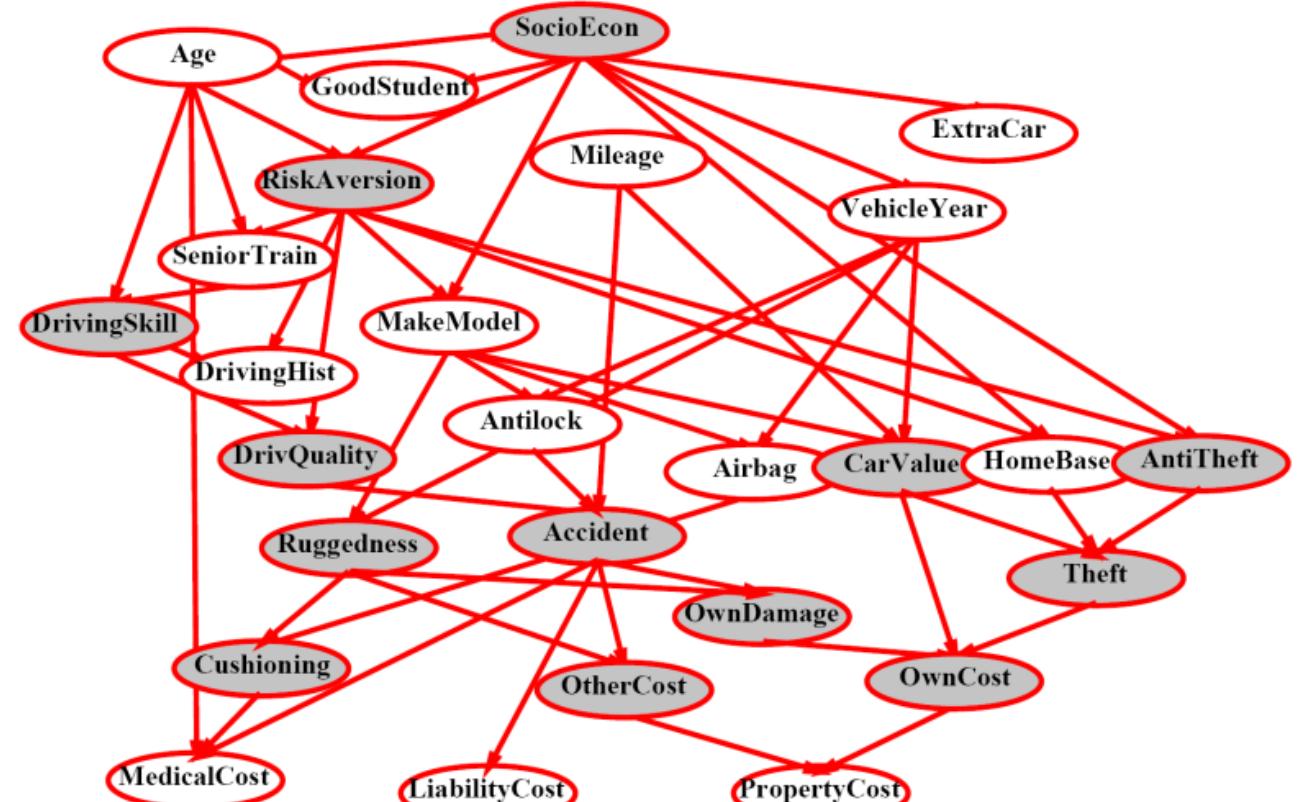


CSCI 3202: Intro to Artificial Intelligence

Lecture 21 & 22: Introduction to Bayesian Networks

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Uncertainty

→ Probabilistic reasoning gives us a framework for managing uncertain beliefs and knowledge.

In general:

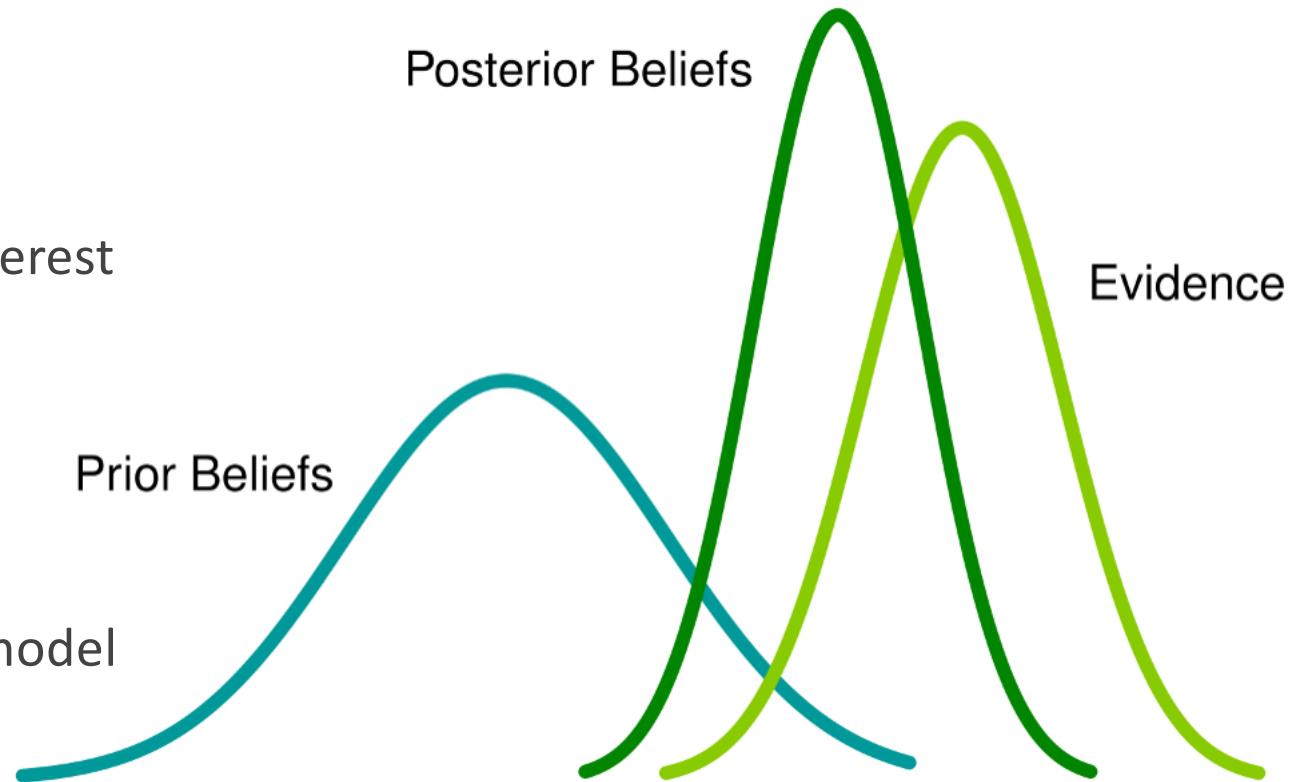
- **Observed variables (evidence):** Agent knows certain things about the state of the world (e.g. sensor readings or symptoms)
- **Unobserved variables:** Agent needs to reason about other aspects (e.g. where an object is or what disease is present)
- **Model:** Agent knows something about how the known variables relate to the unknown variables

