May 2, 2025

Part of the InnovatED STEM and DroneBlocks Land, Air, and Sea Robotics Curriculum Licensed for educational use in schools only.

Redistribution, commercial use, or resale is strictly prohibited.

© 2025 InnovatED STEM & DroneBlocks. All rights reserved.

1 If/Else Logic with the Drone – Student Version

In this lesson, you'll learn how to use **if/else statements** to make the drone **think and react**! You'll write code that checks the drone's sensors and uses conditions to decide how to move.

1.1 Helpful Commands

Command	Description
get_height()	Get the current height of the drone
<pre>get_position()</pre>	Get the drone's (x, y) location
<pre>get_yaw()</pre>	Get the drone's rotation (yaw angle in degrees)
<pre>get_velocity()</pre>	Get the drone's current velocity
<pre>get_status()</pre>	Check if the drone is flying or landed
<pre>get_log()</pre>	View the history of all commands sent
<pre>detect_obstacle()</pre>	Returns True if any sensor detects something close
<pre>get_distances()</pre>	Returns all sensor values as a dictionary
<pre>get_distances()['front']</pre>	Gets distance to an object in front (in meters)
<pre>get_distances()['left']</pre>	Gets distance to the left side (in meters)
<pre>get_distances()['right']</pre>	Gets distance to the right side (in meters)
<pre>get_distances()['back']</pre>	Gets distance to the back side (in meters)

```
[]: # Setup the simulator
from crazyflie_sim import CrazyflieSimulator
drone = CrazyflieSimulator(real=False)
```

1.2 Example: React if there's an obstacle

This example checks if an obstacle is in front of the drone. If so, it moves back.

```
[]: if drone.detect_obstacle(): print("Obstacle ahead! Moving back.")
```

drone.backward(0.2, 0.2)

1.3 Exercise 1: Take off and check height

Take off and then use if to check if the height is over 0.2 meters. If it is, print High enough!

[]: # Your code here:

1.4 Exercise 2: Check left distance

Use get_distances() to check the left side. If it is more than 0.5 meters, move left 0.2 meters.

[]: # Your code here:

1.5 Exercise 3: Move to open space

Check both the left and right distances. - If left is greater, move left. - If right is greater, move right.

[]: # Your code here:

1.6 Exercise 4: Use else

Try using else to make the drone do something if the condition is false. Example: If front is blocked, turn. Else, move forward.

[]: # Your code here:

1.7 Challenge: Escape logic

Write if/else code to help the drone: - Check if it's too close on all sides - If so, print I'm trapped! - Else, move in any safe direction.

[]: # Your code here: