

Cox Proportional Hazard Model

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1 Introduction

In this note we will talk about the Cox's proportional hazards (Cox's PH) model. Suppose we observe some non-informatively right-censored data (U, δ) with covariate vector Z . That is, for subject i , the covariate vector is Z_i , survival time T_i and censoring time C_i . The observed data is (U_i, δ_i) where $U_i = \min(T_i, C_i)$ and $\delta_i = 1(T_i \leq C_i)$. Also $T_i \perp C_i | Z_i$.

And now we want to model the relationship between Z and T . One way to do that is to incorporate Z into the hazard function $h(\cdot)$, e.g.,

$$T \sim \text{Exp}(\lambda_Z) \implies h(t) = \lambda_Z \triangleq e^{\alpha + \beta Z} = \lambda_0 e^{\beta Z},$$

where $\lambda_0 = e^\alpha$ can be viewed as a baseline hazard. If $\beta = 0$ then Z is not associated with T .

We can generalize this idea as

$$h(t|Z) = h_0(t) \times g(Z).$$

So the hazard can be factorized and this model is sometimes called a “multiplicative intensive model” or “multiplicative hazard model” or “proportional hazard model” because this factorization implies that

$$\frac{h(t|Z = z_1)}{h(t|Z = z_2)} = \frac{g(z_1)}{g(z_2)}.$$

The hazard ratio is constant with respect to t , hence the (constant) proportional hazard. So in our previous model (the exponential survival time), the hazard ratio is

$$\frac{h(t|Z = z_1)}{h(t|Z = z_2)} = e^{\beta(z_1 - z_2)}.$$

Also this exponential form of $g(Z)$

$$h(t|Z) = h_0(t) \cdot e^{\beta Z} \tag{1}$$

is the **Cox's PH** model.

2 Estimation

(1) implies that

$$\begin{aligned}
 S(t|Z) &= \exp(-H(t|Z)) \\
 &= \exp\left(-\int_0^t h(u|Z) du\right) \\
 &= \exp\left(-\int_0^t h_0(t) du \cdot g(Z)\right) \\
 &= (S_0(t))^{g(Z)} = (S_0(t))^{\exp(\beta Z)},
 \end{aligned}$$

where $S_0(t) = \exp\left(-\int_0^t h_0(u) du\right)$, the survival function for $Z = 0$, hence $S(t|Z = 0)$. Also remember that $f(t|Z) = h(t|Z) S(t|Z)$. Thus, given n independent data (u_i, δ_i, z_i) , the likelihood (one can refer to our previous notes about survival analysis.) is

$$\begin{aligned}
 L(\beta, h_0(\cdot)) &= \prod_{i=1}^n (f(u_i|z_i))^{\delta_i} (S(u_i|z_i))^{1-\delta_i} = \prod_{i=1}^n h(u_i|z_i)^{\delta_i} S(u_i|z_i) \\
 &= \prod_{i=1}^n (h_0(u_i) e^{\beta z_i})^{\delta_i} \left(\exp\left(-\int_0^{u_i} h_0(t) dt\right) \right)^{\exp(\beta z_i)} \\
 &= \text{function}(data, h_0(\cdot), \beta).
 \end{aligned} \tag{2}$$

If $h_0(\cdot)$ is allowed to be “arbitrary”, then the “parameter space” is

$$\mathcal{H} \times \mathcal{R}^p = \left\{ (h(\cdot), \beta) \mid h_0(\cdot) \geq 0, \int_0^\infty h_0(t) dt = \infty, \beta \in \mathcal{R}^p \right\},$$

where $\int_0^\infty h_0(t) dt = \infty$ ensures that $S_0(\infty) = 0$.

In general this likelihood is hard to maximize. And Cox proposed this idea: to factor $L(\beta, h_0(\cdot))$ as

$$L(\beta, h_0(\cdot)) = L_1(\beta) \times L_2(\beta, h_0(\cdot)),$$

where L_1 only depends on β and its maximization ($\hat{\beta}$) enjoys nice properties such as consistency and asymptotic normality while L_2 contains relatively little information about β . And this L_1 is called a **partial likelihood**.

2.1 What is $L_1(\beta)$

In this section we introduce the L_1 proposed by Cox. First let's assume there are **NO tied** nor censoring observations. And define the distinct times of failure $\tau_1 < \tau_2 < \dots$. Denote

$$R_j = \{i | U_i \geq \tau_j\} = \text{risk set at } \tau_j,$$

and

$$Z_{(j)} = \text{value of } Z \text{ for the subject who fails at } \tau_j.$$

Note that under this setting (no tie, no censor), the full likelihood (2) becomes

$$L(\beta, h_0(\cdot)) = \prod_{i=1}^n h_0(u_i) e^{\beta z_i} \left(\exp\left(-\int_0^{u_i} h_0(t) dt\right) \right)^{\exp(\beta z_i)}.$$

Furthermore, we can assume $u_i = \tau_i$, i.e. the data has been sorted based on survival time. And use the KM idea, i.e. assume the survival function is **discrete** with baseline hazard value h_j at u_j . Then this likelihood becomes

$$L(\beta, h_1, \dots, h_n) = \prod_{i=1}^n h_i e^{\beta z_i} \exp \left(- \sum_{j=1}^i h_j \right)^{\exp(\beta z_i)}. \quad (3)$$

Note that, in previous notes we have deduct that in discrete case, for any $t \in [v_j, v_{j+1})$:

$$H(t) = \sum_{i=1}^j h_i \quad S(t) = \prod_{i=1}^j (1 - h_i).$$

Here in (3) we use the approximation that $e^{h_j} \approx 1 - h_j$ when h_j is close to 0. Then we can use the method of profile likelihood:

we can reconstruct the data from $\{\tau_j\}$, $\{R_j\}$ and $\{Z_{(j)}\}$. And L_1 is defined as

$$L_1(\beta) \triangleq \prod_j \left\{ \frac{e^{\beta Z_{(j)}}}{\sum_{l \in R_j} e^{\beta Z_l}} \right\}$$

3 Inference

References