

COMPOSITE ESTIMATION: AN ASYMPTOTICALLY WEIGHTED LEAST SQUARES APPROACH

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Abstract: The purpose of this study is three-fold. First, based on an asymptotic presentation of initial estimators and model-independent parameters, either hidden in the model or combined with the initial estimators, a pro forma linear regression between the initial estimators and the parameters is defined in an asymptotic sense. Then, a weighted least squares estimation is constructed within this framework. Second, systematic studies are conducted to examine when both the variance and the bias can be reduced simultaneously, and when only the variance can be reduced. Third, a generic rule for constructing a composite estimation and unified theoretical properties is introduced. Important examples, such as a quantile regression, nonparametric kernel estimation, and blockwise empirical likelihood estimation, are investigated to explain the methodology and theory. Simulations are conducted to examine the performance of the proposed method in finite sample situations and a real-data set is analyzed as an illustration. Lastly, the proposed method is compared to existing competitors.

Key words and phrases: Asymptotic representation, composite quantile regression, model-independent parameter, nonparametric regression, weighted least squares.

1. Introduction

1.1. Motivation and existing methodologies

The enhancement of the efficiency of point estimations in various models is an important issue. Recently, composition methodologies have received much attention in the literature. The main goal of these methodologies is to reduce the estimation variance. Zou and Yuan (2008) proposed a composite quantile linear regression to reduce asymptotic variance. Kai, Li and Zou (2010) extended this regression to construct a variance-reduced nonparametric regression estimation. For further developments of this methodology in semiparametric settings, see Kai, Li and Zou (2011). To achieve both variance reduction and robustness, Bradic, Fan and Wang (2011) introduced a penalized composite quasi-likelihood for ultra-

high-dimensional variable selection by combining several convex loss functions, and a weighted L_1 -penalty. Because the common purpose of these methodologies is to reduce the estimation variance, we call them *variance-reduction methodologies*.

Two common approaches used to construct a composite estimator are the following. The first directly defines a weighted sum of initial estimators as a composite estimator:

$$\tilde{\theta} = \sum_{k=1}^m w_k \hat{\theta}_k, \quad (1.1)$$

if a set of initial estimators $\hat{\theta}_k$ of the parameter of interest θ can be defined. We call this a *the direct composition*. Estimation efficiency is achieved by properly selecting the weights using a criterion such as minimizing the estimation variance; see, for example, Koenker (1984) and Kai, Li and Zou (2010). More generally, minimizing a user-chosen risk, such as the mean squared error, can be adopted for this purpose; see, Lavancier and Rochet (2016), and the references therein. A similar methodology, called an *aggregation estimation*, mimics the estimation that uses *weighted averages*. The resulting composite estimator is approximately at least as good as the best linear or convex combination of initial estimators; see, for instance, Juditsky and Nemirovski (2000) and Rigollet and Tsybakov (2007), and the references therein.

Note that when the risk is chosen as the mean squared error, the corresponding methodology can reduce the estimation bias or the estimation variance, or both, in a balanced manner. However, when the biases of the initial estimators are of the same magnitude, this methodology often fails to reduce the bias, unless the weights are chosen to be negative (see Rigollet and Tsybakov (2007)) or strong constraints are imposed on the initial estimators (see Sun, Gai and Lin (2013)).

The second method defines a composite estimator by minimizing a weighted sum of objective functions. This estimator is expressed as

$$\tilde{\theta} = \arg \min_{\theta \in \Theta} \sum_{k=1}^m w_k g_k(Z, \theta), \quad (1.2)$$

provided that the predetermined objective functions $g_k(Z, \theta)$, $k = 1, \dots, m$, contain the same parameter θ . We call this an *the objective function composition*. For example, Zou and Yuan (2008) suggested this method for linear quantile regressions. In their method, objective functions g_k are related to different quantiles τ_k , but the parameter of interest θ is free of τ_k . Compared with the estimator

of θ obtained using a single quantile τ , the composite estimator can reduce the estimation variance when the weights w_k are properly selected. However, this method cannot be extended to handle many other problems. For example, in a nonparametric quantile regression, we can not obtain a weighted sum of the objective functions in (1.2) such that the parameter of interest is free of the quantiles τ . Here, for different α_k (the $100\tau_k\%$ quantile of the model error), the parameters in the objective functions $g_k(Z, \theta_k)$ are $\theta_k = r(x) + \alpha_k$. Although we want to estimate the nonparametric regression function $r(x)$, it is not easy to separate $r(x)$ and α_k (see Kai, Li and Zou (2010)). Sun, Gai and Lin (2013) showed that the weights in the above composition asymptotically play no role in enhancing the estimation efficiency, and the bias cannot be reduced to have a faster convergence rate to zero.

1.2. The contributions of the proposed method

To explore the proposed methodology, we observe a common feature in several cases. That is, a model-independent parameter, say τ , plays a crucial role in the procedure used to construct a set of initial estimators. This parameter is not of interest in terms of the estimation. However, using different values τ_k of the parameter τ , we can define several initial estimators $\hat{\theta}_{\tau_k}$ for the parameter of interest θ . Then, the first question we need to answer is how to find a model-independent parameter for this purpose. In some scenarios, it is hidden in the model, such as the quantile in a quantile regression. However, in other scenarios, particularly in semiparametric and nonparametric setups, such a parameter does not exist in the model; however, it can be identified from the estimation procedure. Examples of this include the following: the quantile in parametric and nonparametric quantile regression estimators (Zou and Yuan (2008); Kai, Li and Zou (2010)); the bandwidth in the Nadaraya-Watson kernel estimator (N-W estimator) and the local linear estimator in a nonparametric regression (Fan and Gijbels (1996)); and the size of the block in a blockwise likelihood (Kitamura (1997); Lin and Zhang (2001)). For more details, see the examples given in Section 3.

In this study, we establish a unified relationship between the estimation and the model-independent parameter under a generic framework. To do so, we use the asymptotic representation of the initial estimator. Specifically, we use (or define) the model-independent parameter and the corresponding initial estimators to build a pro forma linear regression model.

Then, we construct a composite weighted least squares estimator using the

linear regression model. We call this *the asymptotically weighted least squares* (AWLS) method, and the resultant estimation *the AWLS estimation*. The details are presented in Sections 2 and 3.

This method has several desirable features:

1. (*Generality*) The AWLS estimation can be constructed as long as the estimator has an asymptotically linear representation with a known function of the model-independent parameter.
2. (*Variance reduction*) By selecting proper weights, the AWLS estimation can be asymptotically more efficient than those obtained by existing composite methods, such as the composite maximum likelihood and the composite least squares methods.
3. (*Bias reduction*) The AWLS method can, in some cases, reduce the estimation bias in order to accelerate the convergence rate. A nonparametric estimation is an example.
4. (*Generic rule*) More importantly, the results explain how the composition depends on the structure of the asymptotic representation. This has not yet been explored in the literature. From the construction, we can identify those cases in which the AWLS method reduces both the bias and the variance and when it reduces the variance only.

The remainder of this paper is organized as follows. In Section 2, a unified framework for the AWLS method is introduced, and a generic rule for the method and its theoretical properties are investigated. In Section 3, two typical models, the linear quantile regression and nonparametric regression, are used as examples to illustrate the model described in the previous section. The blockwise empirical likelihood is also briefly discussed. Numerical studies, including a simulation study and a real data analysis, are given in Section 4. The proofs of the theorems are provided in the Supplementary Material.

2. A Generic Framework for the AWLS Method

In this section, we first introduce a generic framework for the construction of the AWLS estimation, and then investigate its theoretical properties in different scenarios. Examples are provided in the next section.

2.1. Models and estimations

Given m values $\tau_k, k = 1, \dots, m$, of a model-independent parameter τ , the

m initial estimators $\hat{\theta}_{\tau_k}$ of the parameter of interest θ depend on τ_k , respectively, and have the following asymptotic representation:

$$\hat{\theta}_{\tau_k} = \theta + b_n \xi_n(\tau_k) + \epsilon_n(\tau_k), \quad k = 1, \dots, m. \quad (2.1)$$

Here, n is the sample size, the random variable $\xi_n(\tau)$ is a known function of τ satisfying $\xi_n(\tau) = O_p(1)$, and b_n is independent of τ and is an infinitesimal of lower order than the order of $\epsilon_n(\tau)$, in probability. The convergence rate of $\hat{\theta}_{\tau_k} - \theta$ is then $O_p(b_n)$ for all $k = 1, \dots, m$. The framework in (2.1) sets a pro forma linear model with response variables $\hat{\theta}_{\tau_k}$, covariates τ_k (or $\xi_n(\tau_k)$), intercept θ , and model error $\epsilon_n(\tau_k)$. Here, the intercept θ is the parameter of interest.

This formula has four possible combinations: b_n is either known or unknown, and $\xi_n(\tau)$ is either free of θ or dependent on θ . When the artificial covariate ξ_n in (2.1) is related to θ , we write it as $\xi_n = \xi_n(\tau, \theta)$, for clarity. An initial estimator $\hat{\theta}$ is then required to replace θ . In this case, denote $\hat{\xi}_n(\tau) = \xi_n(\tau, \hat{\theta})$. We find that these combinations lead to different asymptotic properties for the corresponding AWLS estimator. In the following, we separately consider the two cases when b_n is known or unknown because the corresponding AWLS estimators have different expressions. However, for ξ_n , we only give the estimators when ξ_n depends on θ . When ξ_n is free of θ , the AWLS estimators have the same forms if $\hat{\xi}_n$ is replaced by ξ_n .

