

FIRST DIFFERENCES

FELIPE BUCHBINDER

DOES HIGHER INCOME MEAN HIGHER SPENDING?

COULD WE USE POOLED REGRESSION?

$$\text{Spending}_{it} = \beta_0 + \beta_1 \cdot \text{Income}_{it} + U_i + \epsilon_{it}$$

Why or why not?

DOES HIGHER INCOME MEAN HIGHER SPENDING?

POOLED REGRESSION IS NOT A GOOD IDEA

$$\text{Spending}_{it} = \beta_0 + \beta_1 \cdot \text{Income}_{it} + U_i + \epsilon_{it}$$

All these U 's correlate with Income:

- Wage
- Investing ability
- Family/Personal fortune
- Ownership of real estate
- Salary negotiation ability
- Ability to “sell” yourself professionally

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Flash quiz:

- (1) What would happen to the regression estimated coefficients if we *did* run a pooled regression?
- (2) Why did we say “all these U 's correlate with Income” rather than simply “all these U 's affect Spending”?

WHAT IF WE LOOKED AT HOW CHANGES IN INCOME FROM ONE YEAR TO THE NEXT TRANSLATE INTO CHANGES IN SPENDING?

$$\text{Spending}_{it} = \beta_0 + \beta_1 \cdot \text{Income}_{it} + U_i + \epsilon_{it}$$

$$\text{Spending}_{it+1} = \beta_0 + \beta_1 \cdot \text{Income}_{it+1} + U_i + \epsilon_{it+1}$$

WHAT IF WE LOOKED AT HOW CHANGES IN INCOME FROM ONE YEAR TO THE NEXT TRANSLATE INTO CHANGES IN SPENDING?

$$\begin{aligned}\text{Spending}_{it} &= \beta_0 + \beta_1 \cdot \text{Income}_{it} + \cancel{U_i} + \epsilon_{it} \\ \text{Spending}_{it+1} &= \beta_0 + \beta_1 \cdot \text{Income}_{it+1} + \cancel{U_i} + \epsilon_{it+1} \\ \hline \Delta_t \text{Spending}_{it} &= \beta_1 \Delta_t \text{Income}_{it} + \epsilon'_{it}\end{aligned}$$

Since U_i doesn't change from one year to the next, a difference in Spending cannot be due to U_i . It must be due to changes in Income.

FIRST DIFFERENCE MODEL

ELIMINATE **FIXED** UNOBSERVED HETEROGENEITIES BY FOCUSING IN HOW THINGS **CHANGE**.

Rather than regressing Y on X , regress $\Delta_t Y$ on $\Delta_t X$

- Where $\Delta_t Y \stackrel{\text{def}}{=} Y_{i,t+1} - Y_{it}$ and $\Delta_t X \stackrel{\text{def}}{=} X_{i,t+1} - X_{it}$

A FIRST DIFFERENCES MODEL WORKS JUST LIKE OLS REGRESSION BUT WITH CHANGES INSTEAD OF ACTUAL VALUES

OLS Regression

- $Y = X\beta + \epsilon$
- $\beta = (X'X)^{-1}X'Y$
- The assumptions of normality, homoskedasticity and independence must be followed by ϵ

First Differences Regression

- $\Delta_t Y = \Delta_t X\beta + \Delta_t \epsilon$
- $\beta = (\Delta_t X' \Delta_t X)^{-1} \Delta_t X' \Delta_t Y$
- The assumptions of normality, homoskedasticity and independence must be followed by $\Delta_t \epsilon$

IS INVESTMENT DETERMINED BY COMPANY VALUE? THE GRUNFELD DATASET

#Pooled regression

```
pooled <- plm(invest ~ value +
capital, index=c("firm", "year"),
data=Grunfeld, model='pooling')
```

#First Differences model

```
fd <- plm(invest ~ value + capital,
index=c("firm", "year"),
data=Grunfeld, model='fd')
```

Dependent variable:			
	invest		
	Pooled (1)	First Differences (2)	
value	0.115*** (0.006)	0.090*** (0.008)	
capital	0.228*** (0.024)	0.291*** (0.051)	
Constant	-38.410*** (8.413)	-1.654 (3.200)	
Observations	220	209	
R2	0.818	0.411	
Adjusted R2	0.816	0.405	
F Statistic	487.284*** (df = 2; 217)	71.756*** (df = 2; 206)	
Note: *p<0.1: **p<0.05: ***p<0.01			

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Dependent variable:			
	invest		
	Pooled (1)	First Differences (2)	
value	0.115*** (0.006)	0.090*** (0.008)	
capital	0.27*** (0.008)	0.25*** (0.008)	
Constant	-3.41*** (8.41)	-3.41*** (8.41)	
Observations	220	209	
R ²	0.818	0.411	
Adjusted R ²	0.816	0.405	
F Statistic	487.284*** (df = 2; 217)	71.756*** (df = 2; 206)	
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Why do we have less
observations in FD
than in PR?

