

P1

a) $P_m(x) \in \mathbb{R}[x]$, $m \in \mathbb{Z}_{\geq -1}$, $P_{-1} = 0$, $P_0 = 1$

First note that $P_{m+1} - x P_m \in \mathbb{R}_m[x]$ (Since P_ℓ 's are monic)

So, we can write

$$P_{m+1} - x P_m = \sum_{\ell=0}^m a_\ell P_\ell, \quad a_\ell \in \mathbb{R}$$

take the product $\langle \cdot, P_s \rangle$ with $s \in \{0, \dots, m-2\}$, so we get

$$\underbrace{\langle P_{m+1}, P_s \rangle}_{=0} - \langle x P_m, P_s \rangle = \underbrace{\sum_{\ell=0}^m a_\ell \langle P_\ell, P_s \rangle}_{=a_s \langle P_s, P_s \rangle}$$

and $\langle x P_m, P_s \rangle = \langle P_m, x P_s \rangle = 0 \Rightarrow a_s = 0$ for $s = 0, \dots, m-2$

Then, we take the product with P_{m-1} :

$$\underbrace{\langle P_{m+1}, P_{m-1} \rangle}_{=0} - \langle P_m, x P_{m-1} \rangle = a_{m-1} \langle P_{m-1}, P_{m-1} \rangle$$

$\Rightarrow a_{m-1} = - \frac{\langle P_m, x P_{m-1} \rangle}{\langle P_{m-1}, P_{m-1} \rangle} = - \frac{\langle P_m, P_m \rangle}{\langle P_{m-1}, P_{m-1} \rangle}$ here, use that $x \cdot P_{m-1} = P_m + q$, $q \in \mathbb{F}_{m-1}[x]$

Finally we take the product with P_m and we get

$$- \langle P_m, x P_m \rangle = a_m \langle P_m, P_m \rangle \Rightarrow a_m = - \frac{\langle P_m, x P_m \rangle}{\langle P_m, P_m \rangle}$$

So
$$P_{m+1} = \left(x - \frac{\langle P_m, x P_m \rangle}{\langle P_m, P_m \rangle} \right) P_m - \frac{\langle P_m, P_m \rangle}{\langle P_{m-1}, P_{m-1} \rangle} P_{m-1}$$

which is what we wanted

Note: alternatively, we could have considered $f = P_{m+1} - (x - \alpha_m)P_m + \beta_m P_{m-1}$ and show that, ~~adjusting~~ choosing α_m and β_m appropriately $\langle f, P_l \rangle = 0$ for $l = 0, \dots, m$ and $\deg(f) = m$ hence $f = 0$.

b) we consider $\psi = e^{-x^2/2} \cdot u$, so $\frac{d^2\psi}{dx^2} = \frac{d}{dx} \left(-x e^{-x^2/2} u + e^{-x^2/2} \frac{du}{dx} \right)$

$$= e^{-x^2/2} \left(x^2 u - 2x \frac{du}{dx} - u + \frac{d^2u}{dx^2} \right)$$

Replacing back into the Schrödinger eq.:

$$\frac{d^2u}{dx^2} - 2x \frac{du}{dx} + (2\varepsilon - 1)u = 0 \quad (*)$$

c) we try the ansatz $u = \sum_{i=0}^{\infty} C_i x^i$, so $\frac{du}{dx} = \sum_{i=0}^{\infty} i C_i x^{i-1}$

$$\frac{d^2u}{dx^2} = \sum_{i=0}^{\infty} i(i-1) C_i x^{i-2}$$

Putting this in $(*)$, we get

$$\sum_{i=0}^{\infty} \left[i(i-1) C_i x^{i-2} - 2i C_i x^{i-1} + (2\varepsilon - 1) C_i x^i \right] = 0$$

we look at the coeff. of x^i and get:

$$(i+1)(i+2)C_{i+2} - 2i C_i + (2\varepsilon - 1) C_i = 0 \Rightarrow C_{i+2} = C_i \cdot \frac{(2i+1-2\varepsilon)}{(i+1)(i+2)}$$

So, for arbitrary $\varepsilon \in \mathbb{R}$, these solutions are infinite series.

