Feynman Calculus

1. Decays & scattering.

For the three experimental probes of elementary particle interactions bound states, decay, and scattering - nonrelativistic quantum mechanics is well adapted to handbe the first, while QFT is the tool to handel the Executed & third.

(1) Decays the item of greatest interest in the lifetime., or more accurately, the mean lifetime, T.

The decay rate T is the probability per unit time that any given particle will disintegrate.

 $dN = - \Gamma N dt$

 \Rightarrow $N(t) = N(t=0) e^{-\Gamma t}$

that is, the man lifetime is the reciprocal of the decay rate.

For more than one decay channels,

 $T_{tot} = \sum_{i=1}^{n} \Gamma_i$, $T = \frac{1}{\Gamma_{tot}}$

branching ratio for ith decay channel = Ti

Scatterings

That = 2 Ti

the cross section for process i (celled "exclusive" cross section) (called "inclusive " cross Eedian)

At the most naine bevel, we could expect that the cross section to be propordianel to the amount of time the incident particle spends in the vicinity of the target, that is, ox to This behavior is dranation altered in the neighborhood of a "resenance" - a special energy at which the particles involved "like" to interact by forming a short-lived semibound state before breaking apart. Searching these "bump" in the Tus. V (or more commonly platted, Tus. E) graph is the Principle means to discover short-lived particles.

We can use the following two examples to introduce the key carcepts

Example 1. Hand-sphere Scattering Jb de R b is called the impact parameter, G is the scattering angle. b=Rsind. $2d+\theta=\pi$

 $=) \quad \text{sind} = \sin\left(\frac{\pi-\theta}{2}\right) = \cos\frac{\theta}{2}$

In general, $d\theta = R \cos \frac{\theta}{2}$ $d\theta = R \cos \frac{\theta}{2}$

If the particle comes in with an inject parameter between b and btdb,

it will emerge with a scattering angle between & and & + do. Therefore If it passes through an infinitesimal area do, it will scatter into a corresponding solid angle dre. do = D(0,0) do?

(a) called the differential cross section. Go back to the hard-sphere scattering example, $d\tau = |bdbd4|$ don = | Sint dod f |

positive definite, so take absolute value =) $D(\theta, \varphi) = D(\theta) = \frac{|bdb|}{|shee}$ Since no φ dependence usity b = R cos & \Rightarrow $db = -R sin(\frac{1}{2}) \cdot \frac{1}{2} d\theta$ $=) D(\epsilon, \varphi) = \left| \frac{R\cos\frac{\epsilon}{2}}{\sin\epsilon} \left(-\frac{1}{2}R\sin\frac{\epsilon}{2} \right) \right|$ The result is as expected: any particle within this πR^2 area will scatter, Example 2 Pather ford. Scattering and any outside will pass by unaffected.

2 Pather ford Scattering and any outside will pass by unaffected. Neglect the recoil of the target nucleus, then $|\vec{r}_i| = |\vec{P}_f|$, $|\vec{P}_f| = |\vec{P}_i| + |\vec{P}_f|$ and assume elastic scattering,

where the direction of the vector \vec{z} is along the line joining the nucleus to the point of closest approach of the incoming particle; and $\beta = 0$ chosen to be the point of closest approach.

By a subject manestum conservation,

By argular momentum conservation, $m \ b \ V = m \ r^2 \ d\ell$ and $\vec{F}_{\ell} = \frac{d\vec{F}_{\ell}}{dt}$ where m is mass of the incoming particle $\vec{F}_{\ell} = \frac{d\vec{F}_{\ell}}{dt}$ $\vec{F}_{\ell} = \frac{d\vec{F}_{\ell}}{dt}$

 $= \frac{\pi - 6}{|\mathcal{Z}|} = \int_{\frac{\pi - 6}{2}}^{\frac{\pi - 6}{2}} \frac{\xi_1 \xi_2}{4\pi \xi_1 \xi_2} \cos \xi$

= 2, 82 1/ 25/n (TI-B)

Using $\frac{|\vec{z}|}{\sin 6} = \frac{|\vec{P}i|}{\sin(\frac{\pi - 6}{2})} = \frac{\sum mT}{\sin(\frac{\pi - 6}{2})}$, where T is the kinetic energy of the incoming particle.

