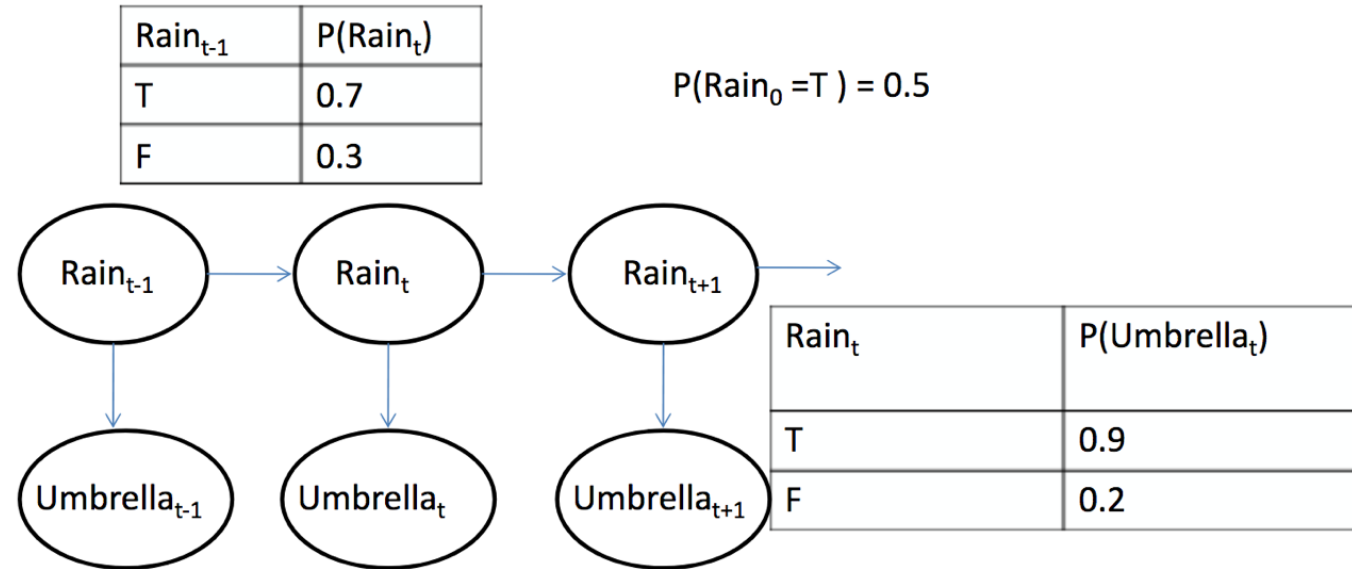


# CSCI 3202: Intro to Artificial Intelligence

## Lecture 30: HMM, Forward-backward

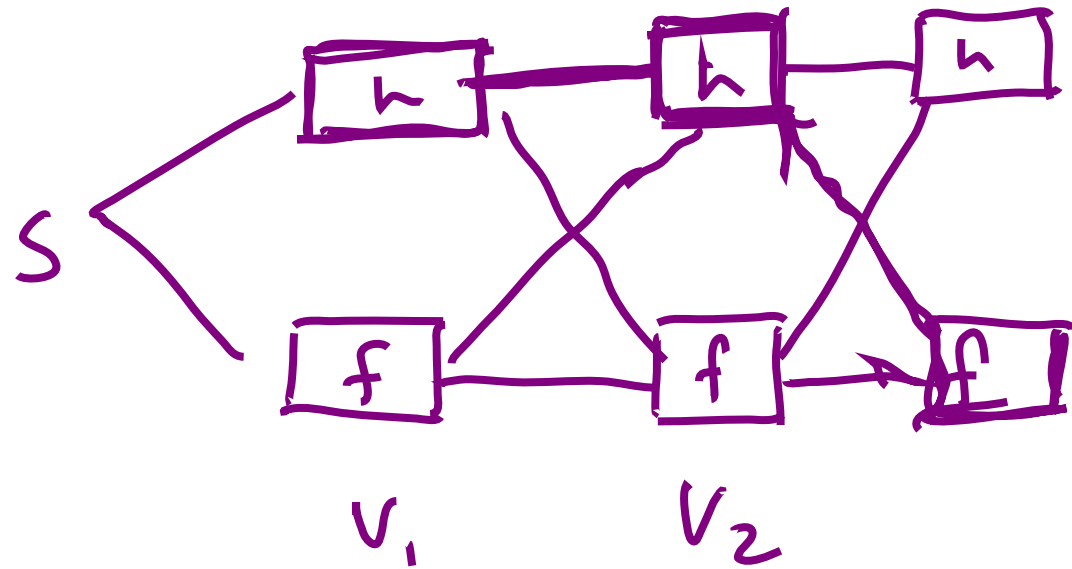
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HMMs — Adapted from Russel and Norvig, Chapter 15.