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Dependent variable:			
	invest		
	Pooled (1)	First Differences (2)	
value	0.115*** (0.006)	0.090*** (0.008)	
capital	0.228*** (0.024)	0.291*** (0.051)	
Constant	-38.418*** (5.123)	-6.54 (4.123)	
Observations			209
R2	0.816	0.411	
Adjusted R2	0.816	0.405	
F Statistic	487.284*** (df = 2; 217)	71.756*** (df = 2; 206)	
Note: *p<0.1: **p<0.05: ***p<0.01			

Why are the
coefficient's standard
errors larger in FD than
in PR?

**A TRICK FIRST
DIFFERENCES
REGRESSION
CAN'T DO:**



**ACCOUNT FOR
THINGS THAT DO
NOT CHANGE IN
TIME**
(WHY?)



FIRST DIFFERENCE MODELS CANNOT ACCOUNT FOR TIME-INVARIANT COVARIATES

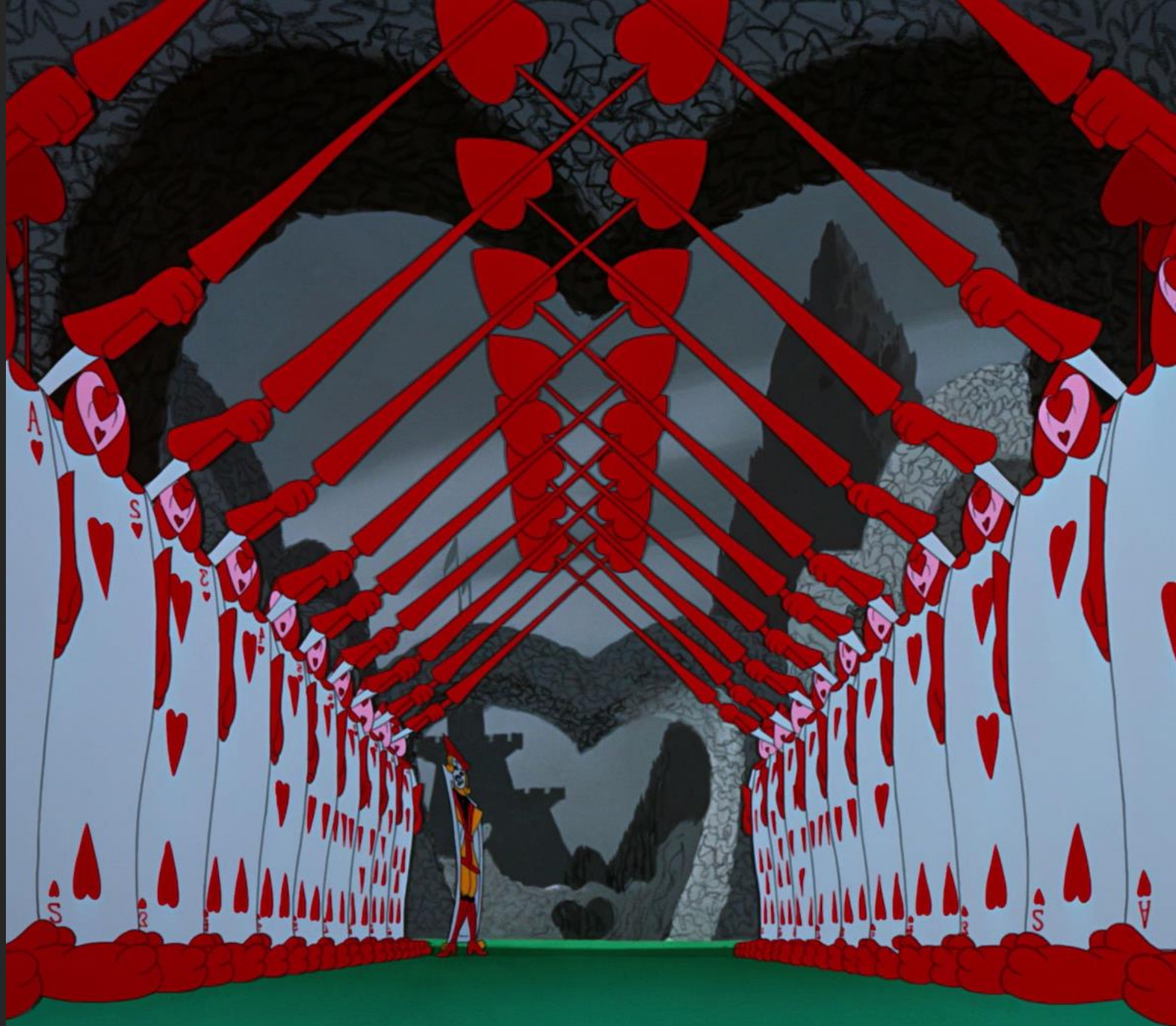
$$\text{Spending}_{it} = \beta_0 + \beta_1 \cdot \text{Income}_{it} + \cancel{\text{Gender}_i} + U_i + \epsilon_{it}$$

