

# AR(p) Model

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Class Web Page (<https://nmimoto.github.io/477/index.html>) – R resource page  
(<https://nmimoto.github.io/R/index.html>)

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## 1. Causal Representation of AR(1)

### Alternative Notation for AR(1)

- We began with writing AR(1) as

$$X_t = \phi X_{t-1} + e_t,$$

- We could also write AR(1) as

$$X_t - \phi X_{t-1} = e_t,$$

and using the **backward operator**, write

$$\underbrace{(1 - \phi B)}_{\Phi(B)} X_t = e_t.$$

- $\Phi(z)$  is called **characteristic polynomial** of AR(1).
- Backward operator makes it go back a day:

$$BX_t = X_{t-1}.$$

## Causal Representation for AR(1)

- If AR(1) representation is

$$X_t = \phi X_{t-1} + e_t,$$

then I can write the same thing for yesterday,

$$X_{t-1} = \phi X_{t-2} + e_{t-1}$$

- Now combining the two, I can write

$$\begin{aligned} X_t &= \phi X_{t-1} + e_t \\ &= \phi \{ \phi X_{t-2} + e_{t-1} \} + e_t \\ &= \phi^2 X_{t-2} + \phi e_{t-1} + e_t \end{aligned}$$

- Do it again, this time for  $X_{t-2}$  and we get

$$\begin{aligned} X_t &= \phi^2 X_{t-2} + \phi e_{t-1} + e_t \\ &= \phi^2 (\phi X_{t-3} + e_{t-2}) + \phi e_{t-1} + e_t \\ &= \phi^3 X_{t-3} + \phi^2 e_{t-2} + \phi e_{t-1} + e_t \end{aligned}$$

- We can keep doing this, and get

$$X_t = \phi^k X_{t-k} + \phi^{k-1} e_{t-(k-1)} + \dots + \phi e_{t-1} + e_t$$

- If  $|\phi| < 1$ , then letting  $k \rightarrow \infty$  will yield

$$X_t = e_t + \phi e_{t-1} + \phi^2 e_{t-2} + \dots = \sum_{i=0}^{\infty} \phi^i e_{t-i}$$

- So here's **causal representation** for AR(1) process

$$X_t = \sum_{i=0}^{\infty} \phi^i e_{t-i} = e_t + \phi e_{t-1} + \phi^2 e_{t-2} + \dots$$

- This is called **causal representation** because we can write  $Y_t$  as infinite sum of **past** errors (innovations).

## Get Mean of AR(1) using Causal Representation

- Now it is easy to see that mean of AR(1)

$$E(X_t) = \sum_{i=0}^{\infty} \phi^i E(e_{t-i}) = 0$$

- Recall  $e_t$  are White Noise with mean 0 and variance  $\sigma$ .
- Or often, we assume

$$e_t \sim N(0, \sigma^2)$$

## Causal Representation and Characteristic Polynomial

- Recall yet another way to write AR(1),

$$(1 - \phi B) X_t = e_t.$$

- This means that we can write

$$X_t = \frac{1}{(1 - \phi B)} e_t.$$

- Compare this with Causal representation

$$X_t = e_t + \phi e_{t-1} + \phi^2 e_{t-2} + \dots = 1 + \phi B + \phi^2 B^2 + \dots e_t$$

- So we have the equivalence on the right hand side,

$$\frac{1}{(1 - \phi B)} = 1 + \phi B + \phi^2 B^2 + \phi^3 B^3 + \dots$$

- This is exactly same as the geometric series,

$$\frac{1}{1-x} = 1 + x + x^2 + x^3 + \dots$$

- Note that the condition for the geometric series is

$$|x| < 1 \quad \text{or} \quad |\phi| < 1$$

Which is same as the **causal (stationary) condition**.

## Another look at Causal Condition

- So if you write AR(1) in causal way,

$$X_t = \sum_{i=0}^{\infty} \phi^i e_{t-i},$$

- Then we can calculate variance as

$$\text{Var}(X_t) = \text{Var} \left[ \sum_{i=0}^{\infty} \phi^i e_{t-i} \right] = \sum_{i=0}^{\infty} \text{Var} [\phi^i e_{t-i}] = \sum_{i=0}^{\infty} \phi^{2i} \text{Var}(e_{t-i}) = \sigma^2 \sum_{i=0}^{\infty} \phi^{2i}$$

This does not converge unless  $|\phi| < 1$ .

- When it does converge, the variance is  $\sigma^2/(1 - \phi^2)$ .

