



LEADING UNIVERSITY

## Assignment

**Course Title :** Computer Graphics

**Course Code :** CSE-4113

**Submitted to :**

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CSE-44<sup>th</sup> Batch Section 10(E)

## Answer to the question number : 01

**Window-to-Viewport transformation :** Is the process of transforming a 2D world-coordinate objects to device coordinates. Objects inside the world or clipping window are mapped to the viewport which is the area on the screen where world coordinates are mapped to be displayed.

## Answe to the question number : 02

**Mathematical calculation of Window-to-Viewport transformation :** It may be possible that the size of the Viewport is much smaller or greater than the Window. In these cases, we have to increase or decrease the size of the Window according to the Viewport and for this, we need some mathematical calculations.

(X<sub>w</sub>, Y<sub>w</sub>): A point on Window

(X<sub>v</sub>, Y<sub>v</sub>): Corresponding point on Viewport

We have to calculate the point (X<sub>v</sub>, Y<sub>v</sub>)

$$\text{Normalized point on Window} \quad \left( \frac{X_w - X_{wmin}}{X_{wmax} - X_{wmin}}, \frac{Y_w - Y_{wmin}}{Y_{wmax} - Y_{wmin}} \right)$$

$$\text{Normalized point on Viewport} \quad \left( \frac{X_v - X_{vmin}}{X_{vmax} - X_{vmin}}, \frac{Y_v - Y_{vmin}}{Y_{vmax} - Y_{vmin}} \right)$$

Now the relative position of the object in Window and Viewport are same

For x coordinate,

$$\frac{X_w - X_{wmin}}{X_{wmax} - X_{wmin}} = \frac{X_v - X_{vmin}}{X_{vmax} - X_{vmin}}$$

For Y coordinate,

$$\frac{Y_w - Y_{wmin}}{Y_{wmax} - Y_{wmin}} = \frac{Y_v - Y_{vmin}}{Y_{vmax} - Y_{vmin}}$$

So, after calculating for x and y coordinate, we get

$$X_v = X_{vmin} + (X_w + X_{wmin})S_x$$

$$Y_v = Y_{vmin} + (Y_w - Y_{wmin})S_y$$

Where, s, is scaling factor of x coordinate and s, is scaling factor of y coordinate

$$S_x = \frac{X_{vmax} - X_{vmin}}{X_{wmax} - X_{wmin}} \quad S_y = \frac{Y_{vmax} - Y_{vmin}}{Y_{wmax} - Y_{wmin}}$$

### Answer to the question number : 03

**Short note on Cohen Sutherland line clipping algorithm :** In the algorithm, first of all, it is detected whether line lies inside the screen or it is outside the screen. All lines come under any one of the following categories:

1. Visible
2. Not Visible
3. Clipping Case

### Answeet to the question number : 04

**Advantages of Cohen Sutherland Line Clipping Algorithm :**

1. It calculates end-points very quickly and rejects and accepts lines quickly.
2. It can clip pictures much large than screen size.

### Answeet to the question number : 05

**Step by step algorithm of Cohen Sutherland algorithm :**

**Step1:** Calculate positions of both endpoints of the line

**Step2:** Perform OR operation on both of these end-points

**Step3:** If the OR operation gives 0000

Then

line is considered to be visible

else

Perform AND operation on both endpoints

If And  $\neq$  0000

then the line is invisible

else

And=0000

Line is considered the clipped case.

**Step4:** If a line is clipped case, find an intersection with boundaries of the window

$$m = (y_2 - y_1)/(x_2 - x_1)$$

where  $X = X_{wmin}$

where  $X_{wmin}$  is the minimum value of X co-ordinate of window

(a) If bit 1 is "1" line intersects with left boundary of rectangle window

$$y_3 = y_1 + m(x - X_1)$$

where  $X = X_{wmax}$

where  $X_{wmax}$  is maximum value of X co-ordinate of the window

(b) If bit 2 is "1" line intersect with right boundary

$$y_3 = y_1 + m(X - X_1)$$

where  $X = X_{wmin}$

where  $X_{wmin}$  is minimum value of X co-ordinate of the window

(c) If bit 3 is "1" line intersects with bottom boundary

$$X3=X1+(y-y1)/m$$

where  $y = yw_{min}$

$yw_{min}$  is the minimum value of Y co-ordinate of the window

(d) If bit 4 is "1" line intersects with the top boundary

$$X3=X1+(y-y1)/m$$

where  $y = yw_{max}$

$yw_{max}$  is the maximum value of Y co-ordinate of the window

### **Answeet to the question number : 06**

#### **Describing Liang-Barsky line clipping algorithm :**

The Liang-Barsky algorithm is a line clipping algorithm. This algorithm is more efficient than Cohen-Sutherland line clipping algorithm and can be extended to 3-Dimensional clipping. This algorithm is considered to be the faster parametric line-clipping algorithm. The following concepts are used in this clipping:

1. The parametric equation of the line.
2. The inequalities describing the range of the clipping window which is used to determine the intersections between the line and the clip window.

### **Answeet to the question number : 07**

#### **Step by step algorithm of Liang Barsky algorithm :**

1. Set  $t_{min}=0$ ,  $t_{max}=1$ .

2. Calculate the values of t ( $t(\text{left})$ ,  $t(\text{right})$ ,  $t(\text{top})$ ,  $t(\text{bottom})$ ),

(i) If  $t < t_{min}$  ignore that and move to the next edge.

(ii) else separate the t values as entering or exiting values using the inner product.

(iii) If t is entering value, set  $t_{min} = t$ ; if t is existing value, set  $t_{max} = t$ .

3. If  $t_{min} < t_{max}$ , draw a line from  $(x_1 + t_{min}(x_2-x_1), y_1 + t_{min}(y_2-y_1))$  to  $(x_1 + t_{max}(x_2-x_1), y_1 + t_{max}(y_2-y_1))$

4. If the line crosses over the window,  $(x_1 + t_{min}(x_2-x_1), y_1 + t_{min}(y_2-y_1))$  and  $(x_1 + t_{max}(x_2-x_1), y_1 + t_{max}(y_2-y_1))$  are the intersection point of line and edge.

