

Reconstruction performance of the stochastic block model (SBM) in empirical networks

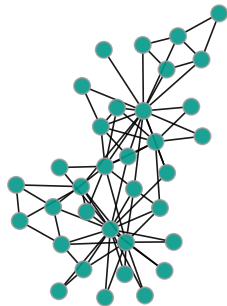
Felipe Vaca-Ramírez & Tiago P. Peixoto

*Central European University
Vienna, Austria*

NetSci, July 2023

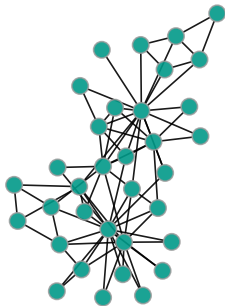
Network data are noisy

Many times we don't observe the true network **A**,

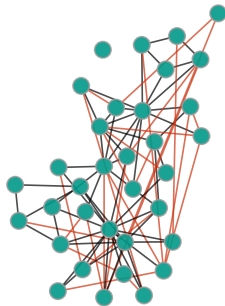


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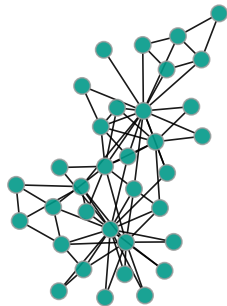
but noisy or incomplete data \mathbf{D}



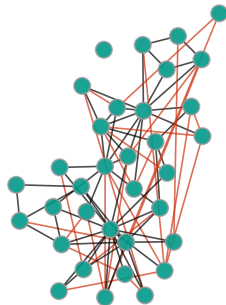
The measurement process is often overlooked: $P(\mathbf{D}|\mathbf{A})$

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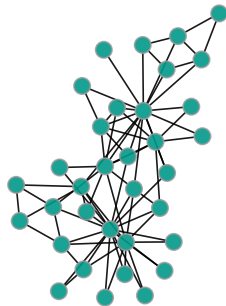


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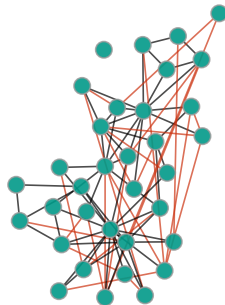
What can we do? Reconstruct the original network: $P(\mathbf{A}|\mathbf{D})$

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The measurement process is often overlooked: $P(\mathbf{D}|\mathbf{A})$

What can we do? Reconstruct the original network: $P(\mathbf{A}|\mathbf{D})$

How? Generative models (e.g., SBM).

We can use the SBM to:

- Generate Networks

$$P(\mathbf{A}|\boldsymbol{\omega}, \mathbf{b}) = \prod_{i < j} \omega_{b_i, b_j}^{A_{ij}} (1 - \omega_{b_i, b_j})^{1-A_{ij}} \quad (1)$$

- Infer node partitions of networks

$$P(\mathbf{b}|\mathbf{A}) = \frac{P(\mathbf{A}|\mathbf{b})P(\mathbf{b})}{P(\mathbf{A})} \quad (2)$$

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$$P(\mathbf{b}|\mathbf{A}) = \frac{P(\mathbf{A}|\mathbf{b})P(\mathbf{b})}{P(\mathbf{A})} \quad (2)$$

- Reconstruct Networks

$$P(\mathbf{A}, \mathbf{b}|\mathbf{D}) = \frac{P(\mathbf{D}|\mathbf{A})P(\mathbf{A}, \mathbf{b})}{P(\mathbf{D})} \quad (3)$$

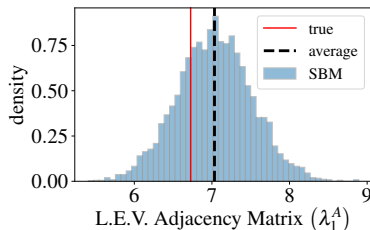
with $P(\mathbf{D}|\mathbf{A})$ being the model of the measurement process,

The SBM can be tested in this framework!

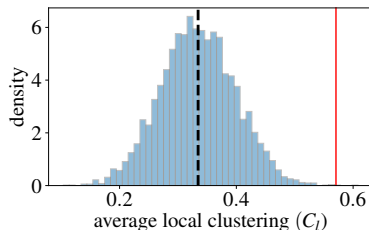
T. P. Peixoto, Physical Review X 8, 041011 (2018).