Case 1. (b_n is unknown). An AWLS estimator $\tilde{\theta}$ of θ can be constructed as the first component of the following minimizers:

$$\begin{pmatrix} \tilde{\theta} \\ \tilde{b}_n \end{pmatrix} = \arg \min_{\theta, b_n} \frac{1}{m} \sum_{k=1}^m w_k (\hat{\theta}_{\tau_k} - \theta - b_n \hat{\xi}_n(\tau_k))^2, \quad (2.2)$$

where $w_k, k = 1, \dots, m$, are weights satisfying $\sum_{k=1}^m w_k = 1$. The estimator has the following closed form:

$$\tilde{\theta} = \sum_{k=1}^m w_k \hat{\theta}_{\tau_k} - \hat{b}_n \bar{\xi}_n, \quad (2.3)$$

where $\bar{\xi}_n = \sum_{k=1}^m w_k \hat{\xi}_n(\tau_k)$ and $\hat{b}_n = \left(\sum_{k=1}^m w_k \hat{\theta}_{\tau_k} \left(\hat{\xi}_n(\tau_k) - \bar{\xi}_n \right) \right) / \left(\sum_{k=1}^m w_k \left(\hat{\xi}_n(\tau_k) - \bar{\xi}_n \right)^2 \right)$.

Case 2. (b_n is known). By the weighted least squares, the AWLS estimator can be expressed as

$$\tilde{\theta} = \sum_{k=1}^m w_k \left(\hat{\theta}_{\tau_k} - b_n \hat{\xi}_n(\tau_k) \right), \quad (2.4)$$

where $w_k, k = 1, \dots, m$, are weights satisfying $\sum_{k=1}^m w_k = 1$.

2.2. Properties

We now investigate the asymptotic properties of the AWLS estimators defined in (2.3) and (2.4).

2.2.1. Convergence rate

First, consider the case where $\xi_n(\tau)$ is free of θ . We define the regenerated weights as

$$\tilde{w}_k = w_k - \bar{\xi}_n \frac{w_k(\xi_n(\tau_k) - \bar{\xi}_n)}{\sum_{k=1}^m w_k(\xi_n(\tau_k) - \bar{\xi}_n)^2}, \quad k = 1, \dots, m. \quad (2.5)$$

These are free of the initial estimators and still satisfy $\sum_{k=1}^m \tilde{w}_k = 1$, but are not necessarily positive. This yields the following theorem.

Theorem 1. *When $\xi_n(\tau)$ is free of θ , the AWLS estimators $\tilde{\theta}$ defined in (2.3) and (2.4) satisfy*

$$\tilde{\theta} - \theta = \sum_{k=1}^m \tilde{w}_k \epsilon_n(\tau_k),$$

where $\epsilon_n(\tau_k)$ are the error terms in the asymptotic representation defined in (2.1).

Remark 1. The theorem yields an important conclusion: when ξ_n is free of the parameter of interest, the convergence rate of the AWLS estimator can be accelerated. More precisely, $\tilde{\theta} - \theta$ has the same convergence rate as that of the error term $\epsilon_n(\tau)$.

Now, consider the case where $\xi_n(\tau)$ depends on θ . We need the following condition:

- (C1) There are constants $c_1 > 0$ and $c_2 > 0$, such that when n is sufficiently large, $c_1 \leq |b_n \xi'_n(\tau, \theta)| \leq c_2$ and $|b_n \xi''_n(\tau, \theta)| \leq c_2$, in probability, where $\xi'_n(\tau, \theta)$ and $\xi''_n(\tau, \theta)$ are, respectively, the first- and second-order partial derivatives of $\xi_n(\tau, \theta)$ with respect to θ .

Condition (C1) is usually mild. For example, when the asymptotic representation (2.1) is obtained using the Bahadur representation or the asymptotic linear estimation (van der Vaart (1998) and Bickel et al. (1998)), this condition holds under some regularity conditions.

Theorem 2. *When $\xi_n(\tau)$ depends on θ and condition (C1) holds, then the AWLS estimators $\tilde{\theta}$ in (2.3) and (2.4) have the same convergence rate, in probability, as that of the initial estimator $\hat{\theta}_\tau$.*

Remark 2. Theorem 1, Theorem 2, and Theorem 3 show that the asymptotic representation can determine whether an AWLS estimator can reduce both the bias and the variance. Here, we choose the representation in which ξ_n is free of the parameter of interest, if possible.

2.2.2. Variance reduction

Now, we consider the variance reduction issue. When $\xi_n(\tau)$ is free of θ , Theorem 1 shows that the AWLS estimator has a faster convergence rate than the initial estimator and, thus, reduces the variance, asymptotically. Consider the case when $\xi_n(\tau)$ depends on θ . The following condition is assumed:

(C2) There is a function $g(\tau)$, such that $g(\tau) \neq 0$ and $b_n \xi'_n(\tau) = g(\tau) + O_p(b_n)$.

From model (2.1) we can see that this condition is mild as well. In a parametric situation, for instance, $b_n = 1/\sqrt{n}$ and $g(\tau)$ is the expectation of $b_n \xi'_n(\tau)$.

Let $\mathbf{w}_g = (w_1 g(\tau_1), \dots, w_m g(\tau_m))^T$ and $\mathbf{1}$ be an m -dimensional column vector with all components equal to one. We have the following theorem.

Theorem 3. If $\xi_n(\tau)$ depends on θ and (C1) and (C2) hold, then the AWLS estimators $\tilde{\theta}$ defined in (2.3) and (2.4) satisfy

$$\tilde{\theta} = - \sum_{k=1}^m w_k g(\tau_k) (\hat{\theta}_{\tau_k} - \theta) + b_n O_p(\hat{\theta}_{\tau_k} - \theta) + o_p(\hat{\theta}_{\tau_k} - \theta) + \epsilon_n(\tau_k),$$

where $b_n O_p(\hat{\theta}_{\tau_k} - \theta) + o_p(\hat{\theta}_{\tau_k} - \theta) + \epsilon_n(\tau_k)$ is an infinitesimal of higher order than the first term. In particular, if θ is a scale parameter of interest, the asymptotic variance of $\sqrt{n} \tilde{\theta}$ defined in (2.3) and (2.4) can be expressed as

$$\lim_{n \rightarrow \infty} n \text{Var}(\tilde{\theta}) = \mathbf{w}_g^T \lim \Sigma_{\hat{\theta}} \mathbf{w}_g,$$

where $\lim \Sigma_{\hat{\theta}}$ is the asymptotic covariance matrix of $\sqrt{n}(\hat{\theta}_{\tau_1}, \dots, \hat{\theta}_{\tau_m})^T$. Moreover, the optimal weight vector (written as \mathbf{w}^*) has the form: $\mathbf{w}^* = (\mathbf{1}^T (\lim \Sigma_{\hat{\theta}})^{-1} \mathbf{1})^{-1} (\lim \Sigma_{\hat{\theta}})^{-1} \mathbf{1}$. Then, $\lim_{n \rightarrow \infty} \text{Var}(\tilde{\theta}) \leq \lim_{n \rightarrow \infty} \text{Var}(\hat{\theta}_{\tau_k})$ for $k = 1, \dots, m$.

Remark 3. (a) Optimal weights. In Theorem 3, the optimal weight vector $\mathbf{w}^* = (w_1^*, \dots, w_m^*)^T = (\mathbf{1}^T (\lim \Sigma_{\hat{\theta}})^{-1} \mathbf{1})^{-1} (\lim \Sigma_{\hat{\theta}})^{-1} \mathbf{1}$ is related to the unknown covariance matrix $\lim \Sigma_{\hat{\theta}}$ and vector $\mathbf{w}_g = (w_1 g(\tau_1), \dots, w_m g(\tau_m))^T$. These can be consistently estimated using classical methods, such as the jackknife method (see, e.g., Shao and Wu (1989)).

(b) Weight selection under the multivariate θ case. For scalar θ , a closed representation of the optimal weight vector \mathbf{w}^* is derived in Theorem 3. When θ is a vector, we have

$$\lim_{n \rightarrow \infty} \text{Cov}(\tilde{\theta}) = \sum_{j=1}^m \sum_{k=1}^m w_j g(\tau_j) w_k g(\tau_k) \lim_{n \rightarrow \infty} \text{Cov}(\hat{\theta}_{\tau_j}, \hat{\theta}_{\tau_k}).$$

In general, a closed solution for the optimal weight might not be attained, unless a numerical approximation is adopted. However, if the initial estimators satisfy

$$H \text{Cov}(\hat{\theta}_{\tau_k}, \hat{\theta}_{\tau_j}) H \rightarrow a_{kj} D, \quad (2.6)$$

where $H = \text{diag}(n^{\delta_1}, \dots, n^{\delta_p})$ with $0 < \delta_j \leq 1/4$, a_{jk} are constants and D is a positive definite matrix, and both are given or estimable, we can obtain a closed solution. For example, the asymptotic covariances of the quantile regression estimators satisfy this; see the results in Section 3. In this situation, by the same argument used above, the closed representation of the optimal weight vector is $\mathbf{w}^* = (\mathbf{1}^T D^{-1} \mathbf{1})^{-1} D^{-1} \mathbf{1}$. When (2.6) does not hold, the following suboptimal weights can be considered. Note that $\lim_{n \rightarrow \infty} \text{tr}(\text{Cov}(\tilde{\theta})) = \sum_{j=1}^m \sum_{k=1}^m w_j g(\tau_j) w_k g(\tau_k) \lim_{n \rightarrow \infty} \text{tr}(\text{Cov}(\hat{\theta}_{\tau_j}, \hat{\theta}_{\tau_k}))$. A suboptimal weight vector can be obtained as $\mathbf{w}_S^* = (\mathbf{1}^T A_S^{-1} \mathbf{1})^{-1} A_S^{-1} \mathbf{1}$, where

$$A_S = \left(\lim_{n \rightarrow \infty} \text{tr}(\text{Cov}(\hat{\theta}_{\tau_j}, \hat{\theta}_{\tau_k})) \right)_{j,k=1}^p.$$

