

VGC Short Course '4D change analysis of near-continuous LiDAR time series for applications in geomorphic monitoring'

Getting started with 4D change analysis in py4dgeo

See the full workflow in https://github.com/tum-rsa/vgc2023-shortcourse-4d/blob/main/course/practical/vgc2023_time_series_change_analysis.html

Katharina Anders
k.anders@tum.de

Technical University of Munich
TUM School of Engineering and Design
Professorship for Remote Sensing Applications

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The case for **py4dgeo**

4D → massive multitemporal point cloud data

- Automating change analysis
- Bundling state-of-the-art methods

Open-source Python library for change analysis in 4D point cloud data: <https://github.com/3dgeo-heidelberg/py4dgeo>

... providing 3D/4D methods:

- M3C2 (Lague et al., 2013)
- 4D objects-by-change (Anders et al., 2021)
- Correspondence-Driven Plane-Based M3C2 (Zahs et al., 2022)
- M3C2-EP (Winiwarter et al., 2021)
- ...

... and a flexible interface for analysis workflows

See the basic usage tutorials: <https://py4dgeo.readthedocs.io> and [materials in the E-TRAINEE online course](#)



py4dgeo

Open source Python library for geographic change analysis in 4D point cloud data

Creating epochs from point cloud arrays:

```
print('[%s] Creating epoch 1...' % (datetime.now().strftime('%Y-%m-%d %H:%M:%S')))
epoch1 = py4dgeo.Epoch(coords1)

print('[%s] Creating epoch 2...' % (datetime.now().strftime('%Y-%m-%d %H:%M:%S')))
epoch2 = py4dgeo.Epoch(coords2)

print('[%s] Epochs successfully created, kd-trees built' % (datetime.now().strftime('%Y-%m-%d %H:%M:%S')))

[2021-12-23 10:41:54] Creating epoch 1...
[2021-12-23 10:41:55] Creating epoch 2...
[2021-12-23 10:41:56] Epochs successfully created, kd-trees built
```

M3C2 distance calculation

Configuring and running M3C2:

```
print('[%s] Configuring M3C2...' % (datetime.now().strftime('%Y-%m-%d %H:%M:%S')))
m3c2 = py4dgeo.M3C2(epochs=(epoch1, epoch2), corepoints=corepoints, radii=
m3c2_multiscale = py4dgeo.M3C2(epochs=(epoch1, epoch2), corepoints=corepoi

print('[%s] Running M3C2...' % (datetime.now().strftime('%Y-%m-%d %H:%M:%S')))
distances_multiscale, uncertainties_multiscale = m3c2_multiscale.run()
print('[%s] Calculation successful' % (datetime.now().strftime('%Y-%m-%d %H:%M:%S')))

[2021-12-23 10:41:56] Configuring M3C2...
[2021-12-23 10:41:56] Running M3C2...
[2021-12-23 10:41:58] Calculation successful
```

Accessing all result information, i.e. `lodetection`, `num_samples`, and `stddev` in `uncert`

```
lodetection = uncertainties['lodetection']
stddev1 = uncertainties['stddev1']
numsamples1 = uncertainties['num_samples1']
stddev2 = uncertainties['stddev2']
numsamples2 = uncertainties['num_samples2']
normals = m3c2.directions()
```

Change Analysis in py4dgeo

class Epoch

- Data: coordinates (nx3 array)
- Property: metadata (dictionary), transformation
- Methods:
 - calculate_normals()
 - transform()
 - save/load()
- Created using `py4dgeo.read_from_las()` / `py4dgeo.read_from_xyz()`

```
# import the library for M3C2 distance calculation  
import py4dgeo  
  
# Load point clouds as epoch objects  
epoch_2009, epoch_2017 = py4dgeo.read_from_las(  
    las_data2009_aligned, las_data2017  
)
```

Bitemporal Change Analysis

... using the M3C2 algorithm (Lague et al., 2013)

Parameters:

- Normal radius (can be multiscale)
- Cylinder radius („projection scale“ $d/2$)
- Max. search depth
- Registration error (for consideration of distance uncertainty)

Obtained variables:

- Distance
- Normal vector (direction)
- Num. samples n
- Spread σ
- Level of detection