# HMMs – Viterbi

max probability of a sequence of states



Start at  $X_T$   
Find max prob  
follow prev to get  
previous.  
Repeat back to  
Start.

Sequence  $h \rightarrow h \rightarrow f$  has max pr.

# Hidden Markov Models (HMMs) – smoothing

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- **Smoothing:** Compute the belief state given the evidence over a previous state using all evidence up to current state.
  - $P(X_k | e_{1:t})$ , where  $0 \leq k < t$
  - Revise our belief about the past given what was observed in the future
  - Split computation into two parts: evidence up to  $k$ , evidence  $k+1$  to  $t$ .

$$\begin{aligned} P(X_k | e_{1:t}) &= P(X_k | e_{1:k}, e_{k+1:t}) \\ &= \alpha P(X_k | e_{1:k}) P(e_{k+1:t} | X_k) \\ &= \alpha \underbrace{f_{1:k}}_{\text{forward f. filtering alg.}} \times \underbrace{b_{k+1:t}}_{\text{backward alg.}} \end{aligned}$$

# Hidden Markov Models (HMMs) – smoothing

•  $b_{k+1:t}$  - runs backward from  $t$

$f_{1:k}$  - runs forward from 1

$$b_{k+1:t} = \sum_{x_{k+1}} \underbrace{P(e_{k+1} | x_{k+1})}_{\text{given in model}} \underbrace{P(e_{k+2:t} | x_{k+1})}_{\text{we need to calculate this}} \underbrace{P(x_{k+1} | x_k)}_{\text{transition, also given in model}}$$

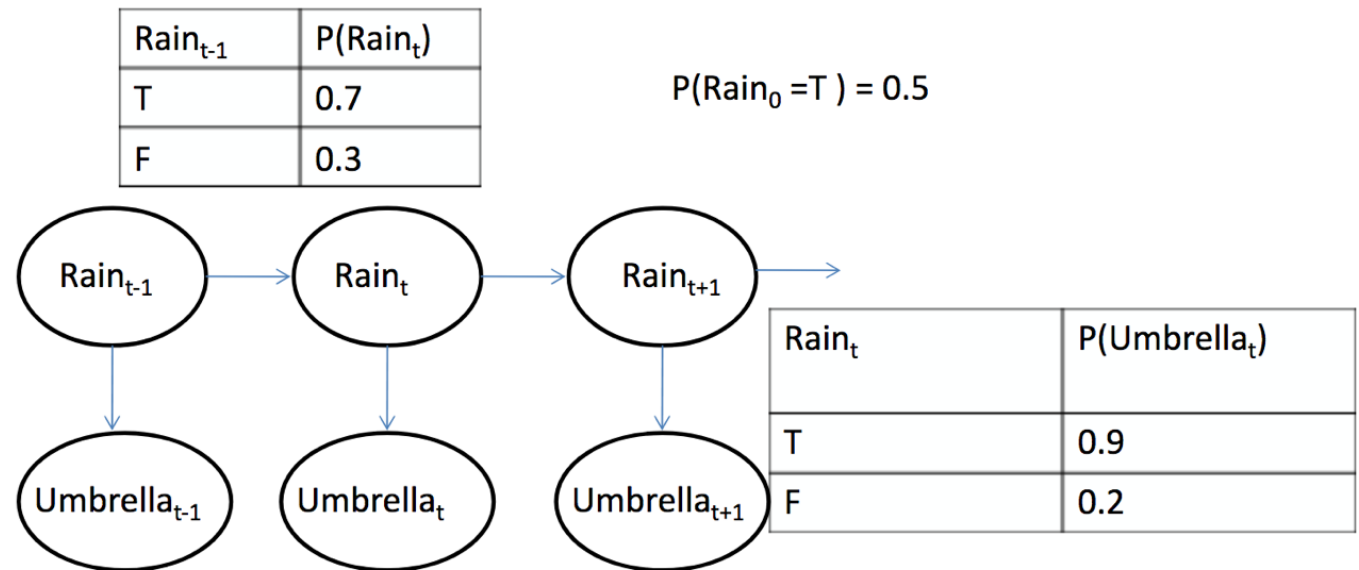
$$b_{k+1:t} = \text{Backward}(b_{k+2:t}, e_{k+1})$$