2.3. Choices of m and values of τ

In practice, we must choose the number m of initial estimators to be combined and the values of the model-independent parameter τ . Here, m can be regarded as a tuning parameter, because its choice influences the performance of the AWLS estimator. It is challenging to use a criterion to select an optimal m and values of τ , because they appear model-dependent. Thus, the choices presented here are empirical. As shown by Zou and Yuan (2008), for a composite quantile regression, a value of 19 for m is practically useful. Thus, the equally spaced quantiles $\tau_k = k/(m+1)$ amount to using the 5%, 10%, ..., 95% quantiles. In the simulations, we find that the AWLS estimator for the composite quantile regression is not sensitive to the choice of m and τ_k . If τ is the bandwidth h in the kernel estimation (discussed in the next section) or the number of knots in the B-spline estimation, the AWLS estimator is reasonably affected by the choice of h because the bandwidth often affects the performance of a nonparametric estimation. However, we show that the AWLS is not very sensitive to m when h_k is around the optimal bandwidth. In practice, we may determine a data-driven bandwidth first, and then take values τ_k such that h_k is around this bandwidth. In the simulation studies in Sec. 4, we discuss this issue in further detail.

On the other hand, although we have a generic framework for the composition, the model-independent parameter selection is, in general, a challenge,

because it relies on the asymptotic presentation of the initial estimator and the relationship between this parameter and the initial estimators. Further research is required to determine whether there is a general way to select this parameter, even when the user has little knowledge about the asymptotics.

3. Examples

In this section, we use linear quantile and nonparametric regressions, and a blockwise empirical likelihood estimation as examples to verify the methods and the theory proposed in the previous section. The conclusions drawn below can be viewed as direct corollaries of those proposed in Section 2. However, for validation and further discussion, we still provide detailed conclusions and proofs. Moreover, for these specific models, several special results are obtained.

3.1. AWLS for linear quantile regression

Consider the following linear regression model:

$$Y = \beta^T X + e.$$

Suppose that the conditional $100\tau\%$ quantile of $Y|X$ can be expressed as the following linear regression form: $\beta^T X + \alpha_\tau$, where α_τ is the $100\tau\%$ quantile of $Y - \beta^T X$. See Koenker (2005) for further details. The quantile regression estimator of $(\alpha_\tau, \beta^T)^T$ can be obtained as

$$\begin{pmatrix} \hat{\alpha}_\tau \\ \hat{\beta}_\tau \end{pmatrix} = \arg \min_{\alpha_\tau, \beta} \sum_{i=1}^n \rho_\tau(Y_i - \alpha_\tau - \beta^T X_i),$$

where $\rho_\tau(t) = \tau t_+ + (1 - \tau)t_-$ is the so-called check function, with $+$ and $-$ denoting the positive and negative parts, respectively. Denote $F_i(y) = F(y|X_i) = P(Y_i < y|X_i)$, and suppose that $F_i(y), i = 1, \dots, n$, are independent and identically distributed (i.i.d.) with a common density function $f(y) > 0$, for all y . Under some regularity conditions (see, e.g., Bahadur (1966); Kiefer (1967); Koenker (2005)), for different quantile positions $\tau = \tau_k, k = 1, \dots, m$, we have the following Bahadur representation:

$$\begin{aligned} \hat{\beta}_{\tau_k} &= \beta + \frac{1}{f_e(\alpha_{\tau_k})n} D_n^{-1} \sum_{i=1}^n X_i (\tau_k - I(Y_i \leq \alpha_{\tau_k} + \beta^T X_i)) + \epsilon_n(\tau_k) \\ &=: \beta + b_n \xi_n(\tau_k) + \epsilon_n(\tau_k), \quad k = 1, \dots, m, \end{aligned} \quad (3.1)$$

where $D_n = (1/n) \sum_{i=1}^n X_i X_i^T$, $f_e(\cdot)$ is the density function of error $e = Y - \beta^T X$, $\epsilon_n(\tau_k), k = 1, \dots, m$, are of order $O_p(n^{-3/4})$, and b_n and $\xi_n(\tau_k)$ are defined,

respectively, as $b_n = 1/\sqrt{n}$ and

$$\xi_n(\tau_k) = \frac{1}{f_e(\alpha_{\tau_k})\sqrt{n}} D_n^{-1} \sum_{i=1}^n X_i(\tau_k - I(Y_i \leq \alpha_{\tau_k} + \beta^T X_i)).$$

It can be seen that $\xi_n(\tau_k) = O_p(1)$, and b_n is of order $n^{-1/2}$, an infinitesimal of lower order than that of $\epsilon_n(\tau_k)$. We first suppose $f_e(\cdot)$ is a given function. Then, the asymptotic representation (3.1) can be included in the framework of (2.1). When α_{τ_k} and β in $\xi_n(\tau_k)$ are replaced by their consistent estimators $\hat{\alpha}_{\tau_k}$ and $\hat{\beta}_{\tau_k}$, respectively, from (2.4), the AWLS estimator of β has the following form:

$$\tilde{\beta} = \sum_{k=1}^m w_k \left\{ \hat{\beta}_{\tau_k} - \frac{1}{f_e(\hat{\alpha}_{\tau_k})n} D_n^{-1} \sum_{i=1}^n X_i(\tau_k - I(Y_i \leq \hat{\alpha}_{\tau_k} + \hat{\beta}_{\tau_k}^T X_i)) \right\}. \quad (3.2)$$

By comparing the above with the Bahadur representation (3.1), we see that in addition to the initial estimators $\hat{\beta}_{\tau_k}$, the main term $b_n \xi_n(\tau_k)$ plays a key role in constructing the AWLS estimator in (3.2). This term is related mainly to the directional derivative of the objective function. This method can be extended to the case when the density function $f_e(\cdot)$ is unknown, but can be consistently estimated. For ease of exposition, we only present the result with a given $f_e(\cdot)$ because, by the Slutsky theorem, the asymptotic distribution of $\tilde{\beta}$ is changeless when a consistent estimator of $f_e(\cdot)$ is used. We now investigate the properties of the above AWLS estimator. To this end, we assume the following conditions:

- (C3) $\max_{1 \leq i \leq n} \|X_i\| \leq cn^\nu$, for some constants $c > 0$ and $0 \leq \nu < 1/2$, where $\|\cdot\|$ is the Euclidean norm and there exists a positive definite matrix D such that $D = \lim_{n \rightarrow \infty} D_n$.
- (C4) The density function $f_e(\cdot)$ of the error e is continuously differentiable and positive at α_{τ_k} for $k = 1, \dots, m$.

The following theorem states the asymptotic properties of the AWLS estimator.

Theorem 4. *Under conditions (C3) and (C4), the AWLS estimator (3.2) has the following asymptotic representation:*

$$\tilde{\beta} - \beta = D^{-1} \frac{1}{n} \sum_{i=1}^n X_i \sum_{k=1}^m \frac{w_k}{f_e(\alpha_{\tau_k})} (\tau_k - I(Y_i \leq \alpha_{\tau_k} + \beta^T X_i)) + O_p(n^{-3/4}).$$

Consequently,

$$\sqrt{n}(\tilde{\beta} - \beta) \xrightarrow{\mathcal{D}} N(0, \mathbf{w}^T A_0 \mathbf{w} D^{-1}),$$

where $\mathbf{w} = (w_1, \dots, w_m)^T$ and $A_0 = ((\min(\tau_k, \tau_j)(1 - \max(\tau_k, \tau_j)))/(f_e(\alpha_{\tau_k}))$

$$f_e(\alpha_{\tau_j}))_{k,j=1}^m.$$

This theorem can be thought of as a corollary of Theorem 3 and Remark 3(b), because the initial estimator $\hat{\beta}_\tau$ satisfies (2.6) (see Koenker (2005)). Moreover, from the theorem, we have the following findings.

Remark 4. (1) When w_k is particularly chosen as $w_k = f_e(\alpha_{\tau_k}) / \sum_{k=1}^m f_e(\alpha_{\tau_k})$, the limiting variance of the AWLS estimator (2.2) is identical to that in Zou and Yuan (2008). In other words, we can have a smaller limiting variance by choosing proper weights. The optimal weight vector is $\mathbf{w}^* = \min_{\mathbf{1}^T \mathbf{w} = 1} \mathbf{w}^T A_0 \mathbf{w}$. Lagrange multipliers lead to the optimal weight vector and the optimal limiting variance, respectively, in the following closed forms:

$$\mathbf{w}^* = (\mathbf{1}^T A_0^{-1} \mathbf{1})^{-1} A_0^{-1} \mathbf{1}, \quad \mathbf{w}^{*T} A_0 \mathbf{w}^* D^{-1} = (\mathbf{1}^T A_0^{-1} \mathbf{1})^{-1} D^{-1}.$$

This is the same as the optimal weight in Remark 3(b). For a univariate linear regression, Koenker (1984) obtained the above estimation efficiency using a direct composition. However, the computation in the latter method is not easy to implement because the optimal weights are the solutions to m nonlinear equations.

