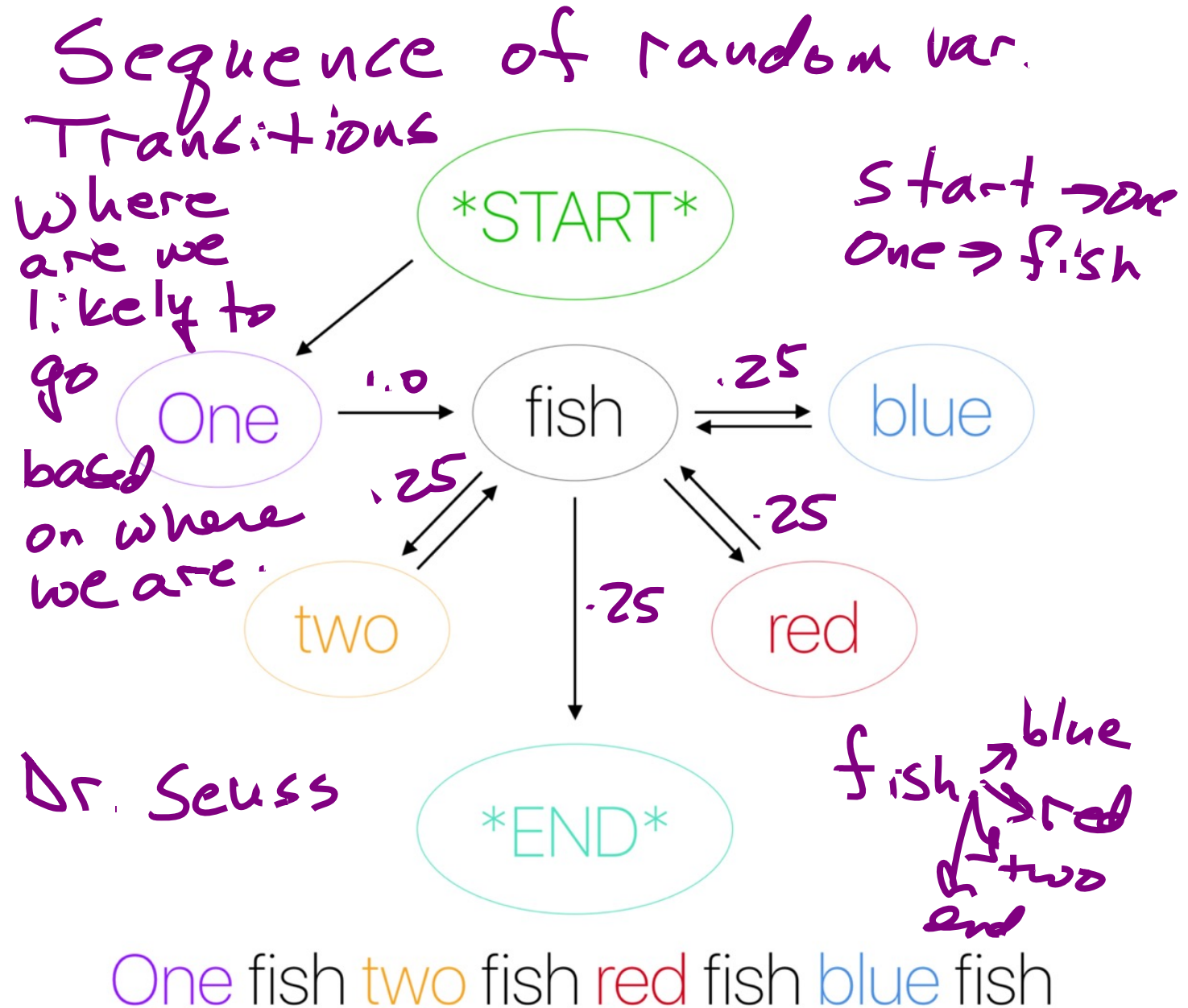


CSCI 3202: Intro to Artificial Intelligence

Lecture 26: Markov Models

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Bayesian Networks – Recap

The point of Bayes nets is to represent full joint probability distributions, and to encode an interrelated set of conditional independence/probability statements.

