

P1

a) $\Lambda: V \rightarrow U$ is defined by $(\Lambda v)(\varphi) = \varphi(v)$, since Λv must be a map $V^* \rightarrow \mathbb{F}$ (i.e. $U = \mathcal{L}(V^*, \mathbb{F})$)

Consider $\alpha v + \beta u \in V$ with $u, v \in V$ and $\alpha, \beta \in \mathbb{F}$, then, we want to show

$$\Lambda(\alpha v + \beta u) = \alpha \Lambda v + \beta \Lambda u$$

in order to do this, we check how $\Lambda(\alpha v + \beta u)$ acts on an arbitrary vector $\varphi \in V^*$

$$(\Lambda(\alpha v + \beta u))(\varphi) = \varphi(\alpha v + \beta u) = \alpha \varphi(v) + \beta \varphi(u) = (\alpha \Lambda v + \beta \Lambda u)(\varphi)$$

use linearity of $\varphi \in V^* = \mathcal{L}(V, \mathbb{F})$

b) $T \in \mathcal{L}(V)$, $T^* \in \mathcal{L}(V^*)$ then $(T^*)^* \in \mathcal{L}((V^*)^*)$ and

$$(V^*)^* = \mathcal{L}(V^*, \mathbb{F}) = U \quad \text{so } (T^*)^* \in \mathcal{L}(U) \text{ and is defined by}$$

$$(*) \quad (T^*)^*(\psi) = \psi \circ T^* \quad \text{for } \psi \in U$$

Now we want to check how the map $(T^*)^* \circ \Lambda \in \mathcal{L}(V, U)$ behaves, or

$$(T^*)^* \circ \Lambda v \in U \quad \text{for } v \in V, \text{ hence we again take an}$$

arbitrary $\varphi \in V^*$ and check how $(T^*)^* \circ \Lambda v$ acts on it

$$((T^*)^* \circ \underbrace{\Lambda v}_U)(\varphi) = \underbrace{\Lambda v}_{\substack{\text{use } (*), \text{ i.e.} \\ \text{definition of } (T^*)^*}}((T^*)^*(\varphi)) = \Lambda v \circ (\varphi \circ T)$$

$$\uparrow = (\varphi \circ T)(v) \quad (1)$$

definition of Λ

(or more precisely, just definition of dual map)

on the other hand $(\Lambda \circ \underbrace{T}_V v)(\varphi) = \varphi(Tv) = \varphi \circ Tv = (1)$
as desired!

c) Since $\dim V = \dim V^* = \dim(V^*)^*$, then we only need to show Λ is injective (we already showed Λ is linear), then, ~~we can~~ consider

$$\Lambda v = 0 \iff (\Lambda v)\varphi = \varphi(v) = 0 \text{ for any } \varphi \in V^*$$

So in ^a particular basis of V , this means $M(\varphi) \cdot v = 0$ for any matrix $M(\varphi)$, in particular invertible matrices. The only solution is $v = 0$, hence Λ is injective.

d) Consider V , a real vector space, of dimension $n < \infty$, then $V^* = \mathcal{L}(V, \mathbb{R})$ and given a basis $\{v_1, \dots, v_n\}$ of V , we define the dual basis $\{\varphi_1, \dots, \varphi_n\}$ of V^* by the functions φ_i satisfying

$$\varphi_j(v_k) = \begin{cases} 1 & \text{if } j=k \\ 0 & \text{if } j \neq k \end{cases}$$

So, for example, in our case $\{1, x, x^2, x^3, \dots, x^m\}$ is a basis of $\mathbb{R}_m[x]$ and so, the dual basis of it is given by $\{\varphi_0, \dots, \varphi_m\}$ that satisfies

$$\varphi_j(x^k) = \begin{cases} 1 & \text{if } j=k \\ 0 & \text{if } j \neq k \end{cases}$$

then, we know $\{\varphi_0, \dots, \varphi_m\}$ is a basis of $(\mathbb{R}_m[x])^*$. so, ~~we~~ if we write

$$f_j = \sum_{i=0}^m L_{ji} \varphi_i, \text{ we just need to show that}$$

$L \in \mathcal{M}_{m+1, m+1}(\mathbb{R})$ is invertible. So, let's find the coefficients of L :

$$f_j(x^k) = \int_0^{a_j} x^k dx = \frac{a_j^{k+1}}{k+1} = \sum_{i=0}^m L_{ji} \varphi_i(x^k) = L_{jk}$$

So

$$L = \begin{bmatrix} a_0 & a_0^2/2 & \dots & a_0^{m+1}/(m+1) \\ a_1 & a_1^2/2 & \dots & a_1^{m+1}/(m+1) \\ \vdots & \vdots & \ddots & \vdots \\ a_m & \dots & \dots & a_m^{m+1}/(m+1) \end{bmatrix}$$