(2) When the density function f_e is unknown, the matrix A_0 can be estimated using a plug-in estimator \hat{f}_e of f_e . For example, as shown by Sun, Gai and Lin (2013), $f_e(\cdot)$ can be consistently estimated by the kernel estimator as $\hat{f}_e(t) = (1/n) \sum_{i=1}^n K_h(\hat{e}_i - t)$, where $\hat{e}_i = Y_i - \hat{\beta}^T X_i$, with $\hat{\beta}$ a root- n consistent estimator; $K_h(t) = (1/h)K(t/h)$, with $K(\cdot)$ a kernel function; and h is the bandwidth. With the plug-in estimator \hat{f}_e , the property of the weight vector \mathbf{w}^* is not discussed here.

3.2. AWLS estimation for a nonparametric regression

Consider the following nonparametric regression:

$$Y = r(X) + e,$$

where $r(x)$ is a smooth nonparametric regression function for $x \in [0, 1]$, and the error term satisfies $E(e|X) = 0$ and $Var(e|X) = \sigma^2$. We now consider the AWLS kernel estimator of $r(x)$ for $x \in (0, 1)$. As is known, $x \in (0, 1)$ is not a necessary constraint; that is, we use it only for simplicity of presentation. In this section, we give two types of composite estimators in order to explore how the estimation efficiency depends on the structure of the asymptotic representation.

Type-1: Expectation-based estimator. It is well known that under certain regularity conditions, such as the second-order continuous and bounded derivatives, a commonly used kernel estimator $\hat{r}_\tau(x)$ (e.g., N-W estimator) of the regression

function $r(x)$ has the mean value:

$$E(\hat{r}_\tau(x)) = r(x) + \frac{1}{2} \left[r''(x) + 2 \frac{r'(x)f'_X(x)}{f_X(x)} \right] \mu_2(K)h^2 + o(h^2), \quad (3.3)$$

where $f_X(x)$ is the density function of X , $x \in (0, 1)$, $\mu_2(K) = \int u^2 K(u) du$, $K(x)$ is a kernel function, and h is a bandwidth satisfying $h = \tau n^{-\eta}$, for constants $\tau > 0$ and $0 < \eta < 1$. Then, for different values of $\tau = \tau_k, k = 1, \dots, m$, we have the following asymptotic representation: for $x \in (0, 1)$ and $k = 1, \dots, m$,

$$\begin{aligned} \hat{r}_{\tau_k}(x) &= r(x) + \left[\frac{1}{2} \left\{ r''(x) + 2 \frac{r'(x)f'_X(x)}{f_X(x)} \right\} \mu_2(K)n^{-2\eta} \right] \tau_k^2 + \epsilon_n(\tau_k) \\ &=: r(x) + b_n \xi_n(\tau_k) + \epsilon_n(\tau_k), \end{aligned} \quad (3.4)$$

where $b_n = (1/2)\{r''(x) + 2(r'(x)f'_X(x)/f_X(x))\}\mu_2(K)n^{-2\eta}$ and $\xi_n(\tau_k) = \tau_k^2$. Under the regularity condition in (C5), specified later, $\epsilon_n = \hat{r}_\tau(x) - E(\hat{r}_\tau(x)) + o(n^{-2\eta})$. This has a mean of order $o(n^{-2\eta})$ and a variance of order $O(n^{-(1-\eta)})$, and thus is of order $o_p(n^{-2\eta})$, provided that $0 < \eta < 1/5$. The asymptotic representation (3.4) has the same framework as that in (2.1). From (2.3), the resulting AWLS estimator of $a = r(x)$ is

$$\tilde{r}_1(x) = \sum_{k=1}^m w_k \hat{r}_{\tau_k}(x) - \tilde{b}_n(x) \bar{\tau}^2, \quad (3.5)$$

where τ_k is chosen to form bandwidths $h_k = \tau_k n^{-\eta}$, $k = 1, \dots, m$, $\tilde{b}_n(x) = \left(\sum_{k=1}^m w_k \hat{r}_{\tau_k}(x)(\tau_k^2 - \bar{\tau}^2) \right) / \left(\sum_{k=1}^m w_k (\tau_k^2 - \bar{\tau}^2)^2 \right)$, and $\bar{\tau}^2 = \sum_{k=1}^m w_k \tau_k^2$. Unlike the quantile linear regression, we use the expectation representation (3.4) to construct the AWLS estimator (3.5) for the nonparametric regression function. The construction procedure is relatively simple.

Type-2: Bahadur representation-based estimator. We can also use the Bahadur representation (see, e.g., Bhattacharya and Gangopadhyay (1990); Chaudhuri (1991); Hong (2003)) to construct a composite estimator. Under certain regularity conditions, for different values of $\tau = \tau_k, k = 1, \dots, m$, the N-W estimators $\hat{r}_{\tau_k}(x)$ have the following Bahadur representation:

$$\begin{aligned} \hat{r}_{\tau_k}(x) &= r(x) + \frac{1}{v_{\tau_k}(x)n} \sum_{i=1}^n K_{\tau_k}(X_i - x)(Y_i - r(x)) + \epsilon_n(\tau) \\ &=: r(x) + b_n \xi_n(\tau_k) + \epsilon_n(\tau_k), \quad x \in (0, 1), \end{aligned} \quad (3.6)$$

where $b_n = 1/\sqrt{n}$, and $\xi_n(\tau_k) = (1/(v_{\tau_k}(x)\sqrt{n})) \sum_{i=1}^n K_{\tau_k}(X_i - x)(Y_i - r(x))$, where $v_\tau(x) = \int K_\tau(u)f_X(x+hu)du$, with $K_\tau(x) = h^{-1}K(x/h)$ and $h = \tau n^{-\eta}$. In this presentation, b_n is a constant and the covariates $\xi_n(\tau_k)$ are related to the function of interest $r(x)$. Once again, $\epsilon_n(\tau)$ is of order $O_p(n^{-3(1-\eta)/4})$. Then,

the asymptotic representation (3.6) has the same framework as that in (2.1). If the density $f_X(\cdot)$ is known to lead to a given v_τ , according to the corresponding estimator (2.4), the resulting AWLS estimator can be expressed as

$$\tilde{r}_2(x) = \sum_{k=1}^m w_k \left(\hat{r}_{\tau_k}(x) - \frac{1}{v_{\tau_k}(x)n} \sum_{i=1}^n K_{\tau_k}(X_i - x)(Y_i - \hat{r}_{\tau_k}(x)) \right), \quad x \in (0, 1). \quad (3.7)$$

If $f_X(\cdot)$ is unknown, we can use its estimator instead, and thus obtain an estimator of v_τ .

We now investigate the asymptotic properties of the estimators in (3.5) and (3.7). Consider the following two regularity conditions:

- (C5) Kernel function $K(u)$ is symmetric with respect to $u = 0$ and satisfies $\int K(u)du = 1$, $\int u^2 K(u)du < \infty$, and $\int u^2 K^2(u)du < \infty$. The regression function $r(x)$ defined above and the density function $f_X(x)$ of X have continuous and bounded second-order derivatives and $f_X(x) > 0$ for all x .
- (C6) Kernel function $K(u)$ is symmetric with respect to $u = 0$ and satisfies $\int K(u)du = 1$, $\int u^4 K(u)du < \infty$, and $\int u^2 K^2(u)du < \infty$. Functions $r(x)$ and $f_X(x)$ have continuous and bounded fourth-order derivatives and $f_X(x) > 0$ for all x .

Denote $s_k(\mathbf{w}) = 1 - \left(\overline{\tau^2}(\tau_k^2 - \overline{\tau^2}) / \sum_{k=1}^m w_k(\tau_k^2 - \overline{\tau^2})^2 \right)$, $g_k = w_k - \overline{\tau^2} \left(w_k(\tau_k^2 - \overline{\tau^2}) / \sum_{k=1}^m w_k(\tau_k^2 - \overline{\tau^2})^2 \right)$, $A_1(\mathbf{w}) = \left((s_k(\mathbf{w})s_j(\mathbf{w})/\tau_k\tau_j) \int K(u/\tau_k)K(u/\tau_j)du \right)_{k,j=1}^m$, and $A_2 = \left((1/\tau_k\tau_j) \int K(u/\tau_k)K(u/\tau_j)du \right)_{k,j=1}^m$. The following theorem states some interesting results.

Theorem 5. Suppose $h_k = \tau_k n^{-\eta}$, $k = 1, \dots, m$.

- (1) Under Condition (C5) or (C6), if $0 < \eta < 1/5$, then, we have $c_n(x) = o(n^{-2\eta})$ or $c_n(x) = n^{-4\eta}c(x) \sum_{k=1}^m g_k \tau_k^4$, with $c(x)$ being a known function, and the AWLS estimator $\tilde{r}_1(x)$ in (3.5) achieves the following asymptotic normality:

$$\sqrt{n^{1-\eta}} \left(\tilde{r}_1(x) - r(x) - c_n(x) \right) \xrightarrow{\mathcal{D}} N \left(0, \mathbf{w}^T A_1(\mathbf{w}) \mathbf{w} \frac{\sigma^2}{f_X(x)} \right), \quad x \in (0, 1).$$

- (2) For the AWLS estimator $\tilde{r}_2(x)$ in (3.7), under Condition (C6), if $1/5 \leq \eta < 1$, then

$$\sqrt{n^{1-\eta}} \left(\tilde{r}_2(x) - r(x) - n^{-2\eta}d(x) \sum_{k=1}^m w_k \tau_k^2 \right) \xrightarrow{\mathcal{D}} N \left(0, \mathbf{w}^T A_2 \mathbf{w} \frac{\sigma^2}{f_X(x)} \right), \quad x \in (0, 1),$$

where $d(x)$ is a given function.

This theorem yields the following conclusions.