How to assess? Absolute assessment

Higher Accuracy
($\text{error} = 0.046$)

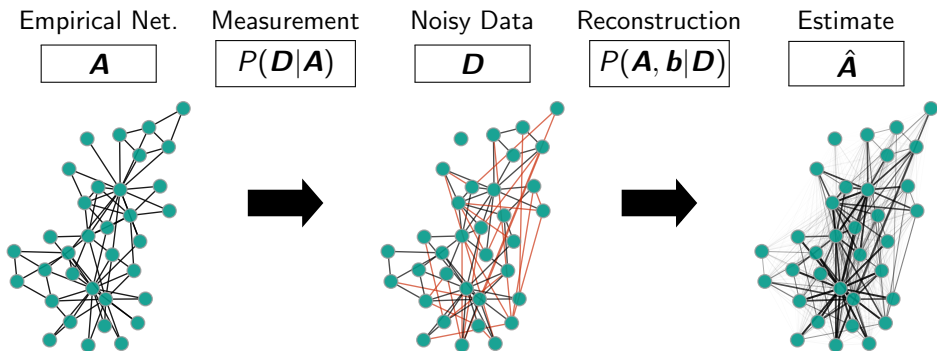


Lower Accuracy
($\text{error} = 0.236$)



How accurate is the SBM in estimating relevant features of empirical networks?

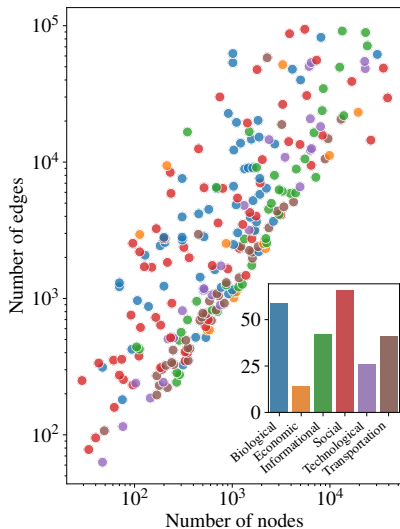
Experimental Setup and the *karate club*



How to generate noisy data?

- flip a coin on every edge and remove it with probability p .
- flip a coin on every non-edge and add a spurious edge with probability q .
- preserve density: $q = pE / \left(\binom{N}{2} - E \right)$.

Network Corpus and Descriptors

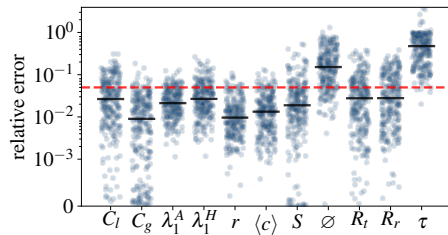


248 real-world networks

Symbol	Descriptor
r	Degree assortativity
$\langle c \rangle$	Mean k -core value
C_l	Mean local clustering coefficient
C_g	Global clustering coefficient
\emptyset	Pseudo-diameter
S	Fraction of nodes in the largest component
λ_1^A	Leading eigenvalue of the adjacency matrix
λ_1^H	Leading eigenvalue of the Hashimoto matrix
τ	Characteristic time of a random walk
R_r	Node percolation profile (random removal)
R_t	Node percolation profile (degree-targeted removal)

Assessing Performance ($p = 0.1$)

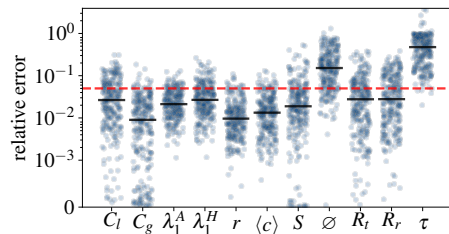
(a) Accuracy



(Distribution of reconstruction errors and **0.05-threshold**. Median in black.)

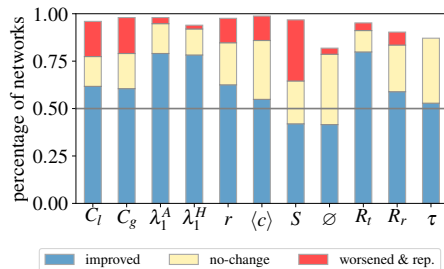
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(a) Accuracy



(Distribution of reconstruction errors and 0.05-threshold. Median in black.)