# Computer Graphics

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Answer to the question no - 8

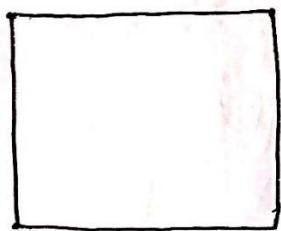
i) I(-4, 7), J(-2, 10)

$$x_{\min} = -3$$

$$y_{\min} = 1$$

$$x_{\max} = 2$$

$$y_{\max} = 6$$



R(2, 6)

L(-3, 1)

Bit 1 : Sign  $(y - y_{\max})$

Bit 2 : Sign  $(y_{\min} - y)$

Bit 3 : Sign  $(x - x_{\max})$

Bit 4 : Sign  $(x_{\min} - x)$

P-2

I(-4, 7)

$$\text{Bit 1: } 7 - 6 = 1 \rightarrow 1$$

$$\text{Bit 2: } 1 - 7 = -6 \rightarrow 0$$

$$\text{Bit 3: } -4 - 2 = -6 \rightarrow 0$$

$$\text{Bit 4: } -3 + 4 = 1 \rightarrow 1$$

$$\therefore I \rightarrow 1001$$

J(-2, 10)

$$\text{Bit 1: } 10 - 6 = 4 \rightarrow 1$$

$$\text{Bit 2: } 1 - 10 = -9 \rightarrow 0$$

$$\text{Bit 3: } -2 - 2 = -4 \rightarrow 0$$

$$\text{Bit 4: } -3 + 2 = -1 \rightarrow 0$$

$$\therefore J \rightarrow 1000$$

Now,

$$I \rightarrow 1001$$

$$J \rightarrow 1000$$

$$\begin{array}{r} 1001 \\ 1000 \\ \hline 1000 \end{array} \xrightarrow{\text{Outside}} \text{Outside}$$

iii) A(-4, 2), B(-1, 7) (F, A) I

Now,  $A = d - F \Rightarrow d = A + F$

$A(-4, 2)$

Bit 1:  $2 - 6 = -4 \rightarrow 0$

Bit 2:  $1 - 2 = -1 \rightarrow 0$

Bit 3:  $-4 - 2 = -6 \rightarrow 0$

Bit 4:  $-3 + 4 = 1 \rightarrow 1$

$\therefore A \rightarrow 0001$  (01, 5-) G

Then,  $B = d - F \Rightarrow d = B + F$

$B(-1, 7)$

Bit 1:  $7 - 6 = 1 \rightarrow 1$

Bit 2:  $1 - 7 = -6 \rightarrow 0$

Bit 3:  $-1 - 7 = -8 \rightarrow 0$

Bit 4:  $-3 + 1 = -2 \rightarrow 0$

$\therefore B \rightarrow 1000$  (00, 5+) G

Hence,

$A \rightarrow 0001$

$1001 \leftarrow I$

$0001 \leftarrow G$

$B \rightarrow 1000$

$0001$   $\rightarrow$  Maybe Clippable

P-4

For, A (-4, 2)

(3, 5) C. (2, 1) & (iii)

$$x = x_{\min}$$

$$= -3$$

$$y = y_1 + m(x_i - x_1)$$

$$= 2 + \frac{5}{3}(-3 + 4)$$

$$= 2 + \frac{5}{3} \times 1$$

$$= \frac{11}{3}$$

$$\therefore A' (-3, \frac{11}{3})$$

$$m = \frac{y_2 - y_1}{x_2 - x_1} = \frac{7 - 2}{-1 + 4} = \frac{5}{3}$$

$$y = y_1 + m(x_i - x_1)$$

$$= 2 + \frac{5}{3}(1 - 2)$$

$$= 2 + \frac{5}{3} \times -1$$

$$= 2 - \frac{5}{3} = \frac{1}{3}$$

$$\therefore B' (\frac{1}{3}, 2)$$

$$For, B (-1, 7)$$

$$y = y_{\max} = 6$$

$$x = x_1 + \frac{1}{m}(y_i - y_1)$$

$$= -4 + \frac{3}{5}(6 - 2)$$

$$= -4 + \frac{3}{5}(4)$$

$$= -\frac{8}{5}$$

$$\therefore B' \left( -\frac{8}{5}, 6 \right)$$

After 6000

iii) C (-1, 5), D (3, 8)

Now, C (-1, 5)

$$\text{Bit 1 : } 5 - 6 = -1 \rightarrow 0$$

$$\text{Bit 2 : } 1 - 5 = -4 \rightarrow 0$$

$$\text{Bit 3 : } -1 - 2 = -3 \rightarrow 0$$

$$\text{Bit 4 : } -3 - 1 = -4 \rightarrow 0$$

$\therefore C \rightarrow 0000$  it is inside the window.

D (3, 8)

$$\text{Bit 1 : } 8 - 6 = 2 \rightarrow 1$$

$$\text{Bit 2 : } 1 - 8 = -7 \rightarrow 0$$

$$\text{Bit 3 : } 3 - 2 = 1 \rightarrow 1$$

$$\text{Bit 4 : } -3 - 3 = -6 \rightarrow 0$$

$\therefore D \rightarrow 1010$

Hence,

$$C \rightarrow 0000$$

$$D \rightarrow 1010$$

$$\underline{0000}$$

$\rightarrow$  It is clipping candidate.

P-6

For, C(-1, 5)

$$x = x_{\min}$$
$$= -3$$

$$m = \frac{y_2 - y_1}{x_2 - x_1} = \frac{8 - 5}{3 + 1}$$

$$(y = y_1 + m(x_i - x_1)) \Rightarrow$$
$$= 5 + \frac{3}{4}(-3 + 1) = \frac{3}{4}$$

$$= 5 + \frac{3}{4}(-2) = \left( \min Y, \min X \right)$$

$$= \frac{14}{4} = \frac{7}{2} = \left( \max Y, \max X \right)$$

$$\therefore C' \left( -3, \frac{7}{2} \right)$$

For, D(3, 8)

