

autovetores

nova base

antigo

$$y_i = U^T x_i$$

Comp. principal

$$\begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} \leftarrow v_1 \rightarrow \\ \leftarrow v_2 \rightarrow \\ \leftarrow v_3 \rightarrow \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$v_i = [v_{i1} \ v_{i2} \ v_{i3}]$$

$$= \begin{bmatrix} v_1^T x \\ v_2^T x \\ v_3^T x \end{bmatrix}$$

x_1
 x_2
 x_3

$$y = \begin{bmatrix} v_{11}x_1 + v_{12}x_2 + v_{13}x_3 \\ v_{21}x_1 + v_{22}x_2 + v_{23}x_3 \\ v_{31}x_1 + v_{32}x_2 + v_{33}x_3 \end{bmatrix}$$

CP
↓

Feature
↓

$$y_1 = v_{11}x_1 + v_{12}x_2 + v_{13}x_3$$

$$v_1 = [v_{11}, v_{12}, v_{13}]$$

autovetor de $\Sigma(\text{cov})$

λ_i não é importância de x_i

(variancia de comp. i)

(feature i)

comp comb. linear das feat

$$y = \underbrace{\omega_{11}}_{\uparrow} x_1 + \underbrace{\omega_{12}}_{\uparrow} x_2 + \underbrace{\omega_{13}}_{\uparrow} x_3$$

$$\omega_1 = [\omega_{11}, \omega_{12}, \omega_{13}]$$

autorrotor '1 $\Sigma^1(\text{cov})$

ps comp

$$y_1 = \underbrace{1.5}_{\text{direção de maior variação}} \cdot \underbrace{\text{Peso}}_{\text{direção de maior variação}} + 0.1 \cdot \underbrace{\text{Alt}}_{\text{direção de maior variação}} + 0.3 \cdot \underbrace{\text{Salário}}_{\text{direção de maior variação}}$$

$$1.5 \gg 0.1, 0.3$$

$$y_1, y_2 \begin{cases} \omega_P + \omega_A + \omega_S \\ 0P + 0A + 1S \end{cases}$$

