

P1/

a) Consider  $y \in V_i$ , then  $V_i = \text{Span}(v, (T - \lambda_i \mathbb{1})v, \dots, (T - \lambda_i \mathbb{1})^{m_i-1}v)$  for some  $v \in V$ , hence  $y = \sum_{k=0}^{m_i-1} c_k (T - \lambda_i \mathbb{1})^k v$ , then write

$$(T - \lambda \mathbb{1})y = (T - \lambda \mathbb{1} + \lambda_i \mathbb{1} - \lambda_i \mathbb{1})y = \underbrace{\sum_{k=0}^{m_i-1} c_k (T - \lambda_i \mathbb{1})^{k+1} v}_{\in V_i} + \underbrace{(\lambda_i - \lambda)y}_{\in V_i} \Rightarrow (T - \lambda \mathbb{1})y \in V_i$$

then  $(T - \lambda \mathbb{1})^k y = (T - \lambda \mathbb{1})^{k-1} \underbrace{(T - \lambda \mathbb{1})y}_{\in V_i}$ , so by induction  $(T - \lambda \mathbb{1})^k y \in V_i$

b) Now, if we restrict to  $V_i$ , we know, that in the basis  $\{v, (T - \lambda_i)v, \dots, (T - \lambda_i)^{m_i-1}v\}$   $M(T)$  takes the form  $M(T) = \begin{pmatrix} \lambda_i & 1 & & 0 \\ & \ddots & \ddots & \\ 0 & & 1 & \\ & & & \lambda_i \end{pmatrix}$ , hence, is easy to see  $\det((T - \lambda \mathbb{1})|_{V_i}) = (\lambda_i - \lambda)^{m_i}$ , hence if  $\lambda \neq \lambda_i$   $(T - \lambda \mathbb{1})|_{V_i}$  is invertible. Likewise  $\det((T - \lambda \mathbb{1})^k|_{V_i}) = (\lambda_i - \lambda)^{k \cdot m_i}$ , so if  $\lambda \neq \lambda_i$  then  $(T - \lambda \mathbb{1})^k|_{V_i}$  is invertible as well, therefore  $\dim((T - \lambda \mathbb{1})^k \cdot V_i) = m_i$

If  $\lambda = \lambda_i$ , then  $(T - \lambda_i \mathbb{1})^k$  acting on an arbitrary vector  $y \in V_i$  gives

$$(T - \lambda_i \mathbb{1})^k \cdot \left( \sum_{l=0}^{m_i-1} c_l (T - \lambda_i \mathbb{1})^l v \right) = \sum_{l=k}^{m_i-1} c_l (T - \lambda_i \mathbb{1})^l v$$

so, any  $u \in (T - \lambda_i \mathbb{1})^k \cdot V_i$  can be expressed as a linear combination of the vectors

$$(T - \lambda_i \mathbb{1})^k v, \dots, (T - \lambda_i \mathbb{1})^{m_i-1} v$$

∴  $\dim (T - \lambda_i \mathbb{1})^k V_i = m_i - k$



$$c) \quad m^2 = \sum_{\lambda_i \neq \lambda} \dim V_i$$

$l_m =$  number of  $V_i$ 's of dimension  $m$  and eigenvalue  $\lambda$  (i.e. # of blocks of dimension  $m$  associated to  $\lambda$ )

$p = \max \dim \cdot$  of  $V_i$ 's associated w/ eigenvalue  $\lambda$

So, in the part b) we learn:

$$\dim (T - \lambda \cdot 1)^k V_i = \begin{cases} m_i & \lambda \neq \lambda_i \\ m_i - k & \lambda = \lambda_i \text{ and } k < m_i \\ 0 & \lambda = \lambda_i \text{ and } k \geq m_i \end{cases}$$

So, let's act with  $(T - \lambda \cdot 1)^k$  on  $V = \bigoplus_{i=1}^r V_i$  and count dimensions:

$$\begin{aligned} \dim((T - \lambda \cdot 1)^k V) &= \sum_{i=1}^r \dim (T - \lambda \cdot 1)^k V_i = \sum_{i, \lambda_i \neq \lambda} \dim (T - \lambda \cdot 1)^k V_i \\ &+ \sum_{i, \lambda_i = \lambda} \dim (T - \lambda \cdot 1)^k V_i = \sum_{\substack{i, \lambda_i \neq \lambda \\ \parallel \\ m^2}}^{\dim V_i} m_i + \sum_{\substack{i, \lambda_i = \lambda \\ k < m_i \\ \parallel \\ (*)}} (m_i - k) \end{aligned}$$

