

# HIDDEN MARKOV MODELS

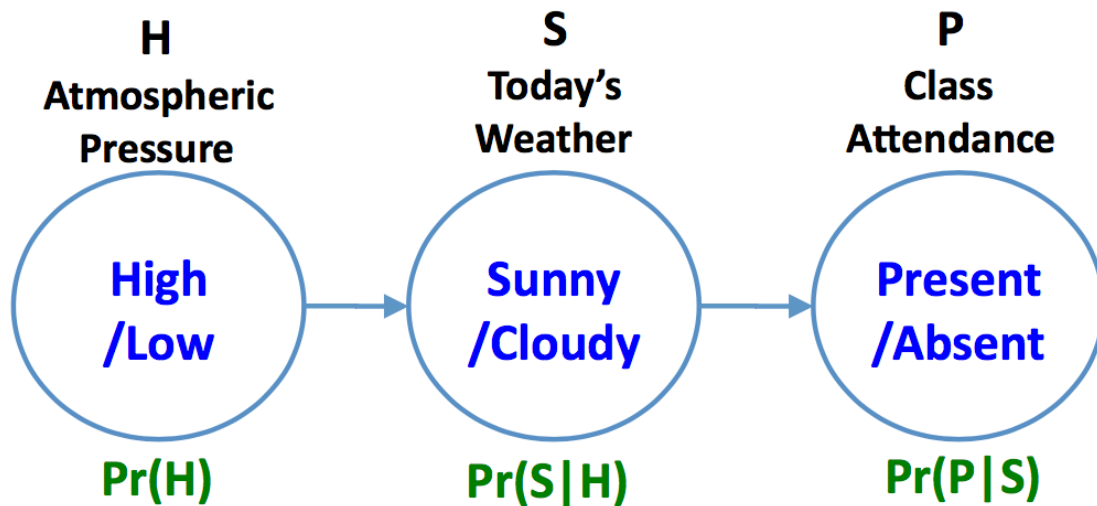


# Outline

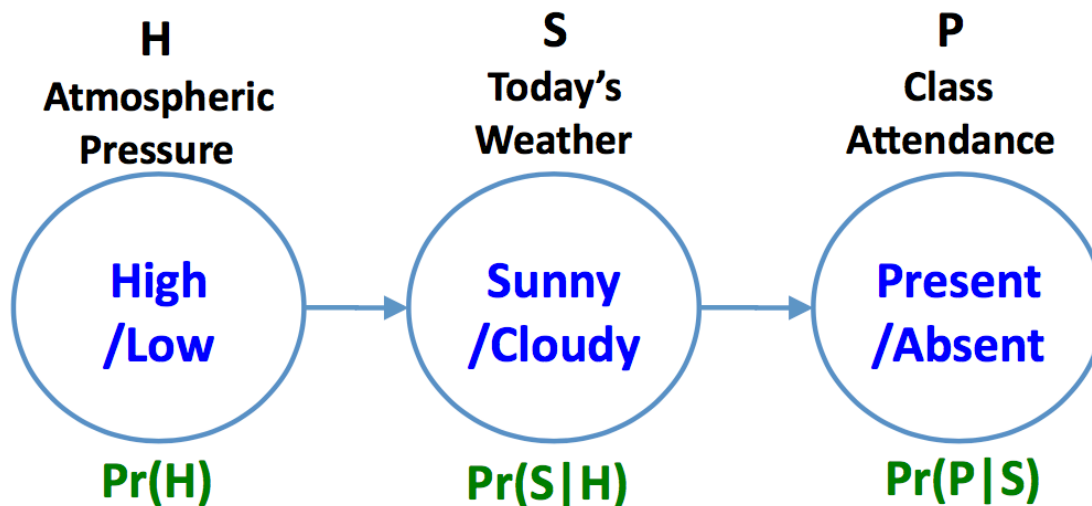
- **Graphical models**
- **Markov process**
- **Hidden Markov Models (HMM)**
- **Forward-backward algorithm**
- **Viterbi algorithm**