 $= \frac{2.2 \cdot 1}{4\pi \epsilon} = \frac{1}{5 \cdot \sqrt{\frac{\pi \cdot 6}{m}}} = \frac{5 \cdot 6 \cdot \sqrt{2m}}{5 \cdot \sqrt{\frac{\pi \cdot 6}{2}}} = \frac{5 \cdot 6 \cdot \sqrt{2m}}{5 \cdot \sqrt{\frac{\pi \cdot 6}{2}}}$

 $=) \qquad b = \frac{2 \operatorname{Sin}(\pi - \theta)}{4\pi \epsilon_0 27} = 2 \operatorname{Sin}(\frac{\pi}{2})$

 $= \frac{2, 2}{4\pi \epsilon_{2T}} \cot(\frac{\theta}{2}) \qquad (\text{in SI unit})$

 $dT = |bdbd\phi|$, $d\Omega = |sin \theta d \theta d \phi|$

 $\frac{d\sigma}{d\Omega} = \frac{b db}{|sin\theta d\theta|} = \frac{b}{|sin\theta|} \frac{2 \cdot 2}{|4\pi \epsilon_0 2T|} \frac{1}{2} \csc^2 \frac{6}{2}$ $= \frac{2 \cdot 2}{|4\pi \epsilon_0 2T|} \frac{2 \cdot 3 \cdot 6}{|sin\theta|} \frac{2 \cdot 2}{|sin\theta|} \frac{2 \cdot 2}{|sin\theta|}$ $= \frac{(2 \cdot 2 \cdot 2)^2}{(4\pi \epsilon_0 4T)^2} \frac{1}{|sin\theta|^2} \frac{1}{|sin\theta|^2}$ $= \frac{2 \pi (\frac{2 \cdot 2}{4\pi \epsilon_0 4T})^2 \int_0^{\pi} \frac{1}{|sin\theta|^2} \frac{1}{|sin\theta|^2} \frac{1}{|sin\theta|^2} \frac{1}{|sin\theta|^2} \frac{1}{|sin\theta|^2} \frac{1}{|sin\theta|^2}$ $= \frac{2 \pi (\frac{2 \cdot 2}{|4\pi \epsilon_0 4T|})^2 \int_0^{\pi} \frac{1}{|sin\theta|^2} \frac{1}{|sin\theta|^2$

L [cm² sec-1] dor incident beam tanget

The number of particles per unit time passing through area do, and hence also the number of particles per unit time scattered into solid angle dr

 $dN = Ld\sigma = LD(\theta, \theta) d\Omega$.

determined by detector experimentalist measure I determined by accelerator.

that is, the differential cross section is

$$D(6, 9) = \frac{d\sigma}{dr} = \frac{dN}{Ldr}$$

If the dector completely surrounds the target, then $N=\sigma L$ (the event rate is the cross section times the (uninosity).

2. The Golden Rule.

Fermi's Golden Rube Eags that a transition rate is given by the product of the phase space and the absolute square of the amplitude.

For the formulas of decay rate and cross section, see my particle physics becture notes.

For the factor in the 2 \rightarrow n scattering cross section $E_1E_2|\vec{V}_1-\vec{V}_2|$, it can be written in general as

 $E_{1}E_{2}|\vec{v}_{1}-\vec{v}_{2}|=E_{1}E_{2}|\vec{P}_{1}-\vec{P}_{2}|=|\vec{p}_{1}E_{2}-\vec{p}_{2}E_{1}|$

Since (P, P2) - (m, m2) - (P, P2) + |P, |2 | P2 |2 = (E,E2-P,B) - mim; - (P,B)+|P,|2|R1 EiEz-2(P.P.) E, Ez-mim + |P, |2 |P|

 $= (m_1^2 + |\vec{p}_1|^2) (m_2^2 + |\vec{p}_1|^2) - 2(\vec{p}_1 \cdot \vec{p}_2) E_1 E_2 - m_1^2 m_2^2 + |\vec{p}_1|^2 |\vec{p}_1|^2$ $= m_1^2 |\vec{p}_1|^2 + m_2^2 |\vec{p}_1|^2 + 2|\vec{p}_1|^2 |\vec{p}_1|^2 - 2(\vec{p}_1 \cdot \vec{p}_2) E_1 E_2$ while $|\vec{p}_1 E_2 - \vec{p}_2 E_1|^2 = 2(\vec{p}_1 \cdot \vec{p}_2) E_1 E_2 + |\vec{p}_1|^2 E_2^2 + |\vec{p}_1|^2 E_1^2$ $= -2(\vec{p}_1 \cdot \vec{p}_2) E_1 E_2 + 2|\vec{p}_1|^2 |\vec{p}_1|^2 + m_2^2 |\vec{p}_1|^2 + m_1^2 |\vec{p}_2|^2$ $= \sum_{i} |\vec{p}_1 - \vec{p}_2| = (p_1 \cdot p_2)^2 - (m_1 \cdot m_2)^2 - (\vec{p}_1 \cdot \vec{p}_2)^2 + |\vec{p}_1|^2 |\vec{p}_2|^2$ The last two terms vanish in the rest frame where \vec{p}_1 and \vec{p}_2 are callinear or the of them is zero.