Recall that there may be more than one  $\lambda_i$  assoc. to  $V_i$  w/ value  $\lambda$

Now, we need to manipulate the second sum. All the  $m_i$ 's appearing there are the dimensions of  $V_i$ 's w/ associated eigenvalue  $\lambda_i = \lambda$ , and, by definition,  $m_i \geq k$  in that sum, so, the possible values of  $m_i$  are  $k+1, k+2, \dots, p$  (for some maximum value we just call  $p$ ). So, let's split the sum  $(*)$  according to these values:

$$\begin{aligned} (*) &= \sum_{\substack{i, \lambda_i = \lambda \\ m_i = k+1}} (k+1 - k) + \sum_{\substack{i, \lambda_i = \lambda \\ m_i = k+2}} (k+2 - k) + \dots + \sum_{\substack{i, \lambda_i = \lambda \\ m_i = p}} (p - k) \\ &= l_{k+1} + 2 \cdot l_{k+2} + \dots + (p - k) l_p \end{aligned}$$



Hence we proved

(2)

$$\dim((T - \lambda \cdot 1)^k V) = m^2 + l_{k+1} + 2 \cdot l_{k+2} + \dots + (p-k) l_p$$

$$d) r_k = \text{rk}((T - \lambda \cdot 1)^k) = \dim(T - \lambda \cdot 1)^k V$$

↑  
definition of rank

Consider  $k=0$ , then  $r_0 = \dim V$ , ~~then  $k=1$  gives  $r_1$~~  and using

c) :

$$\dim V = l_1 + 2l_2 + \dots + pl_p + m^2$$

$$\text{for } r_1 = \dim(T - \lambda \cdot 1)V = l_2 + 2l_3 + \dots + (p-1)l_p + m^2$$

$$r_2 = \dim(T - \lambda \cdot 1)^2 V = l_3 + 2l_4 + \dots + (p-2)l_p + m^2$$

⋮

$$r_p = \dim(T - \lambda \cdot 1)^p V = m^2$$

e) we have the eqs. ( $m = \dim V$ )

$$l_1 + 2l_2 + \dots + pl_p + m^2 = m$$

$$l_2 + \dots + (p-1)l_p + m^2 = r_1$$

⋮

$$m^2 = r_p$$

by Gaussian elimination is easy to get

$$l_1 = m - 2r_1 + r_2$$

$$l_2 = r_1 - 2r_2 + r_3$$

$$l_3 = r_2 - 2r_3 + r_4$$

⋮

$$l_p = r_{p-1} - r_p$$

hence, the numbers  $l_i$  do not depend on the choice of basis (since  $r_i$ 's and eigenvalue  $\lambda$  do not).  ~~$l_i$ 's~~ is the number of ~~linearly~~  $V_i$ 's w/ dimension  $s_i$ , so, knowing the eigenvalues  $\lambda_1, \dots, \lambda_m$  of  $T$  and the numbers  $l_s$  associated to each  $\lambda_i$



We can completely reconstruct the Jordan form of  $T$ . Another way of putting it, is to say, in order to reconstruct the Jordan form of  $T$ , I need to know, for each  $\lambda \in \sigma(T)$ , how many blocks assoc. to  $\lambda$  does  $T$  have, and their dimensions. Fixing  $\lambda$  and computing the  $b_s$ 's gives exactly this information.