# HMM example – rain and the umbrella

**Example:** You are curious if it is raining, and the only contact you have with the outside world is through your advisor. If it is raining, she brings her umbrella 90% of the time, and has it just in case on 20% of sunny days. You know that historically, 70% of rainy days were followed by another rainy day, and 30% of sunny days were followed by a rainy day.

If you observe the umbrella two days in a row, what is the  $P(\text{rain})$  on each day?

Day 1 -  $u_1 = T$   
Day 2 -  $u_2 = T$



## Rain and the umbrella – filtering

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$$\text{Day 1 - filtering} = [.818, .182]$$
$$P(r, | u, )$$

$$\text{Day 2} = [.883, .117]$$

# Rain and the umbrella – filtering

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# Rain and the umbrella – backwards

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Given observation of umbrella on Day 1 and 2, compute the smoothed estimate for rain on Day 1.

Does seeing an umbrella on Day 2 change our belief about rain on day 1.

Initialize

$$b_{t+1:t} = P(e_{t+1:t} | X_t) = [1, 1]$$

evidence at  $t+1$  is empty.

$$P(R_1 | u_1, u_2) = \underbrace{\alpha P(R_1 | u_1)}_{[.818, .182]} \underbrace{P(u_2 | R_1)}_{b_{t+1:t}}$$



## Rain and the umbrella – backwards

$$\begin{aligned} P(u_2 | R_1) &= \sum_{r_2} P(u_2 | r_2) P(r_2) P(r_2 | R_1) \\ &= \sum_{x_{k+1}} P(e_{k+1} | x_{k+1}) P(e_{k+2} | x_{k+1}) P(x_{k+1} | x_k) \\ &= \left[ \underset{R_1 = T}{.9 \times .1 \times .7 + .2 \times .1 \times .3}, \underset{R_1 = F}{.9 \times .1 \times .3 + .2 \times .1 \times .7} \right] \\ &= \left[ .63 + .06 = .69, .27 \times .14 = .41 \right] \end{aligned}$$

$$P(u_2 | R_1) = \left[ \underset{T}{.69}, \underset{F}{.41} \right]$$

Probability of seeing  
umbrella on day 2 given  
 $R_1$  is T, F.

# Forward Backward Algorithm

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Suppose we want to smooth the entire sequence of estimates.

❖ Run the Forward algorithm (filter it)

❖ Then run the Backward algorithm (smooth it)

$$\begin{aligned} P(z_k | u_1, u_2) &= \alpha P(x_k | e_{1:t}) P(e_{k+1:t} | x_k) \\ &= \alpha [818, 182] [69, 41] \\ &= \alpha [564, 075] \\ &= [883, 117] \end{aligned}$$

