

VGC Short Course '4D change analysis of near-continuous LiDAR time series for applications in geomorphic monitoring'

Getting started with 4D change analysis in py4dgeo

See the full workflow in https://github.com/tum-rsa/vgc2023-shortcourse-4d/blob/main/course/practical/vgc2023_time_series_change_analysis.html

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20 September 2023

The case for **py4dgeo**

4D → massive multitemporal point cloud data

- Automating change analysis
- Bundling state-of-the-art methods

Open-source Python library for change analysis in 4D point cloud data: <https://github.com/3dgeo-heidelberg/py4dgeo>

... providing 3D/4D methods:

- M3C2 (Lague et al., 2013)
- 4D objects-by-change (Anders et al., 2021)
- Correspondence-Driven Plane-Based M3C2 (Zahs et al., 2022)
- M3C2-EP (Winiwarter et al., 2021)
- ...

... and a flexible interface for analysis workflows

See the basic usage tutorials: <https://py4dgeo.readthedocs.io> and [materials in the E-TRAINEE online course](#)



py4dgeo

Open source Python library for geographic change analysis in 4D point cloud data

Creating epochs from point cloud arrays:

```
print('[%s] Creating epoch 1...' % (datetime.now().strftime('%Y-%m-%d %H:%M:%S')))
epoch1 = py4dgeo.Epoch(coords1)

print('[%s] Creating epoch 2...' % (datetime.now().strftime('%Y-%m-%d %H:%M:%S')))
epoch2 = py4dgeo.Epoch(coords2)

print('[%s] Epochs successfully created, kd-trees built' % (datetime.now().strftime('%Y-%m-%d %H:%M:%S')))

[2021-12-23 10:41:54] Creating epoch 1...
[2021-12-23 10:41:55] Creating epoch 2...
[2021-12-23 10:41:56] Epochs successfully created, kd-trees built
```

M3C2 distance calculation

Configuring and running M3C2:

```
print('[%s] Configuring M3C2...' % (datetime.now().strftime('%Y-%m-%d %H:%M:%S')))
m3c2 = py4dgeo.M3C2(epochs=[epoch1, epoch2], corepoints=corepoints, radii=
m3c2_multiscale = py4dgeo.M3C2(epochs=[epoch1, epoch2], corepoints=corepoi

print('[%s] Running M3C2...' % (datetime.now().strftime('%Y-%m-%d %H:%M:%S')))
distances, uncertainties = m3c2.run()
distances_multiscale, uncertainties_multiscale = m3c2_multiscale.run()
print('[%s] Calculation successful' % (datetime.now().strftime('%Y-%m-%d %H:%M:%S')))

[2021-12-23 10:41:56] Configuring M3C2...
[2021-12-23 10:41:56] Running M3C2...
[2021-12-23 10:41:58] Calculation successful
```

Accessing all result information, i.e. `lodetection`, `num_samples`, and `stddev` in `uncert`

```
lodetection = uncertainties['lodetection']
stddev1 = uncertainties['stddev1']
numsamples1 = uncertainties['num_samples1']
stddev2 = uncertainties['stddev2']
numsamples2 = uncertainties['num_samples2']
normals = m3c2.directions()
```

Change Analysis in py4dgeo

class Epoch

- Data: coordinates (nx3 array)
- Property: metadata (dictionary), transformation
- Methods:
 - calculate_normals()
 - transform()
 - save/load()
- Created using `py4dgeo.read_from_las()` / `py4dgeo.read_from_xyz()`

```
# import the library for M3C2 distance calculation  
import py4dgeo  
  
# Load point clouds as epoch objects  
epoch_2009, epoch_2017 = py4dgeo.read_from_las(  
    las_data2009_aligned, las_data2017  
)
```

Bitemporal Change Analysis

... using the M3C2 algorithm (Lague et al., 2013)

Parameters:

- Normal radius (can be multiscale)
- Cylinder radius („projection scale“ $d/2$)
- Max. search depth
- Registration error (for consideration of distance uncertainty)

Obtained variables:

- Distance
- Normal vector (direction)
- Num. samples n
- Spread σ
- Level of detection

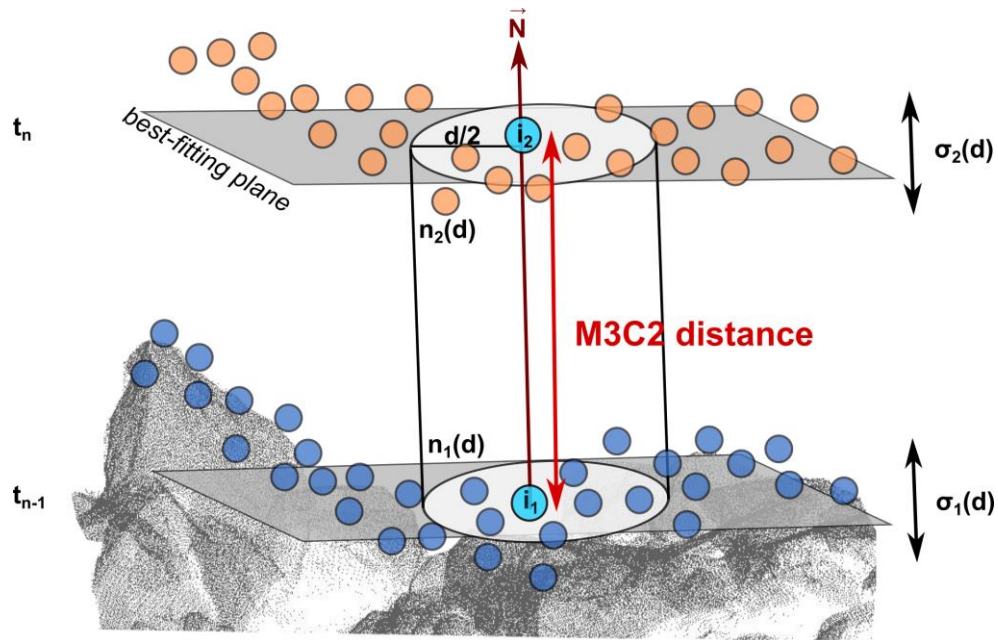


Figure by V. Zahs modified from Zahs et al. (2022)

Bitemporal Change Analysis

... using the M3C2 algorithm (Lague et al., 2013)

- Executed on **core points**
- Parameters are passed on instantiation of the algorithm
- Running the algorithm returns
 - **Distances**
 - **Uncertainty** data → structured array with
 - lodetection
 - num_samples[1/2]
 - spread [1/2]

```
# define a set of corepoints  
corepoints = epoch_2009.cloud[::]
```