Bayesian Reasoning

The whole Bayesian statistical framework can be summarized as follows:

- What is your process of interest?
- Get **data** (evidence) for your process of interest
- Build a **model** $\eta(\theta)$ of this process
Depends on uncertain parameters θ
- Formalize your *a priori* knowledge of the model parameters θ in **prior distributions**, $P(\theta)$
- **Update** your prior knowledge using the match between your model and the data

$$p(y|x) = \frac{p(x|y) p(y)}{p(x)} \begin{matrix} \leftarrow \text{prior} \\ \sim \text{posterior} \end{matrix} \quad \leftarrow \text{evidence}$$



Joint Distributions

coin flip : $\frac{1}{2}$ 

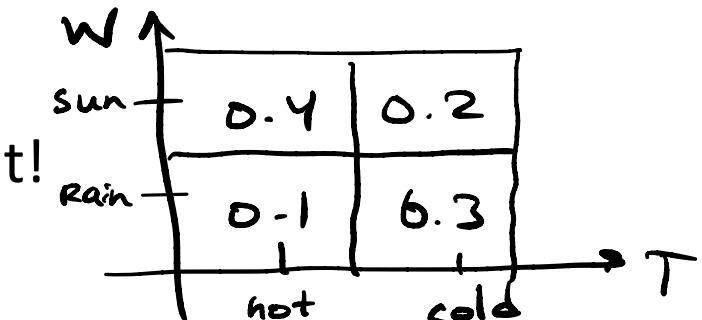
- A *joint distribution* over a set of random variables: X_1, X_2, \dots, X_n specifies a real number for each assignment (or *outcome*):

$$P(X_1 = x_1, X_2 = x_2, X_3 = x_3, \dots, X_n = x_n) \text{ or equivalently: } P(x_1, x_2, \dots, x_n)$$

$$P(\dot{T}, \dot{W})$$

- Must obey: $P(x_1, x_2, \dots, x_n) \geq 0$ and
 - $\sum_{(x_1, x_2, \dots, x_n)} P(x_1, x_2, \dots, x_n) = 1$
- all probabilities are between 0 and 1
- Size of distribution if n variables with domain sizes d?
 - For all but the smallest distributions, impractical to write out!

T	W	P
hot	sun	0.4
hot	rain	0.1
cold	sun	0.2
cold	rain	0.3



Probability Models

- A probability model is a joint distribution over a set of random variables
- Probability models:
 - (Random) variables with domains
 - Assignments are called *outcomes* ↪
 - Joint distributions: say whether assignments (outcomes) are likely
 - *Normalized*: sum to 1.0 ↪
 - Ideally: only certain variables directly interact

Distribution over T,W

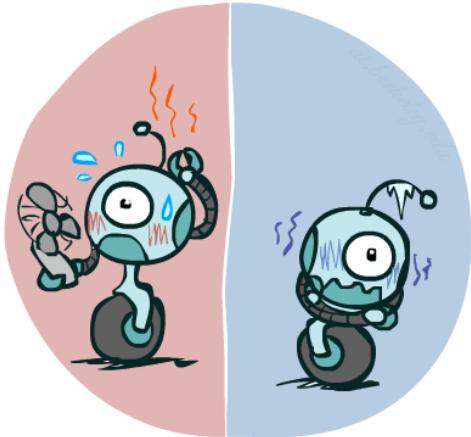
T	W	P
hot	sun	0.4
hot	rain	0.1
cold	sun	0.2
cold	rain	0.3



Probability Distributions

- Associate a probability with each value

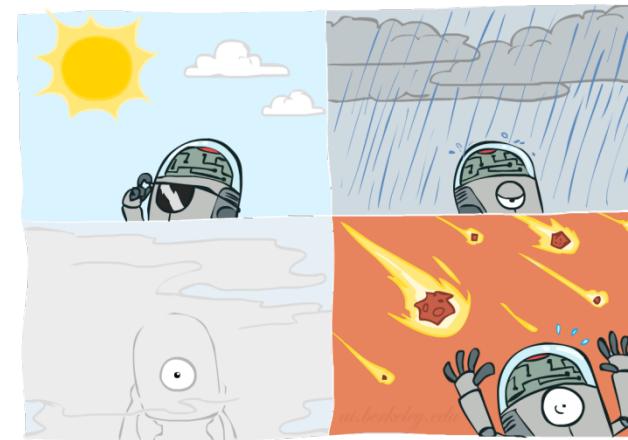
- Temperature:



$P(T)$

T	P
hot	0.5
cold	0.5

- Weather:



