#### **Homework Review**

Professor: Dr. Yanmin Gong

TAs: Francisco Fernandes

Khuong Nguyen

Spring 2019

## Homework 3

- ▶ The default attribute of the **CODE** section of an assembly code is:
  - Read Only
  - Write Only
  - Read and Write
  - None of above

```
AREA myData, DATA, READWRITE; Define a data section
                                     ; Define an array with five integers
        DCD 1, 2, 3, 4, 5
Array
        AREA myCode, CODE, READONLY; Define a code section
        EXPORT main
                                    ; Make main visible to the Linker
        ENTRY
                                    ; Mark the entrance to the entire program
                                    ; PROC marks the beginning of subroutine
        PROC
 main
                                    ; Assembly program starts here
                                    ; Mark the end of a subroutine
         ENDP
         END
                                    ; Mark the end of a program
```

Table 3-3. Skeleton of an ARM assembly program. Textbook page 69

- ▶ The default attribute of the **DATA** section of an assembly code is:
  - Read Only
  - Write Only
  - Read and Write
  - None of above

```
AREA myData, DATA, READWRITE; Define a data section
        DCD 1, 2, 3, 4, 5
                                     ; Define an array with five integers
Array
        AREA myCode, CODE, READONLY; Define a code section
        EXPORT main
                                    ; Make main visible to the Linker
        ENTRY
                                    ; Mark the entrance to the entire program
                                    ; PROC marks the beginning of subroutine
        PROC
 main
                                    ; Assembly program starts here
                                    ; Mark the end of a subroutine
         ENDP
         END
                                    ; Mark the end of a program
```

Table 3-3. Skeleton of an ARM assembly program. Textbook page 69

Most ARM processors support both Big Endian and Little Endian. ARM processor is Little Endian by default.

Endian	First byte (lowest address)	Middle bytes	Last byte (highest address)
big	most significant	•••	least significant
little	least significant	•••	most significant

Memory Address	Memory Data
0x8000	0xEE
0x8001	0x8C
0x8002	0x90
0x8003	0xA7
0x8004	0xFF

Most ARM processors support both Big Endian and Little Endian. ARM processor is Little Endian by default.

Endian	First byte (lowest address)	Middle bytes	Last byte (highest address)
big	most significant	•••	least significant
little	least significant	•••	most significant

Memory Address	Memory Data
0x8000	0xEE
0x8001	0x8C
0x8002	0x90
0x8003	0xA7
0x8004	0xFF

Little Endian

Most ARM processors support both Big Endian and Little Endian. ARM processor is Little Endian by default.

Endian	First byte (lowest address)	Middle bytes	Last byte (highest address)
big	most significant	•••	least significant
little	least significant	•••	most significant

Memory Address	Memory Data
0x8000	0xEE
0x8001	0x8C
0x8002	0x90
0x8003	0xA7
0x8004	0xFF

Little Endian

Most ARM processors support both Big Endian and Little Endian. ARM processor is Little Endian by default.

Endian	First byte (lowest address)	Middle bytes	Last byte (highest address)
big	most significant	•••	least significant
little	least significant	•••	most significant

Memory Address	Memory Data
0x8000	0xEE
0x8001	0x8C
0x8002	0x90
0x8003	0xA7
0x8004	0xFF

Little Endian

By default setting, the word stored at address 0x8000 is: A7 90 8C EE

32 bits or 4 bytes

Byte 3 | Byte 2 | Byte 1 | Byte 0

Most ARM processors support both Big Endian and Little Endian. ARM processor is Little Endian by default.

Endian	First byte (lowest address)	Middle bytes	Last byte (highest address)
big	most significant	•••	least significant
little	least significant	•••	most significant

Memory Address	Memory Data
0x8000	0xEE
0x8001	0x8C
0x8002	0x90
0x8003	0xA7
0x8004	0xFF

A word (32 bits) will always follow this structure for either little or big endian

Little Endian

By default setting, the word stored at address 0x8000 is: A7 90 8C EE

32 bits or 4 bytes

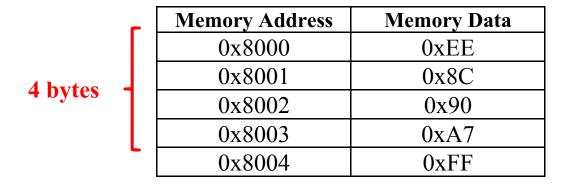
Byte 3 | Byte 2 | Byte 1 | Byte 0

Last byte

1st byte

Most ARM processors support both Big Endian and Little Endian. ARM processor is Little Endian by default.

Endian	First byte (lowest address)	Middle bytes	Last byte (highest address)
big	most significant	•••	least significant
little	least significant	•••	most significant



A word (32 bits) will always follow this structure for either little or big endian

By default setting, the word stored at address 0x8000 is: A7 90 8C EE

32 bits or 4 bytes

Byte 3 | Byte 2 | Byte 1 | Byte 0

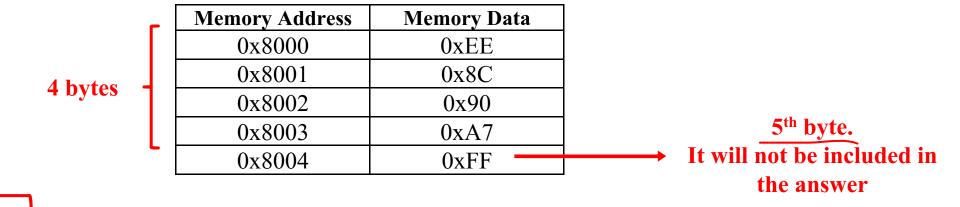
Last byte

1st byte

Little Endian

Most ARM processors support both Big Endian and Little Endian. ARM processor is Little Endian by default.

Endian	First byte (lowest address)	Middle bytes	Last byte (highest address)
big	most significant	•••	least significant
little	least significant	•••	most significant



By default setting, the word stored at address 0x8000 is: A7 90 8C EE

**Little Endian** 

Most ARM processors support both Big Endian and Little Endian. ARM processor is Little Endian by default.

Endian	First byte (lowest address)	Middle bytes	Last byte (highest address)
big	most significant	•••	least significant
little	least significant	•••	most significant

	Memory Address	Memory Data
<b>Least significant</b> ←	0x8000	0xEE
	0x8001	0x8C
	0x8002	0x90
Most significant ←	0x8003	0xA7
	0x8004	0xFF

Most ARM processors support both Big Endian and Little Endian. ARM processor is Little Endian by default.

Endian	First byte (lowest address)	Middle bytes	Last byte (highest address)
big	most significant	•••	least significant
little	least significant	•••	most significant

	Memory Address	Memory Data
<b>Least significant</b> ←	0x8000	0xEE
	0x8001	0x8C
	0x8002	0x90
Most significant ←	0x8003	0xA7
	0x8004	0xFF

Last byte: Most significant

1<sup>st</sup> byte: Least significant

Most ARM processors support both Big Endian and Little Endian. ARM processor is Little Endian by default.