$$y = y_{\max} = 6$$

$$x = x_1 + \frac{1}{m}(y_i - y_1)$$

$$= -1 + \frac{4}{3}(6 - 5)$$

$$= -1 + \frac{4}{3}(1)$$

$$= \frac{1}{3}$$

$$\therefore D' \left( \frac{1}{3}, 6 \right)$$

Answer to the question no - 9

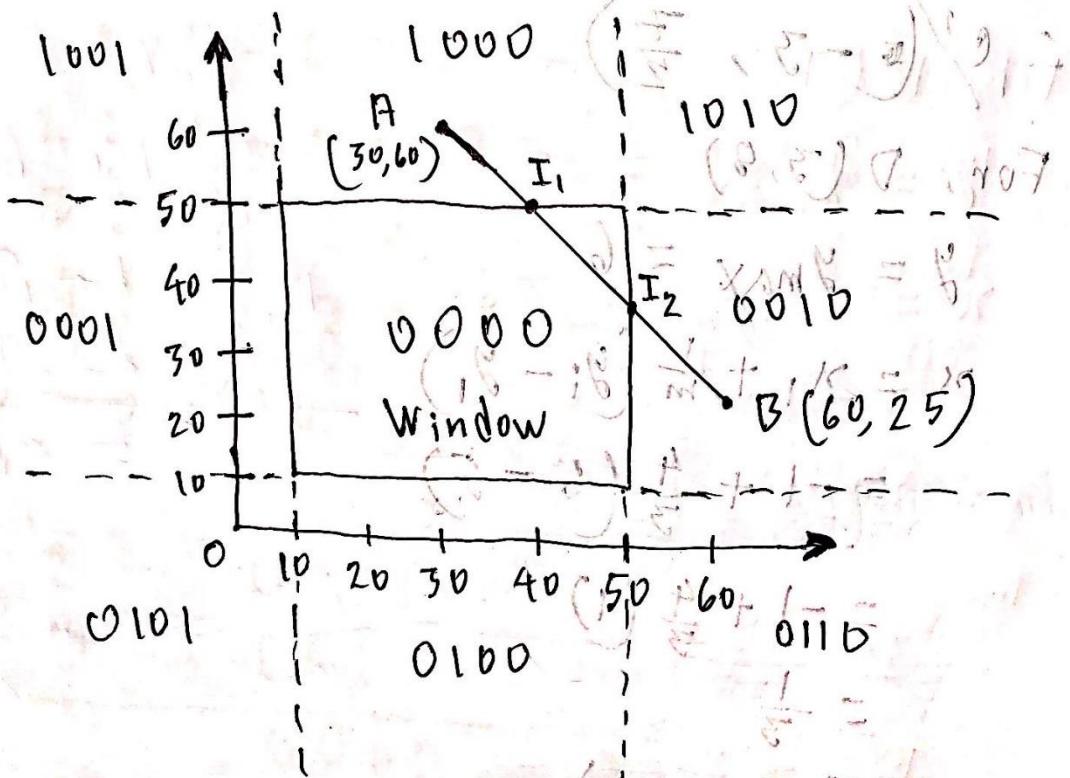
Let, line AB:

$$A(30, 60) \text{ and } B(60, 25)$$

and Window:

$$(x_{wmin}, y_{wmin}) = (x_L, y_B) = (10, 10)$$

$$(x_{wmax}, y_{wmax}) = (x_R, y_T) = (50, 50)$$



Now, clipping with respect to window

$$A \rightarrow 1000$$

$$B \rightarrow 0100$$

$$\text{AND} = 0000$$

Line is clipping candidate

$$\text{slope } m = \frac{y_2 - y_1}{x_2 - x_1}$$

$$= \frac{25 - 60}{60 - 30}$$

$$\frac{7}{6}$$

$$Y_T, x = x_1 + \frac{1}{m}(y_T - y_1)$$

$$= 30 + \left(-\frac{6}{7}\right)(50 - 60)$$

$$= 30 - \frac{6}{7}(-10)$$

$$= \frac{270}{7} = 38.57$$

$$\therefore I_1 = (38.57, 50) \text{ Ans}$$

$$x_R, y = y_1 + m(x_R - x_1)$$

$$= 60 + \left(-\frac{7}{6}\right)(50 - 30)$$

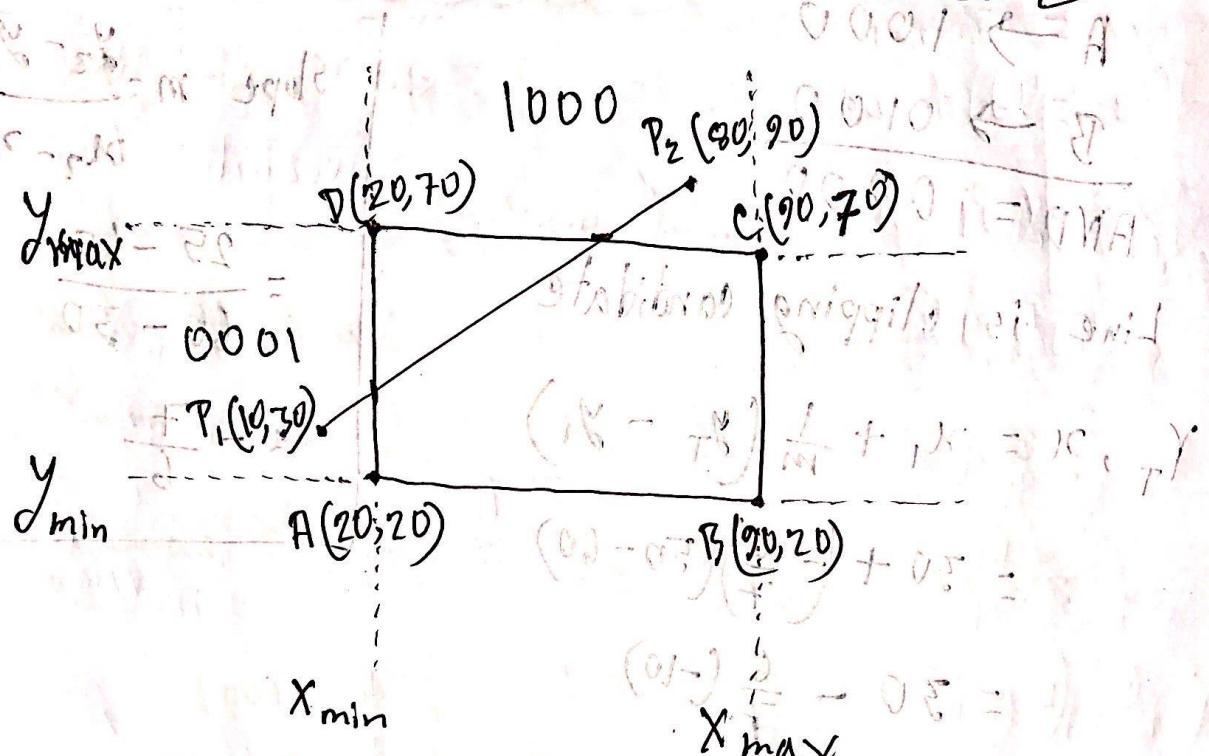
$$= 60 - \frac{7}{6}(20)$$

$$= \frac{220}{6} = 36.66$$

$$\therefore I_2 = (50, 36.66) \text{ Ans}$$

P-9

## Answer to the question no - 10



Region codes:

$$P_1 \rightarrow 0001$$

$$P_2 \rightarrow 1000$$

$$\text{AND} = 0000$$

Line is clipping candidate.

$$\text{slope, } m = \frac{y_2 - y_1}{x_2 - x_1} = \frac{90 - 30}{80 - 10} = \frac{60}{70} = \frac{6}{7}$$