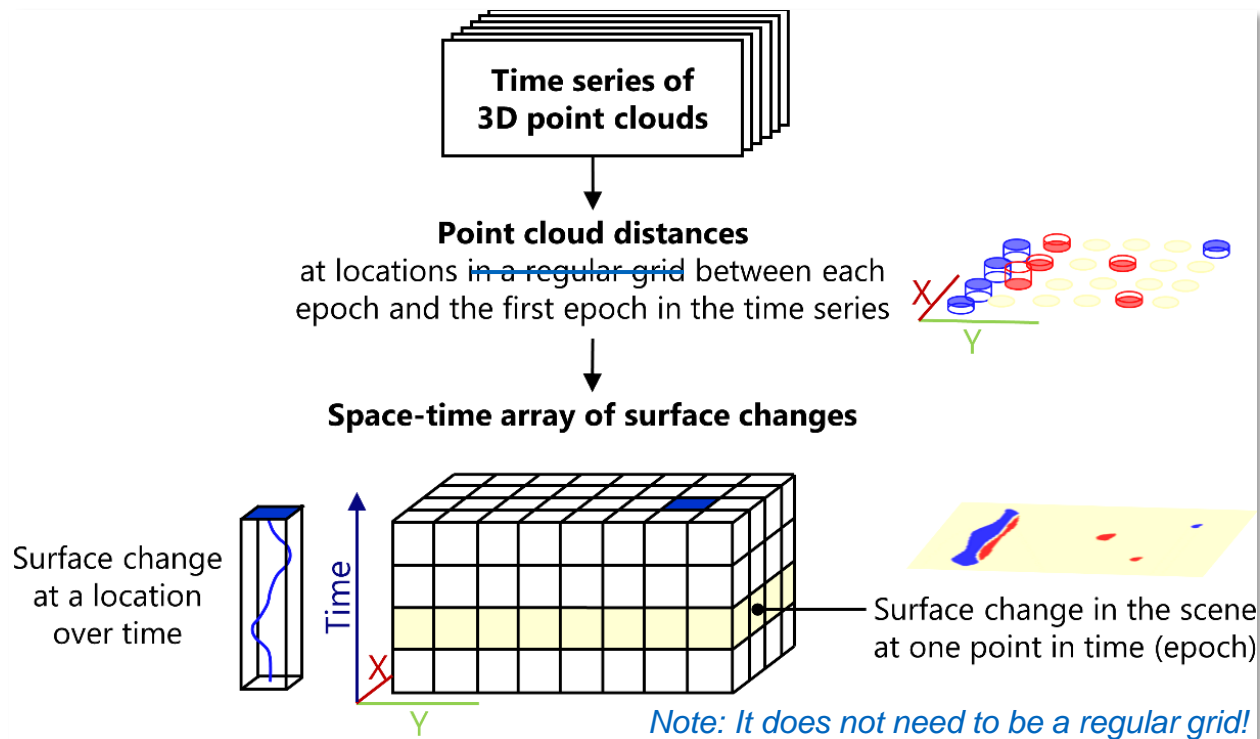
```
m3c2 = py4dgeo.M3C2(  
    epochs=(epoch_2009, epoch_2017),  
    corepoints=corepoints,  
    normal_radii=(2.0, 1.0, 8.0),  
    cyl_radii=(2.0,),  
    max_distance=(50.0),  
    registration_error=(1.31)  
)
```

```
m3c2_distances, uncertainties = m3c2.run()
```

Time Series Change Analysis in py4dgeo

class **SpatiotemporalAnalysis**

- **Data** (properties):
 - corepoints
 - reference_epoch
 - timedeltas
 - m3c2 → algorithm settings
 - **distances** (M2C2 result)
 - uncertainties (M2C2 result)
- Data is added via **add_epochs(*epochs)**



<https://py4dgeo.readthedocs.io/en/latest/pythonapi.html#py4dgeo.SpatiotemporalAnalysis>

Anders et al. (2021)

Creating a SpatiotemporalAnalysis

(1/2)

```
analysis = py4dgeo.SpatiotemporalAnalysis(f'{data_path}/kijkduin.zip', force=True)
```

```
# specify the reference epoch
```

```
reference_epoch_file = os.path.join(pc_dir, pc_list[0])
```

```
# read the reference epoch and set the timestamp
```

```
reference_epoch = py4dgeo.read_from_las(reference_epoch_file)
```

```
reference_epoch.timestamp = timestamps[0]
```

```
# set the reference epoch in the spatiotemporal analysis object
```

```
analysis.reference_epoch = reference_epoch
```

```
# Inherit from the M3C2 algorithm class to define a custom direction algorithm
```

```
class M3C2_Vertical(py4dgeo.M3C2):
```

```
    def directions(self):
```

```
        return np.array([0, 0, 1]) # vertical vector orientation
```

```
# specify corepoints, here all points of the reference epoch
```

```
analysis.corepoints = reference_epoch.cloud[:, :]
```

```
# specify M3C2 parameters for our custom algorithm class
```

```
analysis.m3c2 = M3C2_Vertical(cyl_radii=(1.0,), max_distance=10.0, registration_error = 0.019)
```

