

## Robot Alert – Success Sound

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Create a short, high-pitched tone repeated twice to indicate **SUCCESS**.

### Objective:

Write a command using `node.play_buzzer(freq, on_time, off_time, repeat)` to produce a sound that clearly indicates **Success**.

```
In [ ]: import rclpy
        from omni_robot_controller import OmniWheelControlNode # Import control node

        # Initialize ROS2 node
        rclpy.init()
        node = OmniWheelControlNode()
```

## Step-by-step Instructions

1. Decide on a **frequency** based on the tone you want (higher = sharper, lower = deeper)
2. Set how long the sound plays ( `on_time` ) and how long it's off between beeps ( `off_time` )
3. Choose how many times it should repeat ( `repeat` )

**Hint:** Use a high frequency (e.g., 1000 Hz), short duration (0.2s), and repeat it twice.

```
In [ ]: # Write your buzzer command below:
        # Example:

        node.play_buzzer(
```