Prob. of single outcome

- Consists of nodes (events), and
- Conditional probability tables (CPTs), relating those events.

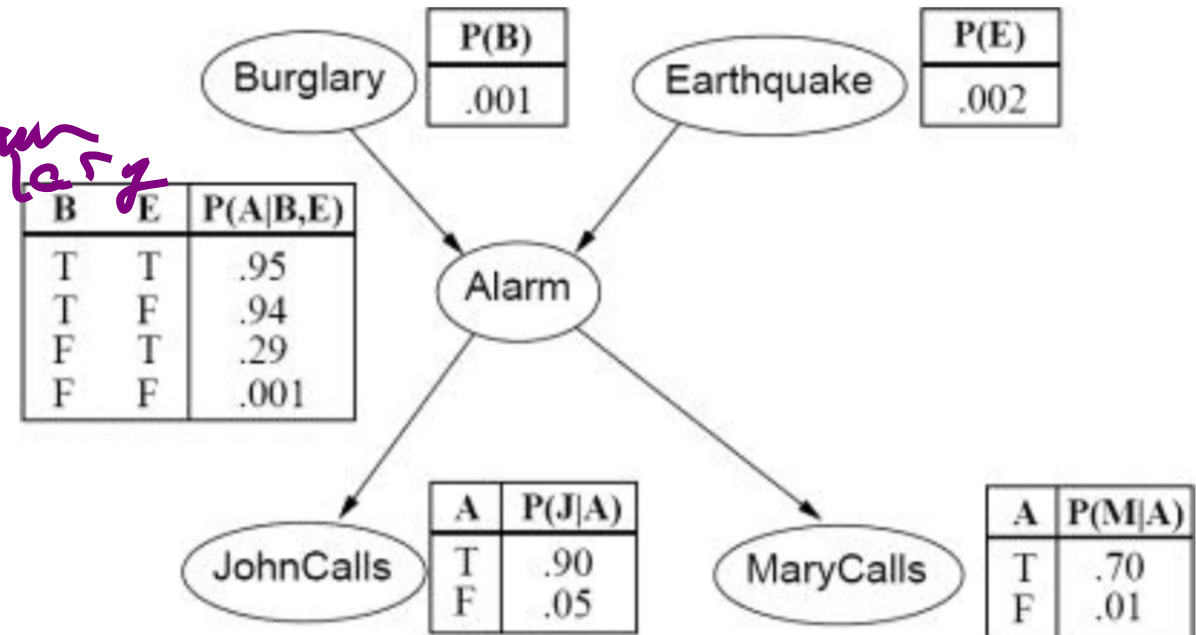
$P(A|B,E)$, $P(J|A)$

- Describes how variables interact locally

Eg. Relationship between alarm and burglary

- Chain together local interactions to estimate global, indirect interactions

*$P(J|B)$ $P(J,A|E)$
 $P(J|M)$ $P(B|J)$*



Markov Models

Used to reason about a **sequence of events** (random variables)

Events at
time $t, t+1, t+2, \dots$

Examples:

- Robot localization Maze navigation. Path planning
- Speech recognition $P(\text{word} | \text{previous word})$
- Medical monitoring Change in blood sugar at time t , given $t-1$
- Weather forecasting rain on day t if rain on $t-1$