Remark 5. (a) *Rate-accelerated convergence.* Note that under Condition (C5), $\tilde{r}_1(x)$ achieves a rate-accelerated bias $o(n^{-2\eta})$ rather than the classical optimal rate $O(n^{-2\eta})$ that the N–W estimator achieves. Under Condition (C5), when the optimal bandwidth $h = O(n^{-1/9})$ is used, $\tilde{r}_1(x)$ has the convergence rate of $O(n^{-4/9})$ without higher-order smoothness conditions on the regression and density functions and, more importantly, without a higher-order kernel. However, the classical N–W estimator requires that these reach a convergence rate of order $O(n^{-4/9})$. This illustrates the conclusion about the convergence rate acceleration in Theorem 1. We also show later that by choosing a proper weight, the AWLS estimator $\tilde{r}_1(x)$ can have a smaller variance as well. In contrast, $\tilde{r}_2(x)$ cannot have a faster convergence rate; however the estimation variance can be reduced.

(b) *Weight selection.* Invoking the same argument as in Remark 4, the optimal weight vector for the second estimator $\tilde{r}_2(x)$ has the closed form:

$$\mathbf{w}_2^* = (\mathbf{1}^T A_2^{-1} \mathbf{1})^{-1} A_2^{-1} \mathbf{1}.$$

This is easy to compute when τ_k and kernel function $K(\cdot)$ are given. However, the definition given before Theorem 5 tells us that $A_1(\mathbf{w})$ of the expectation-based estimator $\tilde{r}_1(x)$ depends on the weight vector \mathbf{w} as well. Thus, the corresponding optimal weight vector for $\tilde{r}_1(x)$ has no closed form. To resolve this problem, we approximate $A_1(\mathbf{w})$ by

$$A_1 = \left(\frac{s_k s_j}{\tau_k \tau_j} \int K\left(\frac{u}{\tau_k}\right) K\left(\frac{u}{\tau_j}\right) du \right)_{k,j=1}^m,$$

where $s_k = 1 - (\overline{\tau^2}(\tau_k^2 - \overline{\tau^2}) / \sum_{k=1}^m (\tau_k^2 - \overline{\tau^2})^2)$ is free of the weight vector \mathbf{w} . A “suboptimal” weight vector for $\tilde{r}_1(x)$ is then

$$\mathbf{w}_1^* = (\mathbf{1}^T A_1^{-1} \mathbf{1})^{-1} A_1^{-1} \mathbf{1}.$$

This “suboptimal weight,” \mathbf{w}_1^* , can be easily computed. With the weights \mathbf{w}_1^* and \mathbf{w}_2^* , $\sqrt{n^{1-\eta}} \tilde{r}_1(x)$ and $\sqrt{n^{1-\eta}} \tilde{r}_2(x)$ have the following limiting variances:

$$(\mathbf{1}^T A_1^{-1} \mathbf{1})^{-1} \frac{\sigma^2}{f_X(x)} \quad \text{and} \quad (\mathbf{1}^T A_2^{-1} \mathbf{1})^{-1} \frac{\sigma^2}{f_X(x)}, \quad (3.8)$$

respectively. The two limiting variances could be smaller than those of the classical kernel estimators in certain scenarios. For example, when the kernel function is chosen as $K(u) = e^{-u^2/2}/\sqrt{2\pi}$, then

$$A_1 = \left(\frac{s_k s_j}{(2\pi)^{1/2} \sqrt{\tau_k^2 + \tau_j^2}} \right)_{k,j=1}^m, \quad A_2 = \left(\frac{1}{(2\pi)^{1/2} \sqrt{\tau_k^2 + \tau_j^2}} \right)_{k,j=1}^m.$$

It is known that with this kernel function, the limiting variance of the N–W estimator is $\sigma^2/(2\sqrt{\pi}f_X(x))$, which is just a special case of the variances in (3.8) with $m = 1$ and $\tau_1 = 1$. Thus, when $\min\{\tau_k; k = 1, \dots, m\} < 1 < \max\{\tau_k; k =$

$1, \dots, m\}$ and the above weights are used, the limiting variances of the AWLS estimators are smaller.

(c) *Kernel selection.* As mentioned above, the AWLS estimators can have either an accelerated convergence rate or a smaller limiting variance, or both. From the technical proof, we see that the estimators still have the kernel estimation types. A natural concern is whether the classical N–W estimator, or an adaption of the N–W estimator, might also enjoy this rate-acceleration property through a careful selection of the kernel function. The proof tells us that this is not possible, and that there is no such kernel function for any single N–W estimator. This is because the AWLS estimators, and particularly the expectation-based estimator $\tilde{r}_1(x)$, are not simply a weighted sum of the initial estimator with positive weights summing to one.

3.3. AWLS estimation for a blockwise empirical likelihood estimation

The values of the model-independent parameters, the quantile τ and bandwidth h in the two examples above, can be continuous. In this subsection, we use an example to show that the value of the model-independent parameter can be discrete.

A blockwise likelihood (see, e.g., Varin, Reid and Firth (2011)) is typically used in models with dependent data. To reduce the data dependency, blockwise versions of the data are considered. Let Y_1, \dots, Y_n be dependent observations from an unknown d -variate distribution $f(y; \theta)$, where the parameter vector $\theta \in \Theta \subset R^p$. Information about θ and $f(y; \theta)$ is available in the form of an unbiased estimating function $u(y; \theta)$, that is, $E(u(Y; \theta^0)) = 0$, where θ^0 is the true value of θ and $u(y; \theta)$ is a given function vector: $R^d \times \Theta \rightarrow R^r$ with $r \geq p$. Let τ and l be integers satisfying $\tau = \lfloor n^{1-c_1} \rfloor$ and $l = \lfloor c_2 n^{1-c_1} \rfloor$, respectively, for some constants $0 < c_1 \leq 1$ and $0 < c_2 \leq 1$, where $\lfloor x \rfloor$ denotes the integer part of x . Denote $B_i = (Y_{(i-1)l+1}, \dots, Y_{(i-1)l+\tau})^T$, $i = 1, \dots, q$, where $q = \lfloor (n - \tau)/l \rfloor + 1$. It can be verified that $q = O(n^{c_1})$. Here B_i denotes a block of observations, τ is the window width, and l is the separation between the block starting points. The observation blocks B_i are used to construct the following estimating function:

$$U_i(\theta, \tau) = \frac{1}{\tau} \sum_{k=1}^{\tau} u(Y_{(i-1)l+k}; \theta).$$

Then, the blockwise empirical Euclidean log-likelihood ratio for dependent data is defined as

$$l_\tau(\theta) = \sup \left\{ -\frac{1}{2} \sum_{i=1}^q (qp_i - 1)^2 \left| \sum_{i=1}^q p_i = 1, p_i \geq 0, \sum_{i=1}^q p_i U_i(\theta, \tau) = 0 \right. \right\},$$

and the empirical Euclidean likelihood estimator of θ is defined as

$$\hat{\theta}_\tau = \arg \sup_{\theta \in \Theta} l_\tau(\theta).$$

Here, we only consider the case of $p = r = 1$. It follows from the asymptotic representation given in the proof of Theorem 2 of Lin and Zhang (2001) that, under certain regularity conditions, the following asymptotic representation holds:

$$\hat{\theta}_{\tau_k} = \theta + b_n \xi_n(\tau_k) + o_p\left(\frac{1}{\sqrt{n}}\right), \quad k = 1, \dots, m, \quad (3.9)$$

where $b_n = 1/(\sqrt{n} \Delta(\theta))$, $\xi_n(\tau_k) = \sqrt{n} \bar{U}(\theta, \tau_k)$, $\bar{U}(\theta, \tau) = (1/q) \sum_{i=1}^q U_i(\theta, \tau)$, and $\Delta(\theta) = E(u'(Y; \theta))$, with $u'(y; \theta)$ being the derivative of $u(y; \theta)$ with respect to θ . Clearly, the above is also within the framework of (2.1) with unknown b_n and a parameter-dependent $\xi_n(\tau_k)$.

In this example, the positive integer τ is the model-independent parameter. This parameter determines the size of the blocks of data points and takes discrete values. From the asymptotic representation of the empirical likelihood (3.9), we see that the blockwise empirical likelihood AWLS estimator has the form given in (2.3), that is,

$$\tilde{\theta} = \sum_{k=1}^m w_k \hat{\theta}_{\tau_k} - \hat{b}_n \bar{\xi}_n, \quad (3.10)$$

where

$$\hat{b}_n = \frac{\sum_{k=1}^m w_k \hat{\theta}_{\tau_k} \left(\sqrt{n} \bar{U}(\hat{\theta}, \tau_k) - \bar{\xi}_n \right)}{\sum_{k=1}^m w_k \left(\sqrt{n} \bar{U}(\hat{\theta}, \tau_k) - \bar{\xi}_n \right)^2}, \quad \bar{\xi}_n = \sum_{k=1}^m w_k \sqrt{n} \bar{U}(\hat{\theta}, \tau_k),$$

with $\hat{\theta}$ being an initial estimator of θ .

The theoretical property and the optimal choice of the weights can be determined using Theorem 3 and Remark 3. The details are omitted here.

4. Numerical Studies

4.1. Simulations

In this subsection, we examine the finite-sample behavior of the newly proposed estimator using simulation studies. To obtain thorough comparisons, we comprehensively compare the estimator with several competitors that are based

on an objective function composition, a direct composition, and an aggregation for linear and nonparametric models. The mean squared error (for the parametric model) and the mean integrated squared error (for the nonparametric model) are used to evaluate the performance of the involved estimators. We also report the simulation results for the estimation bias. Moreover, we consider the asymptotic relative efficiency (RE), defined as $RE(\hat{\beta}, \tilde{\beta}) = \text{Var}(\hat{\beta})/\text{Var}(\tilde{\beta})$, where $\tilde{\beta}$ is the proposed AWLS estimator and $\hat{\beta}$ is a competitor. Here $RE > 1$ indicates better performance by the AWLS estimator.

