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Efficient Implementation and Evaluation of Einstein Summation via Batched Matrix Multiplication

PROJECT WORK

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Abstract

Tensor contractions are a fundamental operation in many scientific computing and machine learning applications, but their complexity and large memory demands often make them a performance bottleneck. Different approaches to computing tensor contractions come with different trade-offs — depending on the design of the algorithm, certain methods are better suited for small or simple pairwise contractions, while others can handle only complex tensor expressions more efficiently. Additionally, many existing implementations are restricted to specific data types and tensor expressions or can only process a small number of tensors, limiting the execution of multi-tensor contractions versatility.

In this project, we present a relatively simple custom implementation for computing tensor contractions, based on the Tensor-Transpose-Batch-GEMM-Transpose (TTBT) approach and expressed using the concise and powerful modern Einstein summation notation. Despite its simplicity, our algorithm is capable of handling arbitrarily large and complex tensor expressions.

The comparison of our implementation against two widely used libraries, Numpy [4] and PyTorch [7], both of which support Einstein summation, shows that our implementation can compete with both libraries, outperforming NumPy in compute-intensive scenarios. These findings show that it is possible to build a custom tensor contraction engine that stays flexible and efficient, handling complex tensor expressions while still keeping up with well-established libraries.

Zusammenfassung

Tensorkontraktionen spielen eine zentrale Rolle in vielen wissenschaftlichen Berechnungen und Anwendungen des maschinellen Lernens. Allerdings sind diese Tensoroperationen oft speicherintensiv und rechenaufwändig und werden dadurch schnell zu einem Bottleneck in Berechnungen. Unterschiedliche Lösungsansätze bringen dabei unterschiedliche Vor- und Nachteile mit sich: Während einige Methoden besonders gut für die Berechnung von Kontraktionen von kleinen Tensoren oder Tensornetzwerken geeignet sind, sind andere wiederum eher auf großen Tensorkontraktionen performant. Viele bisherige Implementierungen sind zudem auf bestimmte Datentypen und Tensorstrukturen beschränkt oder können nur eine begrenzte Anzahl von Tensoren verarbeiten, wodurch die Berechnung von Ausdrücken mit vielen Tensoren problematisch wird.

In diesem Projekt stellen wir eine relativ einfache Implementierung zur Berechnung von Tensorkontraktionen vor, die auch große und komplexe Tensorkontraktionen effizient berechnen kann. Sie basiert auf dem Transpose-Transpose-BMM-Transpose-Ansatz (TTBT) und nutzt die moderne Einsteinsche Summenkonvention zur Formulierung der zu berechnenden Kontraktion. Ein Vergleich mit den weit verbreiteten Bibliotheken NumPy [4] und PyTorch [7], die ebenfalls die Einsteinsche Summenkonvention unterstützen, zeigt, dass unser Ansatz nicht nur konkurrenzfähig ist, sondern in rechenintensiven Szenarien sogar deutlich besser als NumPy abschneidet. Unsere Ergebnisse belegen, dass es möglich ist, eine eigene Tensor-Kontraktions-Engine zu entwickeln, die flexibel, effizient und leistungsstark ist und dabei mit etablierten Bibliotheken mithalten kann.

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1 Introduction

Tensor contractions play an important role in many scientific and machine learning applications. However, due to their complexity and large memory requirements, they can quickly become a performance bottleneck. As a result, developing efficient solutions for this class of problems is of great interest.

Although various approaches to computing tensor contractions exist, each comes with its own limitations. While some implementations are efficient only for small tensors and perform poorly for compute-bound problems, others are restricted to simple tensor networks structures or specific data types. In this project, our goal is to implement a promising approach to tensor contractions that can handle a wide range of tensor structures and data types, and to compare it to existing engines.

Tensor contractions can be expressed elegantly using the so-called modern Einstein summation notation. The original notation was introduced by Albert Einstein in 1916, from which its modern form is derived [3]. While brief and concise, it allows for the clear representation of various tensor operations, including element-wise multiplications, dot products, outer products, and matrix multiplications. Since these expressions can be combined, even complex tensor networks can be described in a simple and readable form using Einstein summation. As a result, well-established libraries such as NumPy [4] and PyTorch [7] have integrated this notation into their tensor contraction engines. In this project, we adopt the Einstein summation convention to compute tensor contractions. Our goal is to support the contractions that can be expressed with this convention, allowing us to handle complicated tensor structures.

We then compare our implementation to two different established libraries Numpy [4] and PyTorch [7], both of which included Einstein summation into their tensor contraction engines. PyTorch broadly follows the same approach as our implementation, mapping the tensor contraction to a batch matrix multiplication, but relies among others on highly optimized libraries for linear algebra operations for that operation. Numpy uses a different strategy and iterates over the indices of the problem. We find that our implementation is able to compete with both of these engines, being more efficient than Numpy for compute-intensive problems. The code to our implementation can be found on <https://github.com/fenjaWagner/TTBMMT>.

This paper is structured as follows: We first provide the necessary background information in Section 2 and explain tensors, Einstein summation notation and tensor contractions. In Section 3 we explore different approaches to tensor contractions as well as contraction paths and existing implementations. Then we will describe our algorithm in detail in Section 4, presenting the benchmark results in Section 5. Finally, we will discuss these results in Section 6 and point out possible improvements to our solution.