## Causal Condition of AR(1)

- We can represent AR(1) in causal representation only when  $|\phi| < 1$ .

$$X_t = e_t + \phi e_{t-1} + \phi^2 e_{t-2} + \dots$$

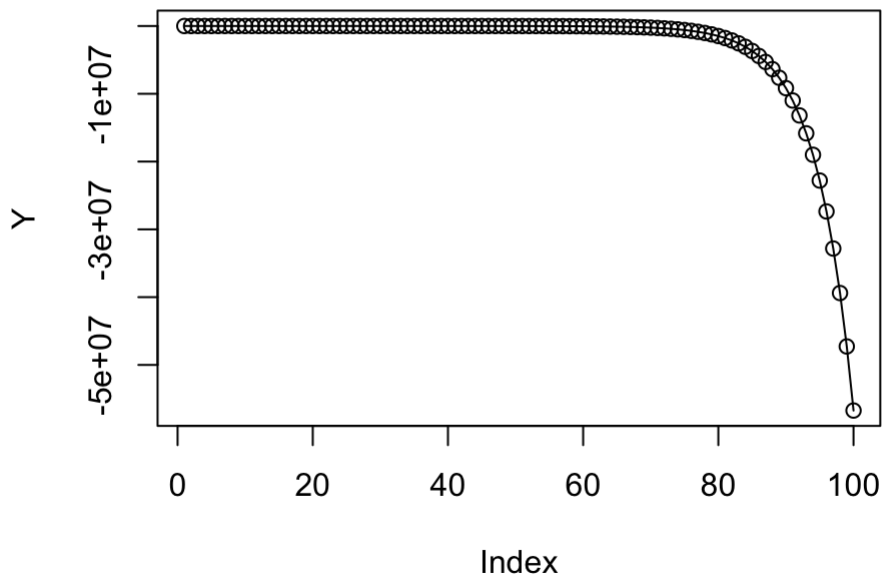
- When AR(1) has  $|\phi| > 1$ , and if you represent that with past errors, then it is called explosive process, and it's not stationary.
- When AR(1) has  $|\phi| > 1$ ,  $Y_t$  can be written as infinite sum of future errors, and it is a unique stationary solution to AR(1) equation.
- When  $|\phi| = 1$ , then there is no stationary solution.  
What is the other name of  $Y_t$  when  $\phi = 1$ ?
- We will assume that all AR process we deal with are causal.
- If AR process is not causal, then it can be re-written as causal process with different innovations. (Prob 3.8).

## Simulating non-causal AR(1)

Let  $\phi = 1.2$ . i.e.  $\Phi(z) = 1 - 1.2z$

```
Y <- arima.sim(list(ar = c(1.2) ), 100 )      ## gives error because of  
phi=1.2
```

```
## Hand written simulation  
Y <- 0.5  
phi <- 1.2  
e <- rnorm(100)  
for (t in 2:100){  
  Y[t] = Y[t-1]*phi + e[t]  
}  
plot(Y, type="o")
```



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## 2. AR(p) processes

- Autoregressive process of order  $p$  is

$$X_t - \phi_1 X_{t-1} - \phi_2 X_{t-2} - \dots - \phi_p X_{t-p} = e_t,$$

where  $e_t \sim WN(0, \sigma^2)$

and  $\phi_1, \dots, \phi_p$  is real valued constant.

- Alternative notation using characteristic polynomial is,

$$\underbrace{(1 - \phi_1 B - \phi_2 B^2 - \dots - \phi_p B^p)}_{\Phi(B)} X_t = e_t.$$

$$\Phi(B) X_t = e_t.$$

## Writing AR(p) in Causal Rep.

- Using the characteristic polynomial,

$$\Phi(B) X_t = e_t$$

$$X_t = \frac{1}{\Phi(B)} e_t$$

- So if we could write AR(p) as causal,

$$X_t = \psi_0 + \psi_1 e_t + \psi_2 e_{t-2} + \psi_3 e_{t-3} + \dots$$

$$= (\psi_0 + \psi_1 B + \psi_2 B^2 + \psi_3 B^3 + \dots) e_t$$

- That means we must be able to write polynomial as

$$\frac{1}{(1 - \phi_1 z - \phi_2 z^2 - \dots - \phi_p z^p)} = \psi_0 + \psi_1 z + \psi_2 z^2 + \psi_3 z^3 + \dots$$

- When can we do this?

## Causal Condition for AR(p)

- From operator theory, we know that if

(complex) root of  $\Phi(z)$  is outside of the unit circle,

we can expand the inverse of  $\Phi(z)$  as

$$\frac{1}{\Phi(z)} = \psi_0 + \psi_1 z + \psi_2 z^2 + \psi_3 z^3 + \dots$$

- This is the condition that allows us to write AR(p) in causal representation.
- We have seen that causal condition for AR(1) was  $|\phi| < 1$ .

- This was because polynomial

$$\Phi(z) = (1 - \phi z)$$

will have root inside the unit circle if  $|\phi| > 1$ .

- AR(p) will admit the causal representation if the characteristic polynomial

$$\Phi(z) = 1 + \phi_1 z + \phi_2 z^2 + \phi_3 z^3 + \dots + \phi_p z^p$$

has all the roots outside of the unit circle. Causal representation will ensure stationarity.

## Example: Checking Causality 1

- Check to see of AR(2) model,

$$Y_t = .4Y_{t-1} - .3Y_{t-2} + e_t$$

is causal (stationary).