$P(W)$

W	P
sun	0.6
rain	0.1
fog	0.3
meteor	0.0

Marginal Distributions

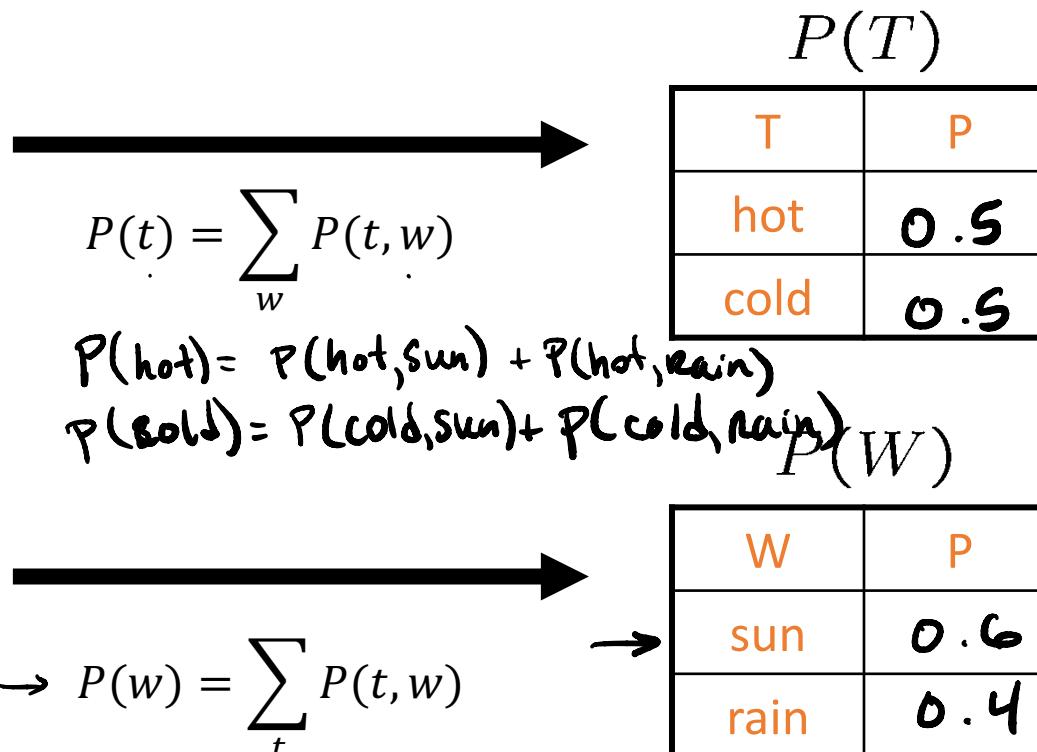
- Marginal distributions are sub-tables which eliminate variables
- Marginalization (summing out): Combine collapsed rows by adding

$$T = \{ \text{hot}, \text{cold} \}$$

$$W = \{ \text{sun}, \text{rain} \}$$

$P(T, W)$

T	W	P
hot	sun	0.4
hot	rain	0.1
cold	sun	0.2
cold	rain	0.3



e.g. $P(X_1 = x_1) = \sum_{x_2} P(X_1 = x_1, X_2 = x_2)$

Probability Models

Example:

- $P(+x, +y) ? \quad 0.2$

- $P(+x) ? \quad 0.2 + 0.3 = 0.5$

- $P(-y \text{ OR } +x) ? \quad 0.6$

$$P(X, Y)$$

X	Y	P
+x	+y	0.2
+x	-y	0.3
-x	+y	0.4
-x	-y	0.1

Marginal Distributions

Exercise

$P(X, Y)$

X	Y	P
+x	+y	0.2
+x	-y	0.3
-x	+y	0.4
-x	-y	0.1

$$P(x) = \sum_y P(x, y)$$

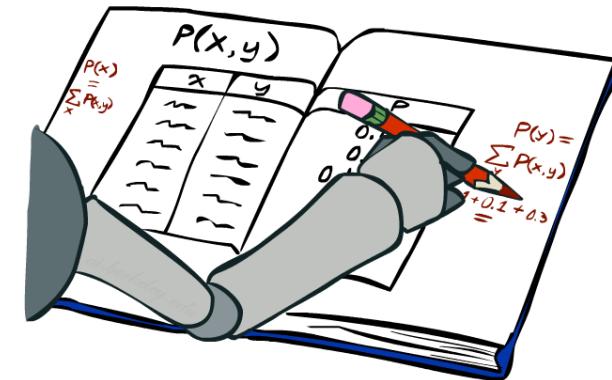
$$P(y) = \sum_x P(x, y)$$

$P(X)$

X	P
+x	
-x	

$P(Y)$

Y	P
+y	
-y	



Conditional Probabilities

$P(X, Y)$

X	Y	P
+x	+y	0.2
+x	-y	0.3
-x	+y	0.4
-x	-y	0.1

- $P(+x \mid +y) ?$

$$P(x \mid +y) \begin{bmatrix} 0.2 \\ 0.4 \end{bmatrix} \rightarrow$$

$$P(+x \mid +y) = \frac{P(+x, +y)}{P(+y)}$$

$$= \frac{0.2}{0.2+0.4} = \frac{1}{3}$$

- $P(-x \mid +y) ?$

$$= \frac{P(-x, +y)}{P(+y)} = \frac{0.4}{0.2+0.4} = \frac{2}{3}$$

- $P(-y \mid +x) ?$

$$= \frac{P(-y, +x)}{P(+x)} = \frac{0.3}{0.5} = .6$$

Conditional Distributions

- Conditional distributions are probability distributions over some variables given fixed values of others

Conditional Distributions

$P(W|T)$

W	P
sun	.8
rain	.2

$P(W|T = hot)$

W	P
sun	.8
rain	.2

$P(W|T = cold)$

W	P
sun	
rain	

$$P(\text{sun} | T = \text{hot}) = \frac{P(\text{sun, hot})}{P(\text{hot})}$$
$$= \frac{0.4}{0.4 + 0.1}$$
$$=$$

