

6

5

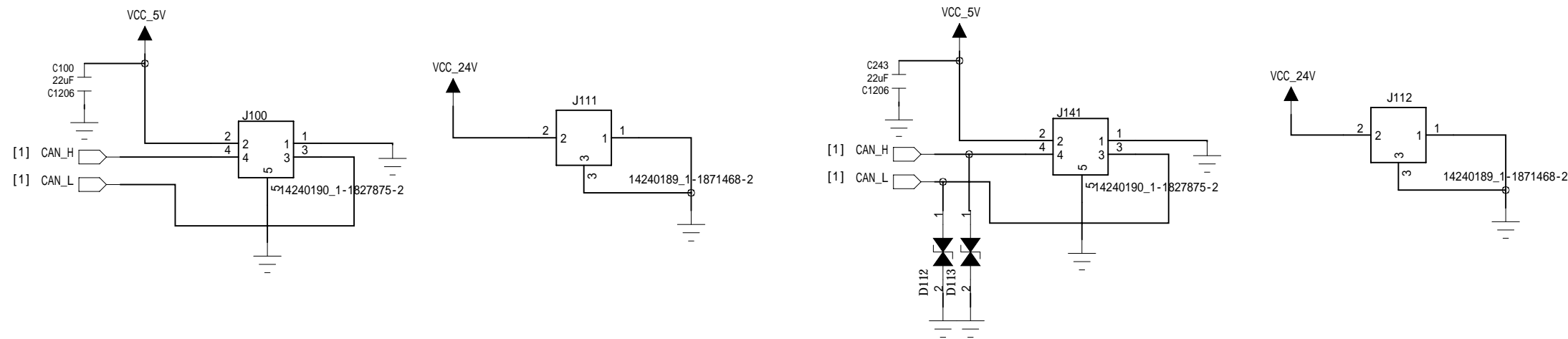
4

3

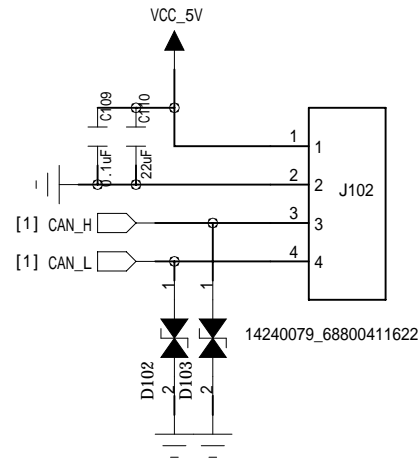
2

1

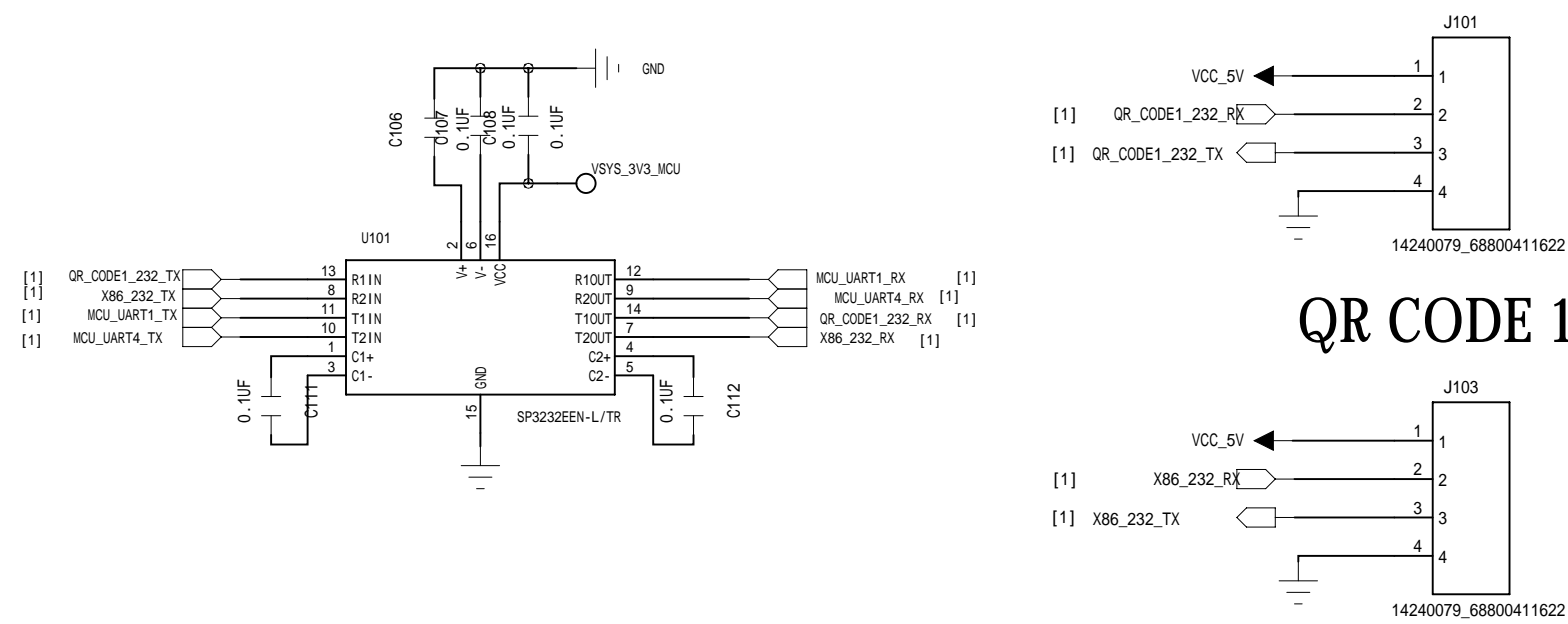
REVISION RECORD			
LTR	ECO NO:	APPROVED:	DATE:



