Computational Science

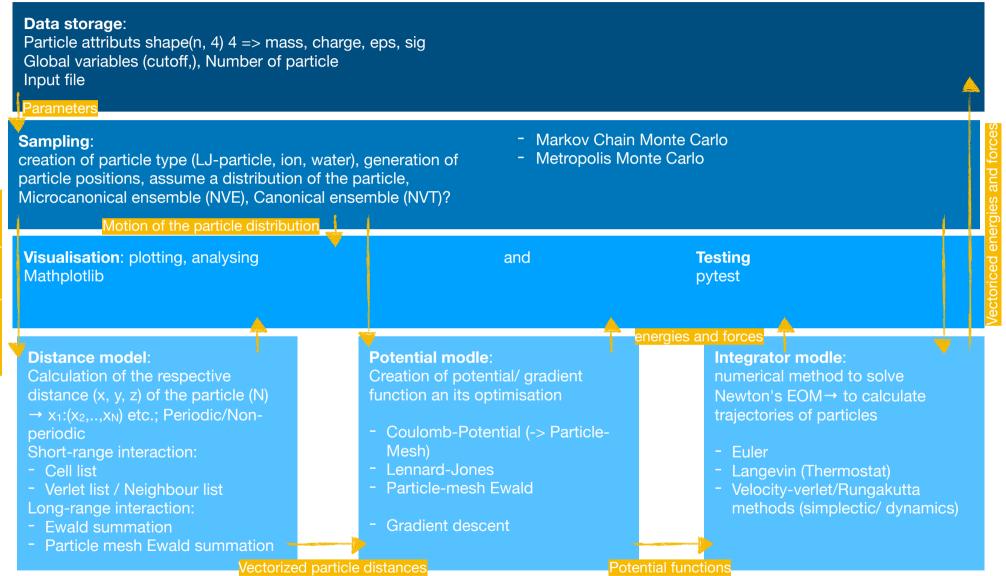
Molecule Dynamic simulation

Task:

Implementation of an MD-simulation for Lennard-Jones particles/ ions/ water in 2D and 3D. →interaction between the particles an thereby causes spatial motion by iterativ calculations

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Workflow

So, 13.01.19

- √ finale aufgaben Verteilung
- √ modules diskutieren
- Labeling festlegen (formate, Bezeichnungen, Abkürzungen, Parameter)
- ✓ Input und Output formate und Benennungen definieren
- ✓ Ziele festlegen für Fortschritt bis zum nächsten Treffen
- Parallelization strategies ? Domain decomposition method
- (Distribution of system data for parallel computing

Selbstständige Arbeitsphase

- Module fertig implementieren

Sa, 19.01.19

- √ Fortschritte präsentieren
- √ Fehler Probleme diskutieren
- testing diskutieren
- Input Beispiele
- Labeling festlegen (formate, Bezeichnungen, Abkürzungen, Parameter)
- ✓ Erste Ideen Wie schreiben wir alles zusammen
- Parallelization strategies ? Domain decomposition method
- ✓ Erster primitiver Testlauf

Arbeitsphase

- Visualisierung, testing
- Sampling optimieren (diffrend properties for particles?)
- Integrator timing, visualisation closed-, pbc- system, grid?
- Minimazation
- Ewald- summation

- Create classes and Bild the structure of the hole code
- Implementing grid ?

Fr/Sa/So, ???

- input examplesCombine all modulesDiscuss extra features
 - Water
 - Parallelisation ?

Overview: Aufgabe für (Person): Phillip (P), Felix (F), Malte (M), Joana (J)

MODUL	INPUT	TASK	OUTPUT	TESTING	VISUALISATION
DATA STORAGE		Configuration ?			
POTENTIAL (F)	C: - Distance shape(nxn), - charge array(n), - ε, σ(nx1), forces LJ: - dis(nxn), - ε, σ(nx1) H: - Box dim (x,y,z min and x,y,z max), - Positionen: r (einteilchen or Mehrteilchen potential), r_0= xmax/2, k???	Particle-particle: - Coulomb - LJ Global potential: - Harmonic	C: - potential(nx1) or (Gesamtpotential for each particle) - gradient shape(nx3) LJ: - potential(nx1) H: Potential	 energy consistency Use simple potential with work and compare 	
SAMPLING (P)	 N = number of particle for each particle charge, mass, ε, σ (nx1), k (federkonstnat) Creating a particle box, pbc, non pbc GLOBAL attributs: ??? 	configuration: Random then: - Markov Chain Monte Carlo - Metropolis Monte Carlo	Position shape(nxdim)Velocity shape(nxdim)	-	distribution of particle plotten

MODUL	INPUT	TASK	OUTPUT	TESTING	VISUALISATION
DISTANCE (P)	- Position shape(nxdim)	⇒box, pbc, non pbc	- dist(nxn)		
INTEGRATOR (J)	 position shape(nxdim), velocity shape(nxdim), attribute shape(n, #numb of attributes) gradient shape(n,dim), Time step (int) Total time (int) Open or close system box, pbc, non pbc global attributes ? 	Euler Velocity Verlet Langevin	 position(size, n, dim) velocity(size, n, dim) Accerelation(size, n, dim) dim) 		
Optimization (M)	??	gradient descent,conjugate gradient,Newton methods			

Information about modules

DATA STORAGE MODULE

????