If we see the ~~character~~ determinant of L as a polynomial ~~in~~ in ~~$\mathbb{R}[a_i]$~~ $\mathbb{R}[a_i]$ (with $R = [a_0, \dots, a_{i-1}, a_{i+1}, \dots, a_m]$) is clear that it vanishes for the values ~~$a_i = 0$ or $a_i = a_j$ for any $j \in \{0, \dots, m\} \setminus \{i\}$~~ $a_i = 0$ or $a_i = a_j$ for any ~~$j \in \{0, \dots, m\} \setminus \{i\}$~~ $j \in \{0, \dots, m\} \setminus \{i\}$. Moreover, the polynomial has ~~degree~~ degree $m+1$ in a_i , so, these are all the roots, we can repeat this for any $i = 0, \dots, m$, hence we conclude that $\det L$ vanishes, whenever any of the a_i 's is zero and whenever $a_i = a_j$ for any pair i, j with $i \neq j$.

Therefore f_0, \dots, f_m form a basis ~~where~~ for all values of ~~$a_0, \dots, a_m \in \mathbb{R} \setminus \{0\}$~~ $a_0, \dots, a_m \in \mathbb{R} \setminus \{0\}$ s.t. ~~$a_i \neq a_j$~~ they are all distinct.

P2]

a) If $v \in \mathcal{L}(V^*, \mathbb{C})$ then, given any $\varphi \in V^*$ $v(\varphi) \in \mathbb{C}$, $\therefore \mathbb{C} \cdot v(\varphi) \in \mathbb{C}$ is just ordinary complex multiplication for any $\varphi \in V^*$, hence makes sense to define $\mathbb{C} \cdot v \in \mathcal{L}(V^*, \mathbb{C})$

b) ~~$\phi \in \mathcal{L}(V^*, \mathbb{R})$~~ $\phi \in \mathcal{L}(V^*, \mathbb{R})$, then $(T^{\mathbb{C}}(\phi))(f) = \phi(T^*(f)) = \phi(f \circ T)$

here $f \circ T \in V^*$ (since $f \circ T: V \rightarrow \mathbb{R}$)

by problem 1, we have an isomorphism $\Lambda: V \rightarrow \mathcal{L}(V^*, \mathbb{R})$, this means, there exist $v \in V$ s.t. $\Lambda(v) = \phi$, hence we write

$$(T^{\mathbb{C}}(\phi))(f) = \Lambda(v)(f \circ T) \underset{\text{definition of } \Lambda}{=} f \circ T v = f(Tv)$$

c) $s = v + iu \in V^{\mathbb{C}}$, so $v, u \in V$ and $T^{\mathbb{C}}(s) = T(v) + iT(u)$

$$\therefore \overline{T^{\mathbb{C}}(s)} = \overline{T(v) + iT(u)} = T(v) - iT(u)$$

$$T^{\mathbb{C}}(\bar{s}) = T^{\mathbb{C}}(v - iu) = T(v) + iT(-u) = T(v) - iT(u) = \overline{T^{\mathbb{C}}(s)}$$

[Forgot to include d_1 , sorry!, at the end]

e) Consider a ~~set~~ ^{basis} v_1, \dots, v_m of V , then we can see them as vectors in $V^{\mathbb{C}}$, just by writing $v_i = v_i + i \cdot 0 \in V^{\mathbb{C}}$

Now consider an arbitrary vector $s \in V^{\mathbb{C}}$, then

$$s = u + i t \quad \begin{matrix} \nearrow \\ u, t \in V \end{matrix} = \sum_{j=1}^m a_j v_j + i \sum_{j=1}^m b_j v_j \quad \begin{matrix} \nwarrow \\ \text{here } a_j, b_j \in \mathbb{R} \end{matrix} = \sum_{j=1}^m (a_j + i b_j) v_j$$

$$= \sum_{j=1}^m c_j v_j \quad \text{where } c_j \in \mathbb{C} \text{ and } v_j \text{ is a vector on } V^{\mathbb{C}}, \text{ by the}$$

previous reasoning. Then v_1, \dots, v_m (seen as $v_j + i \cdot 0$) ~~are~~ form a basis of $V^{\mathbb{C}}$

f) Let's compute the coefficients of $M(T^{\mathbb{C}})$ in the basis defined above:

$$T^{\mathbb{C}}(v_i) = \sum_{j=1}^m (T^{\mathbb{C}})_{ji} v_j \quad \begin{matrix} \nearrow \\ \text{definition of } M(T^{\mathbb{C}}) \\ \text{in a basis } v_1, \dots, v_m \\ \text{of } V^{\mathbb{C}} \end{matrix} = \sum_{j=1}^m T(v_i)_{ji} v_j \quad \begin{matrix} \nearrow \\ \text{definition of } T^{\mathbb{C}}(v_i) \end{matrix}$$

so $M(T^{\mathbb{C}}) = M(T)$, therefore the characteristic polynomial of $M(T^{\mathbb{C}})$ has real coefficients \Rightarrow its roots come in conjugate pairs

g) Suppose $T^{\mathbb{C}}$ is diagonalizable, i.e. \exists a basis ~~for~~ s_1, \dots, s_m of $V^{\mathbb{C}}$ s.t. $T^{\mathbb{C}} s_i = \lambda_i s_i$, $\lambda_i \in \mathbb{C}$