Experiment 1. Consider the linear regression of the form

$$Y = X^T \beta + \epsilon,$$

where $\beta = (3, 2, -1, -2)^T$, the covariate vector $X = (X_1, X_2, X_3, X_4)^T$ follows a multivariate normal distribution $N(0, \Sigma)$, with $\Sigma_{ij} = 0.7^{|i-j|}$ for $1 \leq i, j \leq 4$, and the error term ϵ follows the centralized $\text{Gamma}(2, 2)$, such that its expectation is zero.

We choose $\tau = 0.3$ for the asymmetric distribution of the error term to construct the common quantile regression (QR) estimator $\hat{\beta}_\tau$ defined in Subsec. 3, and select $\tau_k = k/10$ for $k = 1, 2, \dots, 9$ ($m = 9$) to construct the AWLS estimator $\tilde{\beta}$ defined in (2.2). According to Zou and Yuan (2008), the CQR estimator $\hat{\beta}$ is defined by minimizing the following composite objective function:

$$(\hat{\beta}_{CQ}^T, \hat{\alpha}_{\tau_1}, \dots, \hat{\alpha}_{\tau_m})^T = \arg \min_{\beta, \alpha_{\tau_1}, \dots, \alpha_{\tau_m}} \sum_{i=1}^n \sum_{k=1}^m \rho_{\tau_k}(Y_i - \alpha_{\tau_k} - \beta^T X_i). \quad (4.1)$$

According to Bradic, Fan and Wang (2011), the WCQR estimator $\hat{\beta}_{WCQ}$ is determined by minimizing the composite objective function (4.1), with weight w_k for each $\rho_{\tau_k}(\cdot)$.

To obtain a consistent estimator of the density function $f_e(\alpha_{\tau_k})$, we first use the ordinary least squares (OLS) method to estimate a preliminary estimator $\hat{\beta}_{OLS}$, and then compute the residuals as $\hat{\epsilon}_i = Y_i - X_i^T \hat{\beta}_{OLS}$. Then, we estimate $f_e(\alpha_{\tau_k})$ using the nonparametric kernel density estimator through $\hat{\epsilon}_i, i = 1, 2, \dots, n$. Consequently, we obtain the optimal weights for the AWLS estimator $\tilde{\beta}$, defined in (2.2).

For the sample sizes $n = 100, 200$, and 400 , the empirical bias, RE, and mean squared error (MSE) of the four estimators and the OLS estimator over 500 replications are reported in Table 1. The boxplots for the sample size $n = 200$ for the five estimators are depicted in Figure 1. For the different sample sizes of n , the boxplot trends are similar. Furthermore, to check the influence of m on the AWLS estimator, the quantile level τ takes values from 0.1 to 0.9, with three

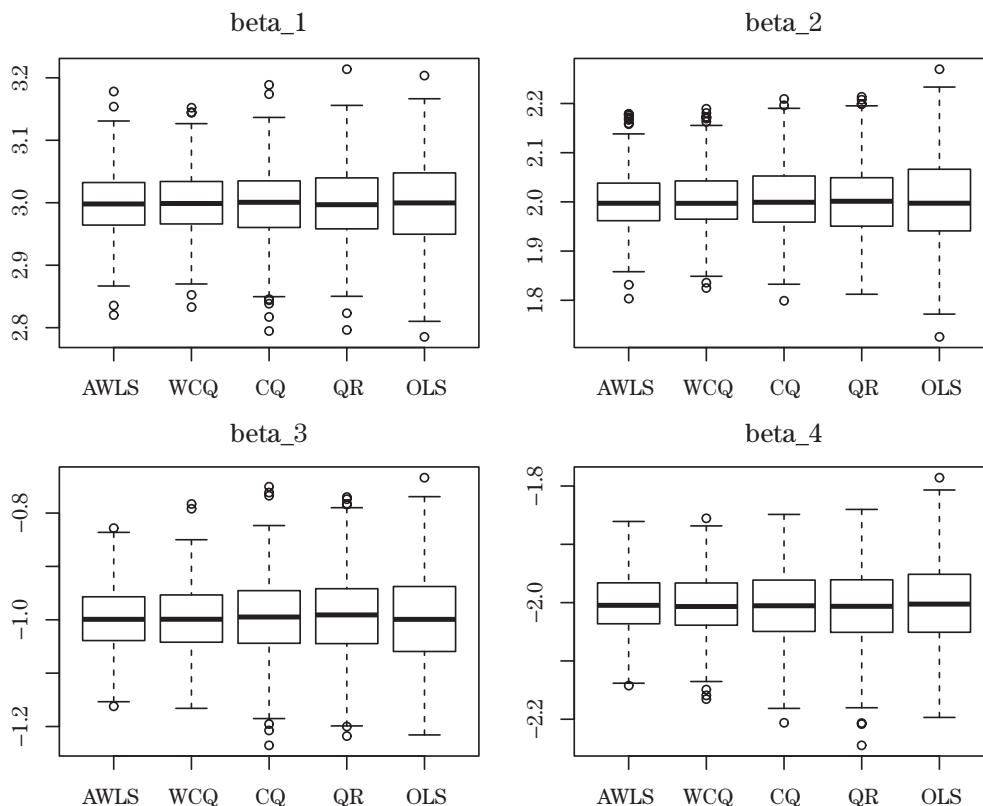


Figure 1. Boxplots of the estimators for β_1 , β_2 , β_3 , and β_4 in Experiment 1.

step lengths, 0.2, 0.1, and 0.05. In these cases, the compositions are based on 5, 9, and 17 initial estimators, respectively. The boxplots of the AWLS estimators with different choices of m and the same sample size $n = 200$ are presented in Figure 2. We also perform simulations for $n = 100$ and $n = 400$. Because the results are not significantly different, we do not report them here.

Table 1 and Figures 1 and 2 suggest the following conclusions. (1) The AWLS estimator $\tilde{\beta}$ and the WCQR estimator of Bradic, Fan and Wang (2011) behave comparably better than the other competitors, in the sense that the MSEs are significantly reduced, the boxplots are observably thinned, and nearly all of the relative efficiencies are greater than one. (2) Without composition, the QR estimator is better than the OLS estimator owing to the skewness of the gamma distribution. (3) In each subfigure of Figure 2, the boxplots are almost identical, showing that the AWLS estimator for the linear quantile regression model is robust to the choice of m .

Note that the simulation result depends on the assumption of the distribution

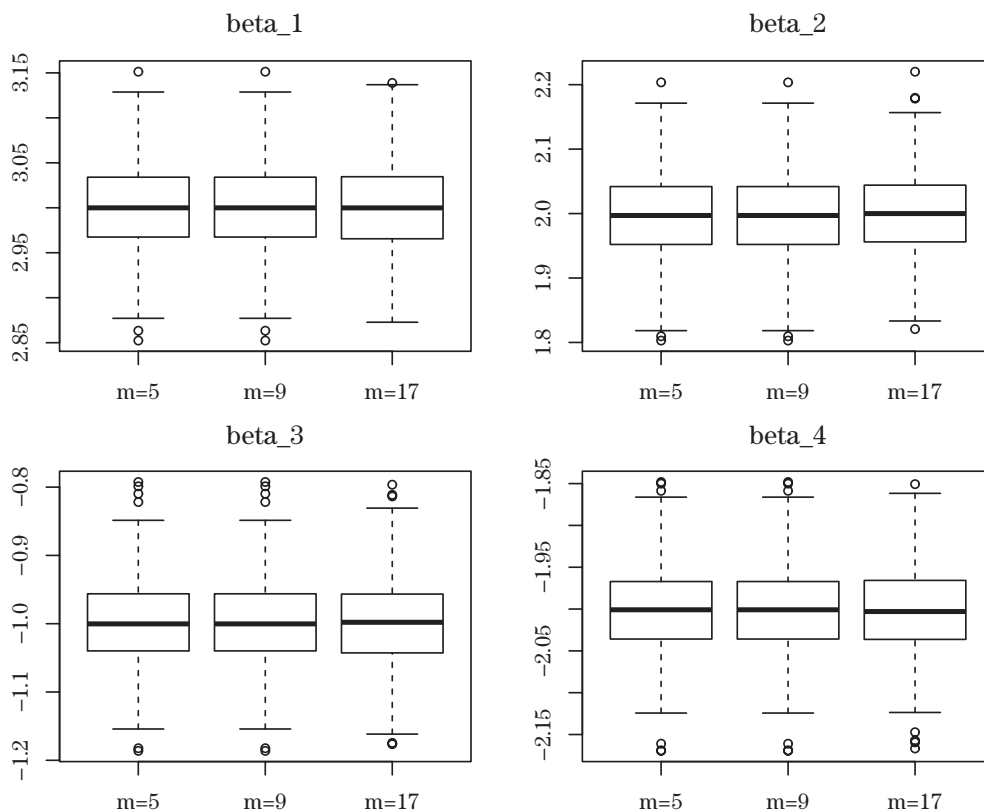


Figure 2. Boxplots of the AWLS estimators for β_1 , β_2 , β_3 , and β_4 with different m in Experiment 1.

of the error term. As shown by a referee, if the error is Gaussian, the OLS is by far the best method in this setting, because the basic quantile regression estimators are much worse than the OLS in this case. In fact, our AWLS aims to combine several quantile regression estimators, in which case, it can be guaranteed that the AWLS estimator is better than any single quantile regression estimator.