For,

$$P_1(10, 30)$$

(Ex. 4)  $x = x_{\min}$

(a)  $y = 70$  (min. value)

$$y = y_1 + m(x - x_1)$$

$$= 30 + \frac{6}{7}(20 - 10)$$

$$= 30 + \frac{6}{7}(10)$$

$$= \frac{270}{7} = 38.57$$

~~$P'_1(20, 38.57)$~~

~~For,  $P_2(80, 70)$~~

$$y = y_{\max} = 70$$

$$x = x_1 + \frac{1}{m}(y_1 - y_1)$$

$$= 10 + \frac{7}{6}(70 - 30)$$

$$= 10 + \frac{7}{6}(40) = \frac{340}{6} = 56.67$$

$$\therefore P'_2(56.67, 70)$$

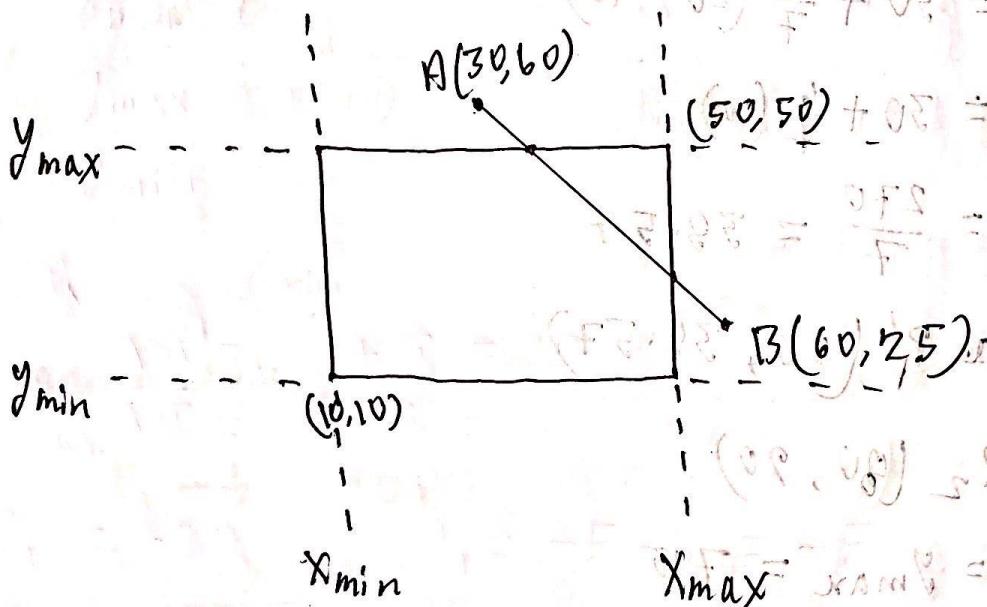
P-11

Ans no - 11

Let, Line AB : A(30, 60) and B(60, 25)

and Window :  $(x_{\min}, y_{\min}) = (10, 10) = (x_L, y_B)$

$(x_{\max}, y_{\max}) = (50, 50) = (x_R, y_T)$



Here,

$$y_{\max} = 50$$

$$y_{\min} = 10$$

$$x_{\max} = 50$$

$$x_{\min} = 10$$

Now,

$$\Delta x = 60 - 30 = 30$$

$$\Delta y = 25 - 60 = -35$$

$$P_1 = -30$$

$$q_1 = 30 - 10 = 20$$

$$P_2 = -30$$

$$q_2 = 50 - 30 = 20$$

$$P_3 = 35$$

$$q_3 = 60 - 50 = 10$$

$$P_4 = -35$$

$$q_4 = 50$$

Since,

$$P_k < 0$$

$$t_1 = \text{MAX} \left( 0, -\frac{20}{30}, -\frac{50}{35} \right)$$

$$= \text{MAX} \left( 0, -\frac{2}{3}, -\frac{5}{7} \right)$$

$$= 0$$

Therefore, A(30, 60) doesn't need to be clipped

and  $P_k > 0$

$$t_2 = \text{MIN} \left( 0, \frac{20}{30}, \frac{10}{35} \right)$$

$$= \text{MIN} \left( 0, \frac{2}{3}, \frac{2}{7} \right)$$

$$= \frac{2}{7}$$

B(60, 25) is clipping candidate.

Here,  $t_1 < t_2$  so the line is clipping candidate.

Finding  $B'$

$$x = 30 + \frac{2}{7} (30)$$

$$= 30 + \frac{60}{7} = \frac{270}{7}$$

$$= 38.57$$

$$y = 60 + \frac{2}{7} (-35)$$

$$= 60 + \left(-\frac{70}{7}\right)$$

$$= 50$$

$$\therefore B' (38.57, 50)$$

Ans:

P-13

Ans no - 12

Given,

$$P(-5, 3) \text{ and } Q(15, 9)$$

Here,

$$x_{\max} = 15 - (-5) = 20$$

$$x_{\min} = 0$$

$$y_{\max} = 10$$

$$y_{\min} = 0$$



PA

$$\Delta x = 15 + 5 = 20$$

$$\Delta y = 9 - 3 = 6$$

$$P_1 = -5 - 0 = -5$$

$$P_2 = 20$$

$$q_2 = 10 + 5 = 15$$

$$P_3 = -6$$

$$q_3 = 3 - 10 = -7$$

$$P_4 = 6$$

$$q_4 = 10$$

$$t_1 = \text{MAX} \left( 0, \frac{5}{20}, \frac{7}{6} \right)$$

$$= \text{MAX} \left( 0, \frac{1}{4}, \frac{7}{6} \right)$$

$$= \frac{7}{6}$$

$$t_2 = \text{MIN} \left( 1, \frac{15}{20}, \frac{10}{6} \right)$$

$$= \text{MIN} \left( 1, \frac{3}{4}, \frac{5}{3} \right)$$

$$= \frac{3}{4}$$

Here,

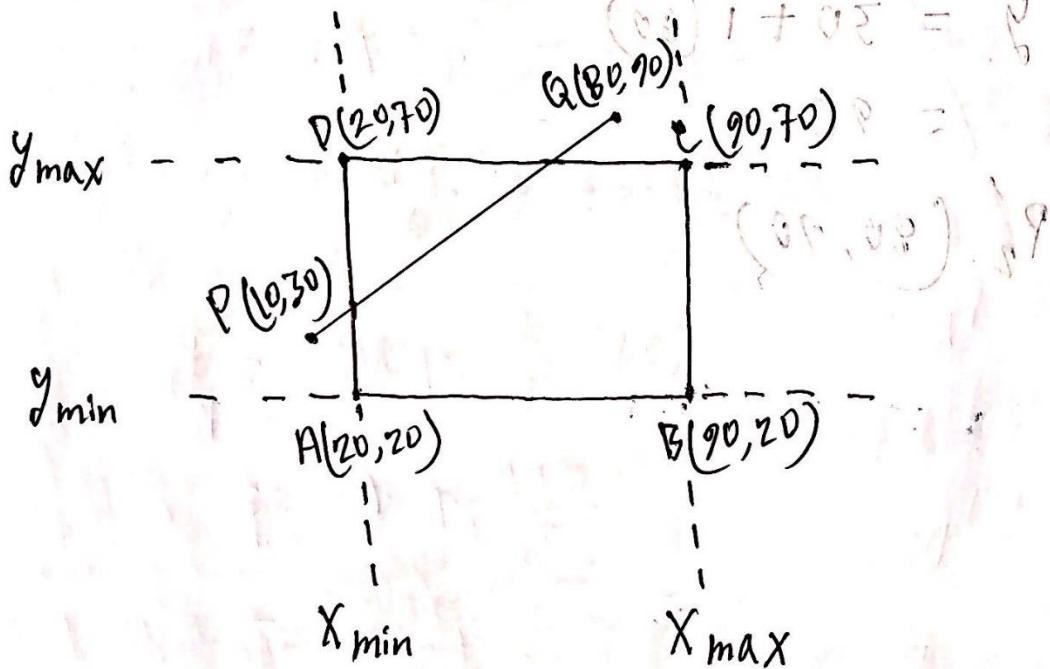
$t_1 > t_2$  so the line is outside.

it is not clipping candidate.