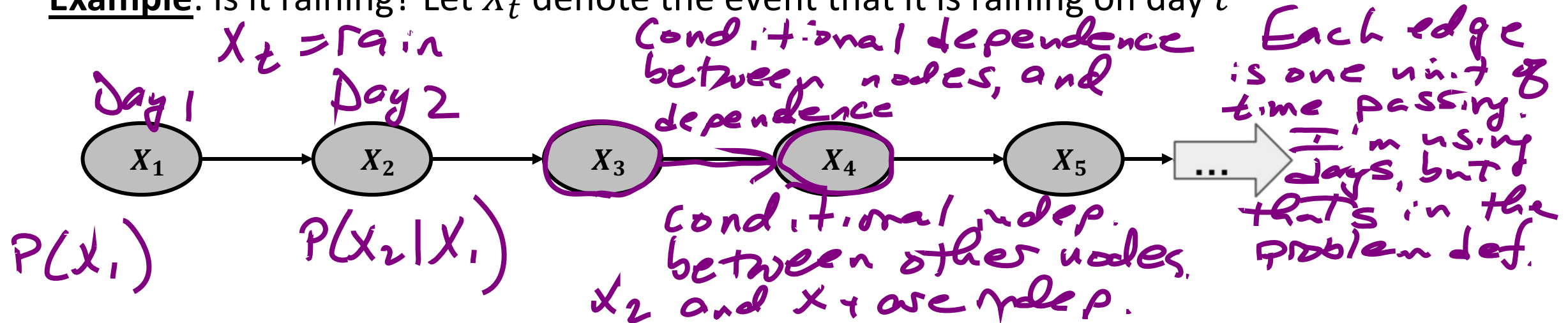
- Need to **introduce time** into our **Bayesian Network** model
- Probability of an event happening as the next state, given the current state of the system
- Long-term behavior e.g.
from individual transitions at t to $t+1$,
get long term probability of rain,
speech patterns, etc.

Markov Models

A **Markov model** is a chain-structured Bayesian network.

- The value of X at a time t is the state at time t *X is random variable*
- Stationary Markov model: All subsequent nodes have the same CPT (identically distributed) *e.g. if rain on day t means 50% chance of rain on day $t+1$, for all values of t .*

Example: Is it raining? Let X_t denote the event that it is raining on day t



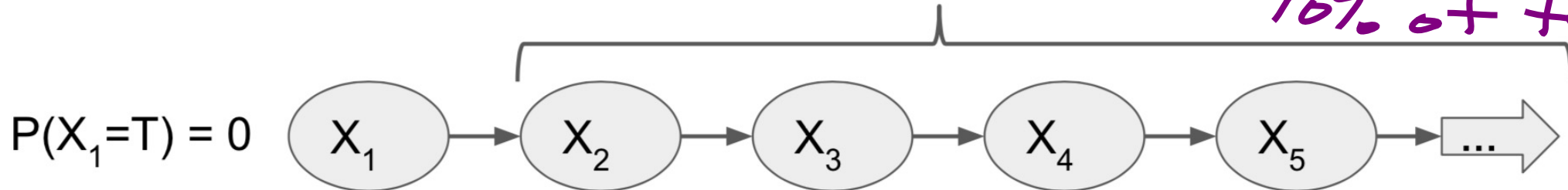
Markov Models

Recall: Causal chain Bayes net forms conditional independence

- Past and future are independent of the present. *X_2 indep. of X_3*
- State at $t + 1$ only depends on state at t *First-order Markov model*
- The CPTs give the transition probabilities from one state to another for this.

*If $X_t = T$, then
 $X_{t+1} = T$ 30%
of time. If
 $X_t = F$, $X_{t+1} = T$
10% of time.*