Joint Distribution

$P(T, W)$

T	W	P
hot	sun	0.4
hot	rain	0.1
cold	sun	0.2
cold	rain	0.3

*

~~~~~  
exercise

# Independence

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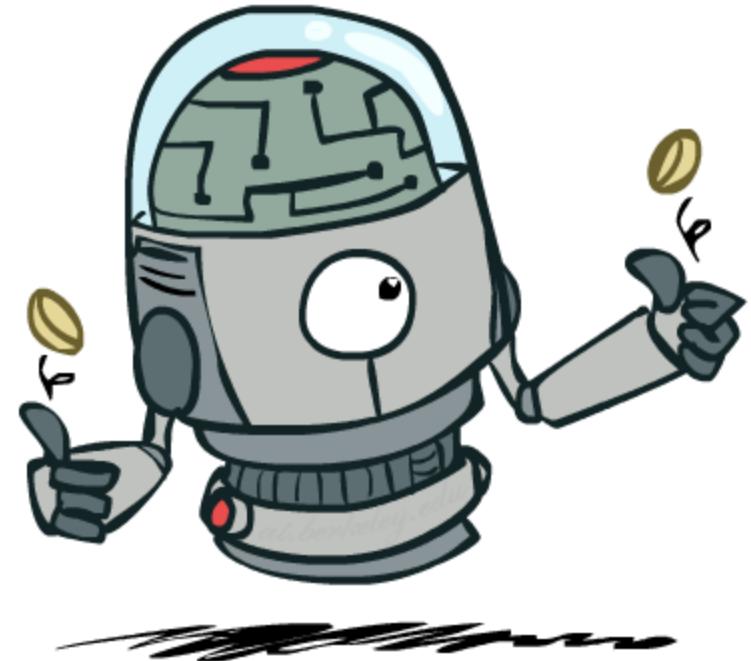
- Two variables are *independent* if:

$$\forall x, y : P(x, y) = P(x)P(y)$$

- This says that their joint distribution *factors* into a product two simpler distributions
- Another form:

$$\forall x, y : \underbrace{P(x|y)}_{= P(x)}$$

- Independence is a simplifying *modeling assumption*
  - *Empirical* joint distributions: at best “close” to independent
  - What could we assume for {Weather, Traffic, Cavity, Toothache}?



# Independence

$T, W$  *not independent*

$P_1(T, W)$

| T    | W    | P   |
|------|------|-----|
| hot  | sun  | 0.4 |
| hot  | rain | 0.1 |
| cold | sun  | 0.2 |
| cold | rain | 0.3 |

$P(T)$

| T    | P   |
|------|-----|
| hot  | 0.5 |
| cold | 0.5 |

$P(W)$

| W    | P   |
|------|-----|
| sun  | 0.6 |
| rain | 0.4 |

$$P_1(T, W) = P(T) P(W)$$

$$= (0.5)(0.6)$$

$$= 0.3$$

If we have independence

of  $T$  and  $W$

$$\Rightarrow p(T, W) = p(T) \cdot p(W)$$

$P_2(T, W)$

| T    | W    | P   |
|------|------|-----|
| hot  | sun  | 0.3 |
| hot  | rain | 0.2 |
| cold | sun  | 0.3 |
| cold | rain | 0.2 |

This distribution assumes  $T, W$  are independent.

# Conditional Independence

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- Unconditional (absolute) independence very rare (why?)