(b) Improvement



(Error *after* reconstruction vs. error *before* reconstruction.)

Average local clustering C_l

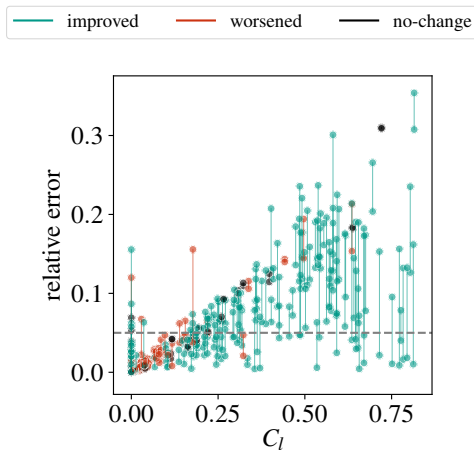


Figure 1: Relative error before and after reconstruction (joined by a line segment) as a function of the original value of the descriptor. The color indicates if the error after reconstruction is smaller than before doing it (i.e., there is improvement) or not. Noise level $p = 0.1$.

Diameter \emptyset

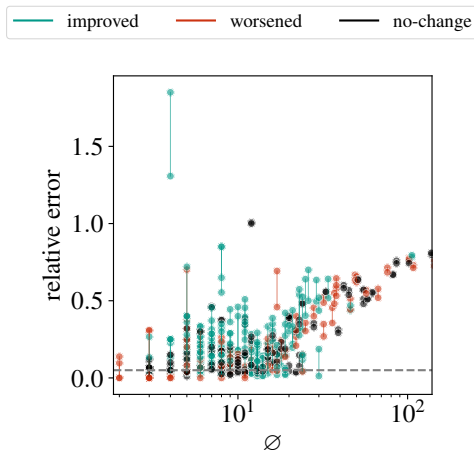
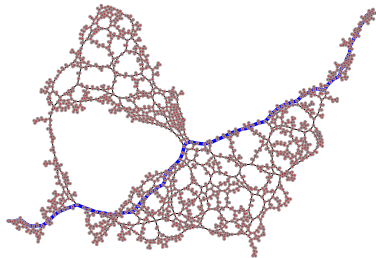


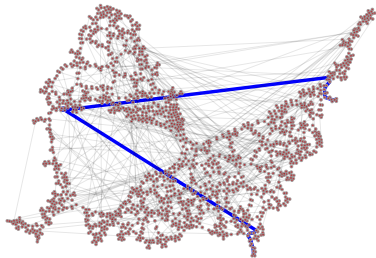
Figure 2: Relative error before and after reconstruction (joined by a line segment) as a function of the original value of the descriptor. The color indicates if the error after reconstruction is smaller than before doing it (i.e., there is improvement) or not. Noise level $p = 0.1$.

Estimation of diameter \varnothing in Venice street network

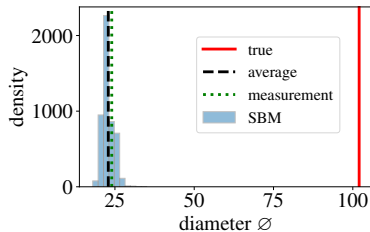
(a) True Net.



