Introduction Computer Arithmetics

732A90 Computational Statistics

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Computational Statistics — In brief

- Even simple data analysis (mean, variance) by hand is tedious
- Today: huge datasets, models capturing system complexity, interactions (between variables **and** observations)
- We will discuss:
 - Being careful with calculations—overflow
 - Generation of random variables including correlated ones
 - \bullet Numerically optimizing functions, esp. maximum likelihood
 - Computing confidence (credible) intervals for distributions when analytical ones are unobtainable

Lesson structure

- Lectures
- Computer Labs
- Seminars
- Examination: Reports, seminars, final exam
- Final exam: computer based
- Answer in English.
- Electronic reports as **.PDF**.
- Disclose **ALL** collaborations and sources.
- Provide source code (if used).
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Course materials, software

- Lecture slides
- 2016 lecture slides (732A38)
- Handouts, R code
- Various suggested www pages or articles
- Googling
- James E. Gentle "Computational Statistics", Springer, 2009
- Geof H. Givens, Jennifer A. Hoeting "Computational Statistics", Wiley, 2013

R

Course contents

- Recap: R
- Recap: Basic Statistics
- Computer Arithmetics (JG pages 85–105)
- Optimization (JG pages 241–272, handouts)
- Random Number Generation (JG pages 305–312, 325–328, handouts)
- Monte Carlo Methods (JG pages 312–318, 328 417–429, handouts)
- Numerical Model Selection and Hypothesis Testing (JG pages 52–56, 424, 435–467, handouts)
- Expectation Maximization Algorithm and Stochastic Optimization (JG pages 275–284, 296–298, 480–483, handout)

Pages are recommended reading for each lecture, **NOT** exact lecture content. The lectures will build up on this material.

Examination

Computer labs (need to be passed)

Presentation or opposition and attendance at seminars (see $732 A 90_Computational Statistics VT 2019_Course Information.pdf).$

Computer exam points A: $[18, \infty)$, B: [16, 18), C: [14, 16), D: [12, 14), E: [10, 12), F: [0, 10)

Allowed aids for exam: printed books and own PDF document containing max 100 pages (see 732A90_ComputationalStatisticsVT2019_CourseInformation.pdf).

Computer Arithmetics

SHOULD YOU CARE?

Computer Arithmetics: Examples

Computations can be affected by magnitudes of numbers.



$$t < -rnorm(5, 10^18, 1); t[3] - t[4]; t[1] - t[2]$$

$$x<-10^800; sd<-10^400; y<-x/sd; y$$

And your are doing estimation under a nice, fancy model ...

Data presentation

- Computers store information in binary form
 0
 1
 0
 1
- 1Byte=8bits (typical counting unit)
- 1Word=32 or 64bits (depending on architecture)
- 1KB=1024bytes
- 1MB=1024KB
- and so on

QUESTION: Why binary form?

Character encoding

- ASCII (American Standard Code for Information Interchange)
 - 1 byte per character, 7 bits coding, 1 parity check or 0
 - $2^7 = 128$ characters can be encoded
 - "Usual" English letters, Arabic numerals, punctuation, i.e. "standard" keyboard
 - 1–31 control characters, 0: NULL WHY?
 - Design influenced by contemporary (1960) hardware
 - Extended ASCII: all 8 bits, 256 characters

- Unicode
 - 8, 16 or 32 bits encoding
 - "of more than 128,000 characters covering 135 modern and historic scripts, as well as multiple symbol sets" (Wikipedia)

• read.csv(), read.table() have fileEncoding argument

Fixed-point system (integers)

- We use the base–10 (decimal) system, e.g. $1234 = 1 \cdot 10^3 + 2 \cdot 10^2 + 3 \cdot 10^1 + 4 \cdot 10^0$
- \bullet We could use base–m system for any m
- Computers: base–2 (binary) system
- Each integer represented as: $A = a_0 \cdot 2^0 + a_1 \cdot 2^1 + a_2 \cdot 2^2 + \dots$

EXERCISE: 5, 16, 17, 31, 32, 33, 255, 256 in binary **QUESTION:** What is the range of a byte, word, double word?