# Rain and the umbrella – forward – backward

5 days  
umbrella  
T, T, F, T, T

$P(x_t | e_{1:t})$

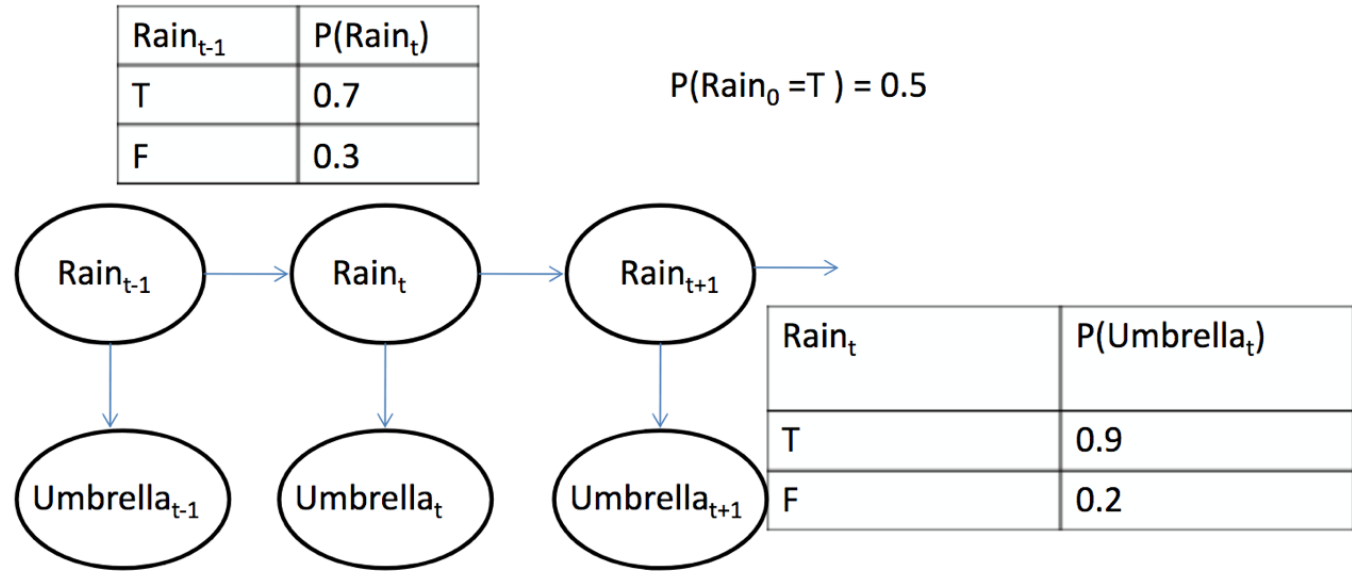
1: [.818, .182]

2: [.883, .117]

3: [.1907, .8093]

4: [.7308, .2692] ←

5: [.8673, .1327]



HMMs — Adapted from Russel and Norvig, Chapter 15.

## Rain and the umbrella – forward – backward

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Day 5

$$P(u_5 | R_4) = \sum_{r_5} P(u_5 | r_5) P(r_5) P(r_5 | R_4)$$
$$= [.69, .41]$$

$$P(R_4 | u_4, u_5) = \alpha P(X_k | e_{1:k}) P(e_{k+1:k} | X_k)$$
$$= \alpha P(R_4 | e_{1:4}) P(u_5 | R_4)$$
$$= \alpha [.7308, .2692] [.69, .41]$$

$$\alpha = .5 + .11$$

$$= \alpha [.5, .11]$$
$$= [.819, .18]$$

## Rain and the umbrella – forward – backward

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Day 4

$$P(u_4 | R_3) = \sum_{r_4} P(u_4 | r_4) P(u_5 | r_4) P(r_4 | R_3)$$

$$= \begin{bmatrix} \overset{R_3=T}{.9 \times .69 \times .7 + .2 \times .41 \times .3}, \\ \underset{R_3=F}{.9 \times .69 \times .3 + .2 \times .41 \times .7} \end{bmatrix}$$

$$= \begin{bmatrix} .459, & .243 \end{bmatrix}$$

# **Rain and the umbrella – forward – backward**

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# **Rain and the umbrella – forward – backward**

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# **Rain and the umbrella – forward – backward**

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# **Rain and the umbrella – forward – backward**

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