

# Advent of Code 2025 in Typst 🧑🏻

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## day 1

### Problem summary

Given a **sequence** of dial **rotations** on a **circular scale** from **0** to **99**, **starting at** position **50**, determine **how often** the dial **reaches position 0** after applying each rotation in order.

### Mathematical formulation

- Let the dial positions be elements of the cyclic group  $\mathbb{Z}_{100}$ .
- Let the initial position be  $x_0 = 50$ .
- Let the sequence of  $n$  rotations be  $(d_i, k_i)$  with  $d_i \in \{L, R\}$  and  $k_i \in \mathbb{N}$ .

Define the signed rotation

$$s_i = \begin{cases} -k_i & \text{if } d_i = L \\ k_i & \text{if } d_i = R \end{cases}$$

and the position update

$$x_i \equiv x_{i-1} + s_i \pmod{100}, \quad i = 1, \dots, n.$$

The password is the number of indices  $i$  for which the dial reaches zero

$$P = |\{i \in \{1, \dots, n\} : x_i = 0\}|.$$

### Mathematische Formulierung

Die Drehscheibe besitzt die Positionen des zyklischen Raums  $\mathbb{Z}_{100}$ . Der Anfangswert ist  $x_0 = 50$ .

Die Eingabe sei eine Folge von ganzen Zahlen  $r_1, r_2, \dots, r_n$ , wobei jede Zahl bereits ein Vorzeichen trägt. Ein Eintrag ist negativ, falls die ursprüngliche Richtung L war, und positiv, falls die ursprüngliche Richtung R war.

Die Aktualisierung der Position erfolgt durch

$$x_i \equiv x_{i-1} + r_i \pmod{100} \quad \text{für } i = 1, \dots, n.$$

Das Passwort ergibt sich aus der Anzahl der Schritte, in denen die Position den Wert null annimmt:

$$P = |\{i \in \{1, \dots, n\} : x_i = 0\}|.$$

### Python3

python

```
1 >>> from main import xs
2 >>>
3 >>> xs
```

```

4 '\nL68\nL30\nR48\nL5\nR60\nL55\nL1\nL99\nR14\nL82\n'
5 >>>
6 >>> xs.split()
7 ['L68', 'L30', 'R48', 'L5', 'R60', 'L55', 'L1', 'L99', 'R14', 'L82']
8 >>>
9 >>> xs.replace("L", "+")
10 '\n+68\n+30\nR48\n+5\nR60\n+55\n+1\n+99\nR14\n+82\n'
11 >>>
12 >>> xs.replace("L", "+").replace("R", "-")
13 '\n+68\n+30\n-48\n+5\n-60\n+55\n+1\n+99\n-14\n+82\n'
14 >>>
15 >>> xs.replace("L", "+").replace("R", "-").split()
16 ['+68', '+30', '-48', '+5', '-60', '+55', '+1', '+99', '-14', '+82']
17 >>>
18 >>> [int(e) for e in xs.replace("L", "+").replace("R", "-").split()]
19 [68, 30, -48, 5, -60, 55, 1, 99, -14, 82]
20 >>>
21 >>> list( map(int, xs.replace("L", "+").replace("R", "-").split()) )
22 [68, 30, -48, 5, -60, 55, 1, 99, -14, 82]
23 >>>
24 >>> (50 + 68) % 100
25 18
26 >>>
27 >>> (50 - 68) % 100
28 82
29 >>>
30 >>> list( map(int, xs.replace("L", "-").replace("R", "+").split()) )
31 [-68, -30, 48, -5, 60, -55, -1, -99, 14, -82]

```

~ Define the signed rotation

$$s_i = \begin{cases} -k_i & \text{if } d_i = L \\ k_i & \text{if } d_i = R \end{cases}$$

```

32 >>>
33 >>> for r in map(int, xs.replace("L", "-").replace("R", "+").split()):
34 ...     print(temp)
35 ...     temp = (temp + r) % 100

```

~ and the position update

$$x_i \equiv x_{i-1} + s_i \pmod{100}, \quad i = 1, \dots, n.$$

```

36 ...     print(temp)
37 ...     if temp == 0: count += 1

```

~ The password is the number of indices  $i$  for which the dial reaches zero

$$P = |\{i \in \{1, \dots, n\} : x_i = 0\}|.$$

```

38 ...     print(count)

```

```

39 ...

```

```

40 50

```

```

41 82

```

```

42 0

```

```

43 82

```

```

44 52

```

```

45 0

```

```

46 52

```

```

47 0

```

```

48 1

```

```

49 0

```

```

50 95

```

```

51 1

```

```

52 95
53 55
54 1
55 55
56 0
57 2
58 0
59 99
60 2
61 99
62 0
63 3
64 0
65 14
66 3
67 14
68 32
69 3
70 >>>
71 >>>
72 >>> (lambda xs: (
73 ...     lambda pos, c:
74 ...         [(pos := (pos + r) % 100,
75 ...           c := c + (pos == 0))
76 ...         for r in map(int, xs.replace("L", "-").replace("R",
77 ...     "+" ).split())],
78 ...         c)[1]
79 ...     )(50, 0))(xs)
80 >>>
81 >>>

```

## typst

```

1 #let count-zeros(xs) = {
2   let steps = xs.replace("L", "-").replace("R", "+").split().map(int)
3   let result = steps.fold((50, 0), (acc, r) => {
4     let pos = calc.rem((acc.at(0) + r), 100)
5     let cnt = acc.at(1) + int(pos == 0)
6     (pos, cnt)
7   })
8   result.at(1)
9 }

```

```
1 #count-zeros("L68 L30 R48 L5 R60 L55 L1 L99 R14 L82")
```