2 Background

2.1 Tensors

Tensors are algebraic objects that extend the concept of scalars, vectors, and matrices to higher dimensions and can be interpreted as a multi-dimensional array. The number of dimensions is usually called the “rank” or “order” of a tensor. A scalar, for example, can represent a zero-order tensor, a vector a first-order tensor, and a matrix a second-order tensor. Higher-order tensors have multiple dimensions. Each of these dimensions of a tensor is represented by an index. A tensor of order n can be written as $T_{i_1 i_2 \dots i_n}$, where each index i_k runs over a certain range. The size of a tensor is determined by the product of the values of each index’s range.

2.2 Tensor Contractions

Tensor contraction is an operation that reduces the order of one or more tensors by summing over their shared indices. It generalizes the concept of matrix multiplication, where summation occurs over a shared index.

For example, for matrices $A \in \mathbb{R}^{m \times p}$ and $B \in \mathbb{R}^{p \times n}$, the result is a new matrix $C \in \mathbb{R}^{m \times n}$, computed as:

$$C_{ij} = \sum_k A_{ik} B_{kj}$$

For higher order tensors, the idea can be extended as follows: Let $T \in \mathbb{R}^{i_1 \times \dots \times i_p \times k_1 \times \dots \times k_r}$ and $S \in \mathbb{R}^{k_1 \times \dots \times k_r \times j_1 \times \dots \times j_q}$. Then,

$$C_{i_1, \dots, i_p, j_1, \dots, j_q} = \sum_{k_1, \dots, k_r} T_{i_1, \dots, i_p, k_1, \dots, k_r} S_{k_1, \dots, k_r, j_1, \dots, j_q}$$

where the indices k_1, \dots, k_r are summed over, reducing the total number of dimensions in the resulting tensor C .

2.3 Tensor Networks

A tensor network represents a complex tensor expression as a graph. Each tensor is represented by a node, and the indices of the tensors are represented by edges. If two tensors share an index, that index is contracted, and an edge connects the two nodes. Tensor networks where more than two tensors share the same index are called “hypernetworks”.

In Figure 2.1 one can see a tensor network representing the tensor contraction

$$C_{jklm} = \sum_i A_{jki} B_{ilm}.$$

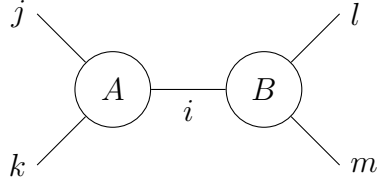


Figure 2.1: A three-dimensional tensor $T_{p,q,r}$ and a tensor network of two tensors A , B with shared index i .

2.4 Einstein Summation

The modern Einstein summation convention is a notation used in tensor calculus that simplifies mathematical expressions. The original convention consists of eliminating the need to explicitly write summation signs by implicitly contracting all indices that are repeated in the input term.

In the example above, the tensor contraction would be represented as

$$C_{jklm} = A_{jki}B_{ilm},$$

where the index i is summed over because it appears in the index sets of both A and B .

This idea is extended in the modern Einstein summation convention by contracting all indices that do not appear in the output term. In modern Einstein summation, our example can be written as

$$A_{jki}B_{ilm} \rightarrow C_{jklm}.$$

This extension leads to an even more powerful formalism. By stating explicitly the indices and their order in the output tensor, we can also express other tensor operations as transpositions, dot products, traces, and outer products in this concise manner. For example, the expression

$$A_{jki}B_{ilm} \rightarrow C_{klj}$$

means contracting the tensors via the index i , taking the result and summing over the axis m (since the index m does not appear in the output tensor) and transposing the tensor to C_{klj} .

When using common Einstein summation APIs such as Numpy [4] or PyTorch [7], the equation is expressed by stating simply the input and output indices as a format string. The format string for our last example would be

$$jki,ilm \rightarrow klj.$$

In the following, we will refer to the Einstein summation convention as “einsum” and use the representation as a format string with the output tensor explicitly marked by an arrow.

3 Related Work

3.1 Calculating Tensor Contractions

Springer and Bientinesi [9] state that even though the concept of tensor contractions is quite similar to matrix multiplications, the calculation of these contractions is usually inefficient compared to highly optimized algorithms for matrix multiplications. However, when performing tensor contractions, there are several methods to improve the performance, depending on the characteristics of the tensor and the hardware architecture. Springer and Bientinesi [9] describe three different approaches to calculating tensor contractions that are used by known tensor contraction libraries.

3.1.1 Nested Loops

The first and most straightforward approach mentioned by Springer and Bientinesi [9] involves nested loops, where the indices of the tensors are iterated over. Each loop corresponds to an index of the tensor, and the contraction is achieved by summing over the repeated indices. However, this approach can suffer from poor memory access patterns, especially when the tensors are complex and large, which often leads to suboptimal memory access patterns. Some of these inefficiencies can be mitigated by applying vectorization, loop transformations such as loop reordering or loop fusion that optimize cache efficiency.

Numpy [4] implements their einsum summation in loops by lowering the expression into a very general form and using a Numpy native iterator loop that effectively becomes a loop-based kernel.

3.1.2 Loops-over-GEMMs

The Loops-over-GEMMs method slices a tensor into multiple 2D sub-tensors (matrices) and contracts them using General Matrix Multiplication (GEMM) operations. This approach is particularly effective when the sub-tensors are large, as it allows efficient use of optimized GEMM routines. However, in some cases, the 2D slices may be small or require strided memory access, which can degrade performance [9].