- Negative numbers
 - Leading bit: first bit 0 if positive, 1 if negative
 - Twos-complement: sign bit 1, remaining bits to opposite value and then +1 e.g. 5 = 00000101, −5 = 11111011 QUESTIONS 5 + (−5) =?, try 12 and −12
 - Range: $[-2^{k-1}, 2^{k-1} 1]$ on k bits **WHY?**

Arithmetic operations

R operations on binary

- Addition, multiplication: base-2 instead of base-10
- Subtraction: A B = A + (-B) (twos-complement)
- Division: tedious, rounded towards 0 as.integer(17/3)



• Overf: adding two large numbers the sign bit can be treated as a high order bit and on some architectures results in a negative number

Floating-point system (rational, "real")



- How can we represent fractions (rational numbers)?
- Sign
- Exponent (signed, read standards if interested)
- Mantissa Significand
- on 64bits:

$$\pm 0.d_1d_2\dots d_p \cdot b^e \qquad b=2, \quad p=52$$

• Range: $\approx [-10^{300}, 10^{300}] \approx [-b^{e_{max}}, b^{e_{max}}]$

Floating-point system

• Rationals rounded towards the nearest computer float

```
options(digits=22) #max possible
0.1
[1] 0.10000000000000055511
```

- **EXAMPLE:** Assume base b = 10 and mantissa has 5 digits p = 5: $1.2345 = +0.12345 \cdot 10^{1}$ $4.0000567 = +0.40000 \cdot 10^{1}$
- Problem remains whatever base (b) is chosen

• **EXERCISE:** Try to convert some numbers

Floating-point system

• Distribution of computer floats

- Dense from -1 to 1
- Density decreases
- same number of points for each exponent:

$$\dots$$
, $\cdot 10^{-3}$, $\cdot 10^{-2}$, $\cdot 10^{-1}$, $\cdot 10^{1}$, $\cdot 10^{2}$, $\cdot 10^{3}$, \dots

• What about integers? $5 = +0.50000 \cdot 10^{1}$

Floating—point system, special "numbers"

- We do not discuss how the exponent is actually coded.
- Usually the maximum allowed number in the exponent is one unit less than possible.
- \pm Inf: exponent is $\exp_{\max} + 1$, mantissa is 0
- NaN: exponent is $\exp_{\max} + 1$, mantissa is $\neq 0$
- 0 **WHY**?

Overflow: number larger than can be represented Underflow: loss of significant digits

```
10^{2}00*10^{2}00 = Inf

10^{4}00/10^{4}00 = NaN

10^{-2}00/10^{2}00 = 0

10^{-2}00*10^{2}00 = 0

0*10^{4}00 = 0

x<-10^{3}00; while (1) \{x<-x+1\}
```

Arithmetic operations

- Floats are rounded so usual mathematical laws do not hold
 floating point arithmetic
- Examples

```
1/3+1/3 = 0.6666667

options (digits=22)

1/3+1/3 = 0.66666666666666666696592

10^{(-200)}/(10^{(-200)}+10^{(-200)}) = 0.5

10^{(-200)}/(10^{(-200)}+20^{(-200)}) = 1
```

- Software is designed to make operations as correct as possible
- Do we need to work with such extreme numbers?

Arithmetic operations

- X + Y, $X \cdot Y$ can display overflow, underflow
- $A \neq B$ but X + A = B + X
- A + X = X but $A + Y \neq Y$
- A + X = X but $X X \neq A$
- COMPARING FLOATS IS TRICKY!

```
options ( digits = 22)
x <-sqrt (2)
x*x
[1] 2.000000000000000444089
(x*x) == 2
[1] FALSE
isTRUE(all.equal(x*x,2))
[1] TRUE</pre>
```

Summation

Underflow problems can occur with any summation (x < -x + 1)

```
options(digits=22)
x<-1:1000000; sum(1/x); sum(1/rev(x))
[1] 14.39272672286572252176
[1] 14.39272672286572429812</pre>
```

• WHICH ONE IS CORRECT?



• WHICH ONE IS MORE ACCURATE?

Potential solutions

Solution A:

- Sort the numbers ascending CAN BE EXPENSIVE
- Sum in this order

Solution B:

- Sum numbers pairwise, from n obtain n/2 numbers HOW TO CHOOSE PAIRS?
- 2 Continue until 1 number left

More on summing

Example

• Computing exponent using Taylor series

$$e^x = 1 + x + x^2/2 + x^3/6 + \dots = \sum_{i=0}^{\infty} \frac{x^i}{i!}$$

The exponential

```
options (digits=22)
fTaylor < -function(x,N) \{1+sum(sapply(1:N,
    function (i,x) \{x^i / prod(1:i) \}, x=x, simplify=
   TRUE))}
\exp(20) #fine
[1] 485165195.4097902774811
fTaylor (20,100)
[1] 485165195.4097902774811
fTaylor(20,100)-exp(20)
[1] 0
\exp(-20) #problem
\begin{bmatrix} 1 \end{bmatrix} 2.061153622438557869942e-09
fTaylor(-20,100)
\begin{bmatrix} 1 \end{bmatrix} -3.853877217352419393137e-10
fTaylor(-20,200)
\begin{bmatrix} 1 \end{bmatrix} -3.853877217352419393137e-10
```

More on summing

Example

• Computing exponent using Taylor series

$$e^x = 1 + x + x^2/2 + x^3/6 + \dots = \sum_{i=0}^{\infty} \frac{x^i}{i!}$$

- WHY?
- Varying sign of terms
- CANCELLATION adding two numbers of almost equal magnitude but of opposite sign
- Effects of cancellations accumulate
- **SOLUTION:** Different algorithm ...