- *Conditional independence* is our most basic and robust form of knowledge about uncertain environments.

- X is conditionally independent of Y given Z

$$X \perp\!\!\!\perp Y \mid Z$$

if and only if:  $\forall x, y, z : P(x, y|z) = P(x|z)P(y|z)$  ↪

or, equivalently, if and only if  $\forall x, y, z : P(x|z, y) = P(x|z)$

↑      ↪ easier  
                to compute

# Bayesian Networks

## Directed Acyclic Graph

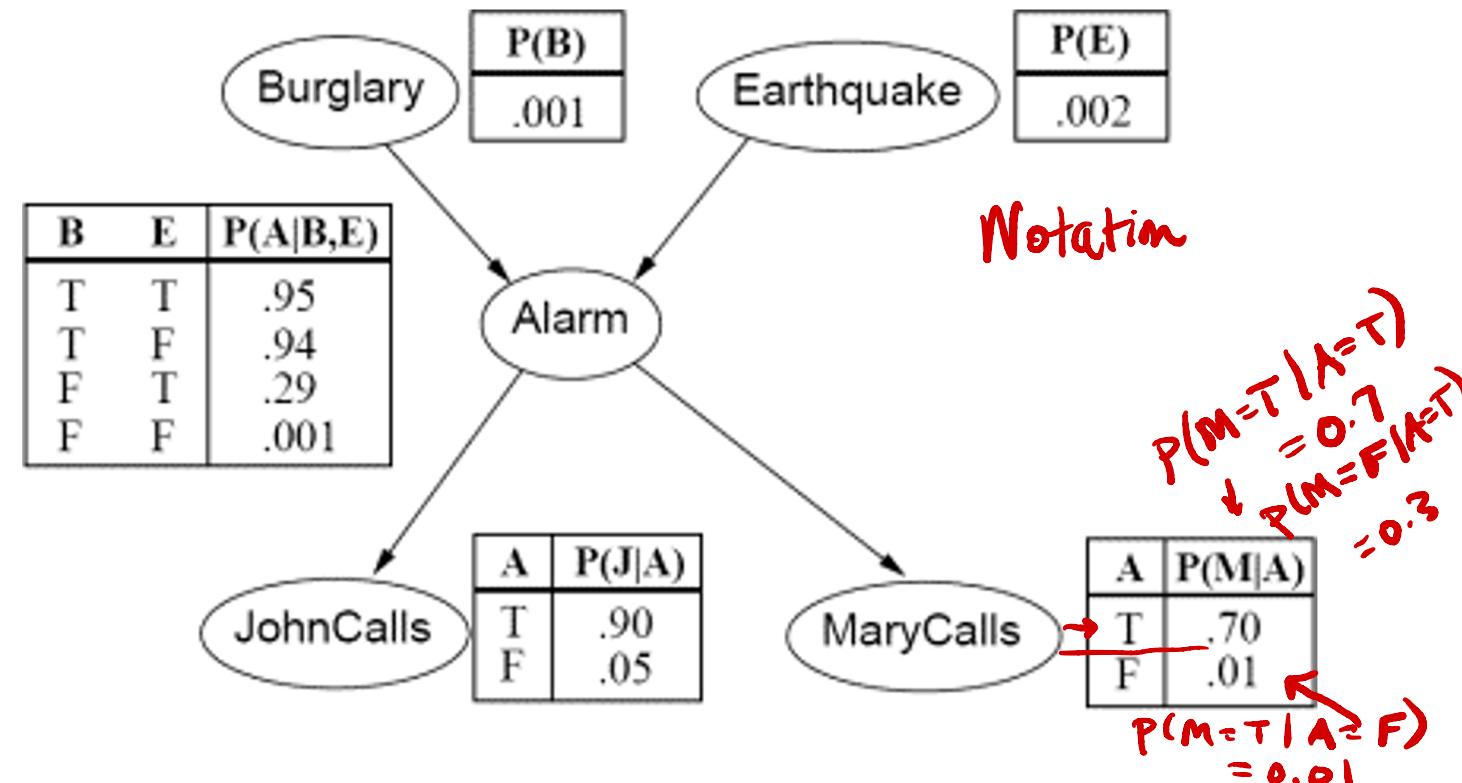
The point of Bayes nets is to represent full joint probability distributions, and

to encode an interrelated set of conditional independence/probability statements

Full Joint Distribution

$$P(B, E, A, J, M) = P(M | B, E, A, J) \overbrace{P(B, E, A, J)}^{\text{Chain rule}}$$

- Consists of nodes (events), and
- conditional probability tables (CPTs), relating those events
- Describe how variables interact locally
- Chain together local interactions to estimate global, indirect interactions



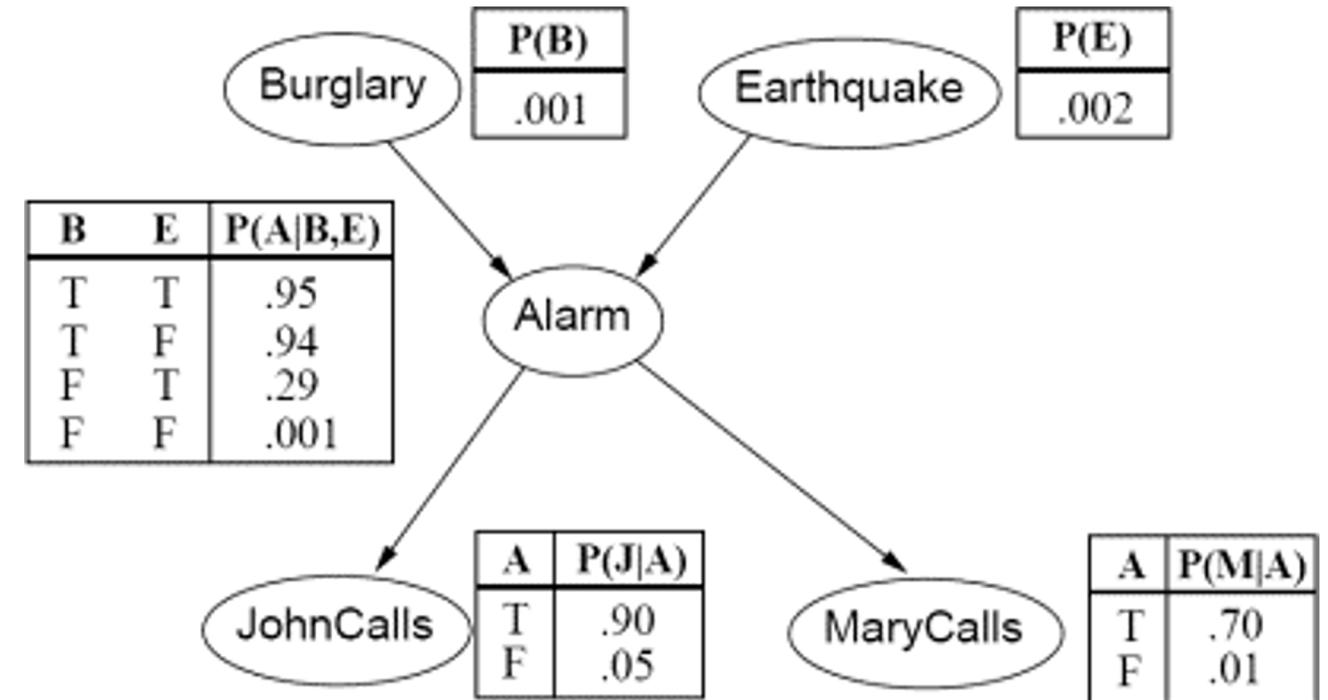
# Bayesian Networks

The point of Bayes nets is to represent full joint probability distributions, and

to encode an interrelated set of conditional independence/probability statements

Notations:  $P(A|B,E) = P(+A | +B, +E)$   
 $= P(A=True | B=T, E=T)$

- Consists of nodes (events), and
- conditional probability tables (CPTs), relating those events