3.1.3 Transpose-Transpose-GEMM-Transpose (TTGT)

Another method that is explained by Springer and Bientinesi [9] is to transpose and flatten the tensors so that they can be interpreted as matrices. This approach involves transposing and flattening the tensors, multiplying them using a General Matrix Multiply (GEMM) operation, and then transposing the result back to match the output tensor's shape. One key insight is that every tensor contraction can be represented as a matrix multiplication by dividing the index sets of the two to-be-contracted tensors A and B and the output tensor C into sets I_A, I_B , the indices that appear in both A and C or in B and C , and the set I_{con} , the contracted indices that appear in both A and B but not in C . A is then flattened into a

matrix $A' \in \mathbb{R}^{I_A \times I_{con}}$, B into a matrix $B' \in \mathbb{R}^{I_{con} \times I_B}$, the result $A' \times B' = C' \in \mathbb{R}^{I_A \times I_B}$ must then be reshaped and transposed, so its indices match the ones given for C . The advantage of this approach is that it reduces the contraction operation to a matrix multiplication, which is a highly optimized operation in most linear algebra libraries such as BLAS [2]. However, the need to transpose the tensors and the result introduces an overhead due to additional storage and data movement. The performance of this method is bandwidth-bound if the transposing steps take most of the runtime. In compute-bound scenarios, where the computation is more expensive than the memory transfer, this method can perform very well because GEMM can be highly optimized, especially when using modern hardware, such as GPUs and specialized matrix-multiplication units.

3.1.4 GEMM-like Tensor Tensor multiplication (GETT)

Springer and Bientinesi [9] introduce an approach called “GEMM-like Tensor Tensor multiplication” (GETT), that aims to combine the benefits of the aforementioned approaches while avoiding their drawbacks. While the concept of GETT is basically similar to that of TTGT, it avoids the overhead of the tensor transposition by implicitly reorganizing the data while packing it into the caches. In the next step, the data that is loaded into the cache can be processed by highly optimized macro-kernels.

3.1.5 Transpose-Transpose-BMM-Transpose (TTBT)

Just as any tensor can be represented as a single matrix, it can also be written in the form of a batched matrix. By adopting the concept of Transpose-Transpose-GEMM-Transpose, one can replace the GEMM with a batched matrix multiplication (BMM). Similar to the TTGT approach, TTBT usually performs well for compute-bound problems, while the overhead during the pre- and post-processing of the tensors remains a drawback for bandwidth-bound calculations. PyTorch’s einsum implementation [7] adopts the TTBT approach by partitioning the index set into subsets and mapping the problem to a BMM whenever its structure allows.

3.1.6 Code Generation for Specific Problems

Another approach is to generate optimized code for specific tensor contractions. TACO (the Tensor Algebra Compiler) [5] can generate efficient solutions for both sparse and dense tensor operations. However, since the generated code is tailored to a specific pairwise contraction of two given tensors, TACO lacks the flexibility needed to process arbitrary tensor operations dynamically at runtime.

3.2 Contraction Paths

Since tensor contractions are associative, a multi-tensor contraction can be broken down into a sequence of pairwise tensor contractions. The order of these pairwise

contractions, called the “contraction path”, influences the calculation’s performance immensely. Consequently, it is crucial to choose an efficient contraction path, but the computation of these paths is very costly itself. Optimized Einsum (`opt_einsum`) [8] is a package for optimizing the tensor contraction order for a problem. For executing pairwise contractions, the user can select from different backends. Orgler and Blacher [6] improve the contraction path determination of `opt_einsum` and introduce a greedy approach that allows calculating a path either optimized for the size of the biggest intermediate tensor or the total number of floating-point operations needed for the contraction. Blacher et al. [1] state that choosing the path that optimizes the number of flops does not necessarily result in better performance, since a size-optimized path results in more balanced intermediate tensors and therefore a better cache usage.

4 The Algorithm

4.1 Pairwise Tensor Contraction

An arbitrarily complex multi-tensor contraction can be decomposed into pairwise tensor contractions, guided by a specified contraction path. In this section, we present our algorithm for performing a single pairwise tensor contraction using the Transpose-Transpose-BMM-Transpose (TTBT) approach.

Given a format string $a_1 \dots a_k, b_1 \dots b_l \rightarrow c_1 \dots c_r$ that contains the indices of the input tensors $A_{a_1 \dots a_k}, B_{b_1 \dots b_l}$ and the indices of the output tensor $C_{c_1 \dots c_r}$ in the right order, we divide the index sets of the two to-be-contracted tensors A and B and the output tensor C into the four sets

- $I_{bt} = \{i_{bt_1}, \dots, i_{bt_k}\}$, the indices that appear in A , B and C ,
- $I_A = \{i_{A_1}, \dots, i_{A_l}\}$, the indices that appear in both A and C but not in B ,
- $I_B = \{i_{B_1}, \dots, i_{B_m}\}$, the indices that appear in both B and C but not in A ,
- $I_{con} = \{i_{con_1}, \dots, i_{con_n}\}$, the contracted indices that appear in both A and B but not in C .

Consider that all indices appear at most once in the sets, and that indices which appear solely in A or B but not in C are excluded from all four sets. Because we will need the ranges of the indices in the post-processing, we store the range of each index in a dictionary.

By transposing A to A' using the format string

$$indices_A \rightarrow i_{bt_1} \dots i_{bt_k} i_{A_1} \dots i_{A_l} i_{con_1} \dots i_{con_n},$$

and B to B' using

$$indices_B \rightarrow i_{bt_1} \dots i_{bt_k} i_{con_1} \dots i_{con_n} i_{B_1} \dots i_{B_m},$$

we reorder the tensors so that batch and contracted dimensions align properly. Using Numpy's einsum engine [4] to process the respective format strings, we can transpose, eliminate traces, and sum over arbitrary axes in a single step.

This procedure ensures that our implementation can handle all possible einsum expressions. In addition, removing traces and arbitrary indices before the contraction results in smaller tensors and therefore smaller intermediate tensors and a lower number of floating-point operations.