P-15

Ans no - 13

Given, ABCD Rectangular window with A(20, 20)  
B(90, 20), C(90, 70), D(20, 70) and line PQ with  
P(10, 30) and Q(80, 90)



Hence,

$$x_{\min} = 20$$

$$y_{\min} = 20$$

$$x_{\max} = 90$$

$$y_{\max} = 70$$

Now,

$$\Delta x = 80 - 10 = 70$$

$$\Delta y = 90 - 30 = 60$$

$$P_1 = -70 \quad q_1 = 10 - 20 = -10$$

$$P_2 = 70 \quad q_2 = 90 - 10 = 80$$

$$P_3 = -60 \quad q_3 = 30 - 70 = -40$$

$$P_4 = 60 \quad q_4 = 70$$

Since,

$$P_k < 0$$

$$t_1 = \text{MAX} \left( 0, \frac{10}{70}, \frac{40}{60} \right)$$

$$= \text{MAX} \left( 0, \frac{1}{7}, \frac{2}{3} \right)$$

$$= \frac{2}{3}$$

$$t_2 = \text{MIN} \left( 1, \frac{80}{70}, \frac{70}{60} \right)$$

$$= \text{MIN} \left( 1, \frac{8}{7}, \frac{7}{6} \right)$$

$$= 1$$

Since,  $t_1 < t_2$  line is clipping candidate

Now, Finding  $P'$

$$x = 10 + \frac{2}{3}(70)$$

$$\begin{aligned} &= 10 + \frac{140}{3} \\ &= \frac{170}{3} = 56.66 \end{aligned}$$

$$y = 30 + \frac{2}{3}(60)$$

$$\begin{aligned} &= 30 + \frac{120}{3} \\ &= \frac{210}{3} = 70 \end{aligned}$$

$$\therefore P'(56.66, 70)$$

Since,  $t_2 = 1$ , Q will not be clipped.

Ans:

## Answer to the question number : 14

**3D Transformation :** In Computer graphics, Transformation is a process of modifying and re-positioning the existing graphics.

## Answer to the question number : 15

Different techniques of 3D Transformation are the followings :

1. Translation
2. Rotation
3. Scaling
4. Reflection
5. Shear

## Answer to the question number : 16

**Translation :** In Computer graphics, 3D Translation is a process of moving an object from one position to another in a three dimensional plane.

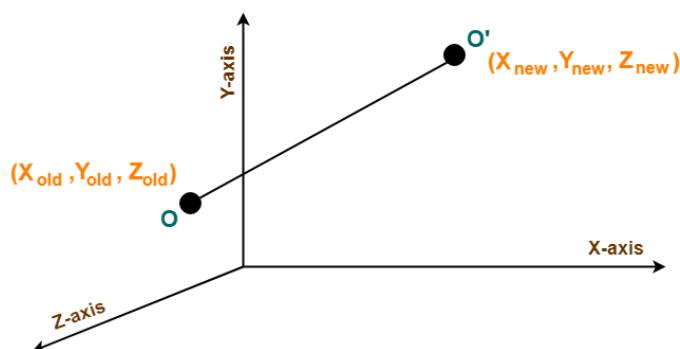
Example : Consider a point object O has to be moved from one position to another in a 3D plane.

Let-

- Initial coordinates of the object O =  $(X_{old}, Y_{old}, Z_{old})$
- New coordinates of the object O after translation =  $(X_{new}, Y_{new}, Z_{old})$
- Translation vector or Shift vector =  $(Tx, Ty, Tz)$

Given a Translation vector  $(Tx, Ty, Tz)$ -

- $Tx$  defines the distance the  $X_{old}$  coordinate has to be moved.
- $Ty$  defines the distance the  $Y_{old}$  coordinate has to be moved.
- $Tz$  defines the distance the  $Z_{old}$  coordinate has to be moved.



3D Translation in Computer Graphics

This translation is achieved by adding the translation coordinates to the old coordinates of the object as-

- $X_{\text{new}} = X_{\text{old}} + T_x$  (This denotes translation towards X axis)
- $Y_{\text{new}} = Y_{\text{old}} + T_y$  (This denotes translation towards Y axis)
- $Z_{\text{new}} = Z_{\text{old}} + T_z$  (This denotes translation towards Z axis)

In Matrix form, the above translation equations may be represented as-

$$\begin{bmatrix} X_{\text{new}} \\ Y_{\text{new}} \\ Z_{\text{new}} \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & T_x \\ 0 & 1 & 0 & T_y \\ 0 & 0 & 1 & T_z \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} X_{\text{old}} \\ Y_{\text{old}} \\ Z_{\text{old}} \\ 1 \end{bmatrix}$$

**3D Translation Matrix**

**Rotation :** In Computer graphics, 3D Rotation is a process of rotating an object with respect to an angle in a three dimensional plane.

Example : Consider a point object O has to be rotated from one angle to another in a 3D plane.

Let-

- Initial coordinates of the object O =  $(X_{\text{old}}, Y_{\text{old}}, Z_{\text{old}})$
- Initial angle of the object O with respect to origin =  $\Phi$
- Rotation angle =  $\theta$
- New coordinates of the object O after rotation =  $(X_{\text{new}}, Y_{\text{new}}, Z_{\text{new}})$

In 3 dimensions, there are 3 possible types of rotation-

- X-axis Rotation
- Y-axis Rotation
- Z-axis Rotation

#### **For X-Axis Rotation-**

This rotation is achieved by using the following rotation equations-

- $X_{\text{new}} = X_{\text{old}}$
- $Y_{\text{new}} = Y_{\text{old}} \times \cos\theta - Z_{\text{old}} \times \sin\theta$
- $Z_{\text{new}} = Y_{\text{old}} \times \sin\theta + Z_{\text{old}} \times \cos\theta$

In Matrix form, the above rotation equations may be represented as-

$$\begin{bmatrix} X_{\text{new}} \\ Y_{\text{new}} \\ Z_{\text{new}} \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos\theta & -\sin\theta & 0 \\ 0 & \sin\theta & \cos\theta & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} X_{\text{old}} \\ Y_{\text{old}} \\ Z_{\text{old}} \\ 1 \end{bmatrix}$$

**3D Rotation Matrix**  
**(For X-Axis Rotation)**

### For Y-Axis Rotation-

This rotation is achieved by using the following rotation equations-

- $X_{\text{new}} = Z_{\text{old}} \times \sin\theta + X_{\text{old}} \times \cos\theta$
- $Y_{\text{new}} = Y_{\text{old}}$
- $Z_{\text{new}} = Y_{\text{old}} \times \cos\theta - X_{\text{old}} \times \sin\theta$

In Matrix form, the above rotation equations may be represented as-

$$\begin{bmatrix} X_{\text{new}} \\ Y_{\text{new}} \\ Z_{\text{new}} \\ 1 \end{bmatrix} = \begin{bmatrix} \cos\theta & 0 & \sin\theta & 0 \\ 0 & 1 & 0 & 0 \\ -\sin\theta & 0 & \cos\theta & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} X_{\text{old}} \\ Y_{\text{old}} \\ Z_{\text{old}} \\ 1 \end{bmatrix}$$

**3D Rotation Matrix**  
**(For Y-Axis Rotation)**

### For Z-Axis Rotation-

This rotation is achieved by using the following rotation equations-

- $X_{\text{new}} = X_{\text{old}} \times \cos\theta - Y_{\text{old}} \times \sin\theta$
- $Y_{\text{new}} = X_{\text{old}} \times \sin\theta + Y_{\text{old}} \times \cos\theta$
- $Z_{\text{new}} = Z_{\text{old}}$

In Matrix form, the above rotation equations may be represented as-

$$\begin{bmatrix} X_{\text{new}} \\ Y_{\text{new}} \\ Z_{\text{new}} \\ 1 \end{bmatrix} = \begin{bmatrix} \cos\theta & -\sin\theta & 0 & 0 \\ \sin\theta & \cos\theta & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} X_{\text{old}} \\ Y_{\text{old}} \\ Z_{\text{old}} \\ 1 \end{bmatrix}$$

**3D Rotation Matrix**  
**(For Z-Axis Rotation)**

**Scaling :** In Computer graphics, scaling is a process of modifying or altering the size of objects.

- Scaling may be used to increase or reduce the size of object.
- Scaling subjects the coordinate points of the original object to change.
- Scaling factor determines whether the object size is to be increased or reduced.
- If scaling factor  $> 1$ , then the object size is increased.
- If scaling factor  $< 1$ , then the object size is reduced.

Example : Consider a point object O has to be scaled in a 3D plane.

Let-

- Initial coordinates of the object O =  $(X_{old}, Y_{old}, Z_{old})$
- Scaling factor for X-axis =  $S_x$
- Scaling factor for Y-axis =  $S_y$
- Scaling factor for Z-axis =  $S_z$
- New coordinates of the object O after scaling =  $(X_{new}, Y_{new}, Z_{new})$

This scaling is achieved by using the following scaling equations-

- $X_{new} = X_{old} \times S_x$
- $Y_{new} = Y_{old} \times S_y$
- $Z_{new} = Z_{old} \times S_z$

In Matrix form, the above scaling equations may be represented as-

$$\begin{bmatrix} X_{new} \\ Y_{new} \\ Z_{new} \\ 1 \end{bmatrix} = \begin{bmatrix} S_x & 0 & 0 & 0 \\ 0 & S_y & 0 & 0 \\ 0 & 0 & S_z & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} X_{old} \\ Y_{old} \\ Z_{old} \\ 1 \end{bmatrix}$$

**3D Scaling Matrix**

**Reflection :** In Computer graphics, It is a transformation which produces a mirror image of an object. The mirror image can be either about x-axis or y-axis. The object is rotated by  $180^\circ$ .

- Reflection is a kind of rotation where the angle of rotation is  $180$  degree.
- The reflected object is always formed on the other side of mirror.
- The size of reflected object is same as the size of original object.

Example : Consider a point object O has to be reflected in a 3D plane.

Let-

- Initial coordinates of the object O = (Xold, Yold, Zold)
- New coordinates of the reflected object O after reflection = (Xnew, Ynew, Znew)

In 3 dimensions, there are 3 possible types of reflection-

- Reflection relative to XY plane
- Reflection relative to YZ plane
- Reflection relative to XZ plane

### **Reflection Relative to XY Plane:**

This reflection is achieved by using the following reflection equations-

- Xnew = Xold
- Ynew = Yold
- Znew = -Zold

In Matrix form, the above reflection equations may be represented as-

$$\begin{bmatrix} X_{\text{new}} \\ Y_{\text{new}} \\ Z_{\text{new}} \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} X_{\text{old}} \\ Y_{\text{old}} \\ Z_{\text{old}} \\ 1 \end{bmatrix}$$

**3D Reflection Matrix**  
(Reflection Relative to XY plane)

### **Reflection Relative to YZ Plane:**

This reflection is achieved by using the following reflection equations-

- Xnew = -Xold
- Ynew = Yold
- Znew = Zold

In Matrix form, the above reflection equations may be represented as-

$$\begin{bmatrix} X_{\text{new}} \\ Y_{\text{new}} \\ Z_{\text{new}} \\ 1 \end{bmatrix} = \begin{bmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} X_{\text{old}} \\ Y_{\text{old}} \\ Z_{\text{old}} \\ 1 \end{bmatrix}$$

**3D Reflection Matrix**  
(Reflection Relative to YZ plane)

## Reflection Relative to XZ Plane:

This reflection is achieved by using the following reflection equations-

- $X_{\text{new}} = X_{\text{old}}$
- $Y_{\text{new}} = -Y_{\text{old}}$
- $Z_{\text{new}} = Z_{\text{old}}$

In Matrix form, the above reflection equations may be represented as-

$$\begin{bmatrix} X_{\text{new}} \\ Y_{\text{new}} \\ Z_{\text{new}} \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} X_{\text{old}} \\ Y_{\text{old}} \\ Z_{\text{old}} \\ 1 \end{bmatrix}$$

**3D Reflection Matrix**  
(Reflection Relative to XZ plane)

**Shearing :** In Computer graphics, 3D Shearing is an ideal technique to change the shape of an existing object in a three dimensional plane.

In a three dimensional plane, the object size can be changed along X direction, Y direction as well as Z direction.

So, there are three versions of shearing-

1. Shearing in X direction
2. Shearing in Y direction
3. Shearing in Z direction

Example : Consider a point object O has to be sheared in a 3D plane.