# Graphical Models 101

- Marriage between probability theory and graph theory
- An effective tool to represent complex structure of dependence/independence between random variable
- Vertex : a random variable
- Edge : dependency between random variables



# An **example** graphical model



Is  $H \perp P$  ? (marginal independence)

Is  $H \perp P \mid S$  ? (conditional independence)

# An example probability distribution

| $H$ |      | $\Pr(H)$ |
|-----|------|----------|
| 0   | Low  | 0.3      |
| 1   | High | 0.7      |

| $S$      | $H$    | $\Pr(S/H)$ |
|----------|--------|------------|
| 0 Cloudy | 0 Low  | 0.7        |
| 1 High   | 0 Low  | 0.3        |
| 0 Cloudy | 1 High | 0.1        |
| 1 High   | 1 High | 0.9        |

| $P$       | $S$      | $\Pr(P/S)$ |
|-----------|----------|------------|
| 0 Absent  | 0 Cloudy | 0.5        |
| 1 Present | 0 Cloudy | 0.5        |
| 0 Absent  | 1 Sunny  | 0.1        |
| 1 Present | 1 Sunny  | 0.9        |

# The full **joint** distribution

| $H$ |      | $\Pr(H)$ |
|-----|------|----------|
| 0   | Low  | 0.3      |
| 1   | High | 0.7      |

| $H$ | $S$ | $P$ | $\Pr(H,S,P)$ |
|-----|-----|-----|--------------|
| 0   | 0   | 0   | 0.105        |
| 0   | 0   | 1   | 0.105        |
| 0   | 1   | 0   | 0.009        |
| 0   | 1   | 1   | 0.081        |
| 1   | 0   | 0   | 0.035        |
| 1   | 0   | 1   | 0.035        |
| 1   | 1   | 0   | 0.063        |
| 1   | 1   | 1   | 0.567        |

| $S$      | $H$    | $\Pr(S/H)$ |
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# Conditional distribution

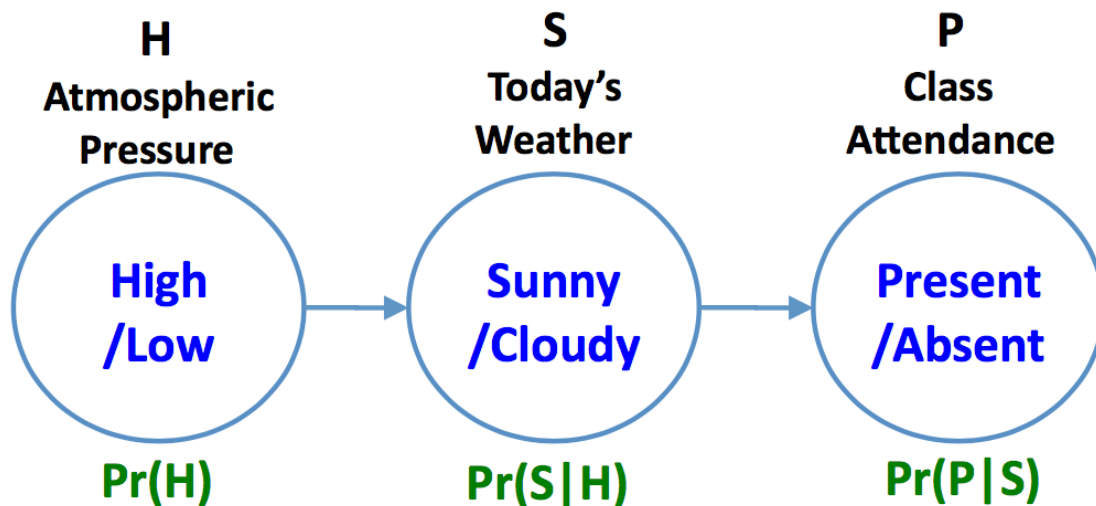
Is  $H \perp P \mid S$  ?

| $H$ | $P$ | $S$ | $\Pr(H,P/S)$ |
|-----|-----|-----|--------------|
| 0   | 0   | 0   | 0.3750       |
| 0   | 1   | 0   | 0.3750       |
| 1   | 0   | 0   | 0.1250       |
| 1   | 1   | 0   | 0.1250       |
| 0   | 0   | 1   | 0.0125       |
| 0   | 1   | 1   | 0.1125       |
| 1   | 0   | 1   | 0.0875       |
| 1   | 1   | 1   | 0.7875       |

| $H$ |      | $S$ |        | $\Pr(H/S)$ |
|-----|------|-----|--------|------------|
| 0   | Low  | 0   | Cloudy | 0.750      |
| 1   | High | 0   | Cloudy | 0.250      |
| 0   | Low  | 1   | Sunny  | 0.125      |
| 1   | High | 1   | Sunny  | 0.875      |

| $P$ |         | $S$ |        | $\Pr(P/S)$ |
|-----|---------|-----|--------|------------|
| 0   | Absent  | 0   | Cloudy | 0.5        |
| 1   | Present | 0   | Cloudy | 0.5        |
| 0   | Absent  | 1   | Sunny  | 0.1        |
| 1   | Present | 1   | Sunny  | 0.9        |

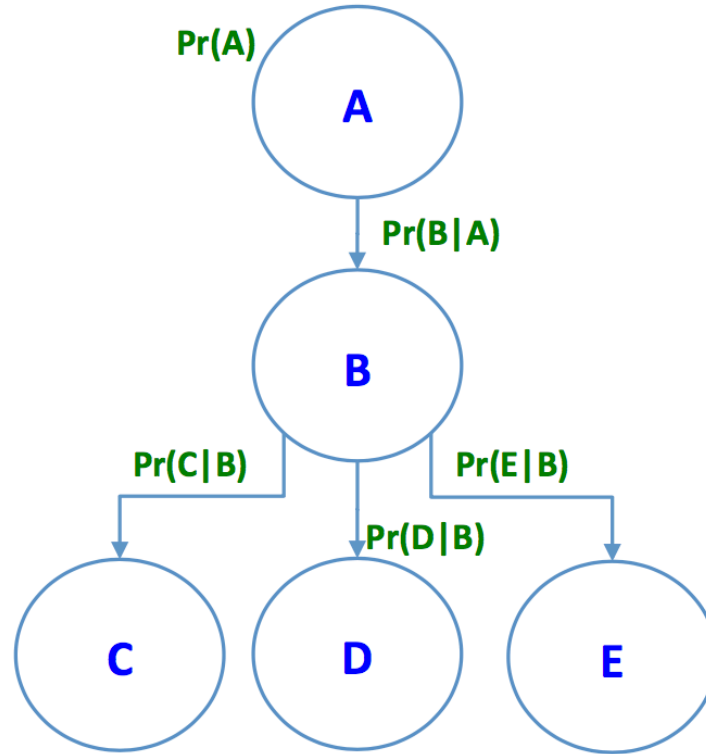
$H$  and  $P$  are **conditionally** independent given  $S$



- $H$  and  $P$  does not have direct path in the graph
- All paths from  $H$  to  $P$  are connected through  $S$
- In such cases, conditioning on  $S$  separates  $H$  and  $P$



# More **conditional** independence

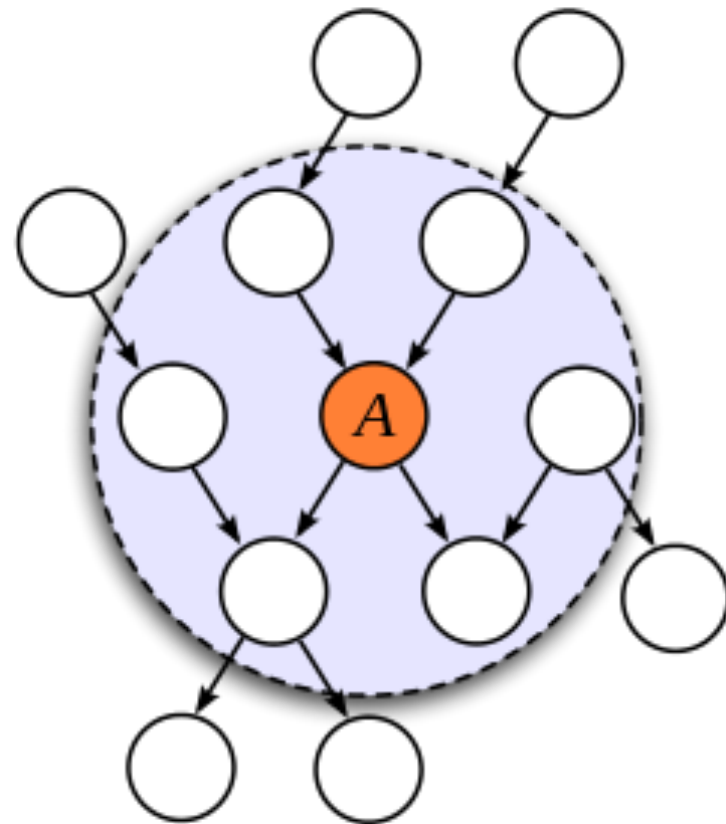


$$\Pr(A, C, D, E|B) = \Pr(A|B) \Pr(C|B) \Pr(D|B) \Pr(E|B)$$

# Markov blanket

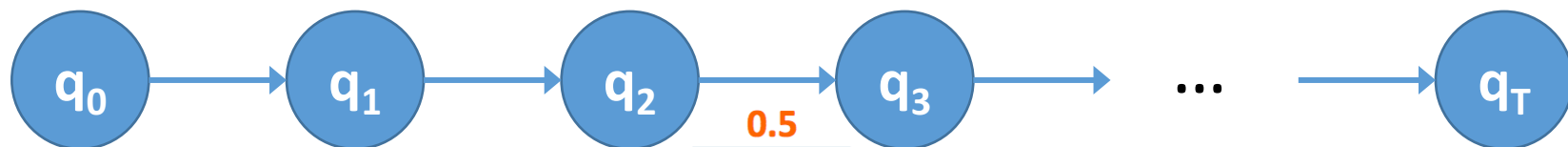
- Markov blanket  $\partial A$  for node  $A$  is a set of nodes composed of  $A$ 's parents, children, and the other parents of its children.
- Fact : Node  $A$  is conditionally independent given its Markov blanket  $\partial A$ .

$$A \perp (U - A - \partial A) \mid \partial A$$



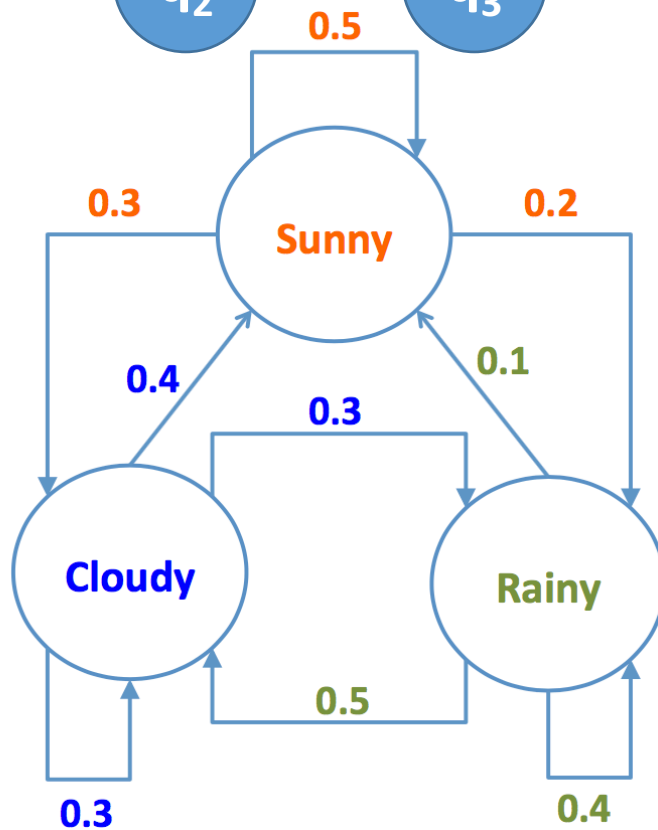
[https://en.wikipedia.org/wiki/Markov\\_blanket](https://en.wikipedia.org/wiki/Markov_blanket)

# Markov process



State diagram

$\Pr(q_{t+1}|q_t)$



# Markov process : **mathematical** representation

$$\pi = \begin{pmatrix} \Pr(q_1 = S_1 = \text{Sunny}) \\ \Pr(q_1 = S_2 = \text{Cloudy}) \\ \Pr(q_1 = S_3 = \text{Rainy}) \end{pmatrix} = \begin{pmatrix} 0.7 \\ 0.2 \\ 0.1 \end{pmatrix}$$

$$A_{ij} = \Pr(q_{t+1} = S_j | q_t = S_i)$$

$$A = \begin{pmatrix} 0.5 & 0.3 & 0.2 \\ 0.4 & 0.3 & 0.3 \\ 0.1 & 0.5 & 0.4 \end{pmatrix}$$

# Markov process : example questions

- What is the chance of rain in day 2?
- If it rains today, what is the chance of rain on the day after tomorrow?
- What is the stationary distribution when  $T$

# Markov process : example questions

- What is the chance of rain in day 2?

$$\Pr(q_2 = S_3) = (A^T \pi)_3 = 0.24$$

- If it rains today, what is the chance of rain on the day after tomorrow?

$$\Pr(q_3 = S_3 | q_1 = S_3) = \left[ (A^T)^2 \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right]_3 = 0.33$$

- What is the stationary distribution when  $t$  is very large?

$$\mathbf{p} = A^T \mathbf{p}$$

$$p = (0.346, 0.359, 0.295)^T$$

# Markov process dependencies

- If it rains today, what is the chance of rain on the day after tomorrow?

$$\Pr(q_3 = S_3 | q_1 = S_3) = \left[ (A^T)^2 \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right]_3 = 0.33$$

- If it has rained for the past 3 days in a row, what is the chance of rain on the day after tomorrow?

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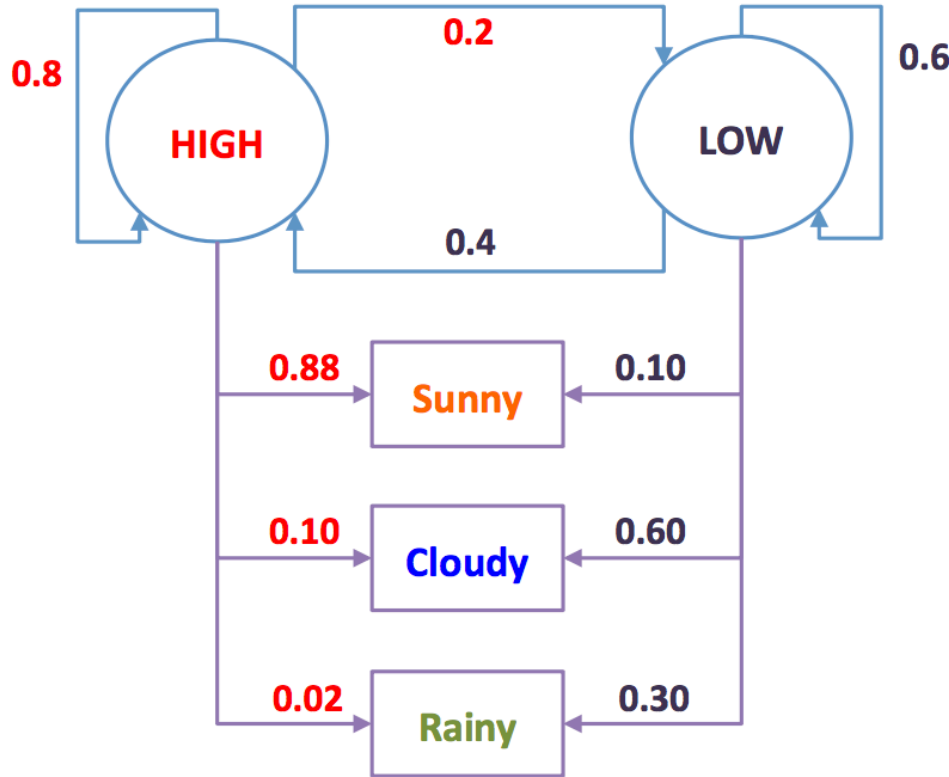
$$\Pr(q_5 = S_3 | q_1 = q_2 = q_3 = S_3) = \Pr(q_5 = S_3 | q_3 = S_3) = 0.33$$



# Hidden Markov Models (HMMs)

- A graphical model composed of **hidden** states and **observed** data.
- The hidden states follow a **Markov** process
- The distribution of observed data depends **only** on the hidden state.

# An example of HMM



- **Hidden states:**

- HIGH
- LOW

- **Observed data**

- Sunny
- Cloudy
- Rainy

# Mathematical representation of the example

- States  $S = \{S_1, S_2\} = (\text{HIGH}, \text{LOW})$
- Observed Data  $O = \{O_1, O_2, O_3\} = (\text{SUNNY}, \text{CLOUDY}, \text{RAINY})$
- Initial States  $\pi_i = \Pr(q_1 = S_i), \pi = \{0.7, 0.3\}$
- Transition  $A_{ij} = \Pr(q_{t+1} = S_j | q_t = S_i)$

$$A = \begin{pmatrix} 0.8 & 0.2 \\ 0.4 & 0.6 \end{pmatrix}$$

- Emission  $B_{ij} = b_{q_t}(o_t) = b_{S_i}(O_j) = \Pr(o_t = O_j | q_t = S_i)$

$$B = \begin{pmatrix} 0.88 & 0.10 & 0.02 \\ 0.10 & 0.60 & 0.30 \end{pmatrix}$$

# Marginal probabilities

- What is the chance of rain in the day 4?

$$\begin{pmatrix} \Pr(q_4 = S_1) \\ \Pr(q_4 = S_2) \end{pmatrix} = (A^T)^3 \pi = \begin{pmatrix} 0.669 \\ 0.331 \end{pmatrix}$$

$$\begin{pmatrix} \Pr(o_4 = O_1) \\ \Pr(o_4 = O_2) \\ \Pr(o_4 = O_3) \end{pmatrix} = B^T (A^T)^3 \pi = \begin{pmatrix} 0.621 \\ 0.266 \\ 0.233 \end{pmatrix}$$

# Conditional probabilities

- If the observation was

(SUNNY, SUNNY, CLOUDY, RAINY, RAINY) =  $(O_1, O_1, O_2, O_3, O_3)$

**from day 1 to day 5, what is the distribution of the hidden states on each day?**

$$\Pr(q_i | o_1, o_2, o_3, o_4, o_5; \lambda = (\pi, A, B)) \\ (1 \leq i \leq 5)$$

