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## Challenge 3: Robot Alerts on Movement

In this challenge, you'll create two sound alerts:

- A **short beep** when the robot **starts moving**.
- A longer beep when the robot stops moving.

```
In []: import rclpy
    from omni_robot_controller import OmniWheelControlNode # Import control nod
# Initialize ROS2 node
    rclpy.init()
    node = OmniWheelControlNode()
```

## Step-by-step Instructions:

- Use a short duration (e.g., 0.2s) for the movement start sound.
- Use a longer duration (e.g., 1.0s) for the stop sound.

```
In [ ]: # Try it here:
    # Example starter code:
    node.play_buzzer(
```