We then calculate the shape of the combined batch dimensions, the combined contracted dimensions, and the combined kept dimensions for A and B by multiplying the ranges of the respective indices.

The result C' is calculated by a blocked and parallelized batched matrix multiplication algorithm that we generated using TACO [5] and optimized by blocking to

improve cache usage and avoid unnecessary data movement. It is parallelized for problems that exceed a certain size. This algorithm takes the flattened tensors A and B and returns $C' = A' \times B' \in \mathbb{R}^{\text{size}(I_{bt}) \cdot \text{size}(I_A) \cdot \text{size}(I_B)}$. C' is then reshaped and transposed so its indices and their order match the given output indices. For the pseudocode of our pairwise tensor contraction refer to Algorithm 1.

Algorithm 1 CUSTOM PAIRWISE TENSOR CONTRACTION

Require: format_string, Tensors A, B

Ensure: Tensor C

- 1: Retrieve $I_A, I_B, I_{bt}, I_{con}$
 - 2: Store the sizes of the indices
 - 3: Preprocess A : transpose, remove traces and sum over arbitrary axes
 - 4: Preprocess B : transpose, remove traces and sum over arbitrary axes
 - 5: Calculate the sizes of the index sets: $s_A = \prod_{i \in I_A} \text{range}(i)$,
 - 6: $s_B = \prod_{i \in I_B} \text{range}(i)$,
 - 7: $s_{bt} = \prod_{i \in I_{bt}} \text{range}(i)$,
 - 8: $s_{con} = \prod_{i \in I_{con}} \text{range}(i)$.
 - 9: Reshape $A \leftarrow A_{s_{bt} s_A s_{con}}$
 - 10: Reshape $B \leftarrow B_{s_{bt} s_{con} s_B}$
 - 11: $C \leftarrow \text{BMM}(A, B)$
 - 12: Reshape $C \leftarrow C_{i_{batch_1} \dots i_{batch_k} i_{A_1} \dots i_{A_l} i_{B_1} \dots i_{B_m}}$
 - 13: Transpose $C \leftarrow C_{outputIndices}$
 - 14: **return** C
-

The mapping of the tensors A and B to batched matrices and the remapping of the output tensor C' to the desired shape is processed in Python, while the batched matrix multiplication is written in C++.

Our implementation can process int_16, int_32, int_64, float_32, and float_64 as data types.

4.2 Multi-Tensor Contraction

Our multi-tensor contraction algorithm takes the format string for the tensor contraction, the list of the referring tensors, a contraction path, and a backend flag. Our algorithm for pairwise contractions can process format strings composed of UTF8 symbols. However, PyTorch [7] and Numpy [4] can only handle alphabetic characters. To allow for the comparison of our algorithm to these approaches, we use einsum.benchmark [1] to generate an annotated contraction path. This annotated path contains a list of pairs of indices for the tensors in the tensor list that are to be contracted and the short format strings for these specific pairwise contractions. This short format string consists only of alphabetic characters. We then perform the pairwise contraction with the backend indicated by the flag. We implemented Numpy's and PyTorch's einsum engine and our pairwise contraction as possible

backends. Our own implementation will be referred to as “custom”. Since Numpy’s highly optimized matrix multiplication engine (matmul) can also process batched matrices [4], we added a fourth backend that consists of our pairwise contraction algorithm in combination with Numpy’s matmul method instead of our BMM. We will call this backend “np_mm” to distinguish it from our custom implementation. The result of the pairwise tensor contraction is then appended to the tensor list. If the tensors A or B were not in the original tensor list, they are set to None to avoid unnecessary intermediate of data.

For the pseudocode of the multi-tensor contraction refer to Algorithm 2.

Algorithm 2 MULTI-TENSOR CONTRACTION

Require: contraction_path, tensor_list, format_string, backend_flag

Ensure: Tensor C

```

1: Store the length of tensor_list in  $t\_l$ .
2: Calculate the ssa path from the contraction_path.
3: Calculate the annotated_ssa_path from the ssa path and the format_string.
4: for every path_tuple in annotated_ssa_path do
5:   Retrieve tensors  $A$  and  $B$  from tensor_list with indices from the path_tuple.
6:   Retrieve the short_format_string from the path_tuple.
7:   Set pc_method depending on the backend_flag
8:    $C = \text{pc\_method}(A, B, \text{short\_format\_string}, \text{backend\_flag})$ 
9:   if index for tensor  $A \geq t\_l$  then
10:     Delete  $A$ 
11:   end if
12:   if index for tensor  $B \geq t\_l$  then
13:     Delete  $B$ 
14:   end if
15:   Append  $C$  to tensor_list
16: end for
17: return  $C$ 

```

5 Experiments

We compare our custom tensor contraction algorithm to the einsum engines of PyTorch and Numpy as well as to the np.mm backend. To evaluate the performance of each engine, we use two different sets of problems: First, we test all four engines on simple pairwise tensor contractions with different structural characteristics. Second, we evaluate the four einsum engines on real-world einsum expressions.

Blacher et al. [1] point out that most current tensor libraries are optimized for a limited range of tensor operations, particularly those involving large, dense tensors. However, real-world applications often require a much broader variety of tensor operations, which can cause performance issues. To solve this problem, they present the einsum_benchmark dataset that includes a wide range of tensor operations and covers the diverse types of operations used in practice. To address this issue, we assess the performance of all four implementations on 28 real-world problems from that dataset.

We measure the iterations per second for all experiments, that is, how often a given einsum expression can be executed within one second.

