

Xiaohan Fei

	UCLA VisionLab, Engineering VI #386 University of California, Los Angeles Los Angeles, CA 90095, USA	Phone: (310) 890-8064 E-mail: feixh@cs.ucla.edu Website: http://feixh.github.io
EDUCATION	UNIVERSITY OF CALIFORNIA, LOS ANGELES Ph.D. in Computer Science Supervisor: Prof. Stefano Soatto Research Group: UCLA Vision Lab (http://vision.ucla.edu) GPA: 3.88/4.0	Fall 2014-present
	ZHEJIANG UNIVERSITY B.Eng. in Information and Communication Engineering Major: Information and Communication Engineering Minor: Advanced honor Class of Engineering Education (ACEE), Chu-Kechen College GPA: 3.98/4.0(92.35/100) Title of Undergraduate Thesis: Wide-baseline feature matching for panoramic images Undergraduate Thesis Supervisor: Prof. Zhiyu Xiang	Fall 2010-Spring 2014
RESEARCH EXPERIENCE	NVIDIA RESEARCH, SANTA CLARA, CALIFORNIA Research Intern Worked on unsupervised learning of structural representation for 3D objects.	Summer 2018
	META COMPANY, SAN MATEO, CALIFORNIA Research Intern Developed a tightly-coupled visual-inertial SLAM algorithm for Augmented Reality.	Summer 2017
	UNIVERSITY OF CALIFORNIA, LOS ANGELES Graduate Student Researcher Conducting research activities under the supervision of Prof. S. Soatto. Main projects include: image based re-localization, visual-inertial sensor fusion and object-level (semantic) mapping.	Fall 2014-present
AWARDS & DISTINCTIONS	2013: Meritorious Winner of Mathematical Contest in Modeling (top 15% of 6000 teams worldwide) 2012: National Scholarship (highest honor for undergraduates in China)	
PUBLICATIONS	[1] X. Fei, A. Wong, and S. Soatto. Geo-Supervised Visual Depth Prediction. Under review. [2] X. Fei, S. Soatto. Visual-Inertial Object Detection and Mapping. ECCV, 2018. [3] J. Dong*, X. Fei*, and S. Soatto. Visual-Inertial-Semantic Scene Representation for Object Detection. CVPR, 2017. [4] X. Fei, K. Tsotsos, and S. Soatto. A Simple Hierarchical Pooling Data Structure for Loop Closure. ECCV, 2016.	
PROFESSIONAL SERVICES	Reviewer of ICCV 2017. International Journal of Medical Robotics and Computer Assisted Surgery (IJMRCAS).	
TALKS & WORKSHOPS	Visual-Inertial-Semantic Scene Representation, Bridges to 3D Workshop, CVPR 2017.	
TEACHING	CS M152A Introductory Digital Design Laboratory, Spring 2018.	
RELEVANT COURSEWORK	University of California, Los Angeles: Machine Perception (Prof. S. Soatto), Convex Optimization (Prof. L. Vandenberghe), Calculus of Variations (Prof. L. Vese), Vision as Bayesian Inference (Prof. A. Yuille), Applied Probability (Prof. Y. Wu), Theoretical Statistics (Prof. A. Amini), Numerical Analysis (Prof. J. Teran), Machine Learning Algorithm (Prof. M. Sarrafzadeh) Zhejiang University: Computer Vision (Prof. Z. Xiang), Spectral Analysis of Signals (Prof. X. Gong), Information Theory (Prof. Z. Zhang), Mathematical Modeling (Prof. Q. Yang)	
RELEVANT SKILLS	Programming Language: C/C++, Python, MATLAB, GLSL, Android Software Framework: ROS, OpenCV, TensorFlow	