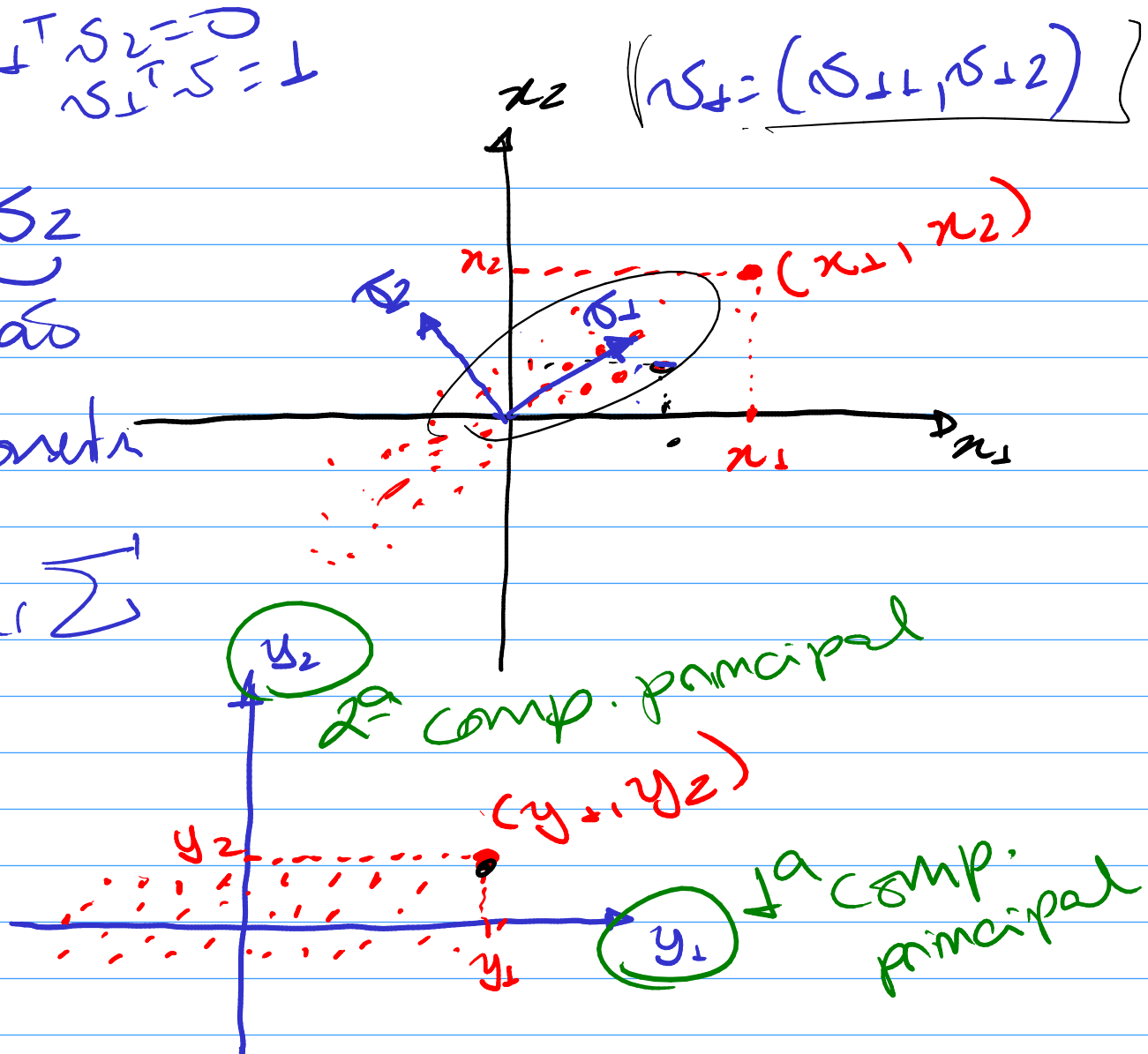
perder interpretações

Possou usar o peso das features no 1º componente

$$\Sigma^T \Sigma = 0$$

$$\Sigma^T \Sigma = I$$

Σ_1, Σ_2
direções
das
componentes
auto
vetor Σ



$$(x_1, x_2) \xrightarrow{?} (y_1, y_2)$$

$$y_1 = \Sigma_{11} \cdot x_1 + \Sigma_{12} \cdot x_2 = \Sigma_1^T x$$

$$y_2 = \Sigma_{21} \cdot x_1 + \Sigma_{22} \cdot x_2 = \Sigma_2^T x$$

$$\begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$y = U^T x$$

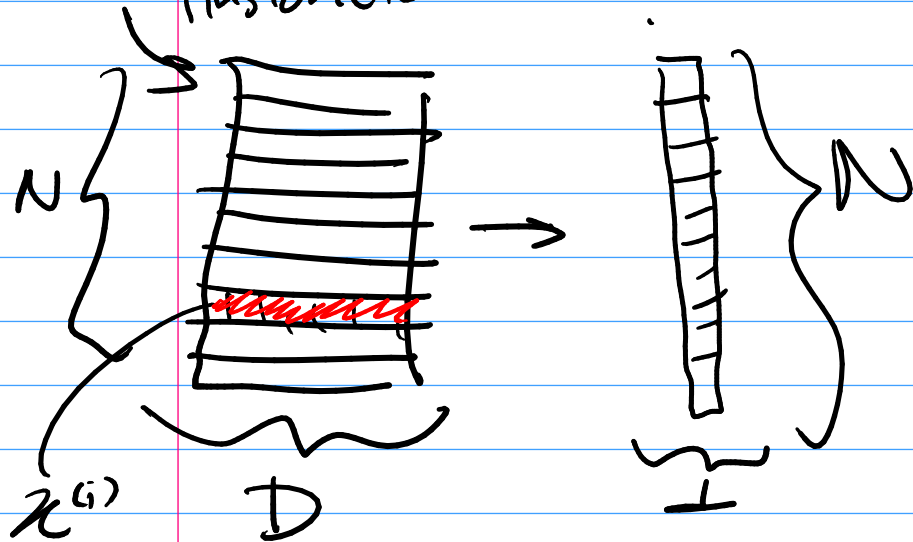
Σ autovetores

$$U = \begin{bmatrix} \Sigma_1^T \\ \Sigma_2^T \end{bmatrix}$$

de Σ
autovetores

$$\begin{matrix} \lambda_1 & \lambda_{11} & \lambda_{12} & \lambda_{13} & \dots \\ & \lambda_{21} & \lambda_{22} & \lambda_{23} & \dots \end{matrix}$$