X_t	$P(X_{t+1}=T X_t)$
T	0.3
F	0.1



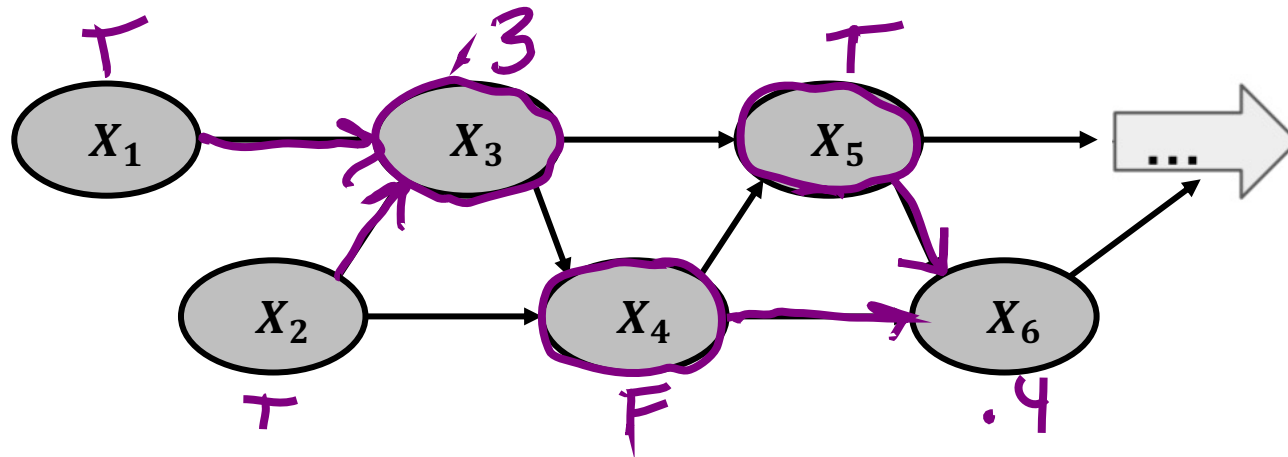
Markov Models

Recall: Causal chain Bayes net forms conditional independence

- Past and future are independent of the present.
- State at $t + 1$ only depends on state at t
- The CPTs give the transition probabilities from one state to another for this.

Markov property
(first-order)

- We could also create models where the state at $t + 1$ depends only on the state at t and $t - 1$ (second-order Markov property), or higher ...



$$P(X_3=T | X_2, X_1)$$

X_{t-1}	X_t	$P(X_{t+1}=T X_t, X_{t-1})$
T	T	0.3
T	F	0.1
F	T	0.4
F	F	0.1

Markov Models

Example: Suppose we want to forecast the weather. From historical data, we know that in our town, if the current day was sunny, then the following day was also sunny 90% of the time, and that if the current day was rainy, then the following day was also rainy 30% of the time.

Draw the state space graph and specify the CPT.

X_t	X_{t+1}	$P(X_{t+1} X_t)$
Sun	Sun	.9 ← given
Sun	Rain	.1
Rain	Sun	.7
Rain	Rain	.3 ← given