POWER IN



3.3V



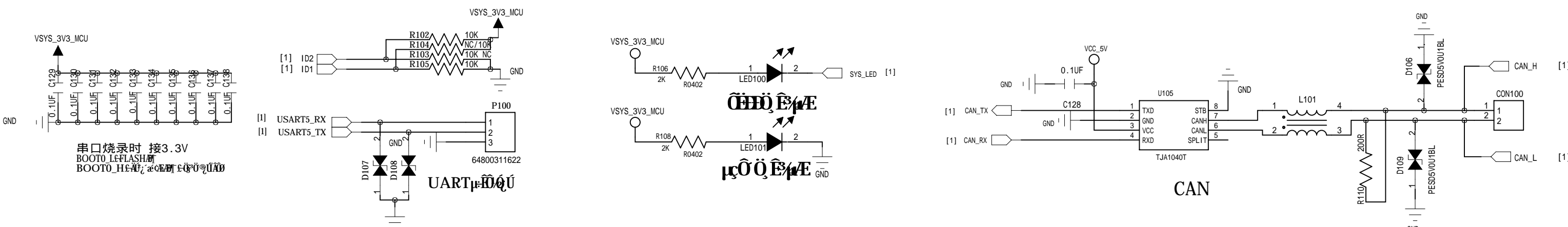
QR CODE 1

QR CODE 2

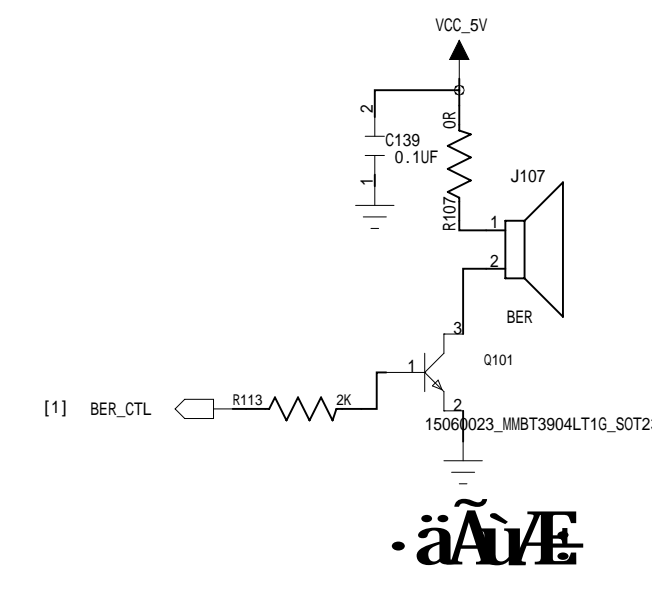
POWER: 5V*3.3V

POWER: 24V*16V

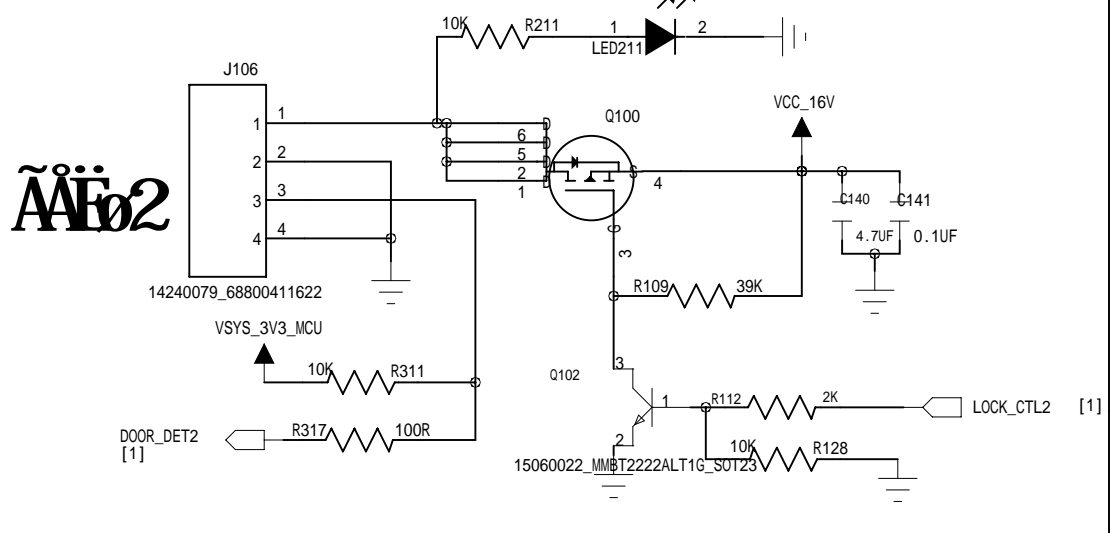
16V



CAN



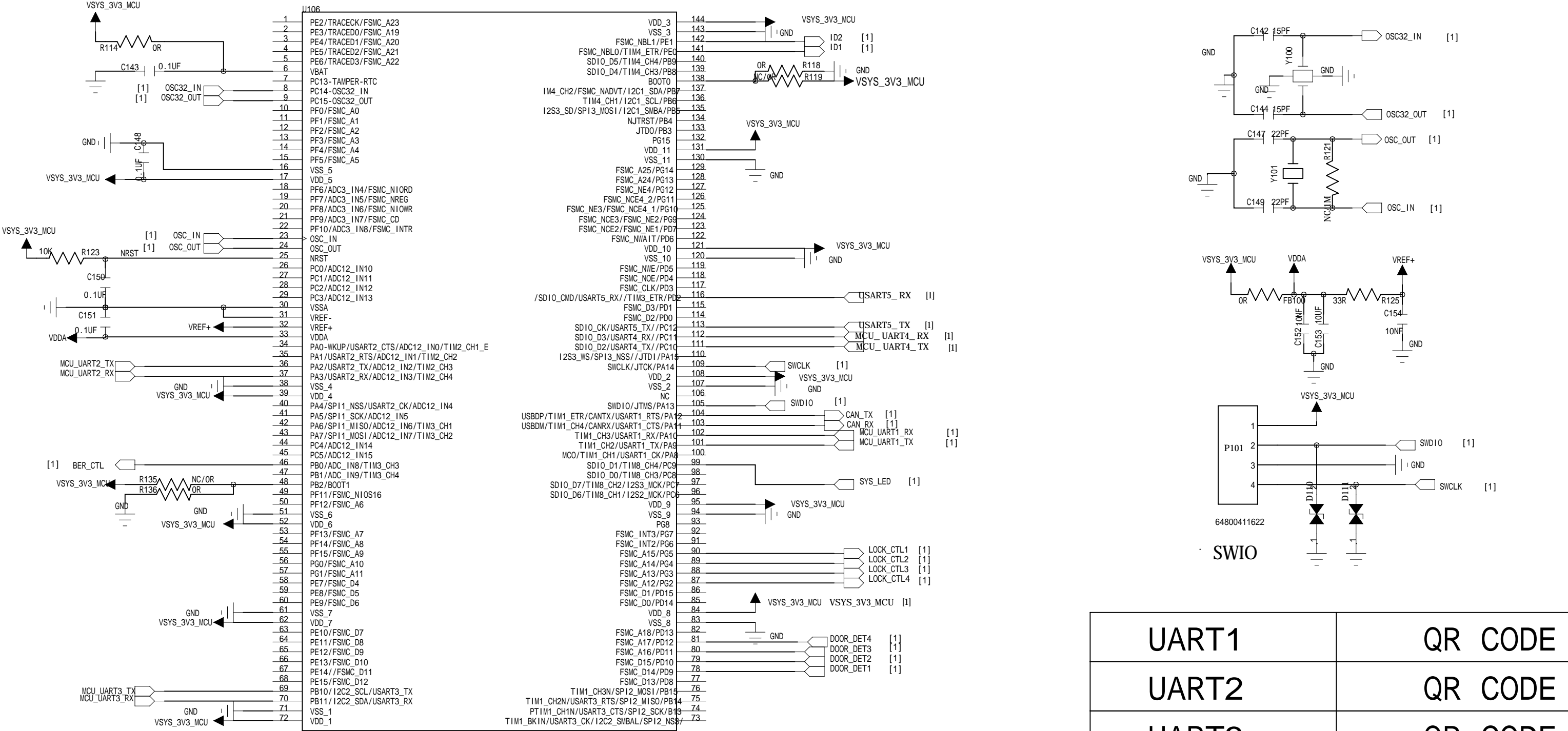
5V



3

4

4



SWIO

1

2

3

4

1

2

3

4

3

4

4

UART1	QR CODE 1
UART2	QR CODE 2
UART3	QR CODE 3
UART4	X86
UART5	DEBUG

MCU

