

Fei MENG

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Education

- **Ph.D. Student, The Chinese University of Hong Kong** 08/2020 – Present
Supervisor: Prof. Max Qinghu MENG, Dept. of Electronic Engineering
- **M.Eng., Harbin Institute of Technology** 09/2017 – 07/2019
Supervisor: Prof. Guangfu MA, Dept. of Control Science and Engineering, School of Astronautics
- **B.Eng., Harbin Institute of Technology** 08/2012 – 07/2016
Dept. of Electrical Engineering and Automation, School of Information & Electrical Engineering

Research Interest

Robot Safety, Learning-based Methods, Motion Planning, Data-Driven Control

Publications

- **Learning-based Risk-Bounded Path Planning Under Environmental Uncertainty**
F. MENG, L. CHEN, H. MA, J. WANG*, Max Q.-H. MENG*
IEEE Transactions on Automation Science and Engineering, 2023
- **Relevant Region Sampling Strategy with Adaptive Heuristic for Asymptotically Optimal Path Planning**
C. LI, F. MENG, H. MA, J. WANG*, Max Q.-H. MENG*
Biomimetic Intelligence and Robotics, 2023
- **NR-RRT: Neural Risk-Aware Near-Optimal Path Planning in Uncertain Nonconvex Environments**
F. MENG, L. CHEN, H. MA, J. WANG*, Max Q.-H. MENG*
IEEE Transactions on Automation Science and Engineering, 2022
- **Bi-Risk-RRT Based Efficient Motion Planning for Mobile Robots**
H. MA, F. MENG, J. WANG*, Max Q.-H. MENG*
IEEE Transactions on Intelligent Vehicles, 2022
- **Hierarchical Policy for Non-prehensile Multi-object Rearrangement with Deep Reinforcement Learning and Monte Carlo Tree Search**
F. BAI, F. MENG, J. LIU, J. WANG, Max Q.-H. MENG*
Biomimetic Intelligence and Robotics, 2022
- **Fast Human-in-the-loop Control for HVAC Systems via Meta-learning and Model-based Offline Reinforcement Learning**
L. CHEN, F. MENG, Y. ZHANG*
IEEE Transactions on Sustainable Computing, 2023
- **An HVAC Control Approach via Combining Model-based Deep Reinforcement Learning and Model Predictive Control**
L. CHEN, F. MENG, Y. ZHANG*
IEEE Internet of Things Journal, 2022
- **A Survey of Learning-based Robot Motion Planning**
J. WANG, T. ZHANG, N. MA, H. MA, F. MENG, Max Q.-H. MENG*
IET Cyber-Systems and Robotics, 2021 (The IET Premium Awards)
- **Reciprocally Rotating Magnetic Actuation and Automatic Trajectory Following for Wireless Capsule Endoscopy**
Y. XU, K. LI, Z. ZHAO, F. MENG, Max Q.-H. MENG*
2021 IEEE International Conference on Robotics and Automation (ICRA)
- **A Nonuniform Sampling Strategy for Path Planning Using Heuristic-based Certificate Set**
H. MA, J. LIU, F. MENG, J. PAN, J. WANG*, Max Q.-H. MENG*
2021 IEEE International Conference on Robotics and Biomimetics (ROBIO)
- **A Model-free Adaptive Controller for Biomimetic Pneumatically Actuated Continuum Manipulators**
F. MENG, Y. Lyu, G. MA, Y. ZHU

Work Experience

- Junior Research Assistant, RPAI Lab, The Chinese University of Hong Kong, HK 07/2019 – 07/2020
Supervisor: Prof. Max Qinghu MENG

Research Experience

- Member Midstream Research Programme for University from ITC of HK SAR 07/2019 – 12/2021
Development of a Robotic Rollator-orthosis System for Mobility Augmentation and Eldercare
- Member Crosswise Task from China Academy of Space Technology 09/2017 – 07/2019
Design & Implementation of Control System for Pneumatically Actuated Continuum Manipulator

Honors & Awards

- Outstanding Student of Heilongjiang Province, China (top 1%) 2018 – 2019
Highest award for students in Heilongjiang Province
- China Electronics Technology Group Corporation Glarun Scholarship (2/1223) 2018 – 2019
Scholarship for only one Ph.D. student out of all postgraduates of School of Astronautics
- Outstanding Graduates of Harbin Institute of Technology (top 10%) 2018 – 2019
Award for graduates with overall outstanding performance
- First-class Academic Postgraduate Students Scholarship of Harbin Institute of Technology 2018 – 2019
Scholarship for postgraduates with distinguished academic performance
- Outstanding Student of Harbin Institute of Technology (top 4%) 2017 – 2018
Award for students with overall outstanding performance
- Top Ten Student Leaders of Harbin Institute of Technology 2014 – 2015
Highest Award for all undergraduate student leaders of HIT
- Second Prize – Provincial Robot Competition 2013 – 2014
Award for winners on bipedal-robot racing
- Second Prize –National "Freescale Cup" Intelligent Car Race for Undergraduates 2012 – 2013
Award for winners on two-wheeled upright robotic vehicle racing

Academic Service

- Journal Reviewer
IEEE Robotics and Automation Letters, IEEE Transactions on Industrial Informatics, IEEE Internet of Things Journal, IEEE Transactions on Automation Science and Engineering, IEEE Transactions on Systems, Man, and Cybernetics: Systems.
- Conference Reviewer IEEE International Conference on Robotics and Automation, IEEE International Conference on Robotics and Biomimetics, IEEE International Conference on Information and Automation.
- Conference Chair
- Session chair of IEEE International Conference on Robotics and Automation, 2021
- Teaching Assistant
Introduction to Electric Power Systems (ELEG3601) for Undergraduates, Spring 2021 CUHK. Fundamentals of Electric Circuits (ELEG2202A) for Undergraduates, Fall 2020/21/22, CUHK.

Skills

- **Programming skills:** C/C++, Python, MATLAB/Simulink, Maple, Julia, R. **Robotic Software:** ROS, Gazebo, MoveIt, Vrep, Pybullet. **Languages:** Mandarin (Native), English (Fluent). **Sports:** Basketball, Badminton.