

NETWORK MODEL

Motivated by anisotropic characteristics in connectivity in local cortical circuits found in the rat's brain, a network model with anisotropic tissue geometry is developed. Employing both a graph theoretic definition and a numerical implementation, distance-dependent connectivity present in the model is exposed. The introduction of a rewiring algorithm and quantitative anisotropy measure lays the foundation for the analysis of structural aspects of the anisotropic network model in Chapter ??.

1.1 REWIRING

*eliminate
anisotropy to find
structures caused
by it*

Distance-dependency as identified in the last section may already account for many of the structural features present in anisotropic networks. A central question of this study is: What structural aspects in the network are truly features of the anisotropy in connectivity? Although a quantitative measure for anisotropy will only be introduced in the next section, already here we are able to qualitatively observe the strong directionality in connectivity - edges originating from one node “point in the same direction”, effectively aligning with the orientation of the axonal projection of the source node (cf. ??). To answer the question above, we need to introduce a method that eliminates this directionality, making networks essentially isotropic in connectivity. Then, structural features present in the original anisotropic networks, but not in their rewired, isotropic counterparts may be attributed to anisotropy.

Rewiring as introduced here, provides the transition from anisotropic connectivity to networks isotropic in connectivity, closely resembling purely distance-dependent networks. Applying this process only partially then allows us to analyse structural features as they change with a varying degree of isotropy, asserting the importance of this process to our study. In designing the specific rewiring algorithm we identify two requirements that our implementation should satisfy:

1. elimination of anisotropy in connectivity
2. preservation of distance-dependent connectivity

The second point is especially important to us, as we want to impose isotropy on the network at “minimal cost”, that is by changing as little as possible about the other characteristics of the network’s connectivity. The following process respects both of the points above:

For every edge between vertices v and v' with inter-vertex distance x , identify neurons with distance to v in the range of $(x - \varepsilon, x + \varepsilon)$ as potential new targets. Then pick at random one of these vertices (including v') as a new target for the current edge, if such an edge doesn’t already exist (Figure 1.1).

In the graph theoretic context we formally define a rewiring as follows:

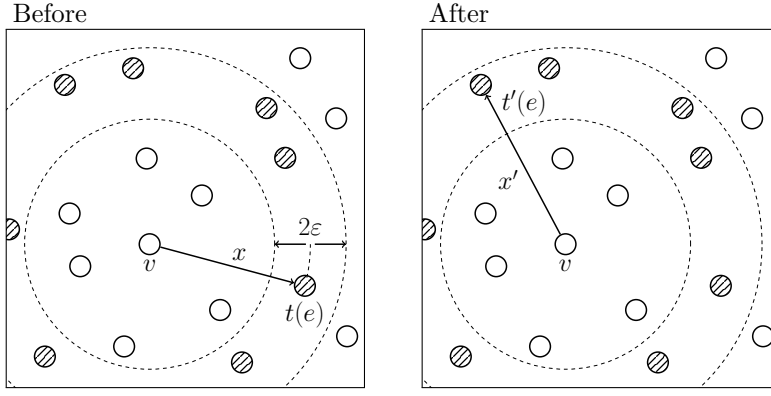


Figure 1.1: Rewiring transforms anisotropic geometric graphs to networks with isotropic connectivity For a given edge e with a distance x from its source vertex v to its target vertex $t(e)$, potential new targets (striped) are found in within a distance $(x - \varepsilon, x + \varepsilon)$ of v . The rewired edge then projects from v to a new target $t'(e)$, randomly chosen from the set of vertices within in this range. Inter-vertex distance between v and $t'(e)$ differs by less than ε from x , ensuring that for small ε the original distance-dependent connectivity is preserved. (Note that all targets within range are eligible for rewiring as no other edges exist. In general this is not the case.)

Definition 1.1. Let G be an anisotropic geometric graph with $|V(G)| = n$ and $\varepsilon > 0$. Then we define a *rewiring* R_ε of G to be probability space over G_Φ^n , induced by the following process: For every edge $e \in E(G)$ uniformly at random pick a potential new target $t'(e)$ from the set $M_e = T_e \setminus K_e$, where T_e is the set of all vertices that differ in their distance to $s(e)$ less than ε from the distance of $s(e)$ to $t(e)$,

$$T_e = \{v \in V(G) \setminus s(e) \mid |d(s(e), v) - d(s(e), t(e))| < \varepsilon\}$$

and K_e the set vertices that already are connected to $s(e)$ by another rewired edge,

$$K_e = \{v \in V(G) \mid \exists e' \in E'(G) : s(e') = s(e), t(e') = v\},$$

where $E'(G)$ is the set of all edges that have been rewired already.