Let's write some of the terms on this recursion relation, to see if we can truncate them for special values of ε :

$$C_2 = C_0 \frac{(1-2\epsilon)}{2}$$

$$C_3 = C_1 \frac{(3-2\epsilon)}{6}$$

$$C_4 = C_2 \frac{(5-2\epsilon)}{12}$$

$$C_5 = C_3 \frac{(7-2\epsilon)}{20}$$

$$C_6 = C_4 \frac{(9-2\epsilon)}{30}$$

⋮

and so on. Clearly, C_k with k odd are related between them and same for k even. So, in order for the series to truncate, we need $\epsilon = \frac{2l+1}{2} = l + \frac{1}{2}$ with $l=0,1,2,\dots$. This will set ~~$C_k = 0$~~ $C_k = 0$ for $k \geq \delta$ for certain δ and, for all odd or even k , and we can set $C_s = 0$ for all ~~even or odd~~ even or odd s respectively, hence solving all equations for the C_i coefficients ~~and~~ by setting only a finite number of them to be non zero.

~~Let's do examples~~ The eq. looks like then:

$$\frac{d^2 u}{dx^2} - 2x \frac{du}{dx} + 2l \cdot u = 0 \quad l=0,1,2,\dots$$

Let's write some of the solutions we found:

$$l=0, \epsilon = \frac{1}{2} \Rightarrow u=1 \quad (\text{only } C_0 \neq 0, \text{ we normalize } C_0=1)$$

$$l=1, \epsilon = \frac{3}{2} \Rightarrow u=x \quad (\text{only } C_1 \neq 0, \text{ we set } C_0=C_2=C_4=\dots=0, \text{ and normalize to make it monic})$$

$$l=2, \epsilon = \frac{5}{2} \Rightarrow u = C_0 - 2x^2 \cdot C_0 \xrightarrow{\text{make it monic}} u = -\frac{1}{2} + x^2$$

$$l=3, \epsilon = \frac{7}{2} \Rightarrow u = -\frac{3}{2}x + x^3$$

~~$$L = 4, E = \frac{9}{2} \Rightarrow u = \frac{3}{4} - 3x^2 + x^4$$~~

P2)

a) Suppose $\lambda \in \sigma(A)$, then $\exists v \neq 0$ s.t. $Av = \lambda v$, also wlog

we can assume k is s.t. $A^k = 0$ and $A^{k-1} \neq 0$, so we have

$$\underbrace{A^k}_{\vec{0}} v = \lambda \cdot A^{k-1} v = \lambda^k \cdot v = 0$$

Since $v \neq 0 \Rightarrow \lambda^k = 0 \Rightarrow \lambda = 0$

~~Q~~ $Q = \begin{pmatrix} A & D \\ 0 & B \end{pmatrix}$ if $Q \in M_{m,m}(F)$ then if the block

A has dimension k (i.e. $A \in M_{k,k}(F)$) then $B \in M_{m-k,m-k}(F)$

and $D \in M_{k,m-k}(F)$ (and the block marked as 0 , is of dimension $(m-k) \times k$)

then we can write (where $\mathbb{1}_\ell$ is the identity of dimension ℓ)

$$\det(Q - \lambda \cdot \mathbb{1}_m) = \det \begin{pmatrix} A - \lambda \cdot \mathbb{1}_k & D \\ 0 & B - \lambda \cdot \mathbb{1}_{m-k} \end{pmatrix} = \det((A - \lambda \cdot \mathbb{1}_k) \cdot (B - \lambda \cdot \mathbb{1}_{m-k}))$$

$$= \det(A - \lambda \cdot \mathbb{1}_k) \det(B - \lambda \cdot \mathbb{1}_{m-k})$$

c) we did this one in the lecture. ~~Up to now~~

If we write $v \in V$ as $v = \sum_{i=1}^m a_i v_i$, then

$$Qv = \sum_{i=1}^m a_i Qv_i = \sum_{i=1}^k a_i \lambda_i v_i + \sum_{\ell=k+1}^m a_\ell \sum_{j=1}^m M(Q)_{\ell j} v_j$$