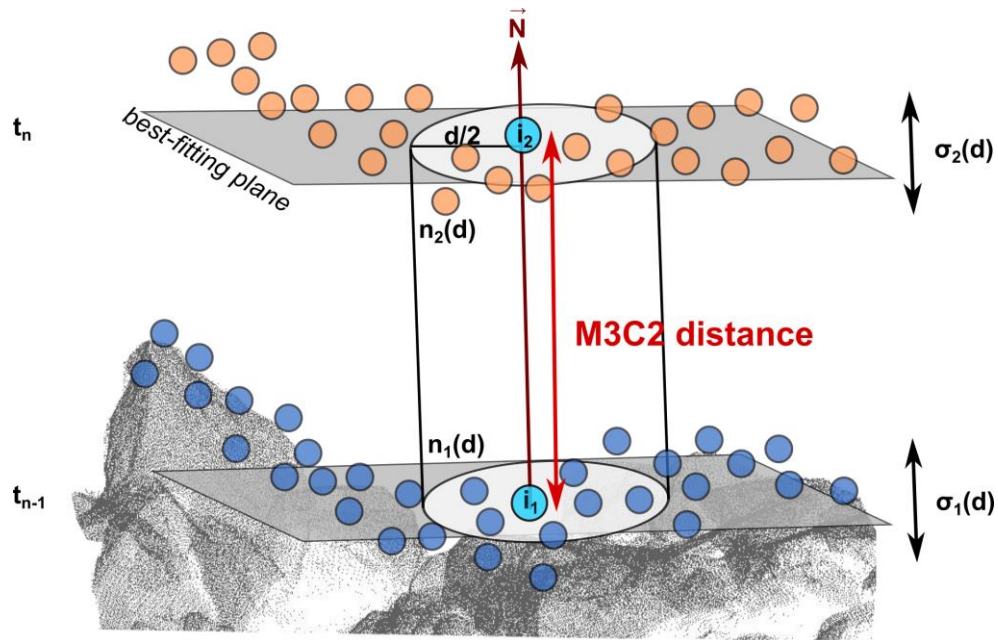


Figure by V. Zahs modified from Zahs et al. (2022)

Bitemporal Change Analysis

... using the M3C2 algorithm (Lague et al., 2013)

- Executed on **core points**
- Parameters are passed on instantiation of the algorithm
- Running the algorithm returns
 - **Distances**
 - **Uncertainty** data → structured array with
 - lodetection
 - num_samples[1/2]
 - spread [1/2]

```
# define a set of corepoints  
corepoints = epoch_2009.cloud[::]
```

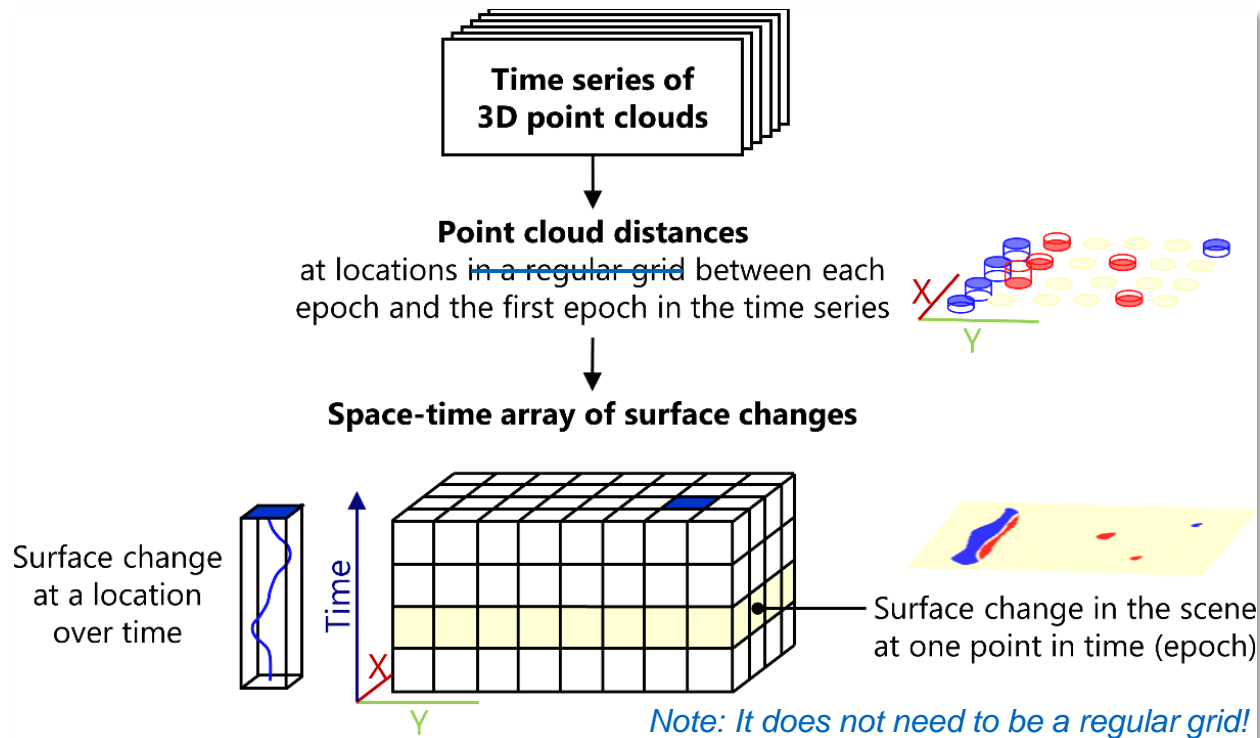
```
m3c2 = py4dgeo.M3C2(  
    epochs=(epoch_2009, epoch_2017),  
    corepoints=corepoints,  
    normal_radii=(2.0, 1.0, 8.0),  
    cyl_radii=(2.0,),  
    max_distance=(50.0),  
    registration_error=(1.31)  
)
```

```
m3c2_distances, uncertainties = m3c2.run()
```