Let-

- Initial coordinates of the object O =  $(X_{\text{old}}, Y_{\text{old}}, Z_{\text{old}})$
- Shearing parameter towards X direction =  $Sh_x$
- Shearing parameter towards Y direction =  $Sh_y$
- Shearing parameter towards Z direction =  $Sh_z$
- New coordinates of the object O after shearing =  $(X_{\text{new}}, Y_{\text{new}}, Z_{\text{new}})$

## Shearing in X Axis-

Shearing in X axis is achieved by using the following shearing equations-

- $X_{\text{new}} = X_{\text{old}}$
- $Y_{\text{new}} = Y_{\text{old}} + Sh_y \times X_{\text{old}}$
- $Z_{\text{new}} = Z_{\text{old}} + Sh_z \times X_{\text{old}}$

In Matrix form, the above shearing equations may be represented as-

$$\begin{bmatrix} X_{\text{new}} \\ Y_{\text{new}} \\ Z_{\text{new}} \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ Sh_y & 1 & 0 & 0 \\ Sh_z & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} X_{\text{old}} \\ Y_{\text{old}} \\ Z_{\text{old}} \\ 1 \end{bmatrix}$$

**3D Shearing Matrix**

(In X axis)

### Shearing in Y Axis-

Shearing in Y axis is achieved by using the following shearing equations-

- $X_{\text{new}} = X_{\text{old}} + Sh_x \times Y_{\text{old}}$
- $Y_{\text{new}} = Y_{\text{old}}$
- $Z_{\text{new}} = Z_{\text{old}} + Sh_z \times Y_{\text{old}}$

In Matrix form, the above shearing equations may be represented as-

$$\begin{bmatrix} X_{\text{new}} \\ Y_{\text{new}} \\ Z_{\text{new}} \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & Sh_x & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & Sh_z & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} X_{\text{old}} \\ Y_{\text{old}} \\ Z_{\text{old}} \\ 1 \end{bmatrix}$$

**3D Shearing Matrix**

(In Y axis)

### Shearing in Z Axis-

Shearing in Z axis is achieved by using the following shearing equations-

- $X_{\text{new}} = X_{\text{old}} + Sh_x \times Z_{\text{old}}$
- $Y_{\text{new}} = Y_{\text{old}} + Sh_y \times Z_{\text{old}}$
- $Z_{\text{new}} = Z_{\text{old}}$

In Matrix form, the above shearing equations may be represented as-

$$\begin{bmatrix} X_{\text{new}} \\ Y_{\text{new}} \\ Z_{\text{new}} \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & Sh_x & 0 \\ 0 & 1 & Sh_y & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} X_{\text{old}} \\ Y_{\text{old}} \\ Z_{\text{old}} \\ 1 \end{bmatrix}$$

**3D Shearing Matrix**

(In Z axis)

Ans no - 17

Given,

Old coordinates of the object = A(1, 3, 5),  
B(3, 5, 3), C(3, 0, 1), D(2, 1, 5)

Translation vector =  $(T_x, T_y, T_z) = (4, 2, 5)$

For Coordinates A(1, 3, 5)

Let the new coordinates of A =  $(X_{\text{new}}, Y_{\text{new}}, Z_{\text{new}})$

Applying the translation equations, we have.

$$X_{\text{new}} = X_{\text{old}} + T_x = 1 + 4 = 5$$

$$Y_{\text{new}} = Y_{\text{old}} + T_y = 3 + 2 = 5$$

$$Z_{\text{new}} = Z_{\text{old}} + T_z = 5 + 5 = 10$$

Thus, New coordinates of A = (5, 5, 10)

Ans:

For Coordinates B (3, 5, 3)

Let the new coordinates of B =  $(X_{\text{new}}, Y_{\text{new}}, Z_{\text{new}})$

Applying the translation equations, we have -

$$X_{\text{new}} = X_{\text{old}} + T_x = 3 + 4 = 7$$

$$Y_{\text{new}} = Y_{\text{old}} + T_y = 5 + 2 = 7$$

$$Z_{\text{new}} = Z_{\text{old}} + T_z = 3 + 5 = 8$$

Thus, New coordinates of B = (7, 7, 8)

For Coordinates C (3, 0, 1)

Let the new coordinates of C =  $(X_{\text{new}}, Y_{\text{new}}, Z_{\text{new}})$

Applying the translation equations, we have -

$$X_{\text{new}} = X_{\text{old}} + T_x = 3 + 4 = 7$$

$$Y_{\text{new}} = Y_{\text{old}} + T_y = 0 + 2 = 2$$

$$Z_{\text{new}} = Z_{\text{old}} + T_z = 1 + 5 = 6$$

Thus, New coordinates of C = (7, 2, 6)

For coordinates D(2, 1, 5)

Let the new coordinates of C

$$C.S.F. = (x_{\text{new}}, y_{\text{new}}, z_{\text{new}}) = (X_{\text{new}}, Y_{\text{new}}, Z_{\text{new}})$$

Applying the translation equations, we have -

$$X_{\text{new}} = X_{\text{old}} + T_x = 2 + 4 = 6$$

$$Y_{\text{new}} = Y_{\text{old}} + T_y = 1 + 2 = 3$$

$$Z_{\text{new}} = Z_{\text{old}} + T_z = 5 + 5 = 10$$

Thus, New coordinates of D = (6, 3, 10)

Ans no - 18

Given,

Old coordinates =  $(X_{\text{old}}, Y_{\text{old}}, Z_{\text{old}}) = (3, 2, 5)$

Rotation angle =  $\theta = 45^\circ$

For  $X$ -axis rotation:

Let the new coordinates after rotation =  $(X_{\text{new}}, Y_{\text{new}}, Z_{\text{new}})$

Applying the rotation equations we have -

$$X_{\text{new}} = X_{\text{old}} = 3$$

$$Y_{\text{new}} = Y_{\text{old}} \cdot \cos \theta - Z_{\text{old}} \cdot \sin \theta = 2 \cdot \cos 45^\circ - 5 \sin 45^\circ$$

$$= 2 \times \frac{1}{\sqrt{2}} - 5 \times \frac{1}{\sqrt{2}} = -\frac{3}{\sqrt{2}}$$

$$Z_{\text{new}} = Y_{\text{old}} \cdot \sin \theta + Z_{\text{old}} \cdot \cos \theta = 2 \cdot \sin 45^\circ + 5 \cos 45^\circ$$

$$= 2 \times \frac{1}{\sqrt{2}} + 5 \times \frac{1}{\sqrt{2}} = \frac{7}{\sqrt{2}}$$

New coordinates after rotation =  $(3, -\frac{3}{\sqrt{2}}, \frac{7}{\sqrt{2}})$

For Y-Axis rotation:

Let the new coordinates after rotation =  $(X_{\text{new}}, Y_{\text{new}}, Z_{\text{new}})$

Applying the rotation equations we have -

$$X_{\text{new}} = Z_{\text{old}} \cdot \sin \theta + X_{\text{old}} \cdot \cos \theta = 5 \sin 45^\circ + 3 \cos 45^\circ$$
$$= 5 \times \frac{1}{\sqrt{2}} + 3 \times \frac{1}{\sqrt{2}} = \frac{8}{\sqrt{2}}$$

$$Y_{\text{new}} = Y_{\text{old}} = 2$$

$$Z_{\text{new}} = Y_{\text{old}} \cdot \cos \theta - X_{\text{old}} \cdot \sin \theta = 2 \cos 45^\circ - 3 \sin 45^\circ$$
$$= 2 \times \frac{1}{\sqrt{2}} - 3 \times \frac{1}{\sqrt{2}} = -\frac{1}{\sqrt{2}}$$