The experiments are performed on a machine with an Intel i5-7200U 2-core processor running Ubuntu 22.04-1 with 8 GB of RAM. Each core has a base frequency of 2.5 GHz and a max boost frequency of 3.1 GHz. The evaluation is done in Python 3.12.8 with PyTorch 2.5.1 and Numpy 2.2.1.

5.1 Experiments on Pairwise Tensor Contractions

We designed four format strings for pairwise tensor contractions with or without batch dimensions, traces and arbitrary indices in different combinations as can be seen in Table 5.1.

Table 5.1: Format string and properties of the four einsum expressions.

Format String	Batch Dimension	Traces	Arbitrary Indices
$aabcd, adeef \rightarrow dcf$	yes	yes	yes
$abcd, adef \rightarrow dbef$	yes	no	yes
$aabcd, adeef \rightarrow bcf$	no	yes	yes
$abcd, adef \rightarrow cbef$	no	no	no

To evaluate the performance of the four einsum engines across scenarios with increasing computational intensity, we repeatedly generated random tensors A and B for each problem, increasing the dimensions for each index in each repetition. For example, the first pair of tensors generated for the einsum expression $aabcd, adeef \rightarrow dcf$ has sizes (2,2,2,2,2) for both tensor A and B , resulting in 128 floating point operations (or 2.11 floating point operations if we use a log10 scale), the second one (5,5,5,5,5), and so forth. A table with the dimension sizes and the resulting number of floating point operations for the four problems can be found in

Table A.1 in the appendix.

As can be seen in Figure ??, our custom implementation outperforms PyTorch and Numpy for problems that contain batch dimensions, traces and arbitrary indices.

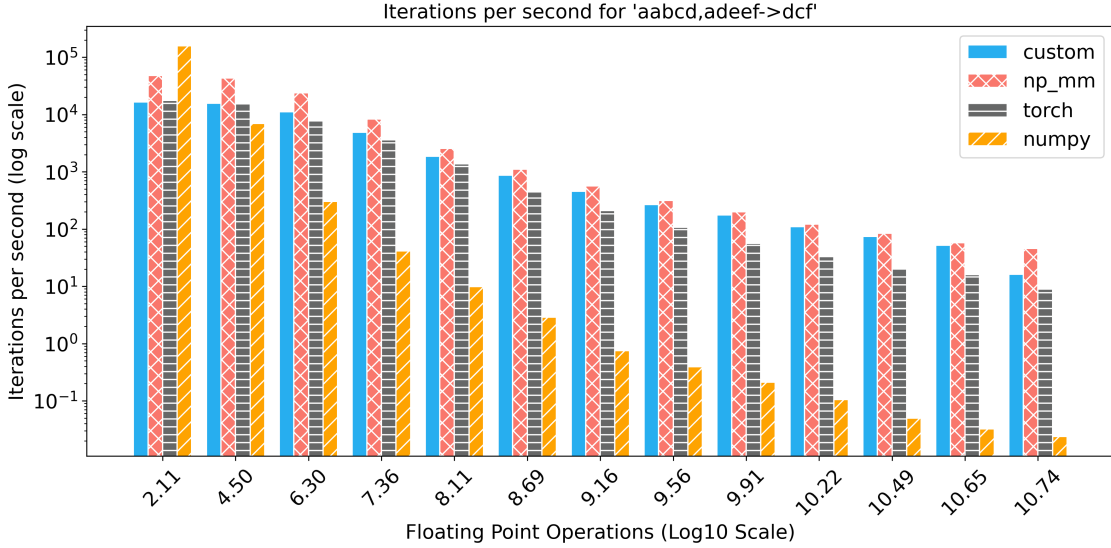


Figure 5.1: Performance Comparison for the pairwise contraction with batch dimensions, traces and arbitrary indices. The x-axis depicts the number of floating point operations corresponding to the gradually increased dimension sizes.

While the performance of all implementations decreases for all four problems with a growing number of floating-point operations, the rate of this degradation varies. Numpy performs better than all the other backends for low counts of floating-point operations in all four contractions, as depicted in Figure ?? in the appendix. However, its performance declines fastly with increasing problem size. For the largest problems, our algorithm with the `np_mm` backend emerges as the most efficient method across all cases, as can be seen in Table 5.2.

Table 5.2: Performance comparison for the largest tensor contractions of the respective problems across the different engines, scaled to the best performance.

Tensor Expression	FLOPS	Custom	np_mm	Numpy	Torch
$abcd, adeef \rightarrow dcf$	10.74	0.35	1	0.00043	0.19
$abcd, def \rightarrow dbef$	10.93	0.36	1	0.0014	0.72
$abcd, adeef \rightarrow bcf$	10.74	0.15	1	0.001	0.42
$abcd, def \rightarrow cbef$	10.93	0.11	1	0.03	0.98

5.2 Einsum Benchmark

We ran the 28 problems from the `einsum_benchmark` dataset [1] that are small enough to fit on our machine and have a non-complex data type. An overview over

the properties of the einsum expressions can be found in the appendix in Table A.2 and the performance results in Table A.3. For our performance discussion we chose five representative problems that depict the differences between the four einsum engines. Table 5.3 lists the relevant properties of these problems.

Table 5.3: Instance data with instance name, number of tensors and the size of the biggest intermediate tensor.