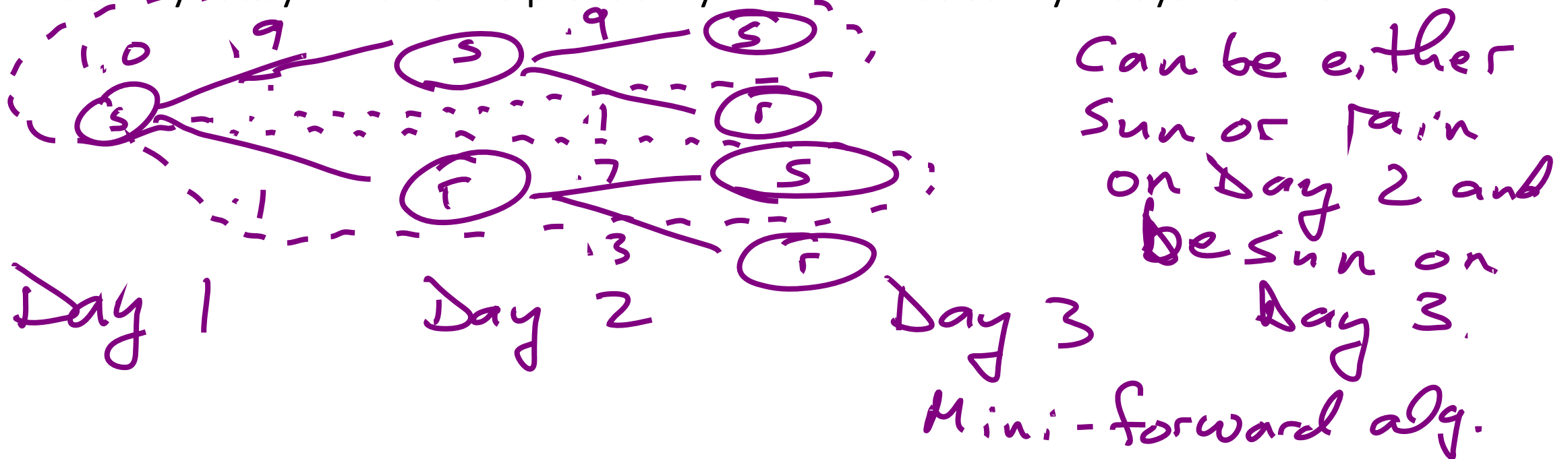


State space graph.
Visual rep.
Draw states with
transition probs
as arrows

Markov Models

Example: Suppose we want to forecast the weather. From historical data, we know that in our town, if the current day was sunny, then the following day was also sunny 90% of the time, and that if the current day was rainy, then the following day was also rainy 30% of the time.

It is sunny today. What is the probability that it will be sunny 2 days from now?



Markov Models

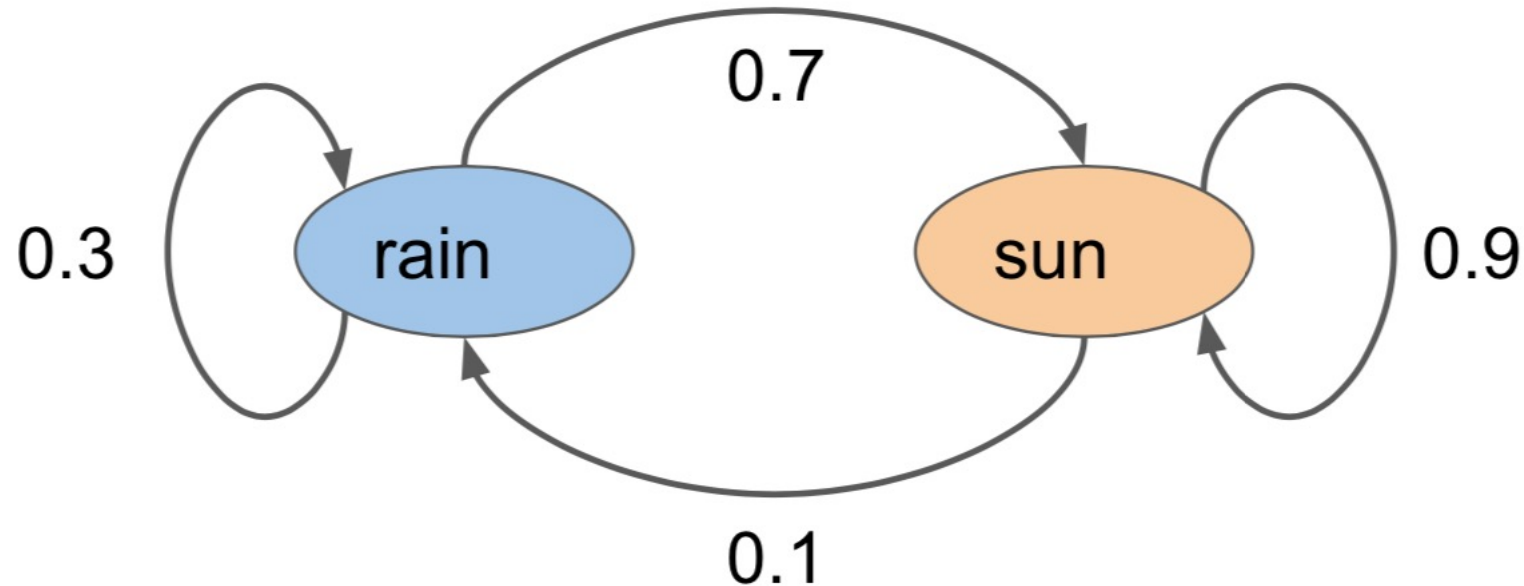
Mini-forward algorithm: incremental belief updating

Suppose that x_1 is known. Day 1 is Sunny

Then for $t = 2, 3, 4, \dots$ $P(x_t) = \sum_{x_{t-1}} P(x_t | x_{t-1}) P(x_{t-1})$

This is what we did.