Time Series Change Analysis in py4dgeo

class **SpatiotemporalAnalysis**

- **Data** (properties):
 - corepoints
 - reference_epoch
 - timedeltas
 - m3c2 → algorithm settings
 - **distances** (M2C2 result)
 - uncertainties (M2C2 result)
- Data is added via **add_epochs(*epochs)**



<https://py4dgeo.readthedocs.io/en/latest/pythonapi.html#py4dgeo.SpatiotemporalAnalysis>

Anders et al. (2021)

Creating a SpatiotemporalAnalysis

(1/2)

```
analysis = py4dgeo.SpatiotemporalAnalysis(f'{data_path}/kijkduin.zip', force=True)
```

```
# specify the reference epoch
```

```
reference_epoch_file = os.path.join(pc_dir, pc_list[0])
```

```
# read the reference epoch and set the timestamp
```

```
reference_epoch = py4dgeo.read_from_las(reference_epoch_file)
```

```
reference_epoch.timestamp = timestamps[0]
```

```
# set the reference epoch in the spatiotemporal analysis object
```

```
analysis.reference_epoch = reference_epoch
```

```
# Inherit from the M3C2 algorithm class to define a custom direction algorithm
```

```
class M3C2_Vertical(py4dgeo.M3C2):
```

```
    def directions(self):
```

```
        return np.array([0, 0, 1]) # vertical vector orientation
```

```
# specify corepoints, here all points of the reference epoch
```

```
analysis.corepoints = reference_epoch.cloud[:, :]
```

```
# specify M3C2 parameters for our custom algorithm class
```

```
analysis.m3c2 = M3C2_Vertical(cyl_radii=(1.0,), max_distance=10.0, registration_error = 0.019)
```

Creating a SpatiotemporalAnalysis (1/2)

ar **Hint:** Explore the

possibilities of py4dgeo with
in-notebook help

?py4dgeo.SpatiotemporalAnalysis

set the reference epoch in the spatiotemporal
analysis.reference_epoch = reference_epoch

Inherit from the M3C2 algorithm class to

```
class M3C2_Vertical(py4dgeo.M3C2):  
    def directions(self):  
        return np.array([0, 0, 1]) # vertical
```

specify corepoints, here all points of the
analysis.corepoints = reference_epoch.cloud

specify M3C2 parameters for our custom algorithm
analysis.m3c2 = M3C2_Vertical(cyl_radii=(1.

```
s(f'{data_path}/kijkduin.zip', force=True)
```

Init signature:

```
py4dgeo.SpatiotemporalAnalysis(  
    filename,  
    compress=True,  
    allow_pickle=True,  
    force=False,  
)
```

Docstring: <no docstring>

Init docstring:

Construct a spatiotemporal segmentation object

This is the basic data structure for the 4D objects by change algorithm and its derived variants. It manages storage of M3C2 distances and other intermediate results for a time series of epochs. The original point clouds themselves are not needed after initial distance calculation and additional epochs can be added to an existing analysis. The class uses a disk backend to store information and allows lazy loading of additional data like e.g. M3C2 uncertainty values for postprocessing.

