Topics in Macro 2

Week 10 - Second Part - Part III - Exercise III

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TSE

Tuesday (17:00-18:30)



TD Second Part: Fiscal Multipliers (Weeks 6 to 10)

Part I

- Exercise I: Habit Persistence and The Keynesian Multiplier (Week 6)
- Exercise II: A Benchmark Model (Week 7)
- Exercise III: Consumption, Labor Supply and the Multiplier (Week 7)

Part II

- Exercise I: Taxes on the Labor Input and the Multiplier (Week 8)
- Exercise II: Public Spending in Utility Function and the Multiplier (Week 8)
- Exercise III: Labor Supply, Public Spending in Utility and the Multiplier (Week 9)

Part III

- Exercise I: Endogenous Public Spending (Week 9)
- Exercise II: Externality in Production and the Multiplier (Week 10)
- Exercise III: Externality in Labor Supply and the Multiplier (Week 10)



Exercise III: Externality in Labor Supply and the Multiplier

The Economy

Utility:

$$log(c_t) - rac{\eta}{1+
u} \left(rac{n_t}{ar{n}_t^ heta}
ight)^{1+
u}$$

Budget constraint:

$$c_t \leq w_t n_t - T_t + \Pi_t$$

Technology:

$$y_t = an_t$$

Profits:

$$\Pi = y_t - w_t n_t$$

Government:

$$T_t = g_t$$

Market clearing:

$$y_t = c_t + g_t$$

Question 1. Determine the optimality condition of the households and then deduce the Marginal Rate of Substitution (MRS)

$$\mathcal{L}(C, N, \lambda) = \log(C_t) - \frac{N}{1+V} \left(\frac{N_t}{n_t^{\theta}}\right)^{1+V} - \lambda_t \left[C_t - W_t N_t - T_t + T_t\right]$$

From
$$C_t$$
: $\frac{1}{C_t} = \lambda_t$

$$N_t : \mathcal{N}\left(\frac{n_t}{\tilde{n}_t^{\theta}}\right)^{\sqrt{\frac{1}{\tilde{n}_t^{\theta}}}} = \lambda_t W_t$$

Answer: $\eta c_t n_t^{\nu} \bar{n}_t^{-\theta(1+\nu)} = w_t$.

Question 2. Determine the optimality condition of the firm.

Question 3. Determine the equilibrium output.

Definition of equilibrium:

$$4. \overline{N}_{t} = N_{t}$$

$$5. Y_{t} = C_{t} + 9_{t}$$

Question 3.

From (1)
$$k(a)$$
: $\gamma \subset_{t} \cap_{t} \cap_{t} = \alpha$

From (3), (4) $k(5)$ $\gamma \subseteq_{t} \cap_{t} \cap_{t} = \alpha$

From $\gamma \in_{t} \cap_{t} \cap_{t} \cap_{t} = \alpha$

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From $\gamma \in_{t} \cap_{t} \cap_$

Answer: $\eta[y_t - g_t] \left(\frac{y_t}{a}\right)^{\nu - \theta(1+\nu)} = a$.

Question 4. Compute the log-linearization of equilibrium output around the deterministic steady-state (we assume that steady-state exists and is unique).

Step 2. Taylor approximation

By Steady State:

$$\frac{1}{\bar{y} - \bar{g}} \left[y_{\xi} - \bar{y} \right] - \frac{1}{\bar{g} - \bar{g}} \left[g_{\xi} - \bar{g} \right] + \left[\sqrt{-\theta(1+\gamma)} \right] \frac{1}{\bar{y} - \bar{g}} \left[y_{\xi} - \bar{y} \right] = 0$$

Step 3. Deviations from the steady state
$$\frac{\bar{y}}{\bar{y}}\frac{1}{\bar{y}-\bar{g}}\left(y_{t}-\bar{y}\right) - \frac{\bar{g}}{\bar{g}}\frac{1}{\bar{g}-\bar{g}}\left(y_{t}-\bar{g}\right) + \left(\sqrt{-\theta(1+\gamma)}\right) - \frac{1}{\bar{y}}\left(y_{t}-\bar{y}\right) = 0$$

$$\frac{1}{1-sg}\hat{y}_{t} - \frac{sg}{1-sg}\hat{g}_{t} + \left(\sqrt{-\theta(1+\gamma)}\right)\hat{y}_{t} = 0$$

$$\frac{1}{1-sg} + \left(\sqrt{-\theta(1+\gamma)}\right)\hat{y}_{t} = \frac{sg}{1-sg}\hat{g}_{t}$$

$$\frac{1}{1-sg} + \left(\sqrt{-\theta(1+\gamma)}\right)\hat{y}_{t} = \frac{sg}{1-sg}\hat{g}_{t}$$
Answer:
$$\frac{\hat{y}_{t}}{\hat{g}_{t}} = \frac{sg}{1+(1-sg)(\nu-\theta(1+\nu))}.$$

Question 5. Compute the output multiplier and discuss the value of this multiplier with respect to θ .

$$\frac{dy_t}{dy_t} = \frac{\hat{y}_t}{\hat{g}_t} \cdot \frac{\bar{y}}{\bar{g}} = \frac{\hat{y}_t}{\hat{g}_t} \cdot \frac{1}{\bar{y}_g} = \frac{1}{1 + (1 - S_g)(v - \theta(1 + v))}$$

If
$$\Theta \nearrow \longrightarrow \frac{dy_t}{dg_t} \nearrow$$

If gt increases, Tt increases. Individuals compensate the loss of income by working more. This increases not and income yt and utility are higher.

$$\text{Answer: } \frac{dy_t}{dg_t} = \frac{\hat{y_t}}{\hat{g}_t} \, \frac{\bar{y}}{\bar{g}} = \frac{1}{1 + (1 - s_g)(\nu - \theta(1 + \nu))}.$$

Question 6. Compute the consumption multiplier and discuss the value of this multiplier with respect to θ .

Answer:
$$\frac{dc_t}{dg_t} = \frac{dy_t}{dg_t} - 1$$
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