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Robot Alert - Success Sound

Create a short, high-pitched tone repeated twice to indicate **SUCCESS**.

Objective:

Write a command using node.play_buzzer(freq, on_time, off_time, repeat) to produce a sound that clearly indicates **Success**.

```
In []: import rclpy
    from omni_robot_controller import OmniWheelControlNode # Import control nod
# Initialize ROS2 node
    rclpy.init()
    node = OmniWheelControlNode()
```

Step-by-step Instructions

- 1. Decide on a **frequency** based on the tone you want (higher = sharper, lower = deeper)
- 2. Set how long the sound plays (on_time) and how long it's off between beeps (off time)
- 3. Choose how many times it should repeat (repeat)

Hint: Use a high frequency (e.g., 1000 Hz), short duration (0.2s), and repeat it twice.

```
In []: # Write your buzzer command below:
    # Example:
    node.play_buzzer(
```