$$\text{Spending}_{it+1} = \beta_0 + \beta_1 \cdot \text{Income}_{it+1} + \cancel{\text{Gender}_i} + U_i + \epsilon_{it+1}$$

$$\Delta_t \text{Spending}_{it} = \beta_1 \Delta_t \text{Income}_{it} + 0 + \epsilon'_{it}$$

Since Gender_i doesn't change from one year to the next, it cancels out when we calculate $\Delta_t \text{Spending}_{it}$.
As a result, we cannot estimate the effect that Gender has on Spending.

**FIRST
DIFFERENCES
REGRESSION
REQUIRES THE
 $\Delta_t \epsilon_{it}$ TO BE
SERIALLY
UNCORRELATED
(WHY?)**





**THIS DOES NOT HAPPEN IF THE ERRORS THEMSELVES
ARE SERIALY UNCORRELATED**

If errors are uncorrelated in the true relationship, then a First Differences model does not satisfy the assumption of serially uncorrelated residuals. The First Difference model is not a good model when the errors in the true relationship are serially uncorrelated.



PROOF

Problem Statement:

The true relationship is

$$y_{it} = X_{it}\beta + U_i + \epsilon_{it}$$

Suppose idiosyncratic errors are serially uncorrelated and homoskedastic. This implies, for all t :

$$\text{Cov}(\epsilon_{t+1}, \epsilon_t) = 0 \text{ (No serial correlation)}$$

$$\text{Cov}(\epsilon_t, \epsilon_t) = \sigma^2 \text{ (Homoskedasticity)}$$

In a First Differences model, the errors will be $\Delta\epsilon_{it}$. Are these $\Delta\epsilon_{it}$ also serially uncorrelated? In other words,

Is $\text{Cov}(\Delta\epsilon_{t+1}, \Delta\epsilon_t)$ also zero?

PROOF

$$\begin{aligned}\text{Cov}(\Delta\epsilon_{t+1}, \Delta\epsilon_t) &= \text{Cov}(\epsilon_{t+1} - \epsilon_t; \epsilon_t - \epsilon_{t-1}) \\ &= \underbrace{\text{Cov}(\epsilon_{t+1}; \epsilon_t)}_0 + \underbrace{\text{Cov}(\epsilon_{t+1}; \epsilon_{t-1})}_0 - \underbrace{\text{Cov}(\epsilon_t; \epsilon_t)}_{\sigma^2} + \underbrace{\text{Cov}(\epsilon_{t+1}; \epsilon_{t-1})}_0 = \sigma^2\end{aligned}$$

So

$$\text{Cov}(\Delta\epsilon_{t+1}, \Delta\epsilon_t) \neq 0$$

Meaning that if errors are uncorrelated in the true relationship, then a First Differences model does not satisfy the assumption of serially uncorrelated residuals. The First Difference model is *not* a good model when the errors in the true relationship are serially uncorrelated.

If errors are uncorrelated in the true relationship, then a First Differences model does not satisfy the assumption of serially uncorrelated residuals. The First Difference model is not a good model when the errors in the true relationship are serially uncorrelated.

The First Difference model works well when errors in the true relationship obey a **random walk**.



ERRORS ARE SAID TO FOLLOW A RANDOM WALK WHEN

$$\epsilon_{t+1} = \epsilon_t + v_t$$

$$v_t \sim N(0; \sigma^2)$$

$$\text{COV}(v_t; v_s) = 0 \quad \forall t \neq s$$



THIS WORKS BECAUSE...

$$\epsilon_{t+1} = \epsilon_t + \nu_t$$

↓

$$\Delta_t \epsilon_t = \nu_t$$

Which are homoscedastic and serially uncorrelated by hypothesis, thus satisfying the requirements of OLS regression.