- We have to look at the root of

$$\Phi(z) = 1 - .4z + .3z^2$$

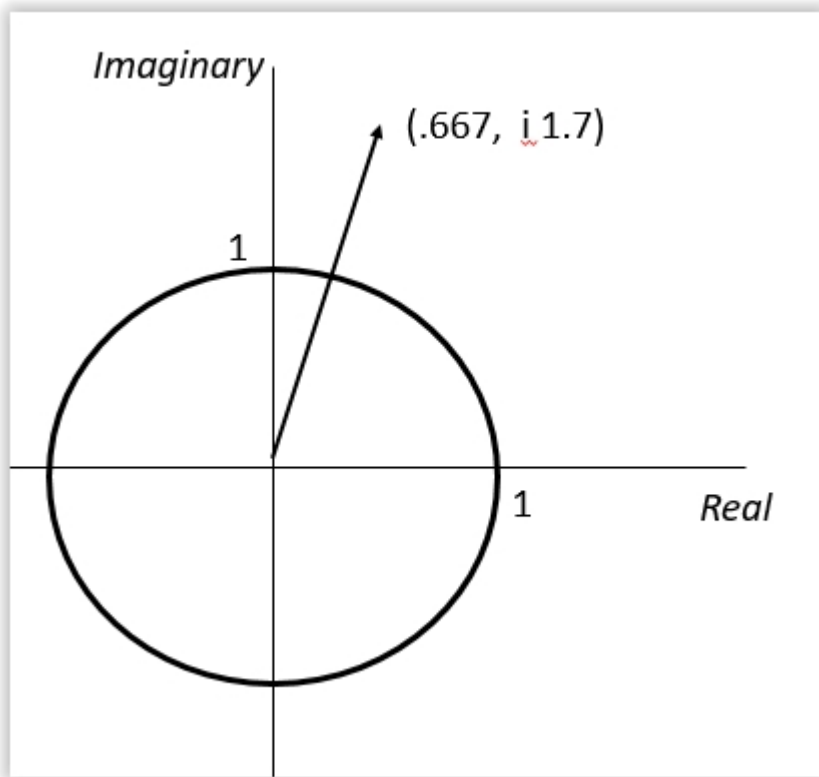
which is

$$\frac{-b \pm \sqrt{b^2 - 4ac}}{2a} = \frac{.4 \pm \sqrt{(.4)^2 - 4(.3)(1)}}{2(.3)} = .667 \pm i1.7$$

- Their distance from the origin is

$$\sqrt{(.667)^2 + (i1.7)^2} = 1.826$$

So the roots are outside the complex unit circle. Thus this AR(2) is causal.



## Example: Checking Causality 2

- Check to see of AR(2) model,

$$Y_t = -.7Y_{t-1} - .6Y_{t-2} + e_t$$

is causal or not.

- We have to look at the root of

$$\Phi(z) = 1 + .7z + .6z^2,$$

which has roots  $-.583 \pm 1.15i$ .

```
z <- polyroot(c(1,.7,.6))    # find root of 1+.7z+.6z^2
z                             #- see the root
```

```
## [1] -0.583333+1.15169i -0.583333-1.15169i
```

```
Mod(z)                        #- Distance from origin
```

```
## [1] 1.290994 1.290994
```

- They are at distance  $\sqrt{(-.583)^2 + (1.15i)^2} = 1.29$  from origin. Therefore, this AR(2) is causal.



## Example: Checking Causality 3

- Given

$$X_t = .7X_{t-1} + .6X_{t-2} + e_t,$$

Check the causality.

- we look at the root of

$$\Phi(z) = 1 - .7z - .6z^2,$$

```
z <- polyroot(c(1,-.7,-.6))  
z
```

```
## [1] 0.8333333+0i -2.0000000+0i
```

```
Mod(z)
```

```
## [1] 0.8333333 2.0000000
```

- The polynomial has roots .833, .2. Therefore, this AR(2) is not causal.

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## Summary

- AR( $p$ ) is defined as

$$\begin{aligned} X_t - \phi_1 X_{t-1} - \phi_2 X_{t-2} - \dots - \phi_p X_{t-p} &= e_t, \\ (1 - \phi_1 B - \phi_2 B^2 - \dots - \phi_p B^p) X_t &= e_t. \\ \Phi(B) X_t &= e_t. \end{aligned}$$

where  $\phi_1, \dots, \phi_p$  is real valued constant, and  $e_t \sim WN(0, \sigma^2)$ .

- AR( $p$ ) can be written in causal representation,

$$X_t = \sum_{i=0}^{\infty} \phi^i e_{t-i},$$

when its characteristic polynomial  $\Phi(z)$  has all the roots **outside** of the unit circle on the imaginary plane.

- When the  $AR(p)$  can be written as causal process, then it is stationary.
- You can use **polyroot()** function in R to calculate the roots of polynomial, and **Mod()** to calculate their distance from the origin.

```
z <- polyroot(c(1,.7,.6))  # find root of 1+.7z+.6z^2
z                          # see the root
Mod(z)                    # Distance from origin
```