To calculate $P(x_t)$, need to know all paths through x_{t-1}



Mini-forward Algorithm

Example: Using the mini-forward algorithm, find $P(X_3 = s)$

$$P(X_3 = s)$$

Assume $P(X_1 = s) = 0.9$

$$P(X_t) = \sum_{x_{t-1}} P(X_t | X_{t-1}) P(X_{t-1})$$

$$P(X_2) = P(X_2 | X_1 = s) P(X_1 = s) + P(X_2 | X_1 = r) P(X_1 = r)$$

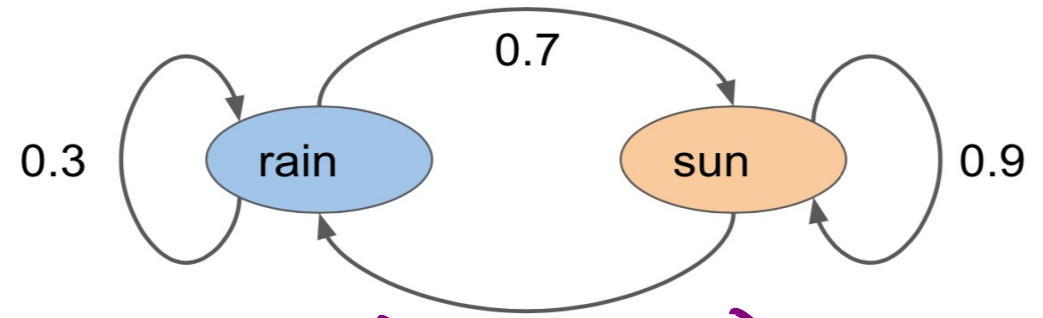
$$= P(X_2 | X_1 = s) = \begin{pmatrix} .9 \\ .1 \end{pmatrix} \begin{Bmatrix} P(s|s) \\ P(r|s) \end{Bmatrix}$$

$$P(X_3) = \sum_{x_2} P(X_3 | X_2) P(X_2)$$

$$P(X_3 = s) = P(X_3 = s | X_2 = s) P(X_2 = s) + P(X_3 = s | X_2 = r) P(X_2 = r)$$

$$= .9 \times .9 + .7 \times .1 = .88$$

$$P(X_3 = r) = P(X_3 = r | X_2 = s) P(X_2 = s) + P(X_3 = r | X_2 = r) P(X_2 = r)$$



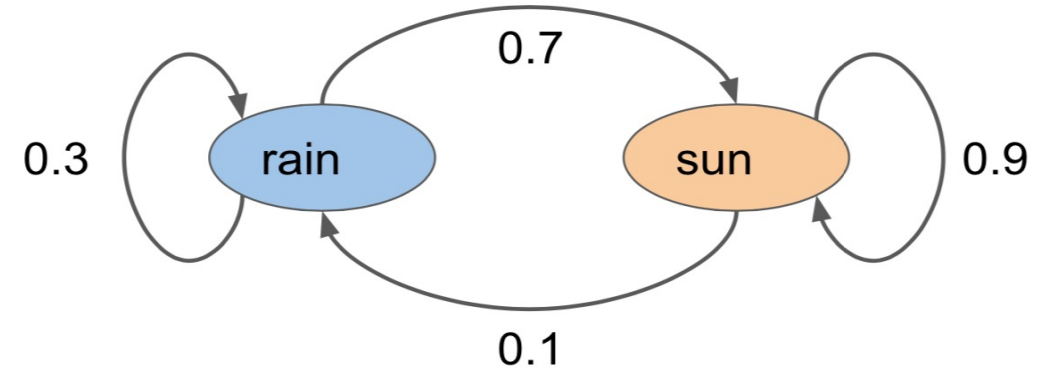
Markov Models

$$[.1 \times .9] + [.3 \times .1] = .12$$

Example: What is the long-run probability that it will be sunny?

Run the mini-forward
alg many, many times.

