1. Consider a univariate Gaussian distribution  $\mathcal{N}(x|\mu,\tau^{-1})$  having conjugate Gaussian-gamma prior given by (1), and a data set  $\mathbf{x} = \{x_1, \dots, x_N\}$  of i.i.d. observations. Show that the posterior distribution is also a Gaussian-gamma distribution of the same functional form as the prior, and write down expressions for the parameters of this posterior distribution. (Exercise 2.44 [Bishop, 2006])

$$p(\mu, \lambda) = \mathcal{N}(\mu | \mu_0, (\beta \lambda)^{-1}) \operatorname{Gam}(\lambda | a, b)$$
(1)

2. Analyze example 10.1.3 from [Bishop, 2006]. a) Generate data from the following model:

$$p(\mathcal{D}|\mu,\tau) = \left(\frac{\tau}{2\pi}\right)^{N/2} \exp\left\{-\frac{\tau}{2} \sum_{n=1}^{N} (x_n - \mu)^2\right\}$$

where the prior for  $\mu$  and  $\tau$  are given by conjugate priors as

$$p(\mu|\tau) = \mathcal{N}\left(\mu|\mu_0, (\lambda_0\tau)^{-1}\right)$$
$$p(\tau) = \operatorname{Gam}\left(\tau|a_0, b_0\right)$$

- b) Adjust the variational model using the data.
- 3. Suppose that p(x) is some fixed distribution and that we wish to approximate it using a Gaussian distribution  $q(x) = \mathcal{N}(x|\mu, \Sigma)$ . By writing down the form of the KL divergence  $\mathrm{KL}(p||q)$  for a Gaussian q(x) and then differentiating, show that minimization of  $\mathrm{KL}(p||q)$  with respect to  $\mu$  and  $\Sigma$  leads to the result that  $\mu$  is given by the expectation of x under p(x) and that  $\Sigma$  is given by the covariance. (Exercise 10.4, [Bishop, 2006])

## References

[Bishop, 2006] Bishop, C. M. (2006). Pattern Recognition and Machine Learning (Information Science and Statistics). Springer-Verlag, Berlin, Heidelberg.