Instance Name	Number of Tensors	Biggest Intermediate Tensor	Data Type
wmc_2023_152	40489	16384	float64
mc_2023_002	26556	131072	float64
mc_2020_arjun_057	905	8388608	int32
mc_2020_017	78784	4194304	int32
lm_batch_likelihood_sentence_4_12d	84	39398400	float64

As can be seen in Figure 5.2, Numpy performs best for problems with small intermediate tensor sizes. Our custom algorithm is more efficient for problems with data type int32, while PyTorch and np_mm are most efficient for problems with the data type double.

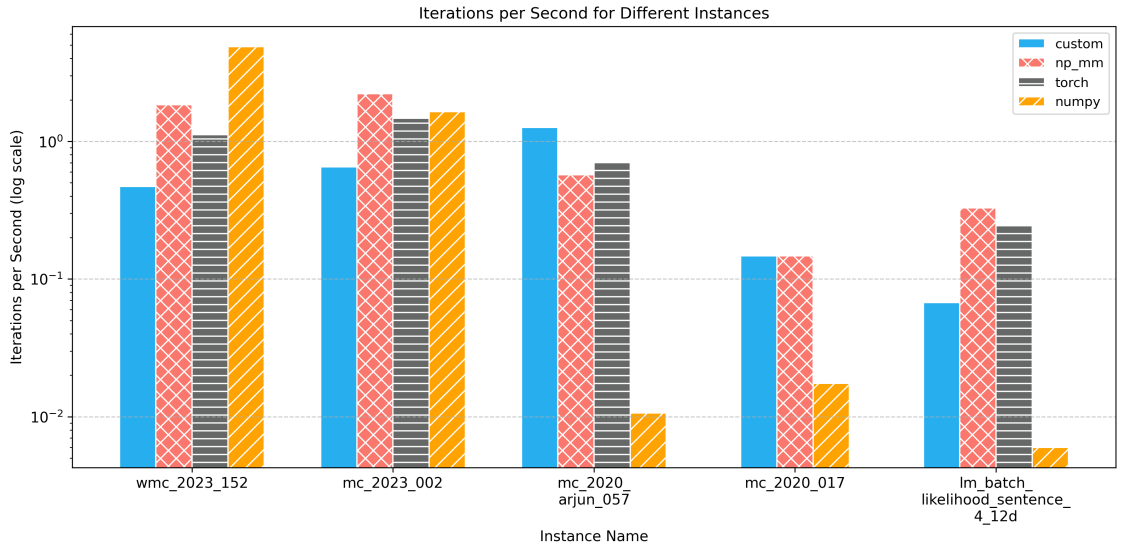


Figure 5.2: Performance Comparison for different problems from einsum_benchmark [1]. PyTorch was unable to compute mc_2020_017 due to hidden conversions from int32 to int64 during pairwise contractions.

To further evaluate the efficiency of PyTorch and np_mm on problems with datatype double, we casted the two problems mc_2020_017 and mc_2020_arjun_057 with datatype int32 to float64 and ran the computation again. As shown in Figure ?? in the appendix, PyTorch and np_mm both outperform the custom algorithm in this scenario.

5.3 Impact of Parallelization

To assess the impact of parallelization, we evaluated the multi-tensor contraction `mc_2020_arjun_046` from `einsum_benchmark` [1] using our custom implementation, our implementation with the `np.mm` backend, and PyTorch on one and two threads. The properties of this problem can be seen in Figure 5.4.

Table 5.4: Instance data of `mc_2020_arjun_046` with number of tensors and the size of the biggest intermediate tensor.

Instance Name	Number of Tensors	Biggest Intermediate Tensor	Data Type
<code>mc_2020_arjun_046</code>	1045	8388608	<code>int64</code>

While NumPy’s batch matrix multiplication is not parallelized, our custom multi-tensor contraction shows an approximate 25% performance improvement when increasing the thread count from one to two. PyTorch’s performance similarly improves by around 20%. Additionally, we measured the isolated performance of our custom BMM computation. Here, the parallelization leads to an almost 50% speed-up when scaling from one to two threads.

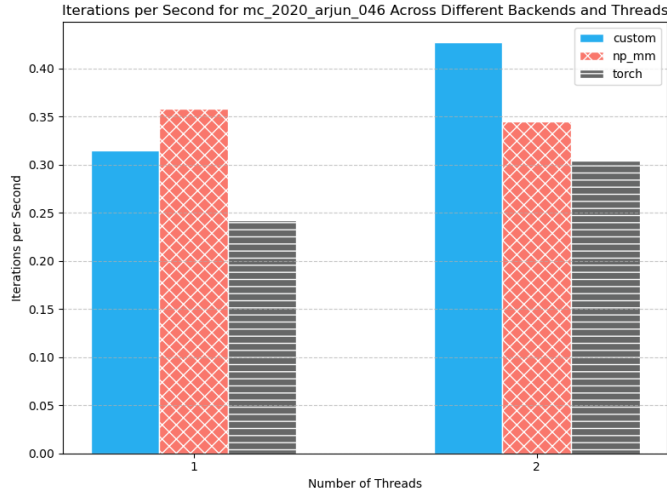


Figure 5.3: Iterations per second vs thread number for `mc_2020_arjun_046` [1].

6 Discussion

In this chapter we seek to explain the results of the experiments and discuss possible improvements to enhance the efficiency of our implementation.

6.1 Understanding the Results

As described by Springer and Bientinesi [9], one of the TTBT-approaches drawbacks is the overhead induced by transposing and reshaping the tensors during pre- and post-processing. This overhead comes in costly, if the calculation is bandwidth-bound, which is the case for tensor contractions with relatively small tensors. This is reflected in our experiments as Numpy always outperforms Pytorch, `np_mm` and our own implementation when the intermediate tensor size is small.