Creating a SpatiotemporalAnalysis

(2/2)

```
# create a list to collect epoch objects
epochs = []
for e, pc_file in enumerate(pc_list[1:]):
    epoch_file = os.path.join(pc_dir, pc_file)
    epoch = py4dgeo.read_from_las(epoch_file)
    epoch.timestamp = timestamps[e]
    epochs.append(epoch)

# add epoch objects to the spatiotemporal analysis object
analysis.add_epochs(*epochs)

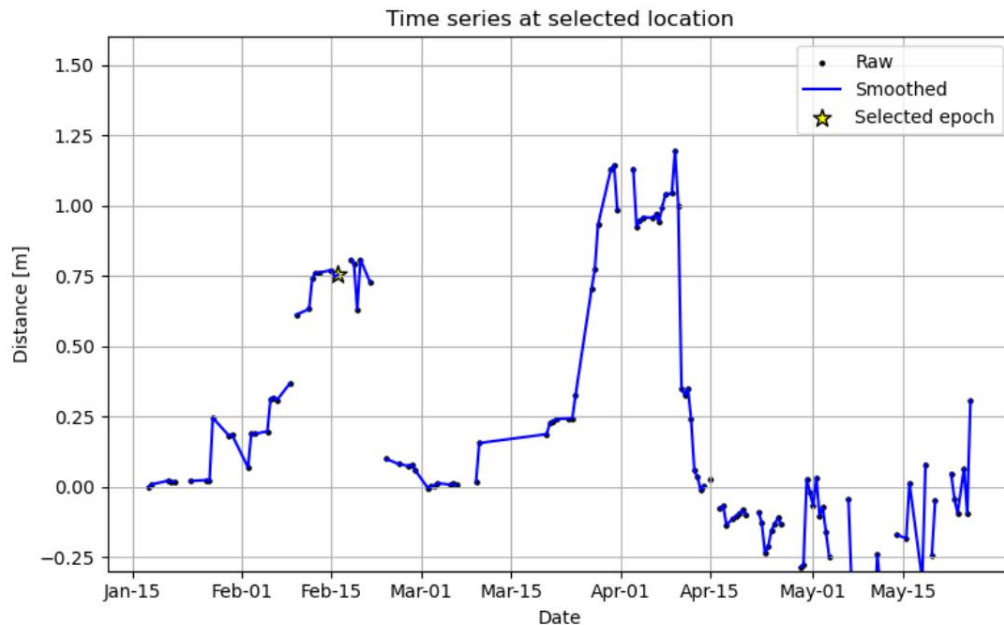
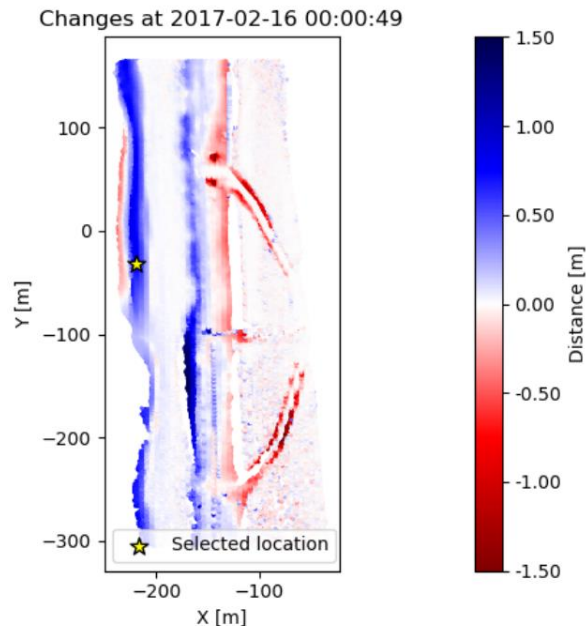
# print the spatiotemporal analysis data for 3 corepoints and 5 epochs, respectively
print(f"Space-time distance array:\n{analysis.distances[:3,:5]}")
print(f"Uncertainties of M3C2 distance calculation:\n{analysis.uncertainties['lodetection'][:3, :5]}")
print(f"Timestamp deltas of analysis:\n{analysis.timedeltas[:5]}")

# get the corepoints
corepoints = analysis.corepoints.cloud

# get the list of timestamps from the reference epoch timestamp and timedeltas
timestamps = [t + analysis.reference_epoch.timestamp for t in analysis.timedeltas]
```