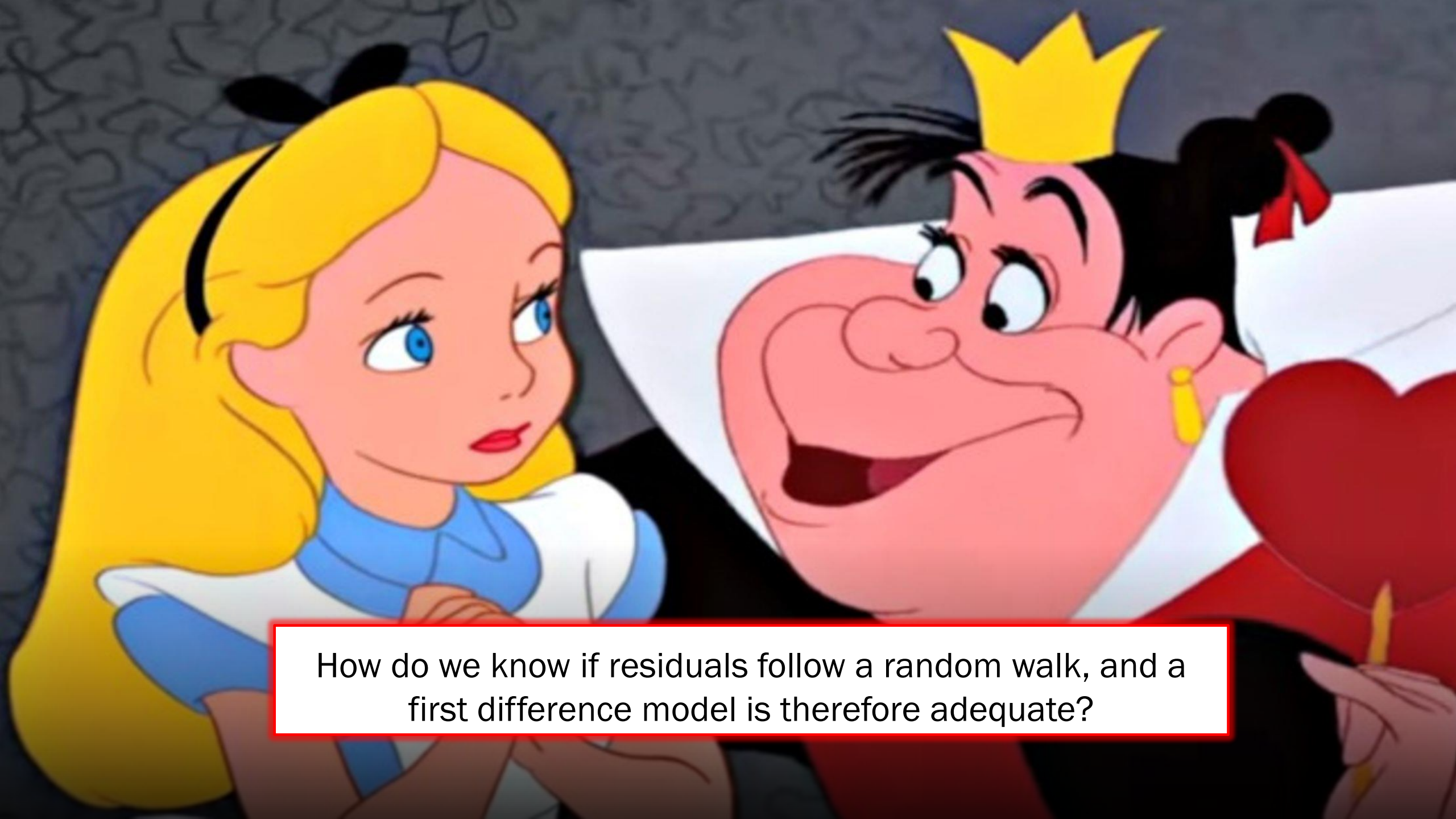
ONE THING YOU SHOULD KNOW BEFORE TAKING A RANDOM WALK...

$$\epsilon_{t+1} = \epsilon_t + \nu_t$$

Random Walks exhibit **long-term dependencies**. Because the effect of a past ϵ_t never vanishes...