However, with a rising number of floating-point operations Numpy's efficiency decreases rapidly, while the performance of the other implementations remains more stable. This is due to the increasing size and complexity of the tensors - while Numpy's looping approach results in poor memory access patterns, the TTBT approach used by Pytorch and our implementation ensures a more efficient cache usage.

Naturally, our algorithm with our custom BMM implementation is less efficient than the `np_mm` version and Pytorch's engine in most cases. Even though our BMM is parallelized and blocked, it is unlikely to compete with the highly optimized linear algebra libraries that the others use for their matrix multiplications. However, our implementation performed better for some problems with data type `int`. A possible reason is that these libraries are optimized for floating-point arithmetics, whereas operations on integer types are handled by more generic, less-optimized code paths.

6.2 Possible Improvements

Our implementation uses Numpy's `einsum` engine to remove traces and arbitrary indices. If the tensors are complex this can lead again to suboptimal memory access patterns. This could be avoided with a more cache oriented implementation of this operation.

Furthermore, we could improve our BMM by dynamically adjusting the block sizes based on the data type and cache size, and by enabling better vectorization through analyzing the data layout carefully and refactoring loop structures.

7 Conclusion

We have successfully implemented the TTBT approach for tensor contractions expressed in Einstein summation notation by mapping the preprocessed tensors to a relatively simple batch matrix multiplication. We have compared our engine with Numpy’s [4] and PyTorch’s [7] einsum library on generated and real-world problems and found that our implementation can compete with these well-known libraries. Moreover, our implementation can handle a wider range of input strings than PyTorch and is more efficient for certain data types. In doing so, we proved it possible to write a simple but yet powerful engine for efficient pairwise tensor contractions that can easily be used for multi-tensor contractions given a contraction path. This engine could be further improved by enhancing memory access patterns of the pre-processing and the BMM implementation.

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Appendix

Table A.1: Number of floating-point operations for different dimension sizes for a, b, c, d, e, f . For the other three contractions $abcd, adef \rightarrow dbef$, $aabcd, adeef \rightarrow bcf$ and $abcd, adef \rightarrow cbef$, the sizes of the tensors are changed in an analogous manner.

Dimension Size	$aabcd, adeef \rightarrow dcf$	FLOPs
2	A:(2,2,2,2,2), B:(2,2,2,2,2)	2.11
5	A:(5,5,5,5,5), B:(5,5,5,5,5)	4.49
10	A:(10,10,10,10,10), B:(10,10,10,10,10)	6.30
15	A:(15,15,15,15,15), B:(15,15,15,15,15)	7.36
20	A:(20,20,20,20,20), B:(20,20,20,20,20)	8.11
25	A:(25,25,25,25,25), B:(25,25,25,25,25)	8.69
30	A:(30,30,30,30,30), B:(30,30,30,30,30)	9.16
35	A:(35,35,35,35,35), B:(35,35,35,35,35)	9.56
40	A:(40,40,40,40,40), B:(40,40,40,40,40)	9.91
45	A:(45,45,45,45,45), B:(45,45,45,45,45)	10.22
50	A:(50,50,50,50,50), B:(50,50,50,50,50)	10.49
53	A:(53,53,53,53,53), B:(53,53,53,53,53)	10.65
55	A:(55,55,55,55,55), B:(55,55,55,55,55)	10.74
57	A:(57,57,57,57,57), B:(57,57,57,57,57)	10.84
59	A:(59,59,59,59,59), B:(59,59,59,59,59)	10.93

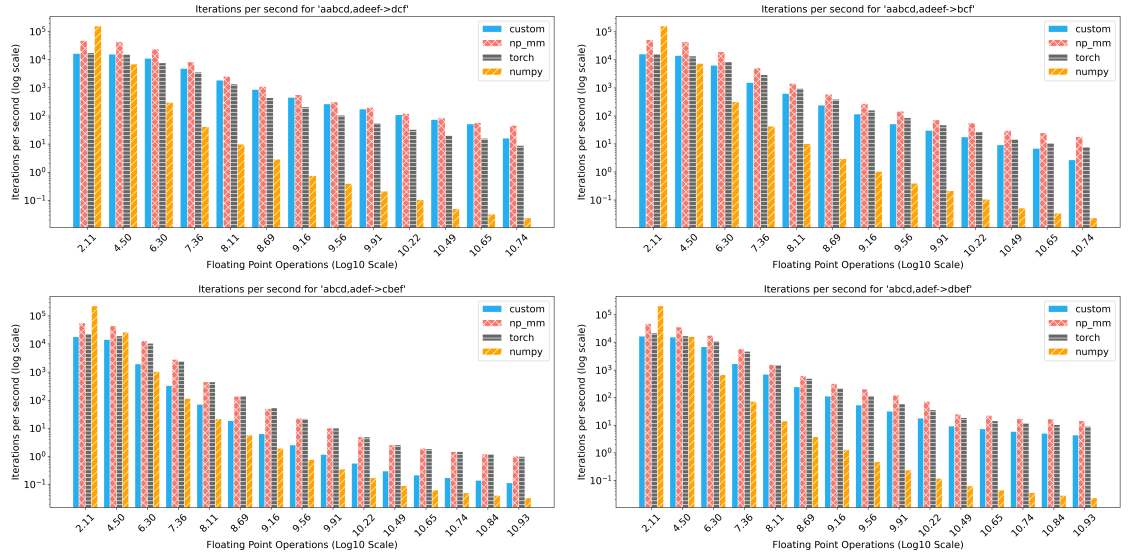


Figure A.1: Performance of the four backends over all four pairwise contractions. In all plots, the x-axis depicts the number of floating point operations corresponding to the gradually increased dimension sizes.

