

view_frames Result

Recorded at time: 1507212953.600



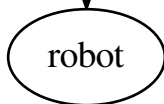
world

Broadcaster: /odometry

Average rate: 10.204 Hz

Most recent transform: 1507212953.509 (0.091 sec old)

Buffer length: 4.900 sec



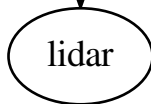
robot

Broadcaster: /lidar_broadcaster

Average rate: 10.204 Hz

Most recent transform: 1507212953.577 (0.022 sec old)

Buffer length: 4.900 sec



lidar