Endian	First byte (lowest address)	Middle bytes	Last byte (highest address)
big	most significant	•••	least significant
little	least significant	•••	most significant

Last byte: Least significant

Memory Address	Memory Data
0x8000	0xEE
0x8001	0x8C
0x8002	0x90
0x8003	0xA7
0x8004	0xFF

In Big Endian? EE 8C 90 A7

1<sup>st</sup> byte: Most significant

▶ Suppose r0 = 0x8000, and the memory layout is as follows:

Address	Data
0x8007	0x79
0x8006	0xCD
0x8005	0xA3
0x8004	0xFD
0x8003	0x0D
0x8002	0xEB
0x8001	0x2C
0x8000	0x1A

What is the value of r1 after running LDR r1, [r0] if the system is little endian or big endian?

▶ Suppose r0 = 0x8000, and the memory layout is as follows:

Address	Data
0x8007	0x79
0x8006	0xCD
0x8005	0xA3
0x8004	0xFD
0x8003	0x0D
0x8002	0xEB
0x8001	0x2C
0x8000	0x1A

What is the value of r1 after running LDR r1, [r0] if the system is little endian or big endian?

This instruction will load a word (32 bits) from the memory data starting from address r0.

▶ Suppose r0 = 0x8000, and the memory layout is as follows:

0x8000 in this case will be used as a memory address. r0 DOES NOT represent data in this context!

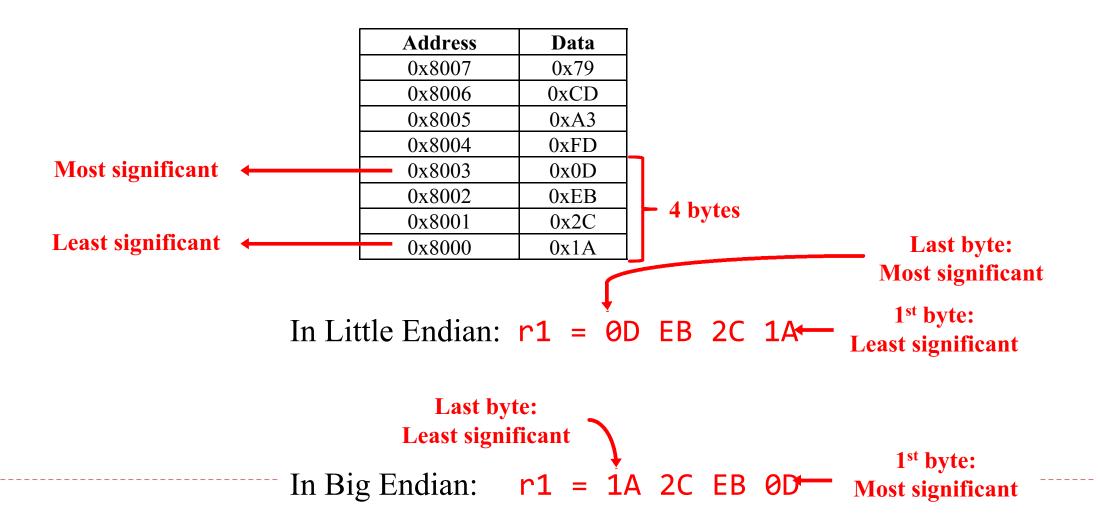
Address	Data
0x8007	0x79
0x8006	0xCD
0x8005	0xA3
0x8004	0xFD
0x8003	0x0D
0x8002	0xEB
0x8001	0x2C
0x8000	0x1A

What is the value of r1 after running LDR r1, [r0] if the system is little endian or big endian?

This instruction will load a word (32 bits) from the memory data starting from address r0.

18

▶ Suppose r0 = 0x8000, and the memory layout is as follows:



▶ Suppose r0 = 0x8000, and the memory layout is as follows:

Address	Data
0x8007	0x79
0x8006	0xCD
0x8005	0xA3
0x8004	0xFD
0x8003	0x0D
0x8002	0xEB
0x8001	0x2C
0x8000	0x1A

▶ Suppose the system is set as little endian. What are the values of r1 and r0 if the instructions are executed separately?

```
▶ LDR r1, [r0, #4]
```

LDR r1, [r0], #4

▶ LDR r1, [r0, #4]!

This means that one instruction does not affect the other. So, when you run the next instruction, r1 and r0 will be reinitialized.

▶ Suppose r0 = 0x8000, and the memory layout is as follows:

Address	Data
0x8007	0x79
0x8006	0xCD
0x8005	0xA3
0x8004	0xFD
0x8003	0x0D
0x8002	0xEB
0x8001	0x2C
0x8000	0x1A

▶ Suppose the system is set as little endian. What are the values of r1 and r0 if the instructions are executed separately?

```
LDR r1, [r0, #4]
LDR r1, [r0], #4
LDR r1, [r0, #4]!
Let's look them one by one!
```

▶ Suppose r0 = 0x8000, and the memory layout is as follows:

▶ LDR r1, [r0, #4] -

In this case, we are accessing the memory data using the <u>pre-index</u> <u>mode</u>

Address	Data
0x8007	0x79
0x8006	0xCD
0x8005	0xA3
0x8004	0xFD
0x8003	0x0D
0x8002	0xEB
0x8001	0x2C
0x8000	0x1A

Suppose r0 = 0x8000, and the memory layout is as follows:



It means we are going to load the memory data from address  $r\theta + 4$  into r1.

Address	Data
0x8007	0x79
0x8006	0xCD
0x8005	0xA3
0x8004	0xFD
0x8003	0x0D
0x8002	0xEB
0x8001	0x2C
0x8000	0x1A

▶ Suppose r0 = 0x8000, and the memory layout is as follows:

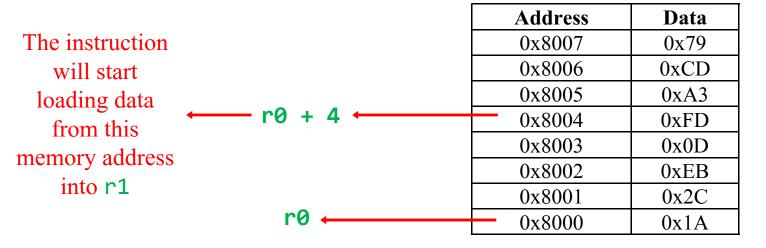


It means we are going to load the memory data from address  $r\theta + 4$  into r1.

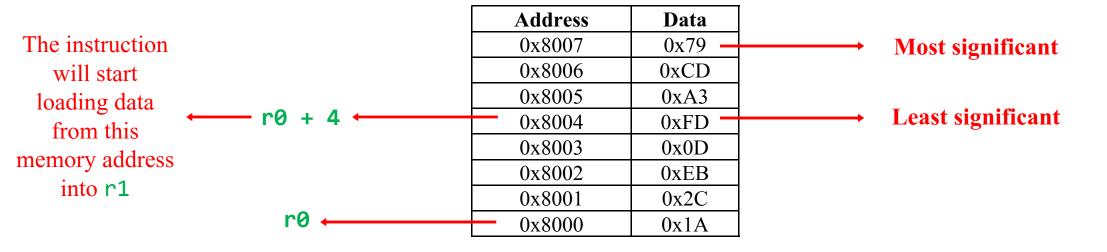
In the pre-index mode ro will NOT be modified.