Thus, New coordinates after rotation =  $(\frac{8}{\sqrt{2}}, 2, -\frac{1}{\sqrt{2}})$

For Z - Axis notation:

Let the new coordinates after rotation =  $(X_{\text{new}}, Y_{\text{new}}, Z_{\text{new}})$

Applying the rotation equations, we have -

$$X_{\text{new}} = X_{\text{old}} \cdot \cos \theta - Y_{\text{old}} \cdot \sin \theta = 3 \cos 45^\circ - 2 \sin 45^\circ \\ = 3 \times \frac{1}{\sqrt{2}} - 2 \times \frac{1}{\sqrt{2}} \times \frac{1}{\sqrt{2}}$$

$$Y_{\text{new}} = X_{\text{old}} \cdot \sin \theta + Y_{\text{old}} \cdot \cos \theta = 3 \sin 45^\circ + 2 \cos 45^\circ \\ = 3 \times \frac{1}{\sqrt{2}} + 2 \times \frac{1}{\sqrt{2}} = \frac{5}{\sqrt{2}}$$

$$Z_{\text{new}} = Z_{\text{old}} = 5$$

Thus, New coordinates after rotation

$$= \left( \frac{1}{\sqrt{2}}, \frac{5}{\sqrt{2}}, 5 \right)$$

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Ans no - 19

Given,

Old coordinates of the object = A(1, 3, 5), B(3, 5, 3)

C(3, 0, 1), D(2, 1, 5)

Scaling factor along X axis = 4

" " " " Y " " = 2

" " " " Z " " = 5

For Coordinates A(1, 3, 5)

Let the new coordinates of A after scaling =  $(X_{\text{new}}, Y_{\text{new}}, Z_{\text{new}})$

Applying the scaling equations we have-

$$X_{\text{new}} = X_{\text{old}} \times S_x = 1 \times 4 = 4$$

$$Y_{\text{new}} = Y_{\text{old}} \times S_y = 3 \times 2 = 6$$

$$Z_{\text{new}} = Z_{\text{old}} \times S_z = 5 \times 5 = 25$$

The new coordinates of A = (4, 6, 25)

For Coordinates B (3, 5, 3)

Let the new coordinates of B after scaling =  $(X_{\text{new}}, Y_{\text{new}}, Z_{\text{new}})$

Applying the scaling equations we have -

$$X_{\text{new}} = X_{\text{old}} \times S_x = 3 \times 4 = 12$$

$$Y_{\text{new}} = Y_{\text{old}} \times S_y = 5 \times 2 = 10$$

$$Z_{\text{new}} = Z_{\text{old}} \times S_z = 3 \times 5 = 15$$

∴ New coordinates of B = (12, 10, 15)

For Coordinates C (3, 0, 1)

Let the new coordinates of C after scaling =  $(X_{\text{new}}, Y_{\text{new}}, Z_{\text{new}})$

Applying the scaling equations we have -

$$X_{\text{new}} = X_{\text{old}} \times S_x = 3 \times 4 = 12$$

$$Y_{\text{new}} = Y_{\text{old}} \times S_y = 0 \times 2 = 0$$

$$Z_{\text{new}} = Z_{\text{old}} \times S_z = 1 \times 5 = 5$$

∴ New coordinates of C = (12, 0, 5)

For Coordinates D (2, 1, 5)

Let the new coordinates of D after scaling  
= (X<sub>new</sub>, Y<sub>new</sub>, Z<sub>new</sub>)

Applying the scaling equations we have -

$$X_{\text{new}} = X_{\text{old}} \times S_x = 2 \times 4 = 8$$

$$Y_{\text{new}} = Y_{\text{old}} \times S_y = 1 \times 2 = 2$$

$$Z_{\text{new}} = Z_{\text{old}} \times S_z = 5 \times 5 = 25$$

∴ New coordinates of D = (8, 2, 25)

(Ans - No - 2 D)

Given,

Old corner coordinates of the triangle  
= A(3, 5, 2), B(4, 2, 7), C(5, 6, 4)

Reflection has to be taken on the XY  
and XZ plane.

For Coordinates A(3, 5, 2)

Let the new coordinates of A after reflection  
=  $(X_{\text{new}}, Y_{\text{new}}, Z_{\text{new}})$

Applying the reflection equations we have

$$X_{\text{new}} = X_{\text{old}} = 3$$

$$X_{\text{new}} = X_{\text{old}} = 3$$

$$Y_{\text{new}} = Y_{\text{old}} = 5$$

$$Y_{\text{new}} = -Y_{\text{old}} = -5$$

$$Z_{\text{new}} = -Z_{\text{old}} = -2$$

$$Z_{\text{new}} = Z_{\text{old}} = 2$$

$\therefore$  New coordinates of A on XY and XZ plane  
= (3, 5, -2) and (3, -5, 2)

For Coordinates B (4, 2, 7) about X = 0

Let the new coordinates of B after

reflection =  $(X_{\text{new}}, Y_{\text{new}}, Z_{\text{new}})$

Applying the reflection equations, we have -

$$X_{\text{new}} = X_{\text{old}} = 4 \quad X_{\text{new}} = X_{\text{old}} = 4$$

$$(Y_{\text{new}} = Y_{\text{old}} = 2) = Y_{\text{new}} = -Y_{\text{old}} = -2$$

$$Z_{\text{new}} = -Z_{\text{old}} = -7 \quad Z_{\text{new}} = Z_{\text{old}} = 7$$

∴ New coordinates of B on XY and

XZ plane =  $(4, 2, 7)$  and  $(4, -2, 7)$

For Coordinates C (5, 6, 4)

Let the new coordinates of C after reflection

=  $(X_{\text{new}}, Y_{\text{new}}, Z_{\text{new}})$

Applying the reflection equations we have

$$X_{\text{new}} = X_{\text{old}} \overset{(5, 6, 4)}{\underset{\text{reflected w.r.t. } Y}{=}} 5$$

$$Y_{\text{new}} = Y_{\text{old}} \overset{b \text{ reflected}}{\underset{Y}{=}} -6$$

$$Z_{\text{new}} = Z_{\text{old}} \overset{-4 \text{ reflected}}{\underset{X}{=}} 4$$

- Now we exchange reflecting with origin  
 ∴ New coordinates of C on XY and  
 $\rho = b/\alpha = w_N X$        $\rho = b/\alpha = w_N X$

~~$XZ - \text{plane} = (5, 6, 4)$  and  $(5, -6, 4)$~~

$$\Sigma = b/\alpha \Sigma = w_N \Sigma$$

Now XY is to reflect with

$$(5, 6, 4) \text{ and } (5, -6, 4) = \text{origin } \Sigma.$$

$(5, 6, 4) \text{ reflected w.r.t. } Y$

Now reflect Y to origin with ref.

$$(w_N \Sigma + w_N Y) = \Sigma$$

and now exchange reflecting with origin