linha instancie



Só 1ª
componente

Para cada instância $x^{(i)}$

$$y_1^{(i)} = x^{(i)T} \begin{matrix} \lambda_{11} & \lambda_{12} & \dots & \lambda_{1D} \\ \lambda_{21} & \lambda_{22} & \dots & \lambda_{2D} \\ \vdots & \vdots & \ddots & \vdots \\ \lambda_{D1} & \lambda_{D2} & \dots & \lambda_{DD} \end{matrix}$$

$$= x_1^{(i)} \cdot \lambda_{11} + x_2^{(i)} \cdot \lambda_{12} + \dots + x_D^{(i)} \cdot \lambda_{1D}$$

← comp.

$$\text{Var}(y_1) = \lambda_1$$

test.

$$\text{Imp}(x_j) = |\lambda_{1j}|$$

$$y_1 = v_{11} \cdot x_1 + v_{12} \cdot x_2 = v_1^T x$$

$$y_2 = v_{21} \cdot x_1 + v_{22} \cdot x_2 = v_2^T x$$

$$\begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} v_{11} & v_{12} \\ v_{21} & v_{22} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$y = U^T x$$

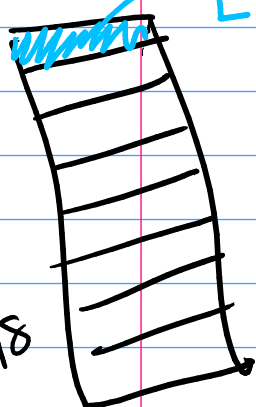
v autovetores

de \bar{Z}
 λ autovalores

$$U = \begin{bmatrix} v_1^T & v_2^T \\ \vdots & \vdots \end{bmatrix}$$

linha

25



$$X \in \mathbb{R}^{498 \times 25}$$

498 pontos
25 dim

$$U \in \mathbb{R}^{25 \times 2}$$

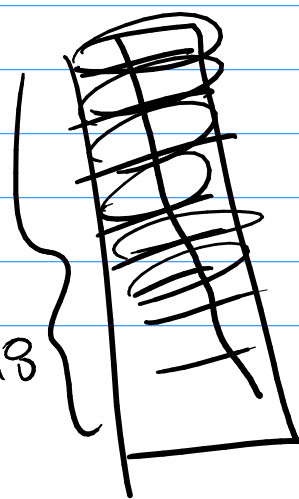
$$A \cdot B = C$$

$$\underline{M \times N} \quad \underline{N \times K}$$

$$M \times K$$

$$XU \in \mathbb{R}^{498 \times 2}$$

498



$$y = U^T x$$

$$\begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} \leftarrow \sigma_1 \rightarrow \\ \leftarrow \sigma_2 \rightarrow \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

column
2x1

$$= \begin{bmatrix} \sigma_{11} & \sigma_{12} \\ \sigma_{21} & \sigma_{22} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