On any given day,
what is $P(X_t = \text{rain})$



Markov Models

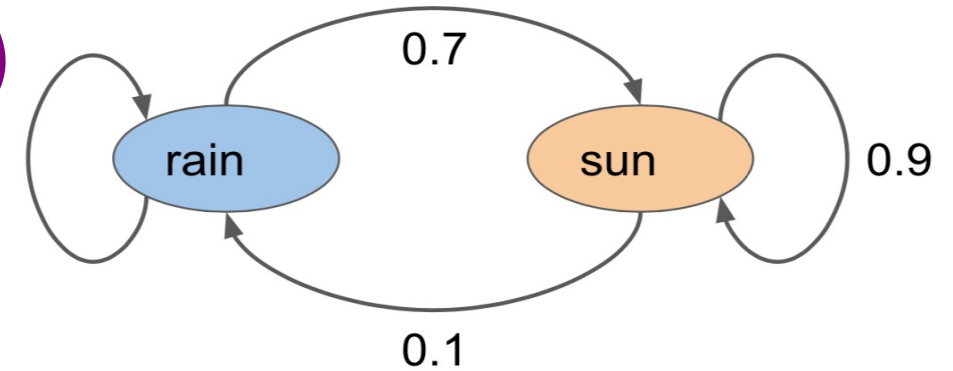
Define the transition matrix T such that T_{ij} = probability of moving from state i to j

Say $X_1 = \text{sun}$, $X_2 = \text{rain}$. Then: $T = \begin{bmatrix} 0.9 & 0.1 \\ 0.7 & 0.3 \end{bmatrix}$

$$T = \begin{matrix} & \begin{matrix} \text{sun} \\ \text{rain} \end{matrix} \\ \begin{matrix} \text{sun} \\ \text{rain} \end{matrix} & \begin{bmatrix} .9 & .1 \\ .7 & .3 \end{bmatrix} \end{matrix}$$

$P(r|s)$

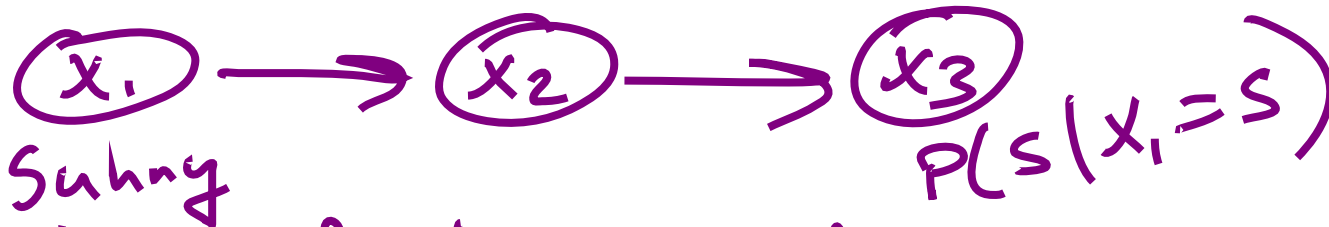
$P(r|r)$



Markov Models

It turns out that the transition matrix also gives us a short-cut for calculating multi-step transition probabilities.

Example: It is sunny today. What is the probability that it will be sunny 2 days from now?