- Describe how variables interact locally
- Chain together local interactions to estimate global, indirect interactions



# Bayesian Networks

The point of Bayes nets is to **represent full joint probability distributions, and**

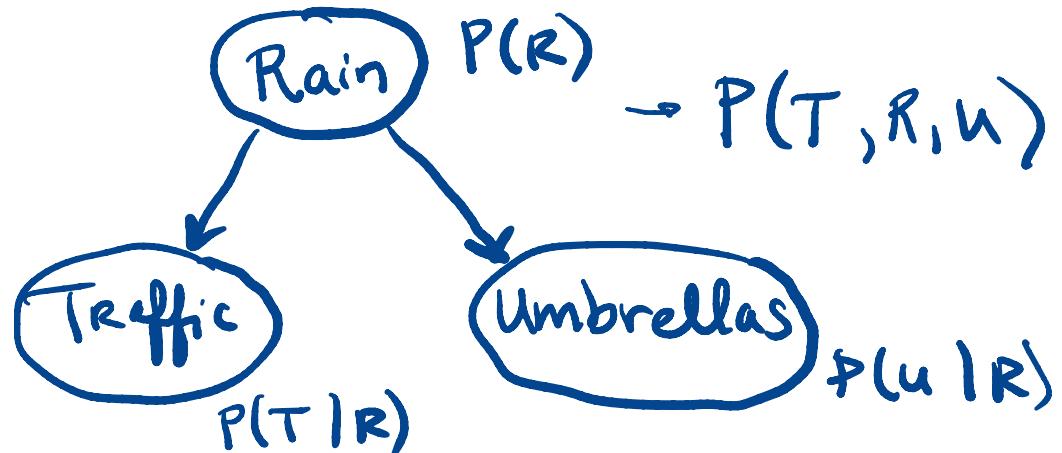
to encode an interrelated set of **conditional independence/probability statements**

Example: Represent the full joint distribution for  $P(\text{Traffic}, \text{Rain}, \text{Umbrella})$

Trivial decomposition:  $P(T, R, u) = P(T|R, u) P(R, u)$

$$= P(T|R, u) P(R|u) P(u)$$

Conditional independence:



$$P(T, R, u) = P(T|R, u) P(R, u)$$

$$= \underline{P(T|R, u)} \underbrace{P(u|R) P(R)}_{\text{Trivial decomposition}}$$

$$= \underline{P(T|R)} P(u|R) P(R)$$

$T \perp\!\!\!\perp u | R$

Trivial  
decomposition

conditional  
independence

# Bayesian Networks

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The point of Bayes nets is to **represent full joint probability distributions, and**  
to encode an interrelated set of **conditional independence/probability statements**

Example (continued): Represent the full joint distribution for  $P(\text{Traffic}, \text{Rain}, \text{Umbrella})$

Trivial decomposition:

Conditional independence:

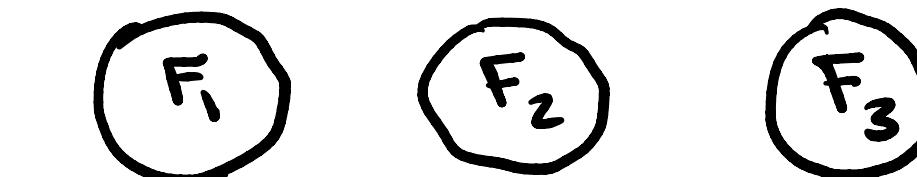
- ♦ Bayes nets (graphical models) help us compactly express conditional independence assumptions/relationships.

# Bayesian Networks

Example: Coin flips