Note that in the way Definition 1.1 is formulated, it is possible for M_e to be empty for some edge e . In this case no new edge is realized and the resulting, rewired network has $|E(G)| - 1$ edges. In practice this happens negligibly seldom, out of approximately on average only 25.68 edges, with a standard deviation of 4.51 and accounting for roughly 0.02% of the rewired edges, are “lost” in this process (4afc2727).

We formulated Definition 1.1 in such a way, that distance-dependent connectivity is preserved. We verify this claim by the following estimation:

$$d(v, w) = \|\Phi(v) - \Phi(w)\|$$

*Euclidean distance
between vertices*

Let $\tilde{C}(x)$ be the distance-dependent connectivity profile of a rewiring R_ε of an anisotropic graph $G_{n,w}$. Denote with $C(x)$ the distance-dependent connection probability of the $G_{n,w}$. The expected value for $\tilde{C}(x)$ at any inter-vertex distance $x \in [0, \sqrt{2}]$ is given as an average over the connection probabilities $C(x)$ of the possible sources to the new edge at distance x

$$\mathbf{E} [\tilde{C}(x)] = \frac{1}{2\varepsilon} \int_{x-\varepsilon}^{x+\varepsilon} C(x') dx'.$$

Note that for this expression to be well defined in the boundary cases, we need to extend $C(x)$ to have $C(x) = 0$ for $x < 0$ and $x > \sqrt{2}$. We can then estimate the expected difference between $\tilde{C}(x)$ and $C(x)$ at any point x as

$$\begin{aligned} |\mathbf{E} [\tilde{C}(x) - C(x)]| &= \left| \frac{1}{2\varepsilon} \int_{x-\varepsilon}^{x+\varepsilon} C(x') - C(x) dx \right| \\ &= \frac{1}{2\varepsilon} \left\{ \int_{x-\varepsilon}^x C(x') - C(x) dx - \int_x^{x+\varepsilon} C(x') - C(x) dx \right\} \\ &\leq \frac{1}{2\varepsilon}, \end{aligned} \tag{1.1}$$

The rewiring margin ε thus simultaneously governs how many new targets are available for each edge and how well distance-dependency is preserved. Setting $\varepsilon = 1.25$ and applying the rewiring algorithm to the 25 sample graphs, we find that distance-dependent connectivity of the original graphs is matched (Figure 1.2) while at the same time ensuring that for any edge e sufficiently many new rewiring targets are available (??).

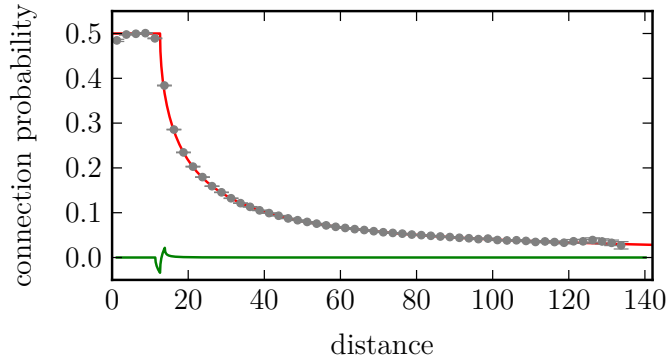


Figure 1.2: Rewiring with $\varepsilon = 1.25$ preserves distance-dependent profile in sample graphs Comparing the distance-dependent connection probabilities of the original graph (Theorem ??) in red with extracted of probabilities from the rewired ($\varepsilon = 1.25$) sample graphs in gray (errorbars SEM) we verify that distance-dependent connectivity is preserved when rewiring. The green curve shows the expected difference between the original and rewired distance profiles as estimated in Equation 1.1. (4f4d4cf1)

As a generalization of Definition 1.1, we define a partial rewiring $R_{\varepsilon,\eta}$, finding new targets only for a fraction η of all edges:

Definition 1.2. Let $\varepsilon > 0$ and $0 \leq \eta \leq 1$. A *partial rewiring* $R_{\varepsilon,\eta}$ of an anisotropic geometric graph $G_{n,w}$ is then a rewiring R_ε of $G_{n,w}$, in which every edge is rewired with a probability of η , otherwise it remains. To avoid the occurrence of multiple edges, K_e is then extended to include the targets of all edges originating from $s(e)$ that will not be rewired.

Clearly the result above of partial rewirings preserve distance-dependent connectivity. Using the we extend our set of sample graphs once more adding rewired graphs with rewiring margin $\varepsilon = 1.25$ with fractions $\eta = 0.25$, $\eta = 0.5$, $\eta = 0.75$ and $\eta = 1$, presenting a complete rewiring.