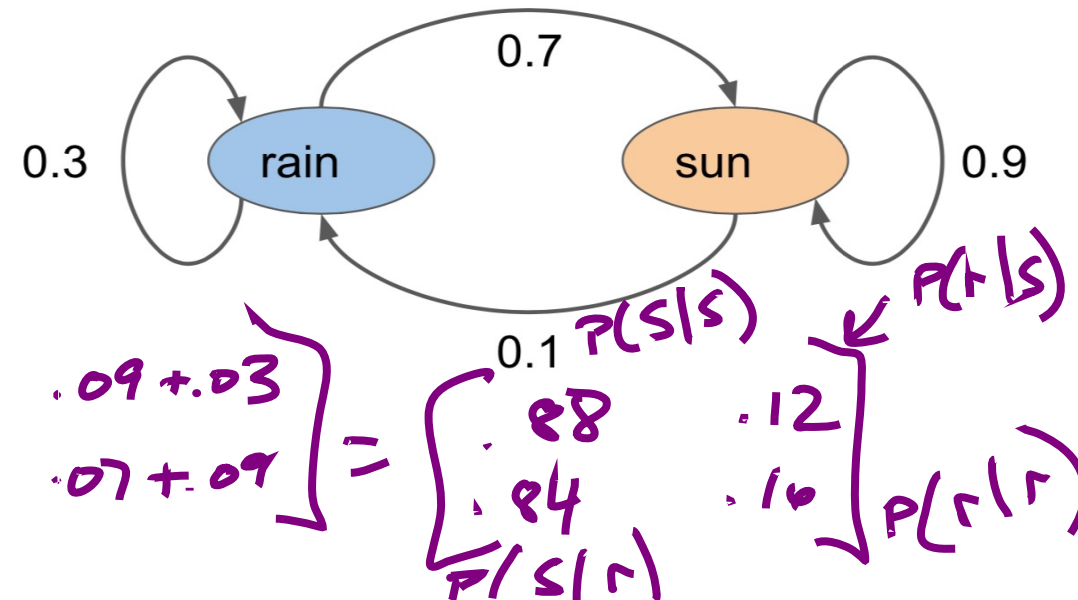


Apply T for timestep $x_1 \rightarrow x_2$
 Apply T again for $x_2 \rightarrow x_3$

$$T^2 = \begin{bmatrix} .9 & .1 \\ .7 & .3 \end{bmatrix} \begin{bmatrix} .9 & .1 \\ .7 & .3 \end{bmatrix} =$$

$$\begin{bmatrix} .9 \times .9 + .1 \times .7 & .9 \times .1 + .1 \times .3 \\ .7 \times .9 + .3 \times .7 & .7 \times .1 + .3 \times .3 \end{bmatrix} = \begin{bmatrix} .81 + .07 & .09 + .03 \\ .63 + .21 & .07 + .09 \end{bmatrix} = \begin{bmatrix} .88 & .12 \\ .84 & .16 \end{bmatrix}$$

$P(S|S)$
 $P(r|r)$
 $P(S|r)$
 $P(r|S)$

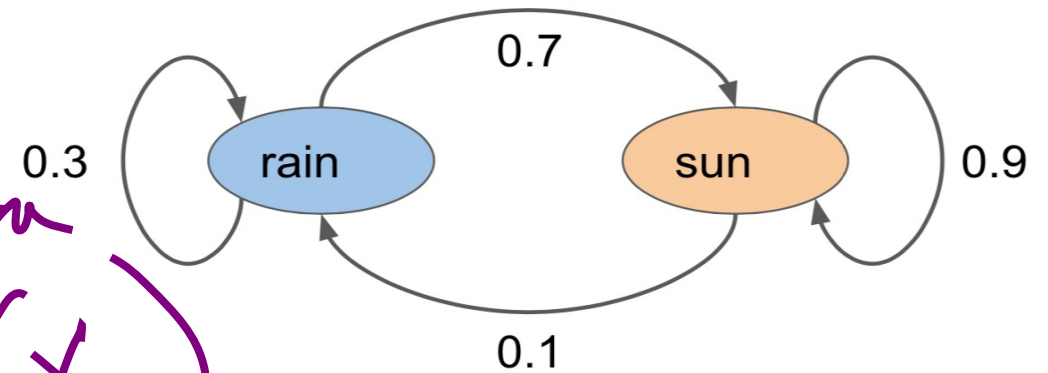


Markov Models

Example: How could we use the transition matrix to find $P(X_\infty = s)$.

```
transition_matrix = np.array([[0.9, 0.1],[0.7, 0.3]])  
  
new = transition_matrix  
  
for k in range(1,13):  
    new = np.matmul(new, transition_matrix)  
    print('T**{} = \n{}'.format(k+1, new))
```

When $T^{t+1} = T^t$
we've computed long-term
Prob of Sun
 $P(X_{t+1}) = P(X_t)$



Next Time

- *Markov Models Notebook Day*