:param filename:

The filename used for this analysis. If it does not exist on the file system, a new analysis is created. Otherwise, the data is loaded from the existent file.

Creating a SpatiotemporalAnalysis

(2/2)

```
# create a list to collect epoch objects
epochs = []
for e, pc_file in enumerate(pc_list[1:]):
    epoch_file = os.path.join(pc_dir, pc_file)
    epoch = py4dgeo.read_from_las(epoch_file)
    epoch.timestamp = timestamps[e]
    epochs.append(epoch)

# add epoch objects to the spatiotemporal analysis object
analysis.add_epochs(*epochs)

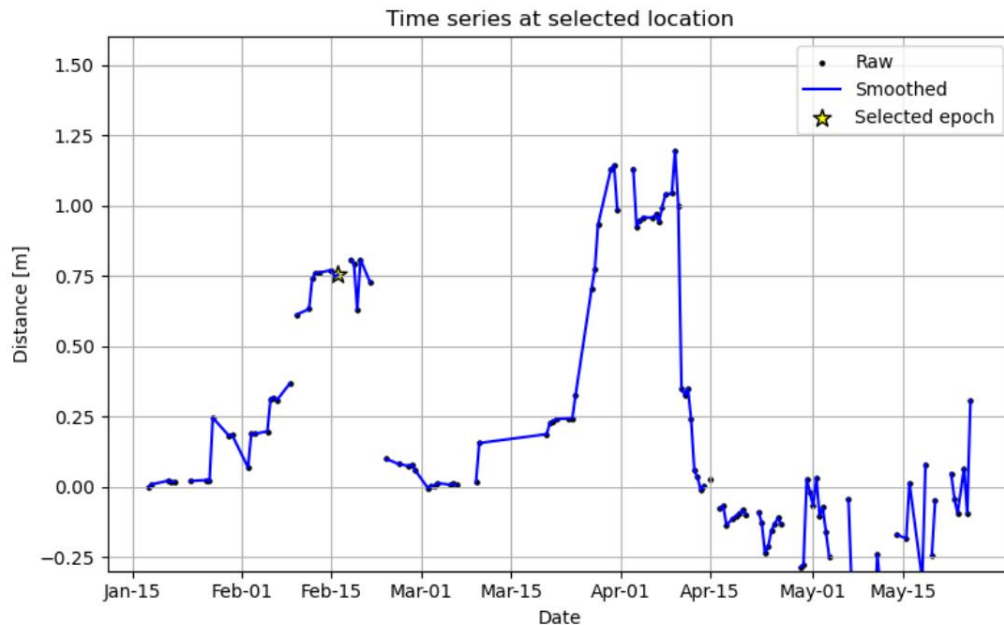
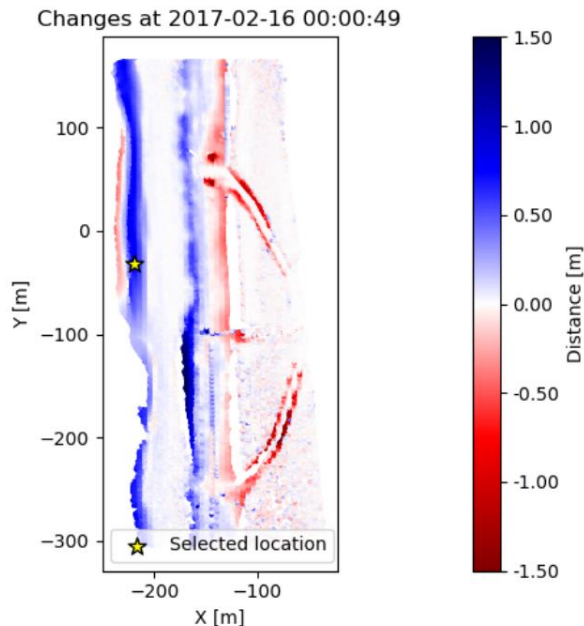
# print the spatiotemporal analysis data for 3 corepoints and 5 epochs, respectively
print(f"Space-time distance array:\n{analysis.distances[:3,:5]}")
print(f"Uncertainties of M3C2 distance calculation:\n{analysis.uncertainties['lodetection'][:3, :5]}")
print(f"Timestamp deltas of analysis:\n{analysis.timedeltas[:5]}")

# get the corepoints
corepoints = analysis.corepoints.cloud

# get the list of timestamps from the reference epoch timestamp and timedeltas
timestamps = [t + analysis.reference_epoch.timestamp for t in analysis.timedeltas]
```