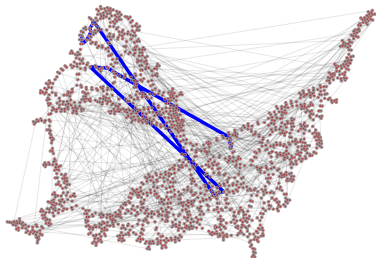
(b) Measurement



(c) Reconstruction



(d) Sample



Network Domains

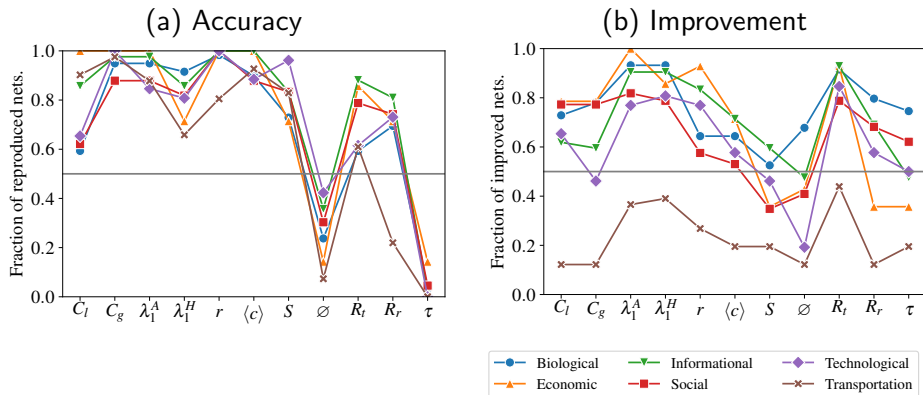


Figure 3: (a) Percentage of accurately estimated networks. (b) Average difference between the error before reconstruction and after reconstruction for each descriptor; in both cases by domain. Noise level $p = 0.1$.

Final remarks

- Does SBM provide accurate estimations of relevant features of empirical networks? Overall, yes...
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 - other parameters (e.g., upper bound for noise).
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THANK YOU!

Appendix: Dealing with error

What do we gain from doing more measurements n ?

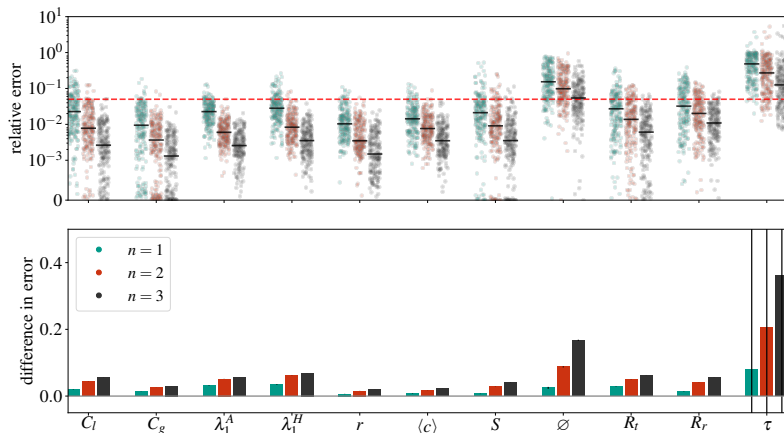


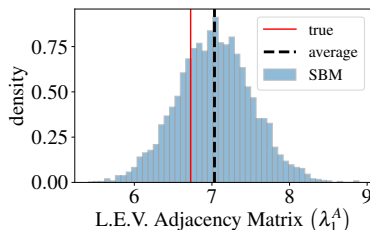
Figure 4: (Top) Percentage of accurately estimated networks. (Bottom) Average difference between the error before reconstruction and after reconstruction for each descriptor. The color maps to the number of times a node pair was measured (n). Noise level $p = 0.1$.

How to assess the Performance of Reconstruction?

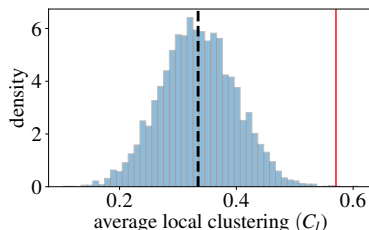
For each descriptor y , we also get a distribution...
and we can compute its average \hat{y} .

Error after reconstruction: $|(y(\mathbf{A}) - \hat{y})/y(\mathbf{A})|$,

Higher Accuracy
(error = 0.046)



Lower Accuracy
(error = 0.236)

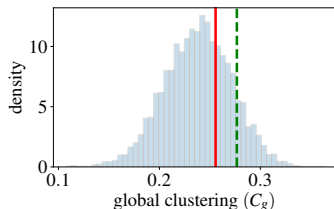


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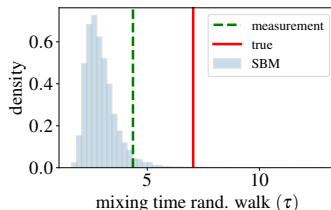
How to assess the Performance of Reconstruction?

We need a base line, e.g., the **Error before reconstruction**...

Less sensitive
(*error* = 0.021)



More sensitive
(*error* = 0.381)



What do we gain from reconstruction?