✓

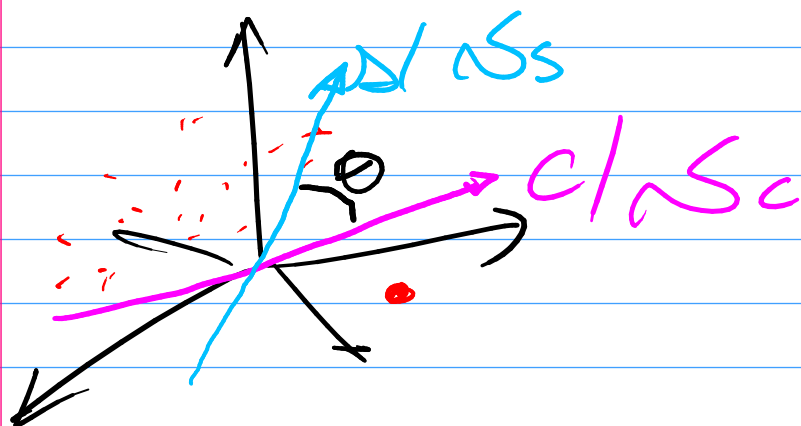
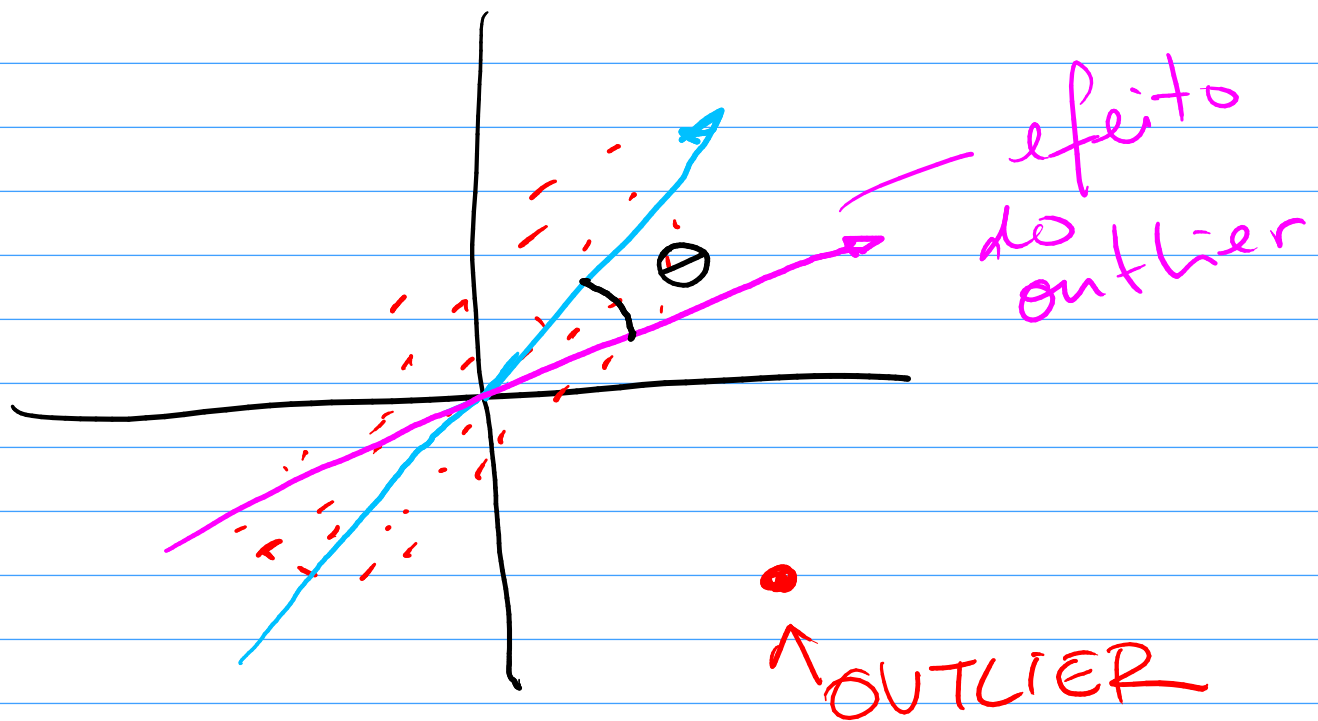
$$= \begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} \sigma_{11} & \sigma_{12} \\ \sigma_{12} & \sigma_{22} \end{bmatrix}$$

1x2 2x2

✗

$$\begin{bmatrix} \sigma_{11} & \sigma_{12} \\ \sigma_{12} & \sigma_{22} \end{bmatrix} \begin{bmatrix} x_1 & x_2 \end{bmatrix}$$

2x2 1x2



$$\cos \theta = \frac{v_s \cdot v_c}{\|v_s\| \cdot \|v_c\|}$$

$$\cos \theta = \frac{a \cdot b}{\|a\| \|b\|}$$

$$\theta = \arccos \left(\frac{a \cdot b}{\|a\| \cdot \|b\|} \right)$$

grand avg

$$\alpha(\alpha_1 + \beta \alpha_2)$$

PCA:

$$\alpha y_1 + \beta y_2$$

$$y = \alpha \alpha_1 + \alpha \alpha_2 + \alpha \alpha_2$$

$\begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \\ y_5 \end{bmatrix}$	λ_1
	λ_2
	λ_3
	λ_4
	λ_5

$$Z = \begin{bmatrix} \cdot & \cdot & \cdot & \cdot & \cdot \end{bmatrix}$$