### 732A96/TDDE15 ADVANCED MACHINE LEARNING

#### LAB 4: GAUSSIAN PROCESSES

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## 1. Instructions

## Deadline for individual and group reports See LISAM.

### · What and how to hand in

Each student must send a report to LISAM with his/her solutions to the lab. The file should be named FirstName\_LastName.pdf. The report must be concise but complete. It should include (i) the code implemented or the calls made to existing functions, (ii) the results of such code or calls, and (iii) explanations for (i) and (ii).

In addition, students must discuss their lab solutions in a group. Each group must compile a collaborative report that will be used for presentation at the seminar. The report should clearly state the names of the students that participated in its compilation and a short description of how each student contributed to the report. This report should be submitted via LISAM. The file should be named Group\_X.pdf where X is the group number. Please, upload also a copy of the group report to the collaborative workspace folder in LISAM. The collaborative reports are corrected and graded. The individual reports are also checked, but feedback on them will not be given. A student passes the lab if the group report passes the seminar and the individual report has reasonable quality, otherwise the student must complete his/her individual report by correcting the mistakes in it.

Attendance to the seminar is obligatory. In the seminar, some groups will be responsible for presenting their group reports. Each student in these groups must be prepared to individually present an arbitrary part of the report. The selection of the speakers is done randomly during the seminar. In the seminar, some groups will act as opponents to the reports provided by the presenters. The opponent group should examine the group report of the presenter group before the seminar (available in the collaborative workspace folder in LISAM), and prepare a minimum of three questions, comments and/or improvements. The opponent group will ask these questions during the seminar. Check LISAM for the list of presenter and opponent groups.

### Resources

The lab is designed to be partially solved with the R package kernlab. You may want to reuse code from the R demo files available on the course website. You may also want to use the RStudio development environment.

#### 2. QUESTIONS

The purpose of the lab is to put in practice some of the concepts covered in the lectures.

2.1. **Implementing GP Regression.** This first exercise will have you writing your own code for the Gaussian process regression model:

$$y = f(x) + \epsilon$$
 with  $\epsilon \sim \mathcal{N}(0, \sigma_n^2)$  and  $f \sim \mathcal{GP}(0, k(x, x'))$ 

You must implement Algorithm 2.1 on page 19 of Rasmussen and Willams' book. The algorithm uses the Cholesky decomposition (chol in R) to attain numerical stability. Note that L in the algorithm is a lower triangular matrix, whereas the R function returns an upper triangular matrix. So, you need to transpose the output of the R function. In the algorithm, the notation  $A \setminus b$  means the vector x that solves the equation Ax = b (see p. xvii in the book). This is implemented in R with the help of the function solve.

Here is what you need to do:

- (1) Write your own code for simulating from the posterior distribution of f using the squared exponential kernel. The function (name it posteriorGP) should return a vector with the posterior mean and variance of f, both evaluated at a set of x-values  $(X_*)$ . You can assume that the prior mean of f is zero for all x. The function should have the following inputs:
  - x: Vector of training inputs.
  - y: Vector of training targets/outputs.
  - XStar: Vector of inputs where the posterior distribution is evaluated, i.e.  $X_*$ .
  - hyperParam: Vector with two elements,  $\sigma_f$  and  $\ell$ .
  - sigmaNoise: Noise standard deviation  $\sigma_n$ .

**Hint**: Write a separate function for the kernel (see the file GaussianProcess.R on the course web page).

- (2) Now, let the prior hyperparameters be  $\sigma_f = 1$  and  $\ell = 0.3$ . Update this prior with a single observation: (x,y) = (0.4,0.719). Assume that  $\sigma_n = 0.1$ . Plot the posterior mean of f over the interval  $x \in [-1,1]$ . Plot also 95 % probability (pointwise) bands for f.
- (3) Update your posterior from (2) with another observation: (x,y) = (-0.6, -0.044). Plot the posterior mean of f over the interval  $x \in [-1,1]$ . Plot also 95 % probability (pointwise) bands for f.

**Hint**: Updating the posterior after one observation with a new observation gives the same result as updating the prior directly with the two observations.

(4) Compute the posterior distribution of f using all the five data points in the table below (note that the two previous observations are included in the table). Plot the posterior mean of f over the interval  $x \in [-1,1]$ . Plot also 95 % probability (pointwise) bands for f.

x	-1.0	-0.6	-0.2	0.4	8.0
y	0.768	-0.044	-0.940	0.719	-0.664

- (5) Repeat (4), this time with hyperparameters  $\sigma_f = 1$  and  $\ell = 1$ . Compare the results.
- 2.2. **GP Regression with kernlab.** In this exercise, you will work with the daily mean temperature in Stockholm (Tullinge) during the period January 1, 2010 December 31, 2015. We have removed the leap year day February 29, 2012 to make things simpler. You can read the dataset with the command:

read.csv("https://github.com/STIMALiU/AdvMLCourse/raw/master/GaussianProcess/ Code/TempTullinge.csv", header=TRUE, sep=";")

Create the variable time which records the day number since the start of the dataset (i.e., time= 1, 2, ...,  $365 \times 6 = 2190$ ). Also, create the variable day that records the day number since the start of each year (i.e., day= 1, 2, ..., 365, 1, 2, ..., 365). Estimating a GP on 2190 observations can take some time on slower computers, so let us subsample the data and use only every fifth observation. This means that your time and day variables are now time= 1, 6, 11, ..., 2186 and day= 1, 6, 11, ..., 361, 1, 6, 11, ..., 361.