Address	Data
0x8007	0x79
0x8006	0xCD
0x8005	0xA3
0x8004	0xFD
0x8003	0x0D
0x8002	0xEB
0x8001	0x2C
0x8000	0x1A

- ▶ Suppose r0 = 0x8000, and the memory layout is as follows:
  - ▶ LDR r1, [r0, #4]



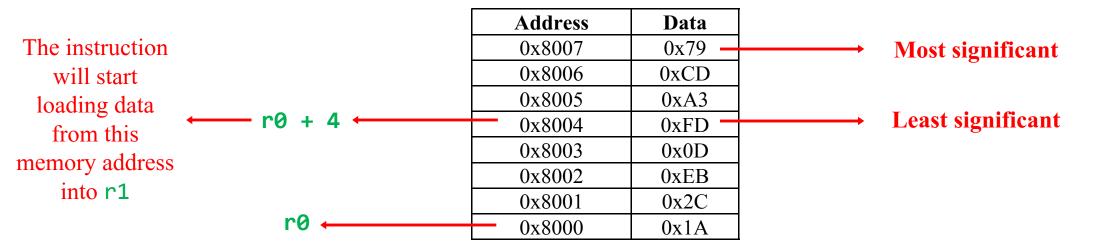
- ▶ Suppose r0 = 0x8000, and the memory layout is as follows:
  - ▶ LDR r1, [r0, #4]



- ▶ Suppose r0 = 0x8000, and the memory layout is as follows:
  - ▶ LDR r1, [r0, #4]

#### **Solution:**

$$r0 = 0x8000 \longrightarrow r0$$
 is unchanged!  
 $r1 = 79$  CD A3 FD



▶ Suppose r0 = 0x8000, and the memory layout is as follows:

▶ LDR r1, [r0], #4 -

In this case, we are accessing the memory data using the *post-index* mode

Data
0x79
0xCD
0xA3
0xFD
0x0D
0xEB
0x2C
0x1A

▶ Suppose r0 = 0x8000, and the memory layout is as follows:



It means we are going to load the memory data from address  $r\theta$  into r1.

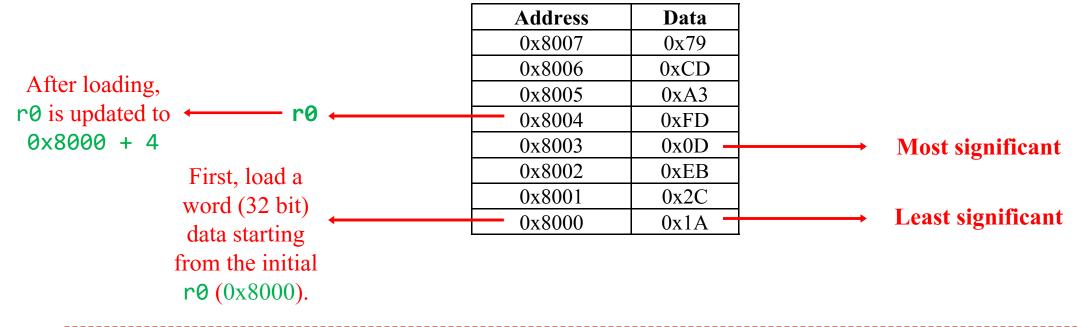
After loading, r0 is updated to become r0 + 4.

Address	Data
0x8007	0x79
0x8006	0xCD
0x8005	0xA3
0x8004	0xFD
0x8003	0x0D
0x8002	0xEB
0x8001	0x2C
0x8000	0x1A

- ▶ Suppose r0 = 0x8000, and the memory layout is as follows:
  - ▶ LDR r1, [r0], #4

	Address	Data
	0x8007	0x79
A.C. 1 1'	0x8006	0xCD
After loading,	0x8005	0xA3
r0 is updated to ← r0 ←	0x8004	0xFD
$0 \times 8000 + 4$	0x8003	0x0D
First, load a	0x8002	0xEB
word (32 bit)	0x8001	0x2C
data starting	0x8000	0x1A
from the initial r0 (0x8000).		

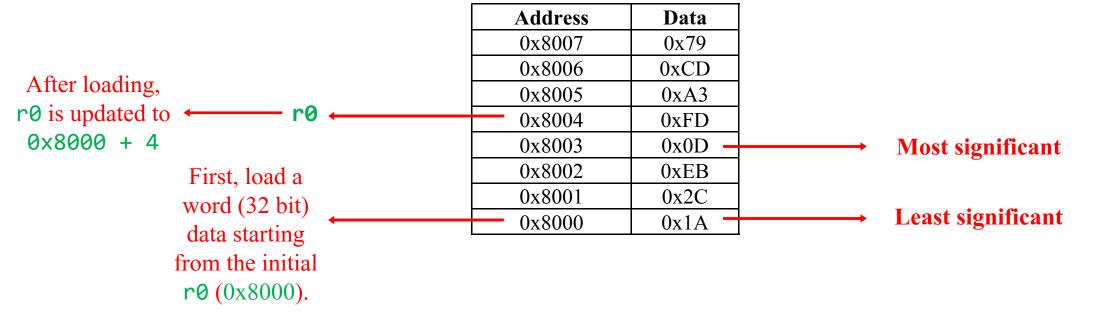
- ▶ Suppose r0 = 0x8000, and the memory layout is as follows:
  - ▶ LDR r1, [r0], #4



- ▶ Suppose r0 = 0x8000, and the memory layout is as follows:
  - ▶ LDR r1, [r0], #4

#### **Solution:**

$$r0 = 0x8004 \longrightarrow r0 = r0 + 4$$
  
 $r1 = 0D EB 2C 1A$ 



▶ Suppose r0 = 0x8000, and the memory layout is as follows:

▶ LDR r1, [r0, #4]!

In this case, we are accessing the memory data using the <u>pre-index with</u> <u>update mode.</u>

Address	Data
0x8007	0x79
0x8006	0xCD
0x8005	0xA3
0x8004	0xFD
0x8003	0x0D
0x8002	0xEB
0x8001	0x2C
0x8000	0x1A

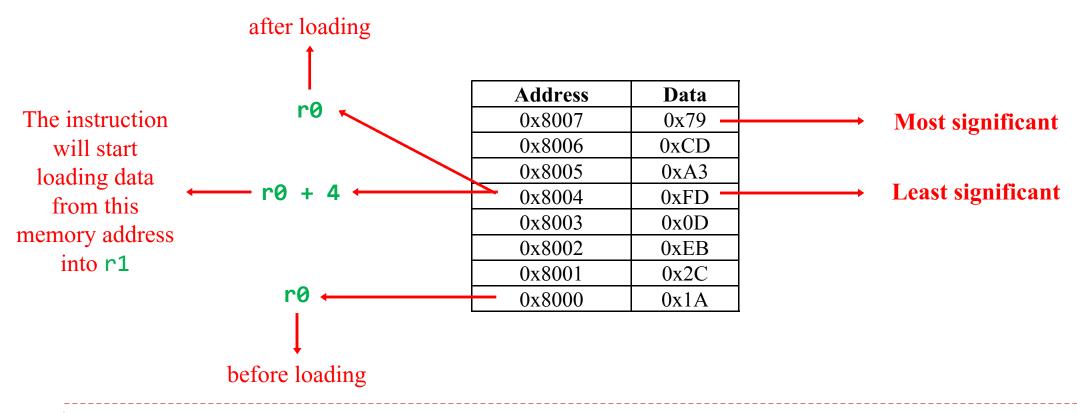
▶ Suppose r0 = 0x8000, and the memory layout is as follows:

It means we are going to load the memory data from address  $r\theta + 4$  into r1.

After loading, r0 is also updated to become r0 + 4.

