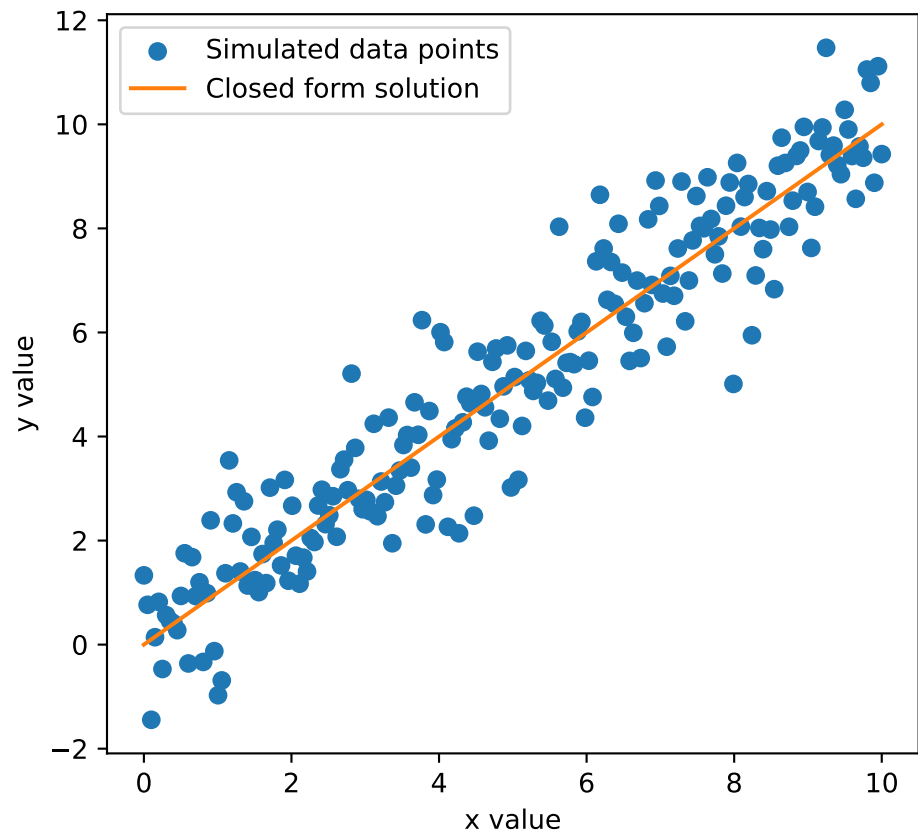


Linear + Gaussian noise data



Stochastic loss vs theoretical value