Making use of the SpatiotemporalAnalysis Object

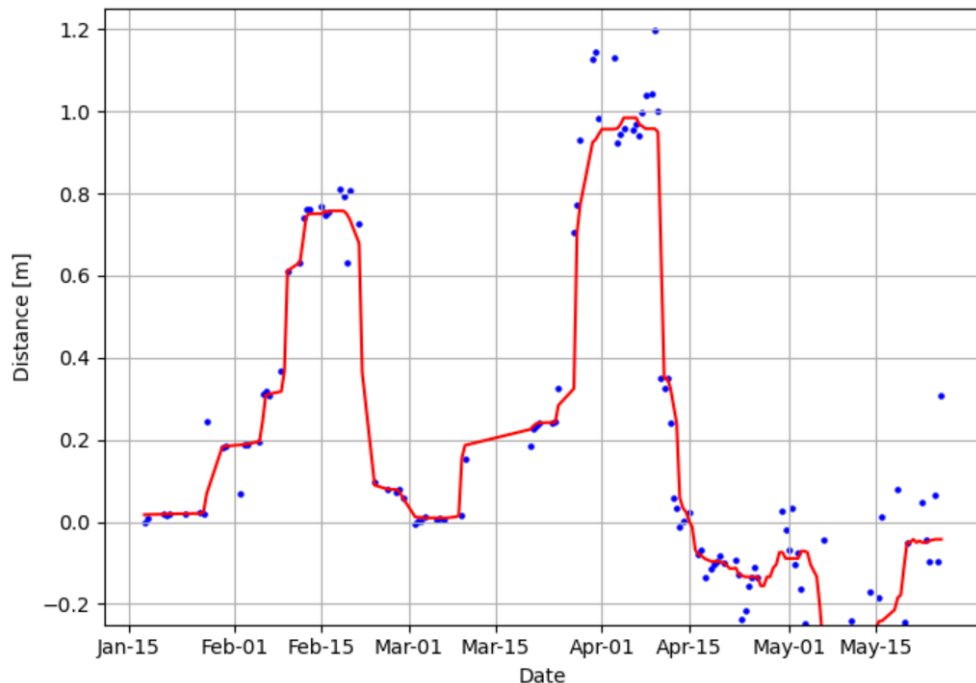
```
cp_idx_sel = 15162 # selected core point index  
epoch_idx_sel = 28 # selected epoch index
```



Temporal Smoothing

... following 4D filtering by Kromer et al. (2015)

```
analysis.smoothed_distances = py4dgeo.temporal_averaging(analysis.distances, smoothing_window=14)
```



References

- Anders, K., Winiwarter, L., Mara, H., Lindenbergh, R., Vos, S. E., & Höfle, B. (2021). Fully automatic spatiotemporal segmentation of 3D LiDAR time series for the extraction of natural surface changes. ISPRS Journal of Photogrammetry and Remote Sensing, 173, pp. 297-308. doi: [10.1016/j.isprsjprs.2021.01.015](https://doi.org/10.1016/j.isprsjprs.2021.01.015).
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- Lague, D., Brodu, N., & Leroux, J. (2013). Accurate 3D comparison of complex topography with terrestrial laser scanner: Application to the Rangitikei canyon (N-Z). ISPRS Journal of Photogrammetry and Remote Sensing, 82, pp. 10-26. doi: [10.1016/j.isprsjprs.2013.04.009](https://doi.org/10.1016/j.isprsjprs.2013.04.009).
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- Zahs, V., Winiwarter, L., Anders, K., Williams, J., G., Rutzing, M. & Höfle, B. (2022). Correspondence-driven plane-based M3C2 for lower uncertainty in 3D topographic change quantification. ISPRS Journal of Photogrammetry and Remote Sensing, 183, pp. 541 - 559. doi: [10.1016/j.isprsjprs.2021.11.018](https://doi.org/10.1016/j.isprsjprs.2021.11.018).