Suppose WLOG $\lambda_1, \dots, \lambda_r \in \mathbb{R}$, then if we write $s_j = v_j + i u_j$ for $j=1, \dots, r$ we have

$$T v_j + i T u_j = \lambda_j v_j + i \lambda_j u_j \Rightarrow \begin{matrix} T v_j = \lambda_j v_j \\ T u_j = \lambda_j u_j \end{matrix} \quad j=1, \dots, r$$

Since s_1, \dots, s_r are L.I., then, there exist r L.I. vectors in the list $\{u_1, \dots, u_r, v_1, \dots, v_r\}$ (To see this just remember that we can pick the ~~and~~ ^{basis} of V , as in part c) and write it as a linear combination, with complex coefficients, of the basis s_1, \dots, s_m)

(3)

Then, just pick any r L.I. vectors from this list ~~and~~, say e_1, \dots, e_r

then, $T e_i = \lambda_i e_i$ (depending which ones we for some $\lambda_i \in \mathbb{R}$)

Now, if $\lambda_j \in \mathbb{C}$, we know $\bar{\lambda}_j$ is also eigenvalue (by part f))

and so $T e_{s_j} = T e_{\tilde{v}_j + i \tilde{u}_j} = T \tilde{v}_j + i T \tilde{u}_j = \lambda_j \tilde{v}_j + i \bar{\lambda}_j \tilde{u}_j$

$$= \operatorname{Re}(\lambda_j) \tilde{v}_j - \operatorname{Im}(\lambda_j) \tilde{u}_j + i \operatorname{Re}(\lambda_j) \tilde{u}_j + i \operatorname{Im}(\lambda_j) \tilde{v}_j$$

and $T \bar{e}_{s_j} = \bar{\lambda}_j \bar{e}_{s_j}$ (from part c)), $\bar{e}_{s_j} = \tilde{v}_j - i \tilde{u}_j$

So, from this eq, we get

$$T \begin{pmatrix} \tilde{v}_j \\ \tilde{u}_j \end{pmatrix} = \begin{pmatrix} \operatorname{Re}(\lambda_j) & -\operatorname{Im}(\lambda_j) \\ \operatorname{Im}(\lambda_j) & \operatorname{Re}(\lambda_j) \end{pmatrix} \begin{pmatrix} \tilde{v}_j \\ \tilde{u}_j \end{pmatrix}$$

and so, in the basis $\{e_1, \dots, e_r, \tilde{v}_{r+1}, \tilde{u}_{r+1}, \dots, \tilde{v}_d, \tilde{u}_d\}$

we can write

$$M(T) = \begin{pmatrix} \lambda_1 & & & \\ & \ddots & & \\ & & \lambda_r & \\ & & & B_{r+1} & & \\ & & & & \ddots & \\ & & & & & B_d \end{pmatrix}, \quad B_i = \begin{pmatrix} \operatorname{Re}(\lambda_i) & -\operatorname{Im}(\lambda_i) \\ \operatorname{Im}(\lambda_i) & \operatorname{Re}(\lambda_i) \end{pmatrix}$$

d) Suppose \exists a basis v_1, \dots, v_m of V s.t. $M(T) = \begin{pmatrix} \lambda_1 & & & \\ & \ddots & & \\ & & \lambda_r & \\ & & & B_1 & & \\ & & & & \ddots & \\ & & & & & B_d \end{pmatrix}$

where $\lambda_i \in \mathbb{R}$ and the blocks B_i are of the form $B_i = \begin{pmatrix} a_i & -b_i \\ b_i & a_i \end{pmatrix}$, then

we can write, in the basis v_i^1, v_i^2 at each of these 2×2 blocks:

$$T v_i^1 = a_i v_i^1 - b_i v_i^2$$

$$T v_i^2 = a_i v_i^2 + b_i v_i^1$$

then is easy to see, that in the basis $\{v_1, \dots, v_r, (v_1^1 + i v_1^2), \dots, (v_d^1 + i v_d^2), (v_1^1 - i v_1^2), \dots, (v_d^1 - i v_d^2)\}$, $T^{\mathbb{C}}$ is diagonal.