Suppose we flip a coin 3 times

↑  
Make  
a Bayes  
net

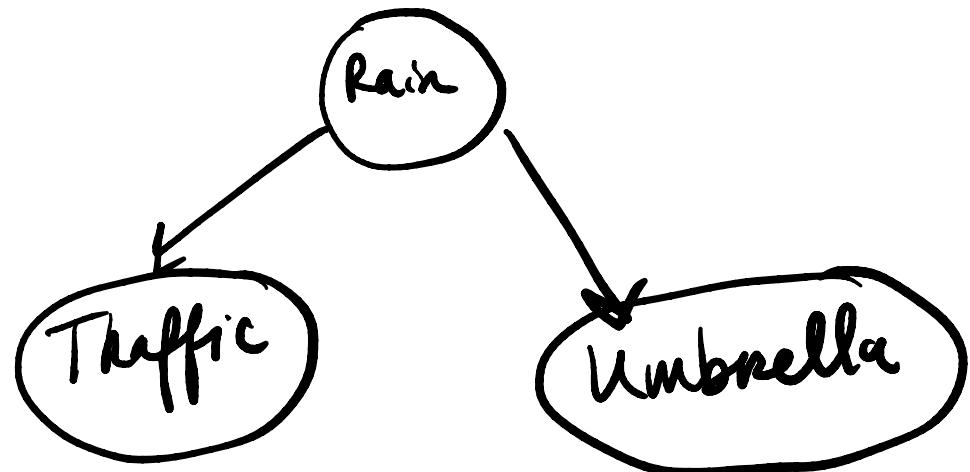


$$P(F_1 = H) = \frac{1}{2}$$

no edges indicates independence  
of the nodes ,

# Bayesian Networks

Example: ~~sunrises~~ Traffic, Rain, Umbrella



This structure indicates that  $T \perp\!\!\!\perp U \mid R$

Reminder:

$X$  and  $Y$  are **independent** if  $\forall x \forall y P(x, y) = P(x) P(y)$

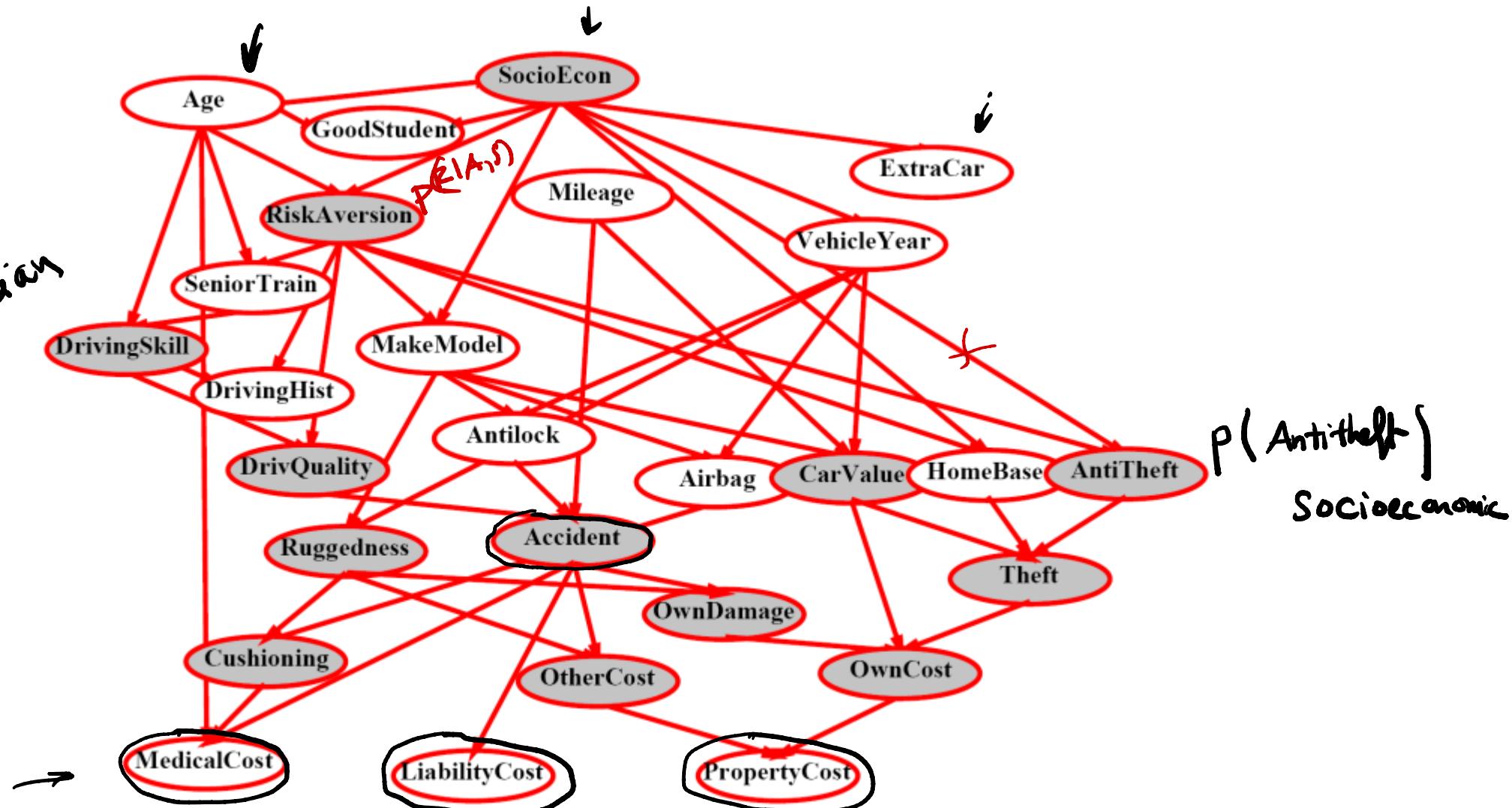
$$X \perp\!\!\!\perp Y$$

$X$  and  $Y$  are **conditionally independent** given  $Z$  if  $\forall x \forall y \forall z P(x, y \mid z) = P(x \mid z) P(y \mid z)$

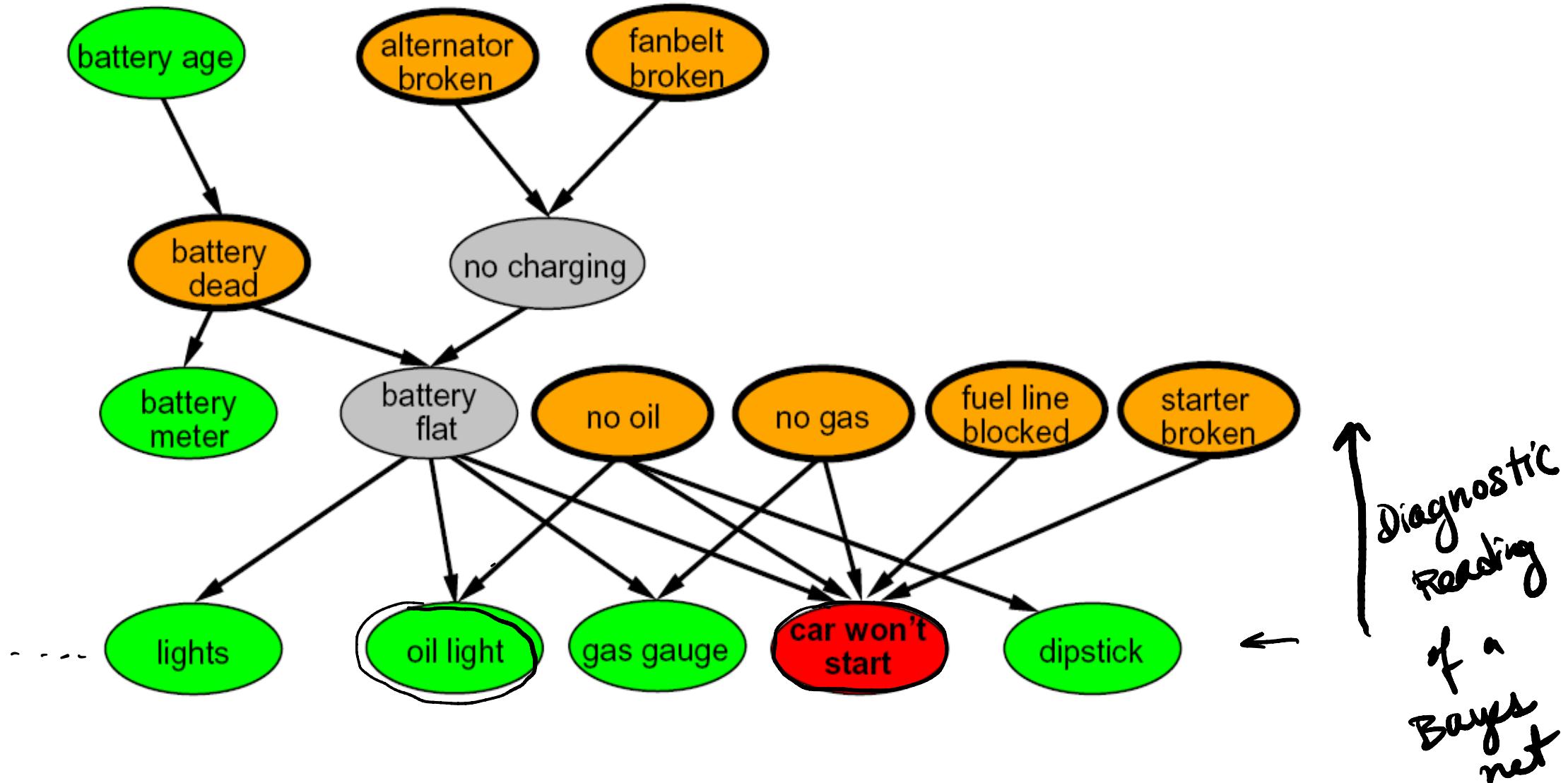
$$X \perp\!\!\!\perp Y \mid Z$$

# Graphical Model Notation

Downward  
Example of  
using network a Bayesian  
to make  
predictions



# Graphical Model Notation



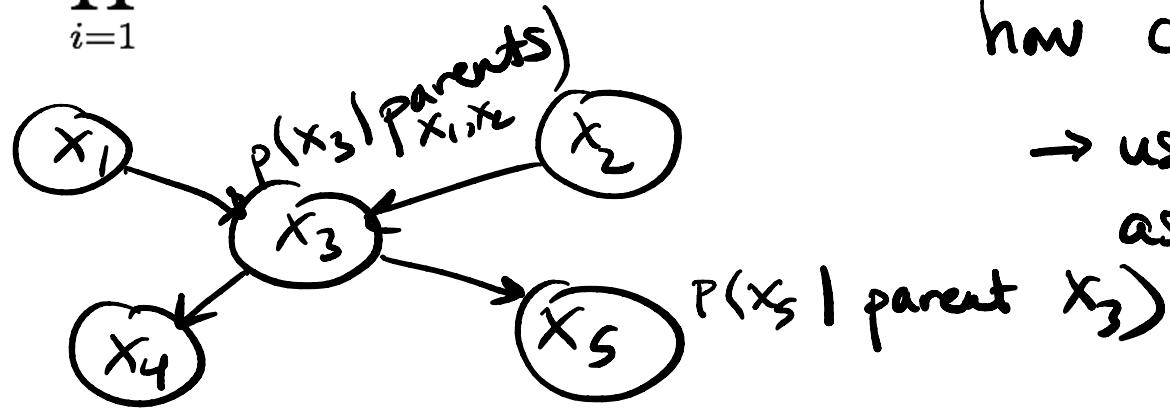
# Bayesian Networks

Bayes nets implicitly encode joint distributions as a product of the local conditional distributions:

$$P(x_1, x_2, \dots, x_n) = ?$$

$$\begin{aligned} P(x_1, x_2, \dots, x_n) &= P(x_n | x_{n-1}, x_{n-2}, \dots, x_2, x_1) P(x_{n-1}, x_{n-2}, \dots, x_2, x_1) \\ &= P(x_n | x_{n-1}, x_{n-2}, \dots, x_2, x_1) P(x_{n-1} | x_{n-2}, \dots, x_2, x_1) P(x_{n-2}, \dots, x_2, x_1) \\ &= \dots \\ &= P(x_n | x_{n-1}, x_{n-2}, \dots, x_2, x_1) P(x_{n-1} | x_{n-2}, \dots, x_2, x_1) \dots P(x_3 | x_2, x_1) P(x_2 | x_1) P(x_1) \\ &= \prod_{i=1}^n P(x_i | x_{i-1}, x_{i-2}, \dots, x_2, x_1) \end{aligned}$$