So, clearly, for $i=1, \dots, k$ ~~$Q \cdot v_i = \lambda_i v_i$~~ $\lambda_i v_i = Q \cdot v_i$ (1)

and for $l=k+1, \dots, m$ ~~$Q \cdot v_l = \sum_{j=1}^m M(Q)_{lj} v_j$~~

then, from (1):

$$M(Q)_{ij} = \begin{cases} \lambda_i & i=j \\ 0 & \text{otherwise} \end{cases} \quad \text{for } i, j \in \{1, \dots, k\} \quad \text{where } \lambda_1 = \dots = \lambda_k = \lambda$$

$$M(Q)_{lj} = 0 \quad \text{for } l \in \{k+1, \dots, m\} \quad j \in \{1, \dots, k\}$$

and for the rest of components of $M(Q)$ we cannot say anything, but this is enough to write:

$$M(Q) = \begin{pmatrix} \lambda \cdot 1_k & D \\ 0 & B \end{pmatrix} \quad \begin{matrix} D \in M_{k, m-k}(\mathbb{R}) \\ B \in M_{m-k, m-k}(\mathbb{R}) \end{matrix}$$

d) Suppose Q has an eigenvalue $\lambda \in \sigma(Q)$, then denote $\{v_1, \dots, v_k\}$ a basis of the space $V_\lambda \subseteq V$, so $k = \dim V_\lambda = \text{mult}_{\text{geom.}}(\lambda)$ (geometric multiplicity of λ). Then, in this basis we can write (from c)):

$$M(Q) = \begin{pmatrix} \lambda \cdot 1_k & D \\ 0 & B \end{pmatrix}$$

Now, we consider the characteristic polynomial of Q (that doesn't depend on the ~~basis~~ choice of basis), using b) to write

$$p(\lambda') = \det(Q - \lambda' \cdot 1) = \det(M(Q) - \lambda' \cdot 1) = (\lambda - \lambda')^k \det(B - \lambda' \cdot 1) \in \mathbb{F}[\lambda']$$

so λ is a root of $p(\lambda')$ of multiplicity (algebraic multiplicity) $\geq k$

An example is $\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$ where $\dim V_{\lambda=1} = 1$ and $\text{mult}_{\text{alg.}}(\lambda=1) = 2$

P3/

a) Clearly, $0 \in V$, so we have to show that given $p(x), q(x) \in V$ and $\alpha, \beta \in \mathbb{R}$, then $\alpha p + \beta q \in V$.

$$\text{write } p = \sum_{i=0}^m a_i x^i, \quad a_i = a_{m-i}$$

$$q = \sum_{i=0}^m b_i x^i, \quad b_i = b_{m-i}$$

$$\text{so } \alpha p + \beta q = \sum_{i=0}^m (\alpha a_i + \beta b_i) x^i = \sum_{i=0}^m c_i x^i$$

$$\text{and } c_i = \alpha a_i + \beta b_i = \alpha a_{m-i} + \beta b_{m-i} = c_{m-i}, \text{ so } \alpha p + \beta q \in V$$

b) Consider $p \in V$, then write $m = 2m$, we can solve the constraints on the coefficients, $a_0 = a_{2m}, a_1 = a_{2m-1}, \dots, a_m = a_m$ ~~and so~~

$$p = \sum_{i=0}^{2m} a_i x^i = a_0 + a_1 x + \dots + a_{m-1} x^{m-1} + a_m x^m + a_{m+1} x^{m+1} + a_{m+2} x^{m+2} + \dots + a_{2m} x^{2m}$$

$$= \sum_{i=0}^{m-1} a_i (x^i + x^{m-i}) + a_m x^m$$

So, any $p \in V$ can be written as a linear combination of $\{x^i + x^{m-i}, i=0, \dots, m-1, x^m\}$. We just have to show this set is L.I., so for this we

solve the equation for $\alpha_0, \dots, \alpha_m$:

$$\sum_{i=0}^{m-1} \alpha_i (x^i + x^{m-i}) + \alpha_m x^m = 0$$

$$= \alpha_0 + \alpha_1 x + \dots + \alpha_{m-1} x^{m-1} + \alpha_m x^m + \alpha_{m-1} x^{m+1} + \dots + \alpha_0 x^{2m}$$

Since $1, x, \dots, x^m$ is a basis of $\mathbb{F}_m[x]$, the only sol. is $\alpha_i = 0 \forall i$.
So $\{x^i + x^{m-i}, i=0, \dots, m-1, x^m\}$ is a basis of $V \Rightarrow \dim V = m+1$