Experiment 2. Consider the dependent data Y_1, Y_2, \dots, Y_n generated from the model

$$Y_i = X_i\theta + \varepsilon_i,$$

where $X_i \sim N(0, 1)$, $\theta = 5$, $\varepsilon_1 = \epsilon_1$, $\varepsilon_i = 0.7\varepsilon_{i-1} + \epsilon_i$, for $i = 2, 3, \dots, n$, and $\epsilon_i, i = 1, \dots, n$, are i.i.d. as $N(0, 1)$. We compare the finite-sample behaviors of the blockwise composite likelihood estimator and the AWLS estimator. To obtain blockwise data and the composite likelihood estimator, we take $c = 1/3$ and $\tau_k = (k + 1)/10, k = 1, 2, \dots, 8$. The simulation results for the bias, MSE, and RE obtained for the different sample sizes and 500 repetitions are listed in

Table 1. Simulation results for Experiment 1.

n			$\hat{\beta}_1$	$\hat{\beta}_2$	$\hat{\beta}_3$	$\hat{\beta}_4$
100	AWLS	Bias	-0.0016	0.0042	-0.0042	0.0015
		MSE	0.0055	0.0085	0.0092	0.0058
	WCQR	Bias	-0.0007	0.0017	-0.0009	-0.0015
		MSE	0.0053	0.0080	0.0090	0.0063
		RE	0.9668	0.9457	0.9800	1.0751
	CQR	Bias	-0.0026	0.0021	-0.0010	-0.0008
		MSE	0.0077	0.0108	0.0117	0.0080
		RE	1.4032	1.2708	1.2756	1.3739
	QR	Bias	-0.0011	0.0036	0.0004	-0.0029
		MSE	0.0077	0.0116	0.0129	0.0082
		RE	1.4160	1.3636	1.4003	1.3922
	OLS	Bias	-0.0015	0.0037	-0.0037	0.0008
		MSE	0.0098	0.0146	0.0153	0.0103
		RE	1.7938	1.7138	1.6640	1.7635
200	AWLS	Bias	-0.0008	-0.0002	0.0025	-0.0023
		MSE	0.0026	0.0036	0.0037	0.0027
	WCQR	Bias	-0.0010	0.0010	0.0026	-0.0031
		MSE	0.0026	0.0037	0.0039	0.0027
		RE	1.0006	0.9955	1.0604	1.0281
	CQR	Bias	-0.0017	0.0024	0.0035	-0.0039
		MSE	0.0036	0.0053	0.0053	0.0039
		RE	1.4126	1.4591	1.4472	1.4630
	QR	Bias	-0.0010	-0.0001	0.0075	-0.0056
		MSE	0.0037	0.0057	0.0060	0.0043
		RE	1.4430	1.5693	1.6230	1.6188
	OLS	Bias	-0.0015	0.0043	0.0009	-0.0000
		MSE	0.0049	0.0075	0.0073	0.0050
		RE	1.9276	2.0504	1.9909	1.8754
400	AWLS	Bias	-0.0023	0.0024	0.0000	-0.0015
		MSE	0.0011	0.0016	0.0017	0.0012
	WCQR	Bias	-0.0014	0.0021	-0.0008	-0.0006
		MSE	0.0011	0.0017	0.0016	0.0012
		RE	1.0008	1.0129	0.9748	0.9976
	CQR	Bias	-0.0009	0.0033	-0.0021	-0.0002
		MSE	0.0019	0.0029	0.0027	0.0018
		RE	1.5535	1.5467	1.4763	1.5712
	QR	Bias	-0.0011	0.0030	-0.0007	-0.0012
		MSE	0.0019	0.0029	0.0027	0.0018
		RE	1.7319	1.7638	1.6553	1.5533
	OLS	Bias	0.0005	0.0021	-0.0013	-0.0009
		MSE	0.0026	0.0035	0.0034	0.0026
		RE	2.3196	2.1202	2.0401	2.2269

Table 2. Simulation results for Experiment 2.

n		Bias	MSE	RE
100	AWLS	-0.0004	0.0228	—
	BCEL	0.0006	0.0254	1.1157
200	AWLS	-0.0012	0.0091	—
	BCEL	0.0011	0.0098	1.0764
400	AWLS	-0.0007	0.0057	—
	BCEL	-0.0021	0.0060	1.0564

Table 2. We conclude that the proposed AWLS estimator improves upon the bias and MSE of the original blockwise likelihood estimator.

Experiment 3. For the nonparametric regression

$$Y_i = \sin(2\pi X_i) + 2 \exp(X_i^2) + \epsilon_i, \quad i = 1, \dots, n,$$

where $X_i \sim U(0, 1)$, the errors are chosen as $\epsilon_i \sim N(0, 0.5^2)$, and the sample sizes are $n = 100, 200$, and 400 , respectively. The common local constant (LC) estimator (kernel estimator) is defined as

$$\hat{r}_h(x) = \frac{\sum_{i=1}^n Y_i K((X_i - x)/h)}{\sum_{i=1}^n K((X_i - x)/h)}. \quad (4.2)$$

As a comparison, we define a composite estimator using the composite objective function method: for $h_k = \tau_k n^{-\eta}$, $k = 1, \dots, m$, the composite local constant (CLC) estimator is the minimizer of the form:

$$\hat{r}(x) = \arg \min_a \sum_{i=1}^n \sum_{k=1}^m (Y_i - a)^2 K\left(\frac{X_i - x}{h_k}\right).$$

This estimator has a closed representation:

$$\hat{r}(x) = \frac{\sum_{i=1}^n \sum_{k=1}^m Y_i K((X_i - x)/h_k)}{\sum_{i=1}^n \sum_{k=1}^m K((X_i - x)/h_k)}, \quad (4.3)$$

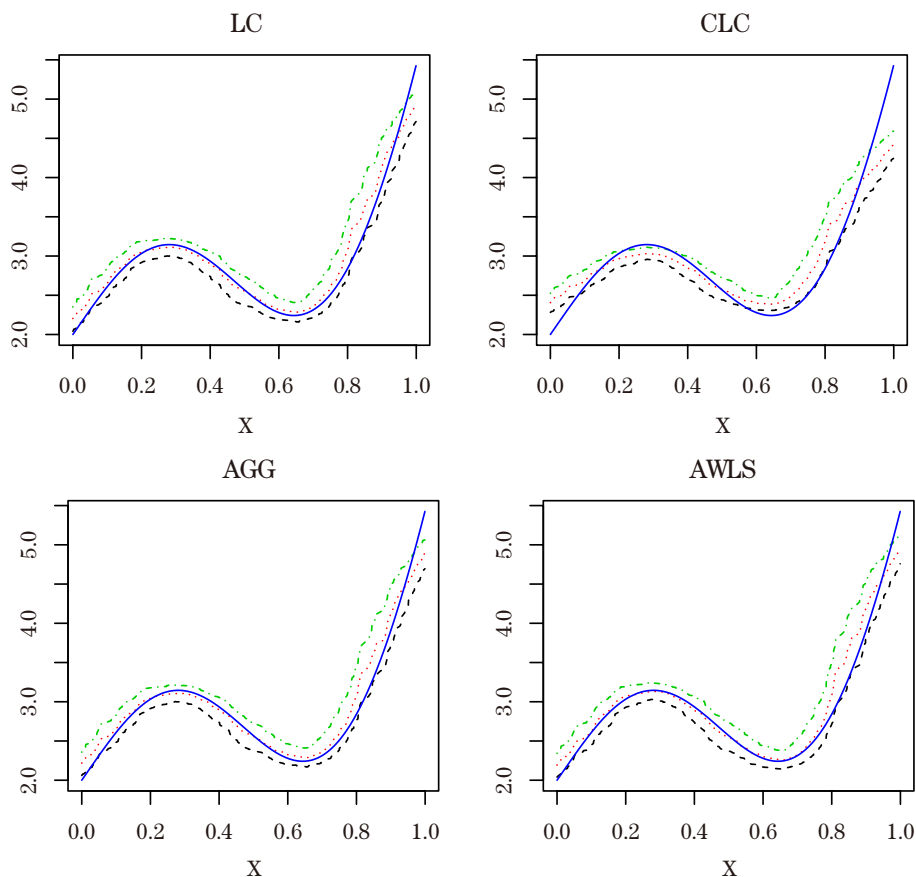
which can be regarded as an indirect composition of the LC estimators (4.2) with different bandwidths. In addition, an aggregation (AGG) estimator (Bunea, Tsybakov and Wegkamp (2004)) is also considered, which has the form

$$\hat{r}^*(x) = \sum_{k=1}^m w_k \hat{r}_{h_k}(x),$$

where w_k satisfies $\sum_{k=1}^m w_k = 1$. The optimal weights are obtained by L_1 -type penalized least squares, defined in equation (2.1) in Bunea, Tsybakov and Wegkamp (2004). To compute the optimal weights w_k , the sample is randomly split into two independent subsamples with equal sample size, where one (training sample)

Table 3. MISE for the nonparametric estimators in Experiment 2.

	n=100	n=200	n=400
LC	0.0397	0.0251	0.0114
CLC	0.0555	0.0475	0.0453
AGG	0.0287	0.0192	0.0121
AWLS	0.0264	0.0157	0.0109

**Figure 3.** Quantile curves for the LC, CLC , AGG, and AWLS estimators in Experiment 2.

is used to construct the estimators \hat{r}_{h_k} , and the other (validation sample) is used to aggregate them. Because the weights rely on the split, 10 random splits of the sample are run, and then the aggregation estimator is obtained by an average using equation (4.1) in Rigollet and Tsybakov (2007).