e.g.



how can we simplify?  
→ use conditional independence assumptions

# Bayesian Networks

---

Bayes nets implicitly encode joint distributions as a product of the local conditional distributions:

$$P(x_1, x_2, \dots, x_n) = \prod_{i=1}^n P(x_i | x_{i-1}, x_{i-2}, \dots, x_2, x_1) = \dots?$$

**Node ordering:** write in such a way that

$$\text{parents}(X_i) \subseteq \{X_{i-1}, X_{i-2}, \dots, X_2, X_1\}$$

→

$$\prod_{i=1}^n P(x_i | x_{i-1}, x_{i-2}, \dots, x_2, x_1) = \prod_{i=1}^n P(x_i | \text{parents}(X_i))$$

This statement:

$$P(X_i | X_{i-1}, X_{i-2}, \dots, X_2, X_1) = P(X_i | \text{parents}(X_i))$$

is key: each node is conditionally independent  
of its other predecessors, given its parents

# Bayesian Networks

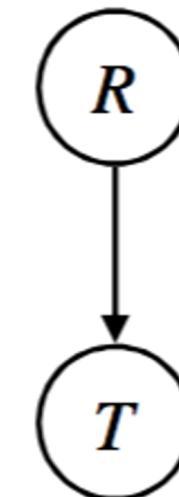
Bayes nets implicitly encode joint distributions as a product of the local conditional distributions:

↓ *warmup*

$$P(x_1, x_2, \dots, x_n) = \prod_{i=1}^n P(x_i \mid \text{parents}(X_i))$$

Example: Traffic

$$P(+r, \neg t) = ?$$



$$P(R)$$

|    |     |
|----|-----|
| +r | 1/4 |
| ¬r | 3/4 |

$$P(T|R)$$

|      |    |     |
|------|----|-----|
| +r → | +t | 3/4 |
|      | ¬t | 1/4 |

|      |    |     |
|------|----|-----|
| ¬r → | +t | 1/2 |
|      | ¬t | 1/2 |

# Next Time

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- Bayesian Inference and Sampling