P3)

a) $M_\lambda = \langle v, (T-\lambda 1)v, \dots, (T-\lambda 1)^{m-1}v \rangle$

then

$$T(T-\lambda 1)^j v = (T-\lambda 1 + \lambda 1)(T-\lambda 1)^j v = (T-\lambda 1)^{j+1} v + \lambda (T-\lambda 1)^j v$$

in particular $T(T-\lambda 1)^{m-1} v = \lambda (T-\lambda 1)^{m-1} v$

then, if we define the basis $v_j = (T-\lambda 1)^j v \quad j=0, \dots, m-1$

$$T \begin{pmatrix} v_0 \\ \vdots \\ v_{m-1} \end{pmatrix} = \begin{pmatrix} \lambda & 1 & & \\ & \ddots & \ddots & \\ & & \ddots & 1 \\ & & & \lambda \end{pmatrix} \begin{pmatrix} v_0 \\ \vdots \\ v_{m-1} \end{pmatrix}$$

b) Consider $v \in M_\lambda$, then $\exists j$ s.t. $(T-\lambda 1)^j v = 0$ and $(T-\lambda 1)^{j-1} v \neq 0$, if $j \leq m$, then $v \neq 0$

obviously $v \in \text{Ker}(T-\lambda 1)^m$. However, the grade of a vector cannot exceed m (otherwise $\langle v, \dots, (T-\lambda 1)^{p-1}v \rangle$ will have dimension higher than m) so j cannot be strictly larger than m , hence

$$M_\lambda \subseteq \text{Ker}(T-\lambda 1)^m$$

\exists ~~ker~~ $v \in \text{Ker}(T-\lambda 1)^m$, then $(T-\lambda 1)^m v = 0 \Rightarrow v \in M_\lambda$, hence

$$M_\lambda = \text{Ker}(T-\lambda 1)^m$$

Suppose $\tilde{\lambda} \notin \sigma(T)$ and $\exists v \neq 0$ s.t. $(T-\tilde{\lambda} 1)^m v = 0$ (since $v \in \text{Ker}(T-\lambda 1)^m$)
 therefore $\det[(T-\tilde{\lambda} 1)^m] = (\det(T-\tilde{\lambda} 1))^m = 0$ i.e. $\tilde{\lambda}$ is a root of the characteristic polynomial of $T \Rightarrow \tilde{\lambda} \in \sigma(T)$ *

c) $A = \begin{bmatrix} 1 & 2 & 0 \\ 1 & 1 & 2 \\ 0 & -1 & 1 \end{bmatrix}$, so $\det(A - \lambda \cdot 1) = (1 - \lambda)^3$ hence $\sigma(A) = \{1\}$ (4)

since $(A - 1)^3 = 0 \Rightarrow M_{\lambda=1} = \mathbb{R}^3$
 \swarrow defined as in b)

d) we compute the principal vectors w/ eigenvalue $\lambda=1$ (normalization is not important for this)

$$(A - 1) \cdot v = 0 \Rightarrow v_1 = \begin{pmatrix} -2 \\ 0 \\ 1 \end{pmatrix} \text{ (only sol.)}$$

$$(A - 1)^2 \cdot v = 0 \Rightarrow v_1 = \begin{pmatrix} -2 \\ 0 \\ 1 \end{pmatrix} \text{ and } v_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \text{ are sol.}$$

$$\underbrace{(A - 1)^3}_{=0} \cdot v = 0 \Rightarrow \text{any vector is a sol., in particular } \underbrace{v_1, v_2}_{\text{obvious solutions}} \text{ and } v_3 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \text{ obviously a solution!}$$

note, these vectors satisfy: $\text{gr } v_1 = 1$, $\text{gr } v_2 = 2$ and $\text{gr } v_3 = 3$

~~if~~ we could have chosen another basis, but we always get a vector of grade 3 i.e.

$$(A - 1)^3 v_3 = 0 \text{ but } (A - 1)^2 v_3 \neq 0, (A - 1) v_3 \neq 0$$

So $\langle (A - 1)^2 v_3, (A - 1) v_3, v_3 \rangle = M_{\lambda=1} = \mathbb{R}^3$

P4

a) when restricted to M_λ , we can always write $T|_{M_\lambda} = \begin{bmatrix} \lambda & 1 & & \\ & \ddots & \ddots & \\ & & \lambda & 1 \end{bmatrix}$, so if $\mu \neq \lambda$, very clearly $\det((T - \mu \cdot 1)|_{M_\lambda}) \neq 0$ hence $T - \mu \cdot 1$ is invertible, so $z = (T - \mu \cdot 1)|_{M_\lambda}^{-1} \cdot y$

b) $y = f(T)v$, $f(x) \in \mathbb{F}[x]$, suppose $(x - \lambda) \mid f(x)$ so $f(x) = (x - \lambda)g(x)$

then $y = (T - \lambda \cdot 1) \cdot \underbrace{g(T) \cdot v}_{= z}$