In this experiment, the Epanechnikov kernel $K(u) = 0.75(1 - u^2)\mathbf{1}_{|u| \leq 1}$ is employed, and to facilitate the computation of the optimal weights for the AWLS

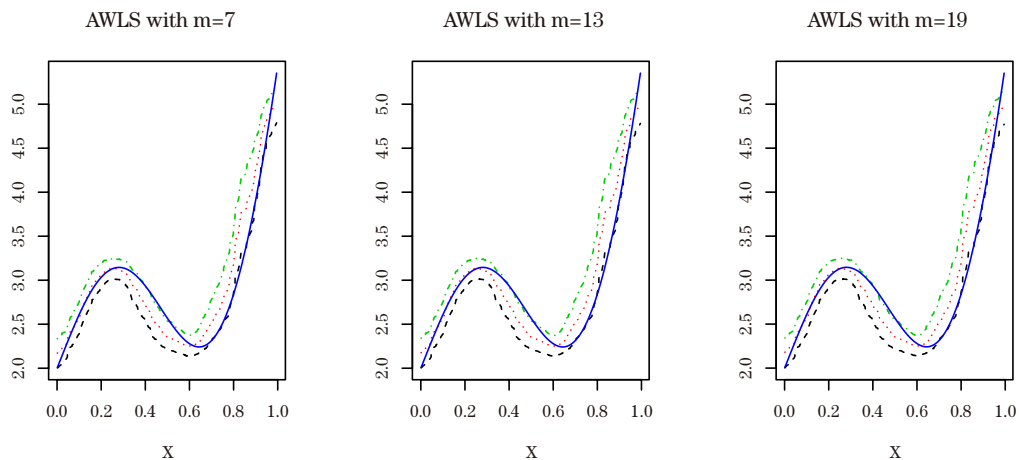


Figure 4. Quantile curves for the AWLS estimators with different values of m in Experiment 2.

estimator, the integral in $A_1(\mathbf{w})$ is approximated using 40 grid intervals. For the three estimation procedures, we use two-fold cross-validation to select a basic bandwidth h_{op} . In the LC estimation procedure, h_{op} is used to define the LC estimator. For the CLC, AGG, and the AWLS with bandwidths of the form $h_k = \tau_k h_{op}$, m values of τ_k are chosen in the range $[0.5, 1.5]$, with a step length of $0.5/l$. We consider the case $l = 6$. Thus, $m = 13$ and the resulting bandwidths are $h_k = (0.5(l+k)/l)h_{op}$ for $k = 0, \dots, 12$. The simulation results are reported in Table 3, where the MISE is the empirical mean integrated squared error through 500 repetitions. The quantile curves of the LC, CLC, AGG, and AWLS estimators for $r(x)$ are also presented. Because the results are similar for different sample sizes of n , we only show the quantile curves for $n = 200$ in Figure 3 to save space. Each subfigure contains 0.05, 0.5, and 0.95 quantile curves of the nonparametric estimator and the true curve of $r(x)$. To evaluate the influence of m , the quantile curves for 0.05, 0.5, and 0.95 for the AWLS estimator, with $n = 200$ and $l = 3, 6$, and 9 (i.e., $m = 7, 13$, and 19), and the true curve of $r(x)$ are presented in Figure 4. We can see that the MISEs of the AWLS estimators are all about 0.0158.

By comparing the MISEs and the quantile curves of the four estimators in Table 3 and Figures 3 and 4, we have the following findings: (1) the AGG works well with small MISE compared with the LC and CLC, but the AWLS is the best of the four estimators; (2) the CLC estimator $\hat{r}(x)$ given in (4.3) performs worst among these estimators, implying that the composite objective function is

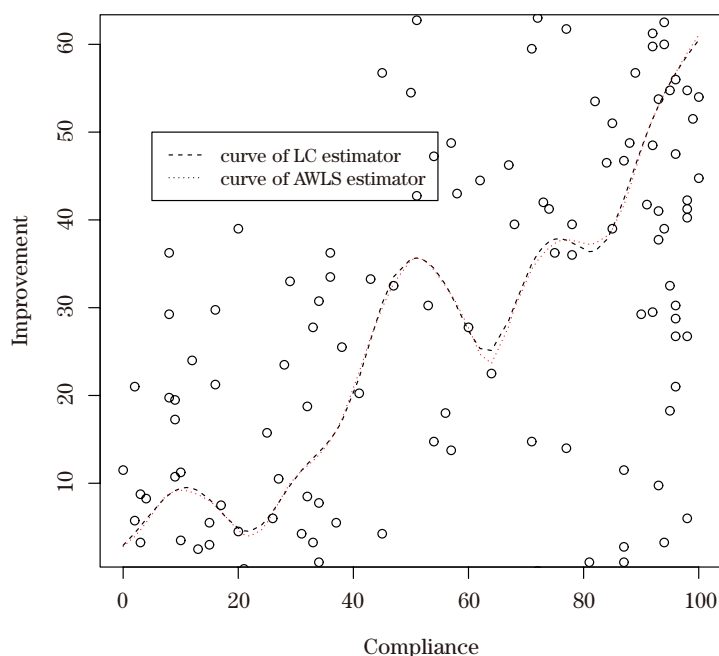


Figure 5. Curves of the LC estimator and AWLS estimator.

not always efficient; and (3) the AWLS is robust to the choice of m .

In summary, the AWLS estimation usually works well and is not very sensitive to the choice of the number of initial estimators m . Based on the limited simulations, a value of m between 10 and 15 is recommended.

4.2. Real-data analysis

In this subsection, the cholestyramine data set in Efron and Tibshirani (1993) is analyzed using the LC and AWLS as an illustration. The data set contains data on 164 individuals who took part in an experiment to determine whether the drug cholestyramine can lower blood cholesterol levels. The men were supposed to take six packets of cholestyramine per day, but many actually took much less. The covariate denoted by X measures “Compliance” as a percentage of the intended dose actually taken. The response denoted by Y is “Improvement” and marks a decrease in the total blood plasma cholesterol level from the beginning to the end of the experiment.

The scatter plot of Y against X in Figure 5 shows that the men who took more cholestyramine tend to exhibit bigger improvements in their cholesterol levels, but the model structure seems complex. Thus, a nonparametric regression

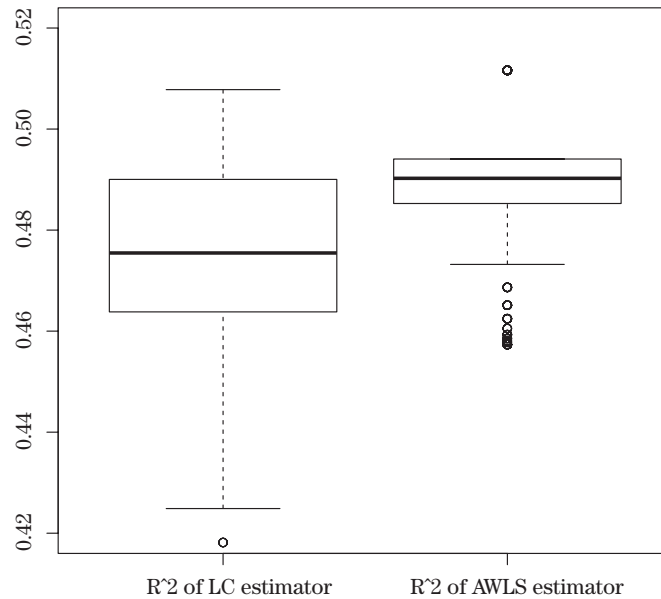


Figure 6. Boxplots of R^2 for the LC estimator and AWLS estimator.

model $Y = r(X) + \epsilon$ is modeled for the relationship between “Improvement” and “Compliance” (see Efron and Tibshirani (1993)). To estimate the function $r(\cdot)$, the LC estimator defined in (4.2) and the AWLS estimator are employed. In the estimation procedures, we use the Epanechnikov kernel $K(u) = 0.75(1 - u^2)\mathbf{1}_{|u| \leq 1}$ to construct nonparametric estimators, and use equal weights to build the AWLS estimator, for simplicity. As in Experiment 2, two-fold cross-validation is used to determine the basic bandwidth h_{op} . In the LC estimation procedure, the resulting bandwidth is $h = 8$. Then, as in Experiment 2, we choose $m = 13$. Figure 5 depicts the scatter plot of “Compliance” and “Improvement” and the curves of the LC estimator and the AWLS estimator of $r(x)$.

We have three observations. The drug cholestyramine can lower blood cholesterol levels, in general, when “Compliance” varies within the intervals $[20, 50]$ and $[70, 100]$, the blood cholesterol levels improve rapidly, and the curves of the LC estimator and the AWLS estimator are close to each other.

Finally, we use the R^2 values of the LC estimator and the AWLS estimator to further confirm the advantage of the new method, where $R^2 = 1 - \sum_{j=1}^n (Y_j - \hat{Y}_j)^2 / \sum_{j=1}^n (Y_j - \bar{Y})^2$, \hat{Y}_j is the predicted value of Y_j , and \bar{Y} is the sample mean of Y_j s. We first use two-fold cross-validation to generate the optimal bandwidth h_{op} , and then use the method suggested in Experiment 2 to produce the bandwidths h_k for the composite estimation construction. The 500 values of R^2 for the two

estimators are computed by repeating this procedure 500 times. The boxplots of the R^2 values are given in Figure 6. These show that the R^2 values of the the AWLS estimators are larger than those of the LC estimators, in general. In addition, the AWLS estimator is more stable than LC estimator owing to its smaller variation. Thus, the AWLS fits the data better.

Supplementary Material

The online supplementary material contains the proofs of all theorems in this paper.

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