ 0 & 0 \end{bmatrix} \Rightarrow 2v_1 - 5v_2 = 0 \Rightarrow v_1 = \frac{5}{2}v_2$$

$\left\{ \begin{bmatrix} 5/2 \\ 1 \end{bmatrix} \right\}$  is a basis for  $N(A - 2I)$ .

→ check by testing  $Av = \lambda v$

References:

Last years course for some definitions

Sergey Treil, Linear Algebra Done Wrong, [https://www.math.brown.edu/streil/papers/LADW/LADW\\_2021\\_01-11.pdf](https://www.math.brown.edu/streil/papers/LADW/LADW_2021_01-11.pdf)