SAMPLING MODULE

Initial configuration (markow chain, Particles equispaced in a box; 2D/3D)

MONTE CARLO

INPUT	ОИТРИТ	
initial configuration r(0), potential, size, beta, step	Position r, potential(r)	

- (1) Start with initial configuration $\mathbf{r}^{(0)}$ and set k = 0.
- (2) Fork=1,...,K:
 - (a) Sample random vector $\eta \in \mathbb{R}^N$ with $\eta_i \sim N(0, \sigma^2)$, i.e. an isotropic multivariate Gaussian distribution/ or function with variances σ^2 .
 - (b) Propose new configuration $\mathbf{r'} = \mathbf{r}^{(k)} + \eta$.
 - (c) Accept new configuration with probability $p_{\rm acc} = \min \left\{ 1, \exp \left(\frac{\phi({\bf r}') \phi({\bf r}^k)}{k_B T} \right) \right\}$

If accepted, set $\mathbf{r}^{(k+1)} = \mathbf{r}'$, otherwise $\mathbf{r}^{(k+1)} = \mathbf{r}^{(k)}$.

Markov Chain Monte Carlo

- create samples from a possibly multi-dimensional continuous random variable, with probability density proportional to a known function.
- these samples can be used to evaluate an integral over that variable, as its expected value or variance.
- in Markov chain Monte Carlo methods are autocorrelated.
- a equilibrium distribution which is proportional to the function given.

Metropolis Monte Carlo

- Konfigurationen gemäß ihrer Boltzmann-Wahrscheinlichkeit + einfachen arithmetischen Durchschnitt
- zuerst eine zufällige Bewegung ausgeführt
- dann die Boltzmann-Wahrscheinlichkeit einer solchen Bewegung ausgewertet wird und die Wahrscheinlichkeit mit einer Zufallszahl verglichen wird.
- Ist die Boltzmann-Wahrscheinlichkeit der Bewegung größer als die Zufallszahl, wird die Bewegung akzeptiert. Andernfalls wird das System auf seine ursprüngliche Konfiguration zurückgesetzt.

Vor- und Nachteile: ?

- not interested in the statistics of momenta anymore, so we integrate them out
- · sampling the probability density.
- simple version of Monte Carlo is Metropolis Monte Carlo

DISTANCE MODULE

INPUT	OUTPUT	
Position r, potential(r)	Matrix distances x1 x2 xN	

- calculation of distances between particles in MD Energy and force Calculation
- Introduce a cutoff and considering only the nearest neighbours within the radius; for LJ.Potential rc= 2.5 σ
 - Reduce effort: loop over all pairs of particle (i,j) = (j,i)

Verlet list

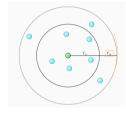
- For each particle i, a Verlet list hat lists all other particles j within a smaller distance than rc+ rs
- Update the neighbour list every Ns tilmestep
- $r_s > N_s v_{\text{tVD}} \delta t$ type speed of particles
- Choice between hash table and array

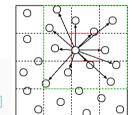
Cell-linked list: get complexity down

- domain into cells with an edge length greater than or equal to the cut-off radius of the interaction to be computed
- particles sorted into cells and the interactions are computed between particles in the same or neighbouring cells
- Needed array HEAD and array LIST
- Think about parallelisation

Cell decomposition approach

- partition the domain into cells and build a cell-linked list
- Verlet list by searching only in the neighbouring cells instead of considering all particles
- Dirty flag?





POTENTIAL MODULE

description how the particles will interact in the simulation; two main approximations: Born-Oppenheimer approximation (dynamics of electrons), point particles that follow classical Newtonian dynamics (nuclei, which are much heavier than electrons)

Coulomb-Potential (-> Particle-Mesh)

$$\phi_i(\mathbf{r}) = \frac{1}{4\pi\varepsilon_0} \frac{q_i}{|\mathbf{r} - \mathbf{r_i}|}$$

$$\frac{1}{4\pi\varepsilon_0} = c_0^2 \mu_0 = \frac{c_0^2 \mu_0}{c_0^2 + c_0^2} = c_0^2 \times 10^{-7} \,\mathrm{H \cdot m^{-1}} = 8.987 \times 10^9 \,\mathrm{Nm^2 C^{-2}}$$

Lennard-Jones

Particle-mesh Ewald

Ewald summation

Usage: standard method for calculating long-range interactions in periodic systems

- rapid convergence of the energy compared with that of a direct summation: high accuracy and reasonable speed when computing long-range interactions

INTEGRATOR MODULE

See notebooks:

Euler

Langevin

Velocity-verlet

MINIMISATION

???

Lecture notes

line_profiler Piecewise @njit

Recent body: not can chance its structure, shake or radle Hard spheres

Ewald analyticaly fouler (strait forward)
Particle mesh a numerical fouler (corektli sparred particle)

Gommecs

Präsentation