P2

a)  $N = \begin{bmatrix} 0 & 1 & & \\ & \ddots & \ddots & \\ & & \ddots & 1 \\ & & & 0 \end{bmatrix}$  is  $N_{ij} = \begin{cases} 1 & j=i+1, 1 \leq i \leq m-1 \\ 0 & \text{otherwise} \end{cases}$

is, it holds for  $N^{r=1} = N$ , assume

$$N_{ij}^r = \begin{cases} 1 & j=i+r, 1 \leq i \leq m-r \\ 0 & \text{otherwise} \end{cases}$$

Now compute  $N^{r+1}$ :

$$N_{ij}^{r+1} = \sum_{s=1}^m N_{is} N_{sj}^r = N_{i, j-r} \underbrace{N_{j-r, j}^r}_{\substack{\text{assume } j-r > r \\ 1}} = N_{i, j-r} = \begin{cases} 1 & j=i+r+1 \\ 0 & \text{otherwise} \end{cases}$$

(Clearly, if  $j \leq r$ ,  $N_{ij}^{r+1} = 0$ )

hence  $N^m$  can only have a nonzero component  $N_{ij}^m$  if  $j=i+m \Rightarrow N^m = 0$

b) ~~But~~ we know  $T$  can be put in Jordan form i.e.

$T = C \text{diag}(B_1, \dots, B_s) C^{-1}$  where  $B_i = \begin{pmatrix} \lambda_i & & \\ & \ddots & \\ & & \lambda_i \end{pmatrix}$  are Jordan blocks, hence

$$T^r = C \text{diag}(B_1^r, \dots, B_s^r) C^{-1}$$



So

$$e^T = \sum_{l=0}^{\infty} \frac{1}{l!} C \operatorname{diag}(B_1^l, \dots, B_s^l) C^{-1} = C \left( \sum_{l=0}^{\infty} \frac{1}{l!} \operatorname{diag}(B_1^l, \dots, B_s^l) \right) C^{-1}$$

$$\Rightarrow \det(e^T) = \det \left( \sum_{l=0}^{\infty} \frac{1}{l!} \operatorname{diag}(B_1^l, \dots, B_s^l) \right)$$

easy to see this  
is strictly upper  
triangular

Now,  $B_i^l = (D_i + N)^l = \sum_{k=0}^l \underbrace{D_i^{l-k} N^k}_{\text{binomial and use that } D_i N = N D_i} \binom{l}{k} = D_i^l + \sum_{k=1}^l D_i^{l-k} N^k \binom{l}{k}$

$\begin{bmatrix} \lambda_i & & \\ & \ddots & \\ & & \lambda_i \end{bmatrix}$   $\begin{bmatrix} 0 & 1 & & \\ & \ddots & \ddots & \\ & & 0 & 1 \\ & & & \ddots & 0 \end{bmatrix}$

$\lambda_i \cdot 1$

by a), this is upper triangular

$$= \begin{bmatrix} \lambda_i^l & & & \\ & \ddots & & \\ 0 & & \lambda_i^l & \\ & & & \ddots & \\ & & & & \lambda_i^l \end{bmatrix}$$

Takes  
this form

then  $\sum_{l=0}^{\infty} \frac{1}{l!} \operatorname{diag}(B_1^l, \dots, B_s^l) = \sum_{l=0}^{\infty} \operatorname{diag}(\underbrace{\lambda_{1/l!}^l, \dots, \lambda_{1/l!}^l}_{\substack{m_1 \\ \text{dim } B_1}}, \dots, \underbrace{\lambda_{s/l!}^l, \dots, \lambda_{s/l!}^l}_{\substack{m_s \\ \text{dim } B_s}})$

+ M, where M is strictly upper triangular, then

$$\det(e^T) = \det \left( \sum_{l=0}^{\infty} \operatorname{diag}(\lambda_{1/l!}^l, \dots, \lambda_{1/l!}^l, \dots, \lambda_{s/l!}^l, \dots, \lambda_{s/l!}^l) \right)$$

$$= \prod_{k=1}^s \left( \sum_{l=0}^{\infty} \lambda_{k/l!}^l \right)^{m_k} = \prod_{k=1}^s e^{\lambda_k m_k}$$

if we don't worry  
about convergence



on the other hand

$$\text{Tr}(T) = \text{Tr}(C \text{diag}(B_1, \dots, B_s) C^{-1}) = \text{Tr}(\text{diag}(B_1, \dots, B_s))$$

$$= m_1 \lambda_1 + \dots + m_s \lambda_s$$

then

$$e^{\text{Tr}(T)} = e^{\sum_{k=1}^s m_k \lambda_k} = \det(e^T)$$