Address	Data
0x8007	0x79
0x8006	0xCD
0x8005	0xA3
0x8004	0xFD
0x8003	0x0D
0x8002	0xEB
0x8001	0x2C
0x8000	0x1A

- ▶ Suppose r0 = 0x8000, and the memory layout is as follows:
  - ▶ LDR r1, [r0, #4]!



before loading

▶ Suppose r0 = 0x8000, and the memory layout is as follows:

▶ LDR r1, [r0, #4]! **Solution:**  $\rightarrow$  r0 = r0 + 4 r0 = 0x8004r1 = 79 CD A3 FDafter loading Address Data The instruction 0x8007 0x79Most significant 0x80060xCDwill start 0x8005 0xA3loading data Least significant 0x8004 0xFDfrom this 0x8003 0x0Dmemory address 0x8002 0xEBinto r1 0x8001 0x2C0x80000x1A

# Homework 4

```
STR r1, [r0], #4

STR r1, [r0, #4]!

STR r1, [r0, 4]
```

Suppose r0 = 0x20000000 and r1 = 0x12345678. All bytes in memory are initialized to 0x00. Suppose the following assembly program has been executed successfully. Draw a table to show the memory value if the processor uses little endian.

STR r1, [r0], #4

STR r1, [r0, #4]!

STR r1, [r0, 4]

In this case, each line of code is NOT independent of each other. We should consider these three lines as a single program.

Suppose r0 = 0x20000000 and r1 = 0x12345678. *All bytes in memory are initialized to 0x00*. Suppose the following assembly program has been executed successfully. Draw a table to show the memory value if the processor uses little endian.

In this case, all memory positions will start empty or equal to 0x00.

STR	r1,	[r0], #4
STR	r1,	[r0, #4]!
		[r0, 4]

Address	Data
0x20000007	
0x20000006	
0x20000005	
0x20000004	
0x20000003	
0x20000002	
0x20000001	
0x20000000	

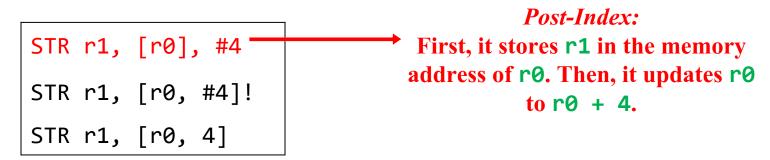
Suppose r0 = 0x20000000 and r1 = 0x12345678. All bytes in memory are initialized to 0x00. Suppose the following assembly program has been executed successfully. Draw a table to show the memory value if the processor uses little endian.

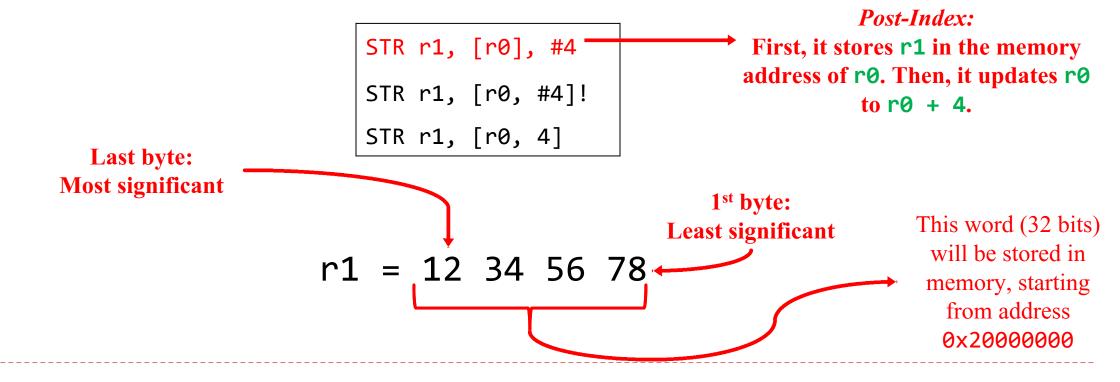
Another important thing to note is that r1 already contains some data and we are going to store this data back in the memory using the STR instruction.

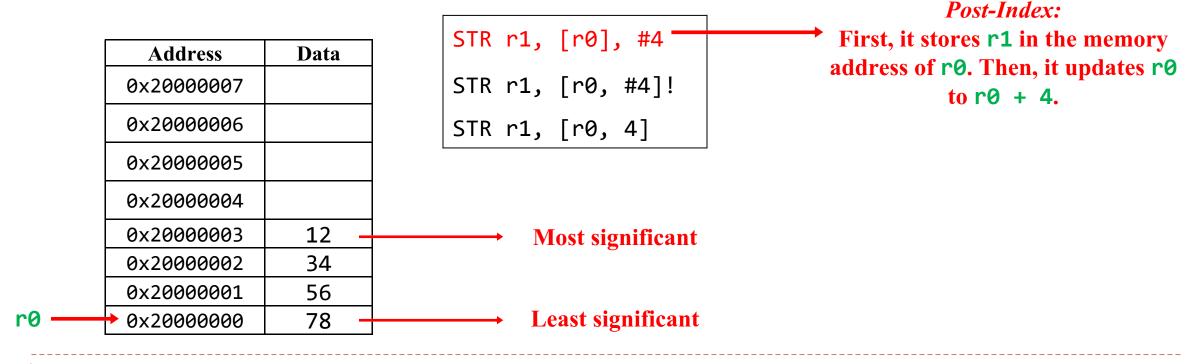
```
STR r1, [r0], #4

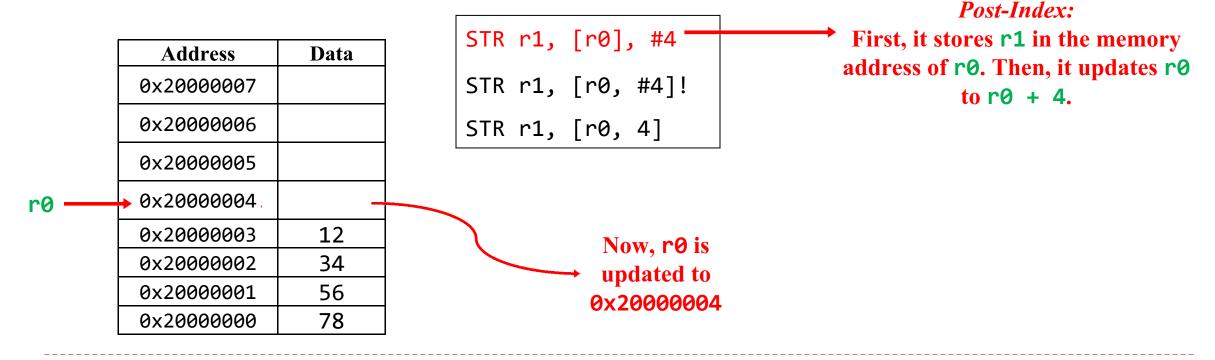
STR r1, [r0, #4]!

STR r1, [r0, 4]
```



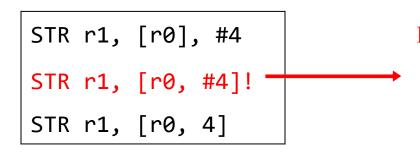






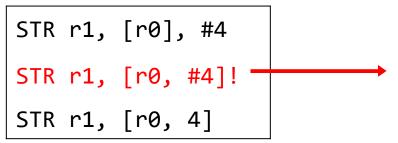
Suppose r0 = 0x20000000 and r1 = 0x12345678. All bytes in memory are initialized to 0x00. Suppose the following assembly program has been executed successfully. Draw a table to show the memory value if the processor uses little endian.