Making use of the SpatiotemporalAnalysis Object

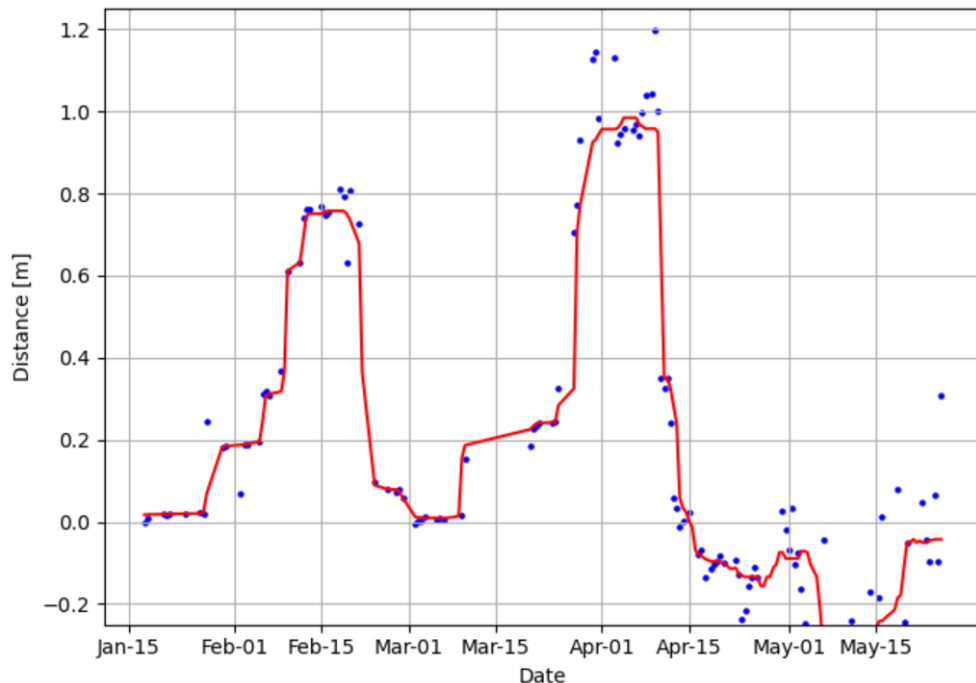
```
cp_idx_sel = 15162 # selected core point index  
epoch_idx_sel = 28 # selected epoch index
```



Temporal Smoothing

... following 4D filtering by Kromer et al. (2015)

```
analysis.smoothed_distances = py4dgeo.temporal_averaging(analysis.distances, smoothing_window=14)
```



References

- Anders, K., Winiwarter, L., Mara, H., Lindenbergh, R., Vos, S. E., & Höfle, B. (2021). Fully automatic spatiotemporal segmentation of 3D LiDAR time series for the extraction of natural surface changes. ISPRS Journal of Photogrammetry and Remote Sensing, 173, pp. 297-308. doi: [10.1016/j.isprsjprs.2021.01.015](https://doi.org/10.1016/j.isprsjprs.2021.01.015).
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- Lague, D., Brodu, N., & Leroux, J. (2013). Accurate 3D comparison of complex topography with terrestrial laser scanner: Application to the Rangitikei canyon (N-Z). ISPRS Journal of Photogrammetry and Remote Sensing, 82, pp. 10-26. doi: [10.1016/j.isprsjprs.2013.04.009](https://doi.org/10.1016/j.isprsjprs.2013.04.009).
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- Zahs, V., Winiwarter, L., Anders, K., Williams, J., G., Rutzing, M. & Höfle, B. (2022). Correspondence-driven plane-based M3C2 for lower uncertainty in 3D topographic change quantification. ISPRS Journal of Photogrammetry and Remote Sensing, 183, pp. 541 - 559. doi: [10.1016/j.isprsjprs.2021.11.018](https://doi.org/10.1016/j.isprsjprs.2021.11.018).