

Xiaohan Fei

UCLA VisionLab, Engineering VI #386	Phone: (310) 890-8064
University of California, Los Angeles	E-mail: feixh@cs.ucla.edu
Los Angeles, CA 90095, USA	Website: http://feixh.github.io

EDUCATION	UNIVERSITY OF CALIFORNIA, LOS ANGELES Ph.D. in Computer Science Supervisor: Prof. Stefano Soatto Research Group: UCLA Vision Lab (http://vision.ucla.edu) GPA: 3.88/4.0 ZHEJIANG UNIVERSITY B.Eng. in Information and Communication Engineering Major: Information and Communication Engineering Minor: Advanced honor Class of Engineering Education (ACEE), Chu-Kechen College GPA: 3.98/4.0(92.35/100) Title of Undergraduate Thesis: Wide-baseline feature matching for panoramic images Undergraduate Thesis Supervisor: Prof. Zhiyu Xiang	Fall 2014-present Fall 2010-Spring 2014
RESEARCH EXPERIENCE	NVIDIA RESEARCH, SANTA CLARA, CALIFORNIA Research Intern Worked on unsupervised learning of structural representation for 3D objects. META COMPANY, SAN MATEO, CALIFORNIA Research Intern Developed a tightly-coupled visual-inertial SLAM algorithm for Augmented Reality. UNIVERSITY OF CALIFORNIA, LOS ANGELES Graduate Student Researcher Conducting research activities under the supervision of Prof. S. Soatto. Main projects include: image based re-localization, visual-inertial sensor fusion and object-level (semantic) mapping.	Summer 2018 Summer 2017
AWARDS & DISTINCTIONS	2013: Meritorious Winner of Mathematical Contest in Modeling (top 15% of 6000 teams worldwide) 2012: National Scholarship (highest honor for undergraduates in China)	
PUBLICATIONS	[1] X. Fei, A. Wong, and S. Soatto. Geo-Supervised Visual Depth Prediction. Under review. [2] X. Fei, S. Soatto. Visual-Inertial Object Detection and Mapping. ECCV, 2018. [3] J. Dong*, X. Fei*, and S. Soatto. Visual-Inertial-Semantic Scene Representation for Object Detection. CVPR, 2017. [4] X. Fei, K. Tsotsos, and S. Soatto. A Simple Hierarchical Pooling Data Structure for Loop Closure. ECCV, 2016.	
PROFESSIONAL SERVICES	Reviewer of ICCV 2017, International Journal of Medical Robotics and Computer Assisted Surgery (IJMRCAS).	
TALKS & WORKSHOPS	Visual-Inertial-Semantic Scene Representation, Bridges to 3D Workshop, CVPR 2017	
TEACHING	Spring 2018, CS M152A Introductory Digital Design Laboratory	
RELEVANT COURSEWORK	University of California, Los Angeles: Machine Perception (Prof. S. Soatto), Convex Optimization (Prof. L. Vandenberghe), Calculus of Variations (Prof. L. Vese), Vision as Bayesian Inference (Prof. A. Yuille), Applied Probability (Prof. Y. Wu), Theoretical Statistics (Prof. A. Amini), Numerical Analysis (Prof. J. Teran), Machine Learning Algorithm (Prof. M. Sarrafzadeh) Zhejiang University: Computer Vision (Prof. Z. Xiang), Spectral Analysis of Signals (Prof. X. Gong), Information Theory (Prof. Z. Zhang), Mathematical Modeling (Prof. Q. Yang)	
RELEVANT SKILLS	Programming Language: C/C++, Python, MATLAB, GLSL, Android Software Frameworks: ROS, OpenCV, TensorFlow	