	Address	Data
	0×20000007	
	0x20000006	
	0x20000005	
r0 —	• 0x20000004	
	0x20000003	12
	0x20000002	34
	0x20000001	56
	0x20000000	78

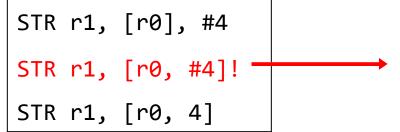


Pre-index with update:
First, it stores r1 in the memory address of r0 + 4. Then, it updates r0 to r0 + 4.

	Address	Data
	0x20000012	
	0x20000011	
	0x20000010	
	0x20000009	
r0 + 4 —	• 0x20000008	
	0x20000007	
	0x20000006	
	0x20000005	
r0 ——	→ 0x20000004	
	0x20000003	12
	0x20000002	34
	0x20000001	56
	0x20000000	78



Pre-index with update:
First, it stores r1 in the memory address of r0 + 4. Then, it updates r0 to r0 + 4.



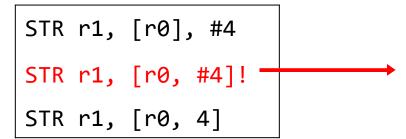
Pre-index with update:

First, it stores r1 in the memory address of r0 + 4. Then, it updates r0 to r0 + 4.

	Address	Data	
	0x2000000C		
	0x2000000B	12 -	
	0x2000000A	34	
	0x20000009	56	
r0 + 4 <del>-</del>	• 0x20000008	78 _	
	0x20000007		
	0x20000006		
	0x20000005		
r0 —	→ 0x20000004		
	0x20000003	12	
	0x20000002	34	
	0x20000001	56	
	0x20000000	78	

Most significant

Least significant

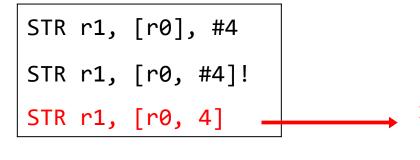


Pre-index with update:
First, it stores r1 in the memory
address of r0 + 4. Then, it
updates r0 to r0 + 4.

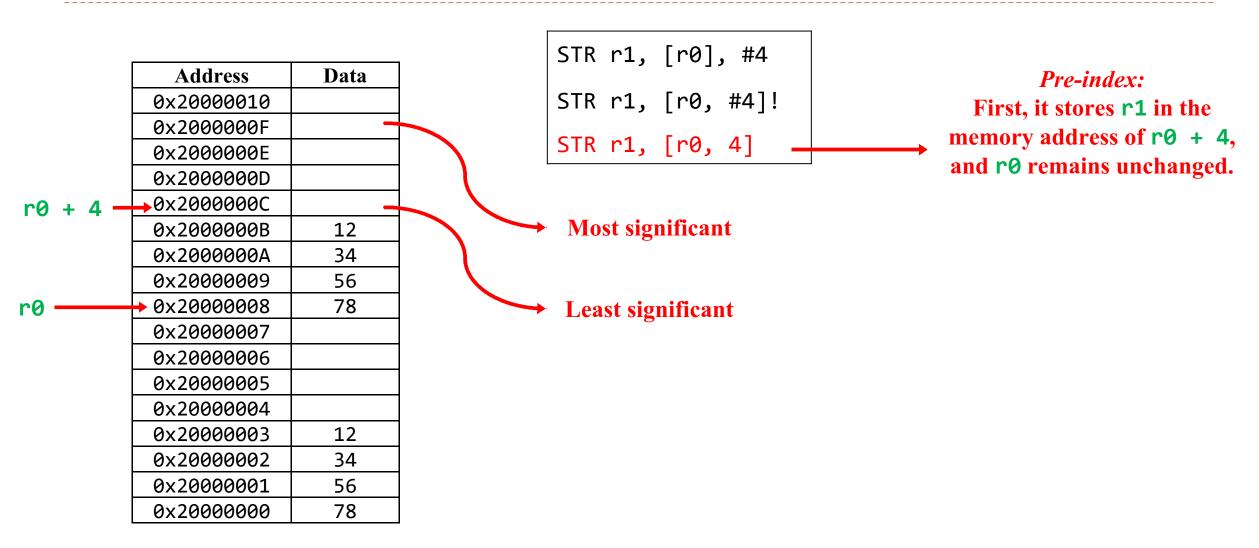
Address	Data
0x2000000C	
0x2000000B	12
0x2000000A	34
0x20000009	56
• 0x20000008	78
0x20000007	
0x20000006	
0x20000005	
0x20000004	
0x20000003	12
0x20000002	34
0x20000001	56
0x20000000	78

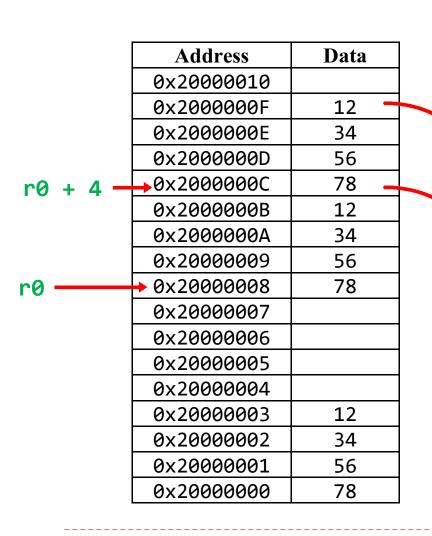
Now, r0 is updated to 0x2000008

	Address	Data
	0x2000000C	
	0x2000000B	12
	0x2000000A	34
	0x20000009	56
~0 <del></del>	• 0x20000008	78
	0x20000007	
	0x20000006	
	0x20000005	
	0x20000004	
	0x20000003	12
	0x20000002	34
	0x20000001	56
	0x20000000	78



Pre-index:
First, it stores r1 in the memory address of r0 + 4, and r0 remains unchanged.





STR r1, [r0], #4

STR r1, [r0, #4]!

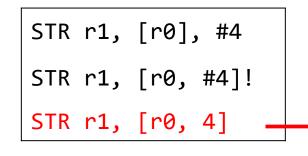
STR r1, [r0, 4]

Pre-index:
First, it stores r1 in the memory address of r0 + 4, and r0 remains unchanged.

**Most significant** 

Least significant

Address	Data
0x20000010	
0x2000000F	12
0x2000000E	34
0x2000000D	56
0x2000000C	78
0x2000000B	12
0x2000000A	34
0x20000009	56
→ 0x20000008	78
0x20000007	
0x20000006	
0x20000005	
0x20000004	
0x20000003	12
0x20000002	34
0x20000001	56
0x20000000	78



Pre-index:
First, it stores r1 in the memory address of r0 + 4, and r0 remains unchanged.

r0 remains unchanged and equal to 0x2000008

Translate the following code into a C program and explain what it does.

```
MOV r2, #1
MOV r1, #1

loop CMP r1, r0
BGT done
MUL r2, r1, r2
ADD r1, r1, #1
B loop

done MOV r0, r2
```

Translate the following code into a C program and explain what it does.

```
MOV r2, #1 ; r2 = 1
MOV r1, #1 ; r1 = 1

loop CMP r1, r0 ; compare r1 to r0. In this case, r0 is our input variable.
BGT done ; If r1 is greater than r0 go to "done"
; If r1 is less or equal to r0 the following lines will run.
MUL r2, r1, r2 ; r2 = r2*r1
ADD r1, r1, #1 ; r1 = r1 + 1
B loop ; go back to "loop"

done MOV r0, r2 ; When r1 is greater than r0, store the result r2 in r0
```

Translate the following code into a C program and explain what it does.

