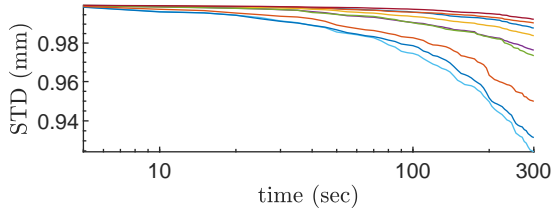


Robot Length Parameters



Robot Angle Parameters