CONNECTOR

DRAWN:	<Drawn By>	DATED:	<Drawn Date>
CHECKED:	<Checked By>	DATED:	<Checked Date>
QUALITY CONTROL:	<QC By>	DATED:	<QC Date>
RELEASED:	<Released By>	DATED:	<Release Date>

COMPANY: Mrobot			
TITLE: Noah_Door_Mcu_V0.1			
CODE: <Code>	SIZE: D	DRAWING NO:	REV:
SHEET: 1 of 2			

6

5

4

3

2

1

REVISION RECORD			
LTR	ECO NO:	APPROVED:	DATE:

D

D

C

C

B

B

A

A

		COMPANY:				Mrobot			
		TITLE:							
		Noah_Door_Mcu_V0.1							
DRAWN:	DATED:	CODE:		SIZE:	DRAWING NO.:			REV:	
<Drawn By>	<Drawn Date>	<Code>		D	V3.0			v3.0	
CHECKED:	DATED:	<Code>		D	V3.0			v3.0	
<Checked By>	<Checked Date>								
QUALITY CONTROL:	DATED:	<Code>		D	V3.0			v3.0	
<QC By>	<QC Date>								
RELEASED:	DATED:	SCALE: <Scale>			SHEET: 2 OF 2				
<Released By>	<Release Date>								