MOV r2, #1
MOV r1, #1

loop CMP r1, r0
BGT done
MUL r2, r1, r2
ADD r1, r1, #1
B loop

done MOV r0, r2

So, the easiest way to know what is this program computing is to plug in some numbers. We know that r0 is the input and r2 is the output.

```
If r0 = 0 \rightarrow r2 = 1 \rightarrow r1 = 1 (the loop will not run)
If r0 = 1 \rightarrow r2 = 1*1 = 1 \rightarrow r1 = 1 + 1 = 2
If r0 = 2 \rightarrow r2 = 1*1 = 1 \rightarrow r1 = 1 + 1 = 2
                 r^2 = 1*2 = 2 \rightarrow r^2 = 2 + 1 = 3
If r0 = 3 \rightarrow r2 = 1*1 = 1 \rightarrow r1 = 1 + 1 = 2
                 r2 = 1*2 = 2 \rightarrow r1 = 2 + 1 = 3
                  r^2 = 3*2 = 6 \rightarrow r^2 = 3 + 1 = 4
If r0 = 4 \rightarrow r2 = 1*1 = 1 \rightarrow r1 = 1 + 1 = 2
                  r2 = 1*2 = 2 \rightarrow r1 = 2 + 1 = 3
                  r2 = 3*2 = 6 \rightarrow r1 = 3 + 1 = 4
                  r^2 = 6*4 = 24 \rightarrow r^2 = 4 + 1 = 5
```

Translate the following code into a C program and explain what it does.

MOV r2, #1
MOV r1, #1

loop CMP r1, r0
BGT done
MUL r2, r1, r2
ADD r1, r1, #1
B loop

done MOV r0, r2

So, the easiest way to know what is this program computing is to plug in some numbers. We know that r0 is the input and r2 is the output.

```
If r0 = 0 \rightarrow r2 = 1 \rightarrow r1 = 1
If r0 = 1 \rightarrow r2 = 1*1 = 1 \rightarrow r1 = 1 + 1 = 2
If r0 = 2 \rightarrow r2 = 1*1 = 1 \rightarrow r1 = 1 + 1 = 2
                  r^2 = 1*2 = 2 \rightarrow r^2 = 2 + 1 = 3
If r0 = 3 \rightarrow r2 = 1*1 = 1 \rightarrow r1 = 1 + 1 = 2
                  r2 = 1*2 = 2 \rightarrow r1 = 2 + 1 = 3
                  r^2 = 3*2 = 6 \rightarrow r^2 = 3 + 1 = 4
If r0 = 4 \rightarrow r2 = 1*1 = 1 \rightarrow r1 = 1 + 1 = 2
                  r2 = 1*2 = 2 \rightarrow r1 = 2 + 1 = 3
                  r2 = 3*2 = 6 \rightarrow r1 = 3 + 1 = 4
                  r^2 = 6*4 = 24 \rightarrow r^2 = 4 + 1 = 5
```

The code is computing the factorial of r0.

Translate the following code into a C program and explain what it does.

```
MOV r2, #1; r2 = 1
MOV r1, #1; r1 = 1

Variables are initialized.

loop CMP r1, r0; compare r1 to r0. In this case, r0 is our input variable.

BGT done; If r1 is greater than r0 go to "done"
; If r1 is less or equal to r0 the following lines will run.

MUL r2, r1, r2; r2 = r2*r1

ADD r1, r1, #1; r1 = r1 + 1

B loop; go back to "loop"

done MOV r0, r2; When r1 is greater than r0, store the result r2 in r0
```

▶ Translate the following code into a C program and explain what it does.

```
MOV r2, #1; r2 = 1
                                     Variables are initialized.
       MOV r1, \#1; r1 = 1
       CMP r1, r0; compare r1 to r0. In this case, r0 is our input variable.
loop
       BGT done ; If r1 is greater than r0 go to "done"
       ; If r1 is less or equal to r0 the following lines will run.
       MUL r2, r1, r2; r^2 = r^2 r^1
                                             This represents a for or a while loop:
       ADD r1, r1, \#1; r1 = r1 + 1
                                             "while r1 is less or equal to r0" do r2 = r2*r1"
                      ; go back to "loop"
          loop
       В
done
       MOV r0, r2
                  ; When r1 is greater than r0, store the result r2 in r0
```

▶ Translate the following code into a C program and explain what it does.

```
MOV r2, #1; r2 = 1
                                      Variables are initialized.
       MOV r1, \#1; r1 = 1
       CMP r1, r0; compare r1 to r0. In this case, r0 is our input variable.
loop
       BGT done ; If r1 is greater than r0 go to "done"
       ; If r1 is less or equal to r0 the following lines will run.
       MUL r2, r1, r2 ; r^2 = r^{2*}r^1
                                              This represents a for or a while loop:
       ADD r1, r1, \#1|; r1 = r1 + 1
                                             "while r1 is less or equal to r0" do r2 = r2*r1"
                       ; go back to "loop"
           loop
       В
done
       MOV r0, r2
                         When r1 is greater than r0, store the result r2 in r0
                                   Return statement.
```

Translate the following code into a C program and explain what it does.

```
int factorial(int r0){
       MOV r2, #1
       MOV r1, #1
                                                          int r1;
                                                          int r2 = 1;
loop
      CMP r1, r0
       BGT done
                                                          for(r1 = 1; r1 <= r0; r1++){
                                                                 r2 = r2*r1;
       MUL r2, r1, r2
       ADD r1, r1, #1
           loop
                                                          return r2;
       MOV r0, r2
done
```

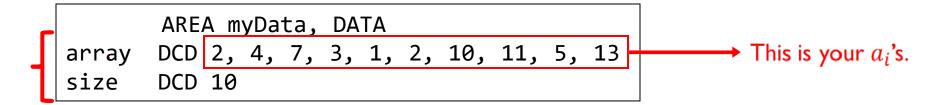
```
AREA myData, DATA

array DCD 2, 4, 7, 3, 1, 2, 10, 11, 5, 13

size DCD 10
```

→ Your code should perform this operation!

The memory addresses of our array can be accessed by using these labels. So, we don't need to know the exactly memory location of the array elements.



```
AREA myData, DATA array DCD 2, 4, 7, 3, 1, 2, 10, 11, 5, 13 size DCD 10
```

The summation indicates to us that we are going to perform some kind of loop.

Accessing an array in assembly can be found in the textbook section 5.4.4, page 105.