Does this make theoretical sense in your research problem?





How do we know if residuals follow a random walk, and a first difference model is therefore adequate?

HOW DO WE KNOW IF ERRORS FOLLOW A RANDOM WALK?

INTUITION

1. Regress $\Delta\epsilon_t$ on $\Delta\epsilon_{t-1}$ i.e.

$$\Delta\epsilon_t = \rho\Delta\epsilon_{t-1} + v_t$$
$$v_t \sim N(0; \sigma^2)$$

2. Test if linear coefficient is statistically significant i.e.

$$\begin{cases} H_0: \rho = 0 \\ H_a: \rho \neq 0 \end{cases}$$

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Tricky question:

Why do we test $\Delta\epsilon_t$,
rather than ϵ_t itself?

HOW DO WE KNOW IF ERRORS FOLLOW A RANDOM WALK?

THE DURBIN-WHATSON STATISTIC

1. Obtain $\Delta\epsilon_t$ and $\Delta\epsilon_{t-1}$
2. Calculate the Durbin-Whatson Statistic

$$DW = \frac{\sum_t (\Delta\epsilon_t - \Delta\epsilon_{t-1})^2}{\sum_t (\Delta\epsilon_t)^2}$$

3. Compare with critical values proper from this Statistic. As a rule of thumb,

$$DW \approx 2(1 - \rho_{\Delta\epsilon_t, \Delta\epsilon_{t-1}})$$

So if $\Delta\epsilon_t$ and $\Delta\epsilon_{t-1}$ are serially uncorrelated,

$$DW \approx 2.$$

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Flash quiz:

What are the maximum and minimum values for the DW statistic?

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Flash quiz:

A rule of thumb says that $DW < 1$ means trouble.

To what value of ρ does this correspond?

PROOF THAT $D \approx 2(1 - \rho_{\Delta\epsilon_t, \Delta\epsilon_{t-1}})$

$$DW = \frac{\sum_t (\Delta\epsilon_t - \Delta\epsilon_{t-1})^2}{\sum_t (\Delta\epsilon_t)^2} = \frac{\sum_t (\Delta\epsilon_t)^2}{\sum_t (\Delta\epsilon_t)^2} - 2 \frac{\sum_t \Delta\epsilon_t \Delta\epsilon_{t-1}}{\sum_t (\Delta\epsilon_t)^2} + \frac{\sum_t (\Delta\epsilon_{t-1})^2}{\sum_t (\Delta\epsilon_t)^2}$$

Note that $\sum_t (\Delta\epsilon_t)^2 \approx \sum_t (\Delta\epsilon_{t-1})^2 \approx \sqrt{\sum_t \Delta\epsilon_t^2 \sum_t \Delta\epsilon_{t-1}^2}$. So

$$DW \approx \underbrace{\frac{\sum_t (\Delta\epsilon_t)^2}{\sum_t (\Delta\epsilon_t)^2}}_1 - 2 \frac{\sum_t \Delta\epsilon_t \Delta\epsilon_{t-1}}{\underbrace{\sqrt{\sum_t \Delta\epsilon_t^2 \sum_t \Delta\epsilon_{t-1}^2}}_{\rho_{\Delta\epsilon_t, \Delta\epsilon_{t-1}}}} + \underbrace{\frac{\sum_t (\Delta\epsilon_{t-1})^2}{\sum_t (\Delta\epsilon_{t-1})^2}}_1$$

$$DW \approx 2 - 2\rho_{\Delta\epsilon_t, \Delta\epsilon_{t-1}}$$

$$DW \approx 2(1 - \rho_{\Delta\epsilon_t, \Delta\epsilon_{t-1}})$$

KEY TAKEAWAYS

1. First Difference Models are a way to eliminate the unobserved effect U_i in panel data regression
2. In First Difference models, rather than using X_{it} to explain y_{it} , we use changes in X_{it} to explain changes in y_{it} .
3. In other words, we regress $\Delta_t y_{it}$ on $\Delta_t X_{it}$
4. First Difference models work well when the idiosyncratic error of y_{it} follows a Random Walk. Unfortunately, we don't see the values of the idiosyncratic errors. We only see their *deltas*
5. One way to test if ϵ_{it} follows a random walk is to regress $\Delta_t \epsilon_{it}$ on $\Delta_t \epsilon_{it-1}$ (no intercept needed) and see if the coefficient is statistically indistinguishable from zero.
6. Another way is to use the Durbin-Whatson Statistic. As a rule of thumb, it should ideally be close to 2.

