

## Problem 1

Consider a matrix  $A \in \mathcal{M}_{n,n}(\mathbb{F})$ , and a function  $f : \mathbb{F} \rightarrow \mathbb{F}$ , in some cases, we can define a matrix valued function (i.e., we can make sense of  $f(A)$ ), for example by the series expansion of  $f(x)$  around a point  $x_0$ , as we did to define  $e^A$ . For the case of  $f(x) \in \mathbb{F}[x]$ ,  $\deg f = m$ , we have the finite Taylor expansion:

$$f(x+y) = \sum_{k=0}^m f^{(k)}(x) \frac{y^k}{k!} \quad f^{(k)}(x) = \frac{d^k f(x)}{dx^k} \quad f^{(0)}(x) = f(x) \quad (1)$$

We will write an expression for  $f(A)$  using the formula above. Assume that, if  $A$  is block diagonal, i.e.  $A = \text{diag}(A_1, \dots, A_k)$ , then  $f(A) = \text{diag}(f(A_1), \dots, f(A_k))$ . Consider  $A$  given in Jordan normal form and write it as  $A = D + N$  where  $D$  is diagonal and  $N$  is nilpotent.

- Use this decomposition, the Taylor expansion (1), and the property of  $f$  on block diagonal matrices to write an expression for  $f(A)$ . **Hint:** consider the Taylor expansion of  $f(D+N)$  with  $x = D$  and  $y = N$ .
- The expression found in the previous item, based on the expansion (1), can actually be generalized for other functions  $f$  (not necessarily polynomial). Consider again the decomposition  $A = D + N$  and use it along with the Taylor expansion:

$$f(x+y) = \sum_{k=0}^{\infty} f^{(k)}(x) \frac{y^k}{k!} \quad (2)$$

to write a matrix expression for  $f(A) = e^{As}$ , where  $s$  is a scalar constant. **Hint:** Since  $N^k = 0$  for  $k$  large enough,  $f(D+N)$  will have a finite expansion.

## Problem 2

Consider a vector of functions  $x(t) = (x_1(t), \dots, x_n(t))$ , so each  $x_i(t)$  is a function  $x_i : \mathbb{F} \rightarrow \mathbb{F}$ ,  $i = 1, \dots, n$ . We can also consider matrices of functions, i.e.,  $A(t)$  is a  $n \times m$  matrix such that each entry  $A_{ij}(t)$  is a function. Define the matrix  $\frac{dA}{dt}$  as the matrix whose entries are  $\frac{dA_{ij}(t)}{dt}$ .

- Show that Leibniz rule hold for  $\frac{d}{dt}$  on matrices i.e.  $\frac{d(AB)}{dt} = \frac{dA}{dt}B + A\frac{dB}{dt}$ , where  $A(t)$  is a  $n \times m$  matrix and  $B(t)$  is a  $m \times r$  matrix. **Hint:** just write the entries of  $\frac{d(AB)}{dt}$ .
- Use the derivative of  $e^{At}$  from homework 11, and the Leibniz rule to show that  $x(t) = e^{At}c$ , where  $c$  is constant vector and  $A$  is a constant  $n \times n$  matrix (i.e. they are independent of  $t$ ), satisfies

$$\frac{dx}{dt} = Ax \quad (3)$$

this means  $x(t) = e^{At}c$  is the solution of a first order system of linear homogeneous differential equations.

- Consider now a constant, invertible,  $n \times n$  matrix  $C$ . Show then that  $y(t) = C^{-1}x(t)$  satisfies the equation

$$\frac{dy}{dt} = A'y \quad A' = C^{-1}AC$$

- Because of the previous result, if we want to study the equations (3) we can restrict our attention to the cases in which  $A$  is in Jordan canonical form. Consider (3) for the case  $n = 2$  and  $\mathbb{F} = \mathbb{R}$  and write explicitly the solutions  $x(t) = e^{At}c$  for two of the three possible cases of Jordan forms that can occur <sup>1</sup>. For this, use the expressions for  $e^{At}$  found in problem 1.
- In the previous problem, there is one case where we cannot write the matrix  $A$  directly as a sum  $D + N$ . Using the series expansion of  $e^A$ , show that

$$e^{C^{-1}AC} = C^{-1}e^AC$$

then use this identity to compute  $x(t) = e^{At}c$  in the case where  $A$  cannot be written as  $D + N$  <sup>2</sup>.

## Problem 3

Suppose  $u, v, w \in V$ , then prove

$$\|w - \frac{1}{2}(u + v)\|^2 = \frac{\|w - u\|^2 + \|w - v\|^2}{2} - \frac{\|u - v\|^2}{4}$$

<sup>1</sup>Do it just for the cases where  $A$  can be written as  $D + N$

<sup>2</sup>Even though the transformation matrices  $C$  you will use may be complex valued, your final answer for  $x(t)$  must be real.