(1) Iterate an array by using pre-index

```
LDR r0, =array ; Using LDR pseudo instruction, r0 = array address
LDR r1, [r0] ; r1 = array[0]. After loading, r0 = array
LDR r2, [r0, #4] ; r2 = array[1]. After loading, r0 = array + 4
LDR r3, [r0, #8] ; r3 = array[2]. After loading, r0 = array + 8
LDR r4, [r0, #12] ; r4 = array[3]. After loading, r0 = array + 12
LDR r5, [r0, #16] ; r5 = array[4]. After loading, r0 = array + 16
```

(2) Iterate an array by using post-index

```
LDR r0, =array ; Using LDR pseudo instruction, r0 = array address
LDR r1, [r0], #4 ; r1 = array[0]. After loading, r0 = array + 4
LDR r2, [r0], #4 ; r2 = array[1]. After loading, r0 = array + 8
LDR r3, [r0], #4 ; r3 = array[2]. After loading, r0 = array + 12
LDR r4, [r0], #4 ; r4 = array[3]. After loading, r0 = array + 16
LDR r5, [r0], #4 ; r5 = array[4]. After loading, r0 = array + 20
```

(3) Iterate an array by using pre-index with update

```
LDR r0, =array ; Using LDR pseudo instruction, r0 = array address
LDR r1, [r0] ; r1 = array[0]. After loading, r0 = array
LDR r2, [r0, #4]! ; r2 = array[1]. After loading, r0 = array + 4
LDR r3, [r0, #4]! ; r3 = array[2]. After loading, r0 = array + 8
LDR r4, [r0, #4]! ; r4 = array[3]. After loading, r0 = array + 12
LDR r5, [r0, #4]! ; r5 = array[4]. After loading, r0 = array + 16
```

```
AREA myData, DATA, READWRITE
            ALIGN
            DCD 2, 4, 7, 3, 1, 2, 10, 11, 5, 13
array
size
            AREA myCode, CODE, READONLY
            EXPORT main
            ALIGN
            ENTRY
            PROC
main
            LDR r0, =size
            LDR r1, [r0]
                               ; r1 = 10
            LDR r0, =array
            LDR r2, [r0], #4
                             ; r2 = a_1 --> get the first position of the array
            MOV r3, #1
                                    ; We are going to use r3 as our counter in the loop
            MOV r4, #0
                                    ; The summation will be stored in r4
            CMP r3, r1
                                    ; Loop while r3 is less than r1 (10)
loop
                                    ; If r3 is greater than r1 (10), we're done
            BGT done
                            ; r5 = a i * a i
            MUL r5, r2, r2
                            ; r5 = r5 * a_i --> r5 = a_i*a_i*a_i
            MUL r5, r5, r2
            ADD r4, r5
                                ; Add the cube operation to the summation (r4)
            LDR r2, [r0], #4
                                  ; get the next array element
            ADD r3, #1
                                  ; Increment r3 by 1
            B loop
            ENDP
                                     ; dead loop
done
            B done
            END
```

Solution using ARM
Assembly.
The one from the book.

Only works with the Keil : "
uVision IDE!

**Note:** This IDE is not being used in our labs!

```
.syntax unified
.cpu cortex-m4
.fpu softvfp
.thumb
.section
             .word 2, 4, 7, 3, 1, 2, 10, 11, 5, 13
array:
size:
             .word 10
.section
             .text
.global
             main
main:
        LDR r0, =size
        LDR r1, [r0]
                         // r1 = 10
        LDR r0, =array
        LDR r2, [r0], #4 // r2 = a 1 --> get the first position of the array
                         // We are going to use r3 as our counter in the loop
        MOV r3, #1
        MOV r4, #0
                         // The summation will be stored in r4
loop:
                         // Loop while r3 is less than r1 (10)
       CMP r3, r1
        BGT done
                         // If r3 is greater than r1 (10), we are done
                        // r5 = a i * a i
        MUL r5, r2, r2
       MUL r5, r5, r2
                        // r5 = r5 * a i
                         // Add the cube operation to the summation (r4)
        ADD r4, r5
        LDR r2, [r0], #4 // get the next array element
                         // Increment r3 by 1
        ADD r3, #1
        B loop
done:
        B done
                          // dead loop
```

Solution using GNU Assembly.

The only kind of assembly that works with the System Workbench for STM32 used in our labs!

Look the textbook
Appendix A to learn more
how to translate from one
to another.

-----

# Chapter 7

#### Chapter 7 – Exercise 1

Write an assembly program that converts all characters of a string to upper

case.

# Hint: Use the ASCII table

```
AREA myData, DATA, READWRITE
             ALIGN
             DCB
                          "caPitalizeme",0
array
            AREA myCode, CODE, READONLY
             EXPORT main
             ALIGN
             ENTRY
main PROC
             LDR r0, =array
            LDRB r4, [r0]
                                      ; Load string into memory
loop
                                       ; Compare to see if we have a cap or a lower case
            CMP r4, #97
            BLT next
            SUBS r4, r4, #32
                                       ; Subtract 32 if we have a lower case
            STRB r4, [r0]
                                       ; Store that in the original string
next
            ADD r0, r0, #1
                                      ; Move to next byte
            LDRB r4, [r0]
            CMP r4, #0
                                       ; Look for null terminator
             BNE loop
done
                   done
             ENDP
             END
```

#### Chapter 7 – Exercise 9

Write an assembly program that checks whether an integer is a square of some integer. For example,

 $25 = 5^2$ .

```
; Input Register: R1
   ; If square, then R2 = sqrt(R1)
   ; If not, then R2 = -1;
   AREA prime, CODE, READONLY
    EXPORT main
    ALIGN
   ENTRY
 main PROC
                ; r1 is our input
   MOV R1, #25
   MOV R3, #1
                   ; We will use r3 to perform the square operation
do0ver
   ADD R3, R3, #1; Increment r3
   MUL R4, R3, R3; Perform r4 = r3*r3
                  ; Is r4 >= r1?
   CMP R4, R1
   BEQ isSquare ; If r4 is equal to r1, than we found the square root of r1
   BGT itsNot
                   ; If r4 is greater than r1, than r1 is not a square of an integer
                   ; If r4 is less than r1, increment r3 and try again
    BLT doOver
isSquare
   MOV R2, R3
                   ; If R1 is a square of an integer, put the square root of r1 into r2
                   ; Go to the dead loop
    B done
itsNot
   MOV R2, #0
                  ; If R1 is NOT a square of an integer,
   SUB R2, R2, #1; then make r2 equal to -1
                  ; Dead loop
done
    ENDP
    END
```

#### Homework 5

Write an assembly program that removes all vowel letters (a, e, i, o, u, A, E, I, O, U) from a string.

```
.syntax unified
.cpu cortex-m4
.fpu softvfp
.thumb
.section .data
input_str:
    .ascii "The quick brown fox jumps over the lazy dog\0"
output str:
    .ascii "\0"
.section .text
.global main
main:
    LDR r0, =input_str
                           // r1 is going to be our original string
    LDRB r1, [r0]
    LDR r3, =output_str
                           // r2 is going to be our destination string
    LDRB r2, [r3]
checkIsLetter:
   CMP r1, #0x00
    BEQ almost_done
                           // If r1 is equal to 0x00, this is the end of the string
   CMP r1, #0x41
    BLT nextChar_withCopy
                           // If it is less than 0x41, the char is not a letter
   CMP r1, #0x5B
    BLT capLetter
                           // If it is greater than or equal to 0x41 AND less than 0x5B, the char is a capitalized letter
   CMP r1, #0x61
    BLT nextChar_withCopy // If it is greater than or equal to 0x5B AND less than 0x61, the char is not a letter
   CMP r1, #0x7B
    BLT smallLetter
                           // If it is greater than or equal to 0x61 AND less than 0x7B, the char is a small letter
    BGE nextChar_withCopy // If it is greater than or equal to 0x7B, the char is not a letter
```