# Most **likely** states

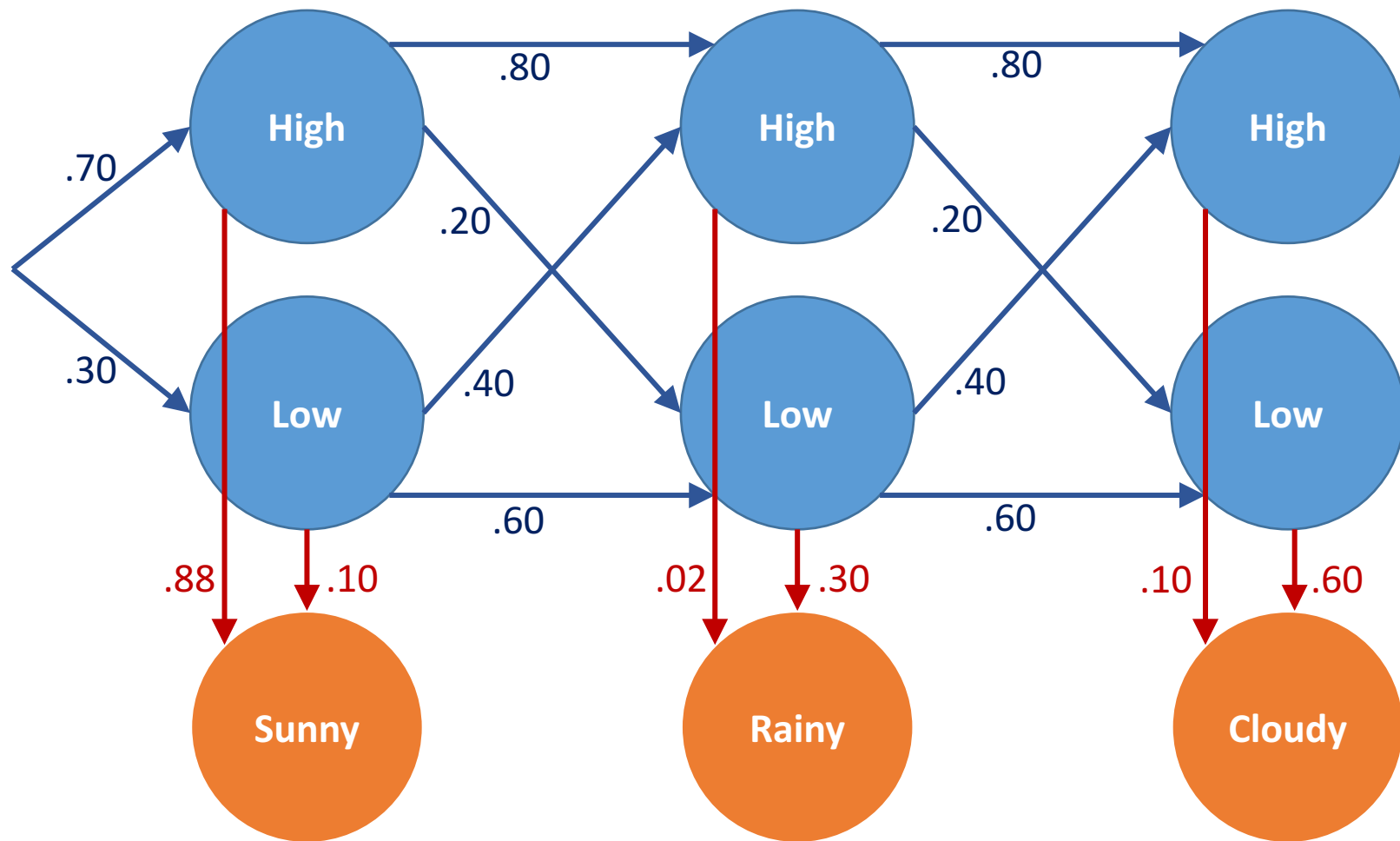
- **If the observation was**

(SUNNY, SUNNY, CLOUDY, RAINY, RAINY) =  $(O_1, O_1, O_2, O_3, O_3)$

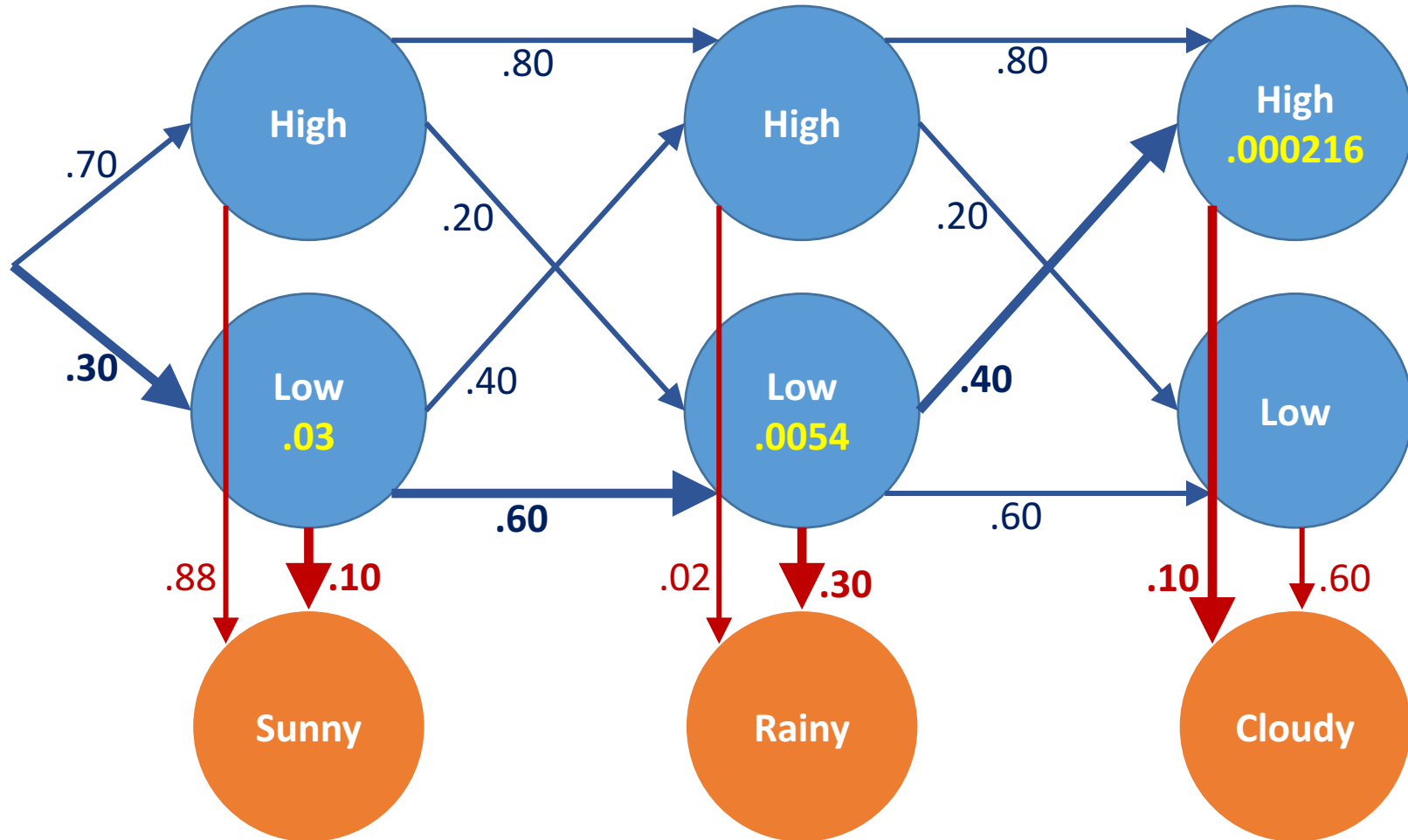
**from day 1 to day 5, what is the most likely combinations of the hidden states?**

$$\arg \max_{(q_1, \dots, q_5)} \Pr(q_1, \dots, q_5 | o_1, \dots, o_5; \lambda = (\pi, A, B))$$

# Finding **MLE** states



# Enumerating a possible state





# Enumerating **all** possible states

| $q_{111}$ | $q_2$    | $q_3$    | $\Pr(q)$    | $\Pr(o_1 q_1)$ | $\Pr(o_2 q_2)$ | $\Pr(o_3 q_3)$ | $\Pr(q,o)$   |
|-----------|----------|----------|-------------|----------------|----------------|----------------|--------------|
| H         | H        | H        | .448        | .88            | .02            | .10            | .0008        |
| H         | H        | L        | .112        | .88            | .02            | .60            | .0012        |
| H         | L        | H        | .056        | .88            | .30            | .10            | .0015        |
| <b>H</b>  | <b>L</b> | <b>L</b> | <b>.084</b> | <b>.88</b>     | <b>.30</b>     | <b>.60</b>     | <b>.0133</b> |
| L         | H        | H        | .096        | .10            | .02            | .10            | <.0001       |
| L         | H        | L        | .024        | .10            | .02            | .60            | <.0001       |
| L         | L        | H        | .072        | .10            | .30            | .10            | .0002        |
| L         | L        | L        | .108        | .10            | .30            | .60            | .0019        |

# Brute-force calculation of MLE states

- Enumerating all possible combination of states takes  $O(2^T)$ .
- Is this reasonable fast or too slow? Why?
- Is there a way to reduce the time complexity? How?