Move it in a Triangle Challenge

For this challenge you need to program your robot to move in an equlaterial triangle of side length 50 centimeters or 0.5 meters.

Start your nodes using the code below

```python
# This part allows VScode to communicate with the robot
# This imports the required libraries and then creates a node for our robot
import sys
import os
import time

# Add parent directory to the Python path
sys.path.insert(0, os.path.abspath('..'))

import rclpy
from controllers.omni_robot_controller import OmniWheelControlNode  # Import

# Initialize ROS2 node
rclpy.init()
node = OmniWheelControlNode()
```

Insert your code below

```python
# Insert your code here
```

Remember to shut down your node

```python
node.destroy_node()
rclpy.shutdown()
```