\_\_\_\_\_

```
nextChar_withCopy:
    MOV r2, r1
    STRB r2, [r3]
                           // If it is not a vowel, just copy the char to our destination string.
                          // Update the memory address of out destination char.
    ADD r3, r3, #1
nextChar:
    ADD r0, r0, #1
                           // Move to the next char in the string
    LDRB r1, [r0]
    B checkIsLetter
capLetter:
    ADD r1, r1, #32
                           // If the char is a capitalized letter, convert to small letter by adding 32 (decimal)
    B checkIsLetter
smallLetter:
   CMP r1, #0x61
                           // r1 = 'a'
    BEQ isVowel
                           // r1 = 'e'
    CMP r1, #0x65
    BEQ isVowel
                           // r1 = 'i'
    CMP r1, #0x69
    BEQ isVowel
   CMP r1, #0x6F
                           // r1 = 'o'
    BEQ isVowel
                           // r1 = 'u'
    CMP r1, #0x75
    BEQ isVowel
    B notVowel
isVowel:
    B nextChar
notVowel:
    B nextChar_withCopy
almost_done:
    ADD r3, r3, #1
   MOV r2, #0x00
    STRB r2, [r3]
done:
                       // dead loop
    B done
```

.end

# Homework 5 - Chapter 7 - Exercise 7

• Write an assembly program that checks whether an unsigned number is a prime number or not.

# Homework 5 - Chapter 7 - Exercise 7

```
.syntax unified
.cpu cortex-m4
.fpu softvfp
.thumb
.section .text
.global main
main:
   MOV r1, #31
                 // r1 will be used as our input
                   // r2 will be our result.
   MOV r2, #1
                   // At the end of the program:
                            If r2 = 1, then the number IS prime.
                            If r2 = 0, then the number is NOT prime.
   MOV r3, #2
                   // r3 will be used as a counter.
testPrime:
   CMP r3, r1
    BEO done
                   // If r3 = r1, we done with the program.
   UDIV r4, r1, r3 // r4 = r1 / r3 (only the integer part)
                // r4 = r4*r3
   MUL r4, r3
   CMP r4, r1
    BNE notPrimeYet
   MOV r2, #0
                   // The division and multiplication gave us the original number.
                   // Therefore, the number is NOT prime and r2 will be 0,
    B done
                   // and we are done with the program.
notPrimeYet:
   ADD r3, #1
                   // Test another integer to perform the division and multiplication.
    B testPrime
done:
    B done
```

```
.syntax unified
.cpu cortex-m4
.fpu softvfp
.thumb
.data
size:
    .word 10
array:
   .word 10,20,30,40,50,60,70,80,90,100
.text
.global main
main:
   LDR r2, =size
   LDR r2, [r2]
                       // r2 = size of the array
                          // r3 = memory address of the array
   LDR r3, =array
   // 1st) Let's compute the mean
   MOV r7, #0
                        // loop index
                       // summation
   MOV r0, #0
                  // Let's loop over the entire array
   B check mean
loop mean:
   LDR r4, [r3, r7, LSL #2] // r6 = array(i), where r7 = i
   ADD r0, r0, r4 // r0 = r0 + array(i) --> Summation
                           // Update the loop index --> r7 = i + 1
   ADD r7, r7, #1
check mean:
   CMP r7, r2
                           // While i <= array size,</pre>
                           // keep summing the array elements
   BLT loop mean
   // If i > array size, summation is done.
   // Let's divide by the size of the array to obtain the mean.
   UDIV r0, r0, r2
                        // r0 = (r0 / array size) --> mean
   // 2nd) Let's compute the variance
                      // loop index
   MOV r7, #0
   MOV r1, #0
                         // sum of squares
   B check variance
```

```
loop variance:
   LDR r4, [r3, r7, LSL #2] // r6 = array(i), where r7 = i
                   // r5 = array(i) - mean
   SUB r5, r4, r0
                       // r1 = r1 + (array(i) - mean)^2 --> Multiple and accumulate
   MLA r1, r5, r5, r1
                           // Update the loop index --> r7 = i + 1
   ADD r7, r7, #1
check variance:
   CMP r7, r2
                           // While i <= array size,</pre>
                           // keep adding (array(i) - mean)^2
    BLT loop variance
   // If i > array size, summation is done.
   // Let's divide by the size of the array to obtain the variance.
   UDIV r0, r1, r2 // r0 --> Variance
stop:
                          // Dead Loop
        stop
.end
```

-----

Homework 6 (variations)

- "PUSH {r3}" is equivalent to what?
  - ▶ Cortex-M processors uses *full descending* stack.
  - It means, r3 will be pushed in the memory position indicated by the stack pointer, and the stack pointer will be decreased by 4.

▶ How many byte does the stack need to pass the arguments when each of the following function is called?

```
int32_t fun1(uint8_t a, uint16_t b, uint8_t c, int32_t d)
```

- ▶ Hint: Page 169
- ▶ In this case, we don't need to use the stack to pass the arguments:

```
a \rightarrow r0
```

b -> r1

 $c \rightarrow r2$ 

 $d \rightarrow r3$ 

- ▶ Which register(s) holds the return value in the following functions?
  - int16\_t fun1()
  - ▶ Hint: Page 169
  - ▶ The return only needs 16 bits. So, we only need r0 to hold the return argument.

Note: some functions in this question return a pointer to a memory address.

# Homework 6 - Chapter 8 – Exercise 17-ish

```
.fpu softvfp
.thumb
                                           GNU Assembly
.data
result:
    .word 0
constants:
   .word 2, 5
.text
.global main
.func computeFunction
main:
   MOV r0, #2 // 1st argument --> x
   MOV r1, #3 // 2nd argument --> y
   BL computeFunction
   // Let's put the result in the memory
   LDR r1, =result
   STR r0, [r1]
stop:
                         // Dead Loop
        stop
computeFunction:
   LDR r2, =constants
   LDR r3, [r2] // r3 = b --> b = 2
   LDR r4, [r2, #4] // r4 = c --> c = 5
   // f(x, y) = b*x*y + c
   MUL r5, r0, r1
                    // r5 = x*y
                    // r5 = b*r5
   MUL r5, r5, r3
   ADD r5, r5, r4
                      // r4 = r5 + c
   MOV r0, r5
                      // return value is stored in r0
   BX LR
.endfunc
.end
```

.syntax unified
.cpu cortex-m4

```
AREA myData, DATA, READWRITE
    ALIGN
result
           DCD 0
constants DCD 2, 5
   AREA myCode, CODE, READONLY
   EXPORT main
    ALIGN
ENTRY
main PROC
   MOV r0, #2; 1st argument --> x
   MOV r1, #3; 2nd argument --> y
    BL computeFunction
    ; Let's put the result in the memory
   LDR r1, =result
   STR r0, [r1]
stop
                     ; Dead Loop
        stop
    ENDP
computeFunction PROC
   LDR r2, =constants
                      ; r3 = b \longrightarrow b = 2
    LDR r3, [r2]
    LDR r4, [r2, #4]
                      ; r4 = c --> c = 5
    ; f(x, y) = b*x*y + c
   MUL r5, r0, r1 ; r5 = x*y
   MUL r5, r5, r3 ; r5 = b*r5
   ADD r5, r5, r4
                      ; r4 = r5 + c
                       ; return value is stored in r0
   MOV r0, r5
    BX LR
    ENDP
    END
```

ARM Assembly