Can you explain why?

```
## Example due to Thomas Ericsson in his
   Numerical Analysis course at Chalmers
f1 < -function(x) \{(x-1)^6\}
f2 < -function(x) \{1 - 6 * x + 15 * x^2 - 20 * x^3 + 15 * x^4 - 6 * x\}
   ^{5}+x^{6}
x < -seq (from = 0.995, to = 1.005, by = 0.0001)
v1 < -f1(x); v2 < -f2(x)
plot (x, y1, pch=19, cex=0.5, ylim=c(-5*10^{\circ}(-15), 20)
   *10^{(-15)}, main="Two_ways_to_calculate_(x
   -1)^6", xlab="x", ylab="y")
points (x, y2, pch=18, cex=0.8)
```

Matrix Calculations

• Many problems (in Statistics, Numerical methods, e.t.c) can be reduced to solving

$$\mathbf{A}\vec{x} = \vec{b}$$

 $\begin{array}{l} \mathbf{A} \ (\mathrm{design}) \ \mathrm{matrix} \\ \vec{x} \ \mathrm{vector} \ \mathrm{of} \ \mathrm{unknowns} \\ \vec{b} \ \mathrm{vector} \ \mathrm{of} \ \mathrm{scalars} \ (\mathrm{data}) \\ \end{array}$

• Algorithm should be numerically stable

(small changes in **A** or \vec{b} imply in small changes in \vec{x})

Example: Linear regression models

Minimize

$$RSS(\beta_0, \beta_1, \dots, \beta_m) = \sum_{i=1}^{n} (y_i - \beta_0 - \beta_1 x_{i1} - \dots - \beta_m x_{im})^2$$

The system of equations

$$\frac{\partial RSS}{\beta_0} = \frac{\partial RSS}{\beta_1} = \dots \frac{\partial RSS}{\beta_m} = 0$$

can be written as

$$\mathbf{X}^T \mathbf{X} \vec{eta} = \mathbf{X} \vec{y}$$

where

$$\mathbf{X} = \begin{bmatrix} 1 & x_{11} & \dots & x_{1m} \\ 1 & x_{21} & \dots & x_{2m} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & x_{n1} & \dots & x_{nm} \end{bmatrix}$$

Solving a linear system

- $\mathbf{A}\vec{x} = \vec{b}$ needs a stable numerical solution
- Computer arithmetics
- Original system: $\mathbf{A}\vec{x} = \vec{b}$
 - Perturbed system: $\mathbf{A}\vec{x'} = \vec{b'}, \ \vec{x'} = \vec{x} + \delta\vec{x}, \ \vec{b'} = \vec{b} + \delta\vec{b}$
- Stable: small perturbation in \vec{b} , small perturbations in \vec{x}
- $\|\vec{b}\| = \|\mathbf{A}\vec{x}\| \le \|\mathbf{A}\| \|\vec{x}\| \text{ implies } \|\vec{x}\|^{-1} \le \|\mathbf{A}\| \|\vec{b}\|^{-1} \|\delta\vec{x}\| = \|\mathbf{A}^{-1}(\delta\vec{b})\| \le \|\mathbf{A}^{-1}\| \|\delta\vec{b}\| \text{ together}$

$$\frac{\|\delta \vec{x}\|}{\|\vec{x}\|} \le \|\mathbf{A}^{-1}\| \|\mathbf{A}\| \frac{\|\delta \vec{b}\|}{\|\vec{b}\|}$$

Solving a linear system

Condition number of a matrix

$$\kappa(\mathbf{A}) = \|\mathbf{A}^{-1}\| \|\mathbf{A}\|$$

- Large $\kappa(\mathbf{A})$ is a bad sign, but does not imply ill–conditioning
- L_2 norm: $\kappa(\mathbf{A})$ is the ratio of the maximum and minimum eigenvalues of \mathbf{A}
- Under L_2 norm

$$\kappa(\mathbf{A}^T\mathbf{A}) \ge \kappa(\mathbf{A})^2 \ge \kappa(\mathbf{A})$$

(regression setting)

Solving a linear system

Dealing with ill-conditioning

- Rescale the variables (columns)
- Use a different algorithm for solving e.g. QR, Cholesky, SVD

Cholesky: A symmetric–positive–definite $\mathbf{A}\vec{x} = \vec{b}$ is equivalent to $\mathbf{L}\mathbf{L}^T\vec{x} = \vec{b}$ WHY?

- Solve $\mathbf{L}\vec{x} = \vec{y}$

Summary

- Computations can behave "differently" at different numerical ranges.
- Floating point system.
- Computer arithmetics is not the same as "usual" arithmetic.

• Summing series, solving linear systems (inversion?)