(4)

c) we know that $\dim \mathbb{F}_{m-1}[x] = m$ and $\dim V = m+1$ (from b)), so we need to show $V \cap \mathbb{F}_{m-1}[x] = \{0\}$ since

$$\dim(V + \mathbb{F}_{m-1}[x]) = \dim V + \dim \mathbb{F}_{m-1}[x] - \dim(V \cap \mathbb{F}_{m-1}[x])$$

Consider $p = \sum_{i=0}^m a_i x^i \in \mathbb{F}_{m-1}[x] \cap V$

Since $p \in \mathbb{F}_{m-1}[x] \Rightarrow p = \sum_{i=0}^{m-1} a_i x^i$ and $a_m = a_{m+1} = \dots = a_{2m} = 0$

Since also $p \in V$, $a_i = a_{2m-i}$ for $i=0, \dots, m \Rightarrow$

$$\begin{aligned} a_0 &= a_m = 0 \\ a_1 &= a_{2m-1} = a_{2m-1} = 0 \\ &\vdots \\ a_{m-1} &= a_{m+1} = 0 \end{aligned}$$

$$\Rightarrow p = 0 \text{ so } V \cap \mathbb{F}_{m-1}[x] = \{0\}$$

d) if $p = \sum_{i=0}^m a_i x^i \in V' \Rightarrow a_m = a_{2m-m} = a_{m-m} = -a_{m-m} = -a_m \Rightarrow a_m = 0$

hence a general element of V' can be written as

$$p = \sum_{i=0}^{m-1} a_i x^i - \sum_{i=0}^{m-1} a_i x^{2m-i} = \sum_{i=0}^{m-1} a_i (x^i - x^{2m-i})$$

by an analogous argument than b), we can show $\dim V' = m$

also is very clear that $V \cap V' = \{0\}$ (since $p \in V \cap V' \Rightarrow a_i = -a_i \forall i$)

$$\therefore \mathbb{F}_m[x] = V \oplus V'$$

P4)

a) A is a symmetric matrix, so we can diagonalize A in the form

$$A = P^* D P^t$$

where P is a matrix made out of an orthonormal basis of eigenvectors of A .

the characteristic polynomial of A is given by

$$\det(A - \lambda I) = (\lambda - 2)\lambda(1 - \lambda)^2 - 1 = \lambda^2(\lambda - 2)^2$$

So we have eigenvalues $\lambda_1 = 0$ and $\lambda_2 = 2$

V_{λ_1} has a orthogonal basis $\left\{ \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \\ 1 \end{pmatrix} \right\}$, we ~~are~~ normalize the vectors and

$$V_{\lambda_1} = \text{Span} \left\{ \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \\ 1 \end{pmatrix} \cdot \frac{1}{\sqrt{2}} \right\}$$

Same for λ_2 gives $V_{\lambda_2} = \text{Span} \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ 0 \\ -1 \\ 1 \end{pmatrix} \right\}$

so $A = P D P^t$ with $P = \begin{pmatrix} 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & \frac{1}{\sqrt{2}} & 0 & -\frac{1}{\sqrt{2}} \\ 0 & \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \end{pmatrix}$ and $D = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 2 \end{pmatrix}$

b) First let's show z_1 is eigenvector of C :

$$C \cdot z_1 = M \cdot z_1 + z_1 (\underbrace{z_1^t z_1}_1) = (\lambda_1 + 1) z_1$$

So, z_1 is eigenvector with eigenvalue $\lambda_1 + 1$. For the rest ($i > 1$)

$$C \cdot z_i = M \cdot z_i + z_1 (\underbrace{z_1^t z_i}_0) = \lambda_i z_i$$

So $z_i, i > 1$ are eigenvectors w/ eigenvalue λ_i

- a) $u \in U \Rightarrow u \in \text{Ker } T \text{ or } Tu = 0 \in U$
- b) Consider $u \in U$, then $Tu \in \text{Image } T \subset U \Rightarrow Tu \in U$
- c) Consider $v \in \text{Ker } S$, then $z = Tv$ and $Sz = STv = TSv = 0$
 $\text{or } z \in \text{Ker } S$ \uparrow
 $v \in \text{Ker } S$
- d) Consider $v \in \text{Image } S$, so we can write $v = S \cdot u$, for some $u \in U$, then

$$Tv = TS \cdot u = STu = S(Tu) \in \text{Image } S$$