- (1) Familiarize yourself with the functions <code>gausspr</code> and <code>kernelMatrix</code> in <code>kernlab</code>. Do <code>?gausspr</code> and read the input arguments and the output. Also, go through the file <code>KernLabDemo.R</code> available on the course website. You will need to understand it. Now, define your own square exponential kernel function (with parameters  $\ell$  (ell) and  $\sigma_f$  (sigmaf)), evaluate it in the point  $\underline{x} = \underline{1}, \underline{x'} = \underline{2}$ , and use the <code>kernelMatrix</code> function to compute the covariance matrix  $K(X, X_*)$  for the input vectors  $X = (1, 3, 4)^T$  and  $X_* = (2, 3, 4)^T$ .
- (2) Consider first the following model:

$$temp = f(time) + \epsilon$$
 with  $\epsilon \sim \mathcal{N}(0, \sigma_n^2)$  and  $f \sim \mathcal{GP}(0, k(time, time'))$ 

Let  $\sigma_n^2$  be the residual variance from a simple quadratic regression fit (using the 1m function in R). Estimate the above Gaussian process regression model using the squared exponential function from (1) with  $\sigma_f=20$  and  $\ell=0.2$ . Use the predict function in R to compute the posterior mean at every data point in the training dataset. Make a scatterplot of the data and superimpose the posterior mean of f as a curve (use type="l" in the plot function). Play around with different values on  $\sigma_f$  and  $\ell$  (no need to write this in the report though).

(3) kernlab can compute the posterior variance of f, but it seems to be a bug in the code. So, do your own computations for the posterior variance of f and plot the 95 % probability (pointwise) bands for f. Superimpose these bands on the figure with the posterior mean that you obtained in (2).

**Hint:** Note that Algorithm 2.1 on page 19 of Rasmussen and Willams' book already does the calculations required. Note also that kernlab scales the data by default to have zero mean and standard deviation one. So, the output of your implementation of Algorithm 2.1 will not coincide with the output of kernlab unless you scale the data first. For this, you may want to use the R function scale.

(4) Consider now the following model:

$$temp = f(day) + \epsilon \text{ with } \epsilon \sim \mathcal{N}(0, \sigma_n^2) \text{ and } f \sim \mathcal{GP}(0, k(day, day'))$$

Estimate the model using the squared exponential function with  $\sigma_f$  = 20 and  $\ell$  = 0.2. Superimpose the posterior mean from this model on the posterior mean from the model in (2). Note that this plot should also have the time variable on the horizontal axis. Compare the results of both models. What are the pros and cons of each model?

(5) Finally, implement a generalization of the periodic kernel given in the lectures:

$$k(x,x') = \sigma_f^2 \exp\left\{-\frac{2\sin^2(\pi|x-x'|/d)}{\ell_1^2}\right\} \exp\left\{-\frac{1}{2}\frac{|x-x'|^2}{\ell_2^2}\right\}$$

Note that we have two different length scales here, and  $\ell_2$  controls the correlation between the same day in different years. Estimate the GP model using the time variable with this kernel and hyperparameters  $\sigma_f=20$ ,  $\ell_1=1$ ,  $\ell_2=10$  and  $d=365/\mathrm{sd}\,(\mathrm{time})$ . The reason for the rather strange period here is that kernlab standardizes the inputs to have standard deviation of 1. Compare the fit to the previous two models (with  $\sigma_f=20$  and  $\ell=0.2$ ). Discuss the results.

# 2.3. **GP Classification with kernlab.** Download the banknote fraud data:

data <- read.csv("https://github.com/STIMALiU/AdvMLCourse/raw/master/
GaussianProcess/Code/banknoteFraud.csv", header=FALSE, sep=",")
 names(data) <- c("varWave", "skewWave", "kurtWave", "entropyWave", "fraud")
 data[,5] <- as.factor(data[,5])</pre>

You can read about this dataset here. Choose 1000 observations as training data using the following command (i.e., use the vector <code>SelectTraining</code> to subset the training observations):

set.seed(111); SelectTraining <- sample(1:dim(data)[1], size = 1000,
replace = FALSE)</pre>

(1) Use the R package kernlab to fit a Gaussian process classification model for fraud on the training data. Use the default kernel and hyperparameters. Start using only

- the covariates <code>varWave</code> and <code>skewWave</code> in the model. Plot contours of the prediction probabilities over a suitable grid of values for <code>varWave</code> and <code>skewWave</code>. Overlay the training data for fraud = 1 (as blue points) and fraud = 0 (as red points). You can reuse code from the file <code>KernLabDemo.R</code> available on the course website. Compute the confusion matrix for the classifier and its accuracy.
- (2) Using the estimated model from (1), make predictions for the test set. Compute the accuracy.
- (3) Train a model using all four covariates. Make predictions on the test set and compare the accuracy to the model with only two covariates.