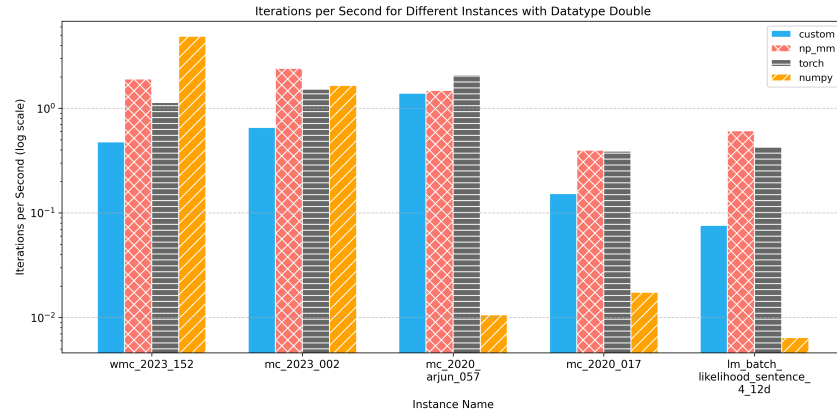


Figure A.2: Performance Comparison for different problems from einsum_benchmark [1], all tensors casted to float_64.

Table A.2: Instance data with instance name, number of tensors, and the size of the biggest intermediate tensor.

Instance Name	Number of Tensors	Biggest Intermediate Tensor	Data Type
mc_2022_167	579972	64	int16
mc_2022_079	3893	2048	float64
wmc_2021_130	5037	4096	float64
wmc_2023_035	9049	4096	float64
str_matrix_chain_multiplication_1000	1000	15621	float64
str_mps_varying_inner_product_2000	2000	11191	float64
wmc_2023_152	40489	16384	float64
str_mps_varying_inner_product_200	200	45847	float64
mc_2023_002	26556	131072	float64
str_matrix_chain_multiplication_100	100	233310	float64
lm_batch_likelihood_sentence_4_4d	84	486400	float64
lm_batch_likelihood_brackets_4_4d	84	510976	float64
mc_2023_188	14613	524288	float64
lm_batch_likelihood_sentence_3_12d	38	1900800	float64
mc_2020_017	78784	4194304	int32
lm_batch_likelihood_sentence_4_8d	84	7782400	float64
mc_2023_arjun_117	6267	8388608	float64
mc_2021_027	331	8388608	int16
mc_rw_blasted_case1_b14_even3	4093	8388608	float64
str_nw_peps_closed_333	333	4976640	float64
wmc_2023_141	230848	16777216	float64
mc_2020_arjun_046	1045	8388608	int64
mc_2020_arjun_057	905	8388608	int32
mc_2021_arjun_171	1601	33554432	float64
str_nw_mera_closed_120	120	31492800	float64
lm_batch_likelihood_sentence_4_12d	84	39398400	float64
str_nw_mera_open_26	26	10103940	float64
rnd_mixed_08	500	37044000	float32

Table A.3: Iterations per second for the custom, np_mm, numpy, and torch over all used problems from einsum.benchmark [1]. The best value in each row is bolded. If a backend failed during the computation due to data type issues, the field is marked with “-”.

Instance Name	custom	np_mm	numpy	torch
mc_2022_167	0.02902	0.10977	0.41380	-
mc_2022_079	4.13003	12.94602	15.63522	8.77809
wmc_2021_130	3.07690	11.28056	38.19010	8.04783
wmc_2023_035	1.66732	5.58773	9.18394	4.07645
str_matrix_chain_multiplication_1000	7.57826	25.66862	15.57929	18.37777
str_mps_varying_inner_product_2000	2.98214	9.09908	3.15003	6.45833
wmc_2023_152	0.46924	1.84391	4.88169	1.11984
str_mps_varying_inner_product_200	9.01819	26.01232	7.22079	28.34449
mc_2023_002	0.65240	2.21285	1.63918	1.46946
str_matrix_chain_multiplication_100	12.67161	37.94583	13.49679	53.26709
lm_batch_likelihood_sentence_4_4d	6.31155	10.55606	4.68459	12.42889
lm_batch_likelihood_brackets_4_4d	7.63325	12.20857	1.40967	13.37427
mc_2023_188	0.36408	0.76063	0.06197	0.91138
lm_batch_likelihood_sentence_3_12d	3.39126	8.55636	1.25902	4.51546
mc_2020_017	0.14763	0.14713	0.01745	-
lm_batch_likelihood_sentence_4_8d	0.56249	1.51651	0.17023	1.19566
mc_2023_arjun_117	0.26414	0.49903	0.00457	0.77977
mc_2021_027	3.24499	1.81888	0.05703	2.74746
mc_rw_blasted_case1_b14_even3	0.11344	0.15607	0.02301	0.27253
str_nw_peps_closed_333	0.30381	1.08955	0.01631	1.32083
wmc_2023_141	0.03194	0.06141	0.00203	0.06274
mc_2020_arjun_046	0.42095	0.33647	0.01436	0.30052
mc_2020_arjun_057	1.26268	0.57259	0.01066	0.70053
mc_2021_arjun_171	0.12230	0.13108	0.01238	0.24522
str_nw_mera_closed_120	0.18247	0.96197	0.01679	0.87889
lm_batch_likelihood_sentence_4_12d	0.06761	0.32923	0.00598	0.24474
str_nw_mera_open_26	0.27014	1.49597	0.03690	1.39167
rnd_mixed_08	0.13898	0.24311	0.00552	0.38247