Zhe Fei (zhe.fei@ucr.edu)

- Linear regression is the most commonly applied procedure in statistics.
- Solving linear least squares problems quickly and reliably

Linear Regression and Matrix Inversion

Four methods for solving linear least squares problems:

- Sweeping, uses the symmetry of matrices and is conceptual simple
- Cholesky decomposition, a lower triangular square root of a positive definite matrix
- Modified Gram-Schmidt procedure, numerically more stable
- Orthogonalization by Householder reflections

The Sweep Operator

The popular statistical software SAS uses sweep operator for linear regression and matrix inversion.

Motivation:

A random vector $X \in \mathbb{R}^p$ with mean vector μ , covariance matrix Σ , and density

$$(2\pi)^{-p/2} |\Sigma|^{-1/2} e^{-rac{1}{2}(x-\mu)^T \Sigma^{-1}(x-\mu)}$$

is said to follow a multivariate normal distribution.

The sweep operator permits straightforward calculation of the quadratic form $(x-\mu)^T\Sigma^{-1}(x-\mu)$ and the determinant of Σ . If we partition X and its mean and covariance so that

$$X = egin{bmatrix} Y \ Z \end{bmatrix}, \qquad \mu = egin{bmatrix} \mu_Y \ \mu_Z \end{bmatrix}, \qquad \Sigma = egin{bmatrix} \Sigma_Y & \Sigma_{YZ} \ \Sigma_{ZY} & \Sigma_Z \end{bmatrix},$$

then conditional on the event Y=y, the subvector Z follows a multivariate normal density with conditional mean and variance

$$E(Z|Y=y) = \mu_Z + \Sigma_{ZY}\Sigma_Y^{-1}(y-\mu_Y), \ ext{Var}(Z|Y=y) = \Sigma_Z - \Sigma_{ZY}\Sigma_Y^{-1}\Sigma_{YZ}.$$

These quantities and the conditional density of Z given Y=y can all be easily evaluated via the sweep operator.

Definition:

Suppose A is an $m \times m$ symmetric matrix.

Sweep on the kth diagonal entry $a_{kk} \neq 0$ of A yields a new symmetric matrix $\widehat{A} = (\widehat{a}_{ij})$ with entries

$$egin{aligned} \hat{a}_{kk} &= -rac{1}{a_{kk}} \ \hat{a}_{ik} &= rac{a_{ik}}{a_{kk}}, \quad i
eq k \ \hat{a}_{kj} &= rac{a_{kj}}{a_{kk}}, \quad j
eq k \ \hat{a}_{ij} &= a_{ij} - rac{a_{ik}a_{kj}}{a_{kk}}, \quad i
eq k, j
eq k. \end{aligned}$$

Inverse sweep sends A to $\check{A}=(\check{a}_{ij})$ with entries

$$egin{aligned} \check{a}_{kk}&=-rac{1}{a_{kk}}\ \check{a}_{ik}&=-rac{a_{ik}}{a_{kk}},\quad i
eq k\ \check{a}_{kj}&=-rac{a_{kj}}{a_{kk}},\quad j
eq k\ \check{a}_{ij}&=a_{ij}-rac{a_{ik}a_{kj}}{a_{kk}},\quad i
eq k,j
eq k. \end{aligned}$$

- $\check{\hat{A}}=A$
- Successively sweeping all diagonal entries of A yields $-A^{-1}$
- ullet Exercise: Invert the 2 imes 2 matrix using the sweep operator:

$$A=\left(egin{matrix} 4 & 3 \ 3 & 2 \end{matrix}
ight)$$

Block form of sweep:

Let the symmetric matrix A be partitioned as

$$A=egin{pmatrix}A_{11}&A_{12}\A_{21}&A_{22}\end{pmatrix}$$

If possible, sweeping on the diagonal entries of A_{11} yields

$$\hat{A} = egin{pmatrix} -A_{11}^{-1} & A_{11}^{-1}A_{12} \ A_{21}A_{11}^{-1} & A_{22} - A_{21}A_{11}^{-1}A_{12} \end{pmatrix}$$

NAS Proposition 7.5.3

- A symmetric matrix A is positive definite if and only if each diagonal entry can be swept in succession and is positive until it is swept.
- ullet When a diagonal entry of a positive definite matrix A is swept, it becomes negative and remains negative thereafter.
- Furthermore, taking the product of the diagonal entries just before each is swept yields the determinant of A.

$$\det A = \det(A_{11})\det(A_{22} - A_{21}A_{11}^{-1}A_{12})$$

Applications of Sweeping

In **linear regression**, start with the matrix

$$\left[egin{array}{ccc} X^TX & X^Ty \ y^TX & y^Ty \end{array}
ight]$$

and sweep on the diagonal entries of X^TX . Then the basic theoretical ingredients

$$egin{aligned} & \begin{bmatrix} -(X^TX)^{-1} & (X^TX)^{-1}X^Ty \ y^TX(X^TX)^{-1} & y^Ty - y^TX(X^TX)^{-1}X^Ty \end{bmatrix} \ = egin{bmatrix} -rac{1}{\sigma^2} ext{Var}(\hat{eta}) & \hat{eta} \ \hat{eta}^T & \|y - \hat{y}\|_2^2 \end{bmatrix} \end{aligned}$$

magically emerge.

Multivariate normal: perform sweeping on the diagonal entries of Σ for the matrix

$$egin{bmatrix} \Sigma & x-\mu \ x^T-\mu^T & 0 \end{bmatrix},$$

we get the quadratic form $-(x-\mu)^T\Sigma^{-1}(x-\mu)$ in the lower-right block of the swept matrix.

- In the process we can also accumulate $\det \Sigma$.
- To avoid underflows and overflows, it is better to compute $\ln \det \Sigma$ by summing the logarithms of the diagonal entries as we sweep on them.

Conditional mean and variance: assume $X=(Y^T,Z^T)^T$, and sweep on the upper-left block of

$$egin{bmatrix} \Sigma_Y & \Sigma_{YZ} & \mu_Y - y \ \Sigma_{ZY} & \Sigma_Z & \mu_Z \ (\mu_Y - y)^T & \mu_Z^T & 0 \end{bmatrix},$$

we get

$$E(Z|Y=y) = \mu_Z + \Sigma_{ZY}\Sigma_Y^{-1}(y-\mu_Y), \ ext{Var}(Z|Y=y) = \Sigma_Z - \Sigma_{ZY}\Sigma_Y^{-1}\Sigma_{YZ}.$$

Exercise: implement the sweep operator, in python, it should start with:

def sweep(A, k):

return A_hat

Cholesky Decompositions

André-Louis Cholesky was a French military officer, geodesist, and mathematician. Cholesky

From a colleague:

The structure should be exploited whenever solving a problem. Common structures include: symmetry, positive (semi)definiteness, sparsity, low rank, ...

Let A be an $m \times m$ positive definite matrix. The Cholesky decomposition L of A is a lower-triangular matrix with positive diagonal entries that serves as an asymmetric square root of A.

How to show such L exists and is unique? By induction.

For m>1, the square root condition $A=LL^T$ can be written as

$$egin{pmatrix} \left(egin{array}{cc} a_{11} & a^T \ a & A_{22} \end{array}
ight) = \left(egin{array}{cc} \ell_{11} & 0^T \ \ell & L_{22} \end{array}
ight) \left(egin{array}{cc} \ell_{11} & \ell^T \ 0 & L_{22}^T \end{array}
ight),$$
 $a_{11} = \ell_{11}^2$

Solving these equations gives

which should satisfy

$$a = \ell_{11} \ell \ A_{22} = \ell \ell^T + L_{22} L_{22}^T.$$

• This proof is constructive and can be easily implemented in computer code.

$$egin{aligned} \ell_{11} &= \sqrt{a_{11}} \ \ell &= \ell_{11}^{-1} a \ L_{22} L_{22}^T &= A_{22} - \ell \ell^T. \end{aligned}$$

- Can compute $\det A$.
- · Positive semidefinite matrices also possess Cholesky decompositions.
- Regression analysis: with

$$(X,y)^T(X,y) = egin{bmatrix} X^TX & X^Ty \ y^TX & y^Ty \end{bmatrix} = egin{bmatrix} L & 0 \ \ell^T & d \end{bmatrix} egin{bmatrix} L^T & \ell \ 0^T & d \end{bmatrix}$$

 $L\ell = X^Ty, \quad L^Teta = \ell$

and

then

$$d^2 =$$

• Forward substitution to solve Lf = v:

$$f_1=\ell_{11}^{-1}v_1 \ f_2= \ldots$$

• Backward substitution to solve Ub = w:

$$egin{aligned} b_m &= u_{mm}^{-1} w_m \ b_{m-1} &= \end{aligned}$$