Phys 512 - PS 3

Fernanda C. Rodrigues Machado

ID# 260905170

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P1

We can expand the equation for the paraboloid and make a parameter substitution to get a function that is linear on its parameters:

Expand and change parameters

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In[145]:= \mathbf{Z} = \mathbf{a} \left( (\mathbf{X} - \mathbf{X}_0)^2 + (\mathbf{y} - \mathbf{y}_0)^2 \right) + \mathbf{Z}_0;

Expand [%]

Collect[Collect[%, -2 a], a]

Collect[

Expand [% /. \left\{ \mathbf{x}_0^2 + \mathbf{y}_0^2 \rightarrow (\mathbf{m}0 - \mathbf{Z}_0) / a \right\} /. \left\{ \mathbf{x}_0 \rightarrow \mathbf{m}1 / (-2 a) \right\} /. \left\{ \mathbf{y}_0 \rightarrow \mathbf{m}2 / (-2 a) \right\} /. \mathbf{a} \rightarrow \mathbf{m}3 \right], \mathbf{m}3 \right]

Out[146]= \mathbf{z} = \mathbf{a} \mathbf{x}^2 + \mathbf{a} \mathbf{y}^2 - 2 \mathbf{a} \mathbf{x} \mathbf{x}_0 + \mathbf{a} \mathbf{x}_0^2 - 2 \mathbf{a} \mathbf{y} \mathbf{y}_0 + \mathbf{a} \mathbf{y}_0^2 + \mathbf{z}_0

Out[147]= \mathbf{z} = \mathbf{a} \left( \mathbf{x}^2 + \mathbf{y}^2 + \mathbf{x}_0^2 + \mathbf{y}_0^2 - 2 (\mathbf{x} \mathbf{x}_0 + \mathbf{y} \mathbf{y}_0) \right) + \mathbf{z}_0

Out[148]= \mathbf{z} = \mathbf{m}0 + \mathbf{m}1 \mathbf{x} + \mathbf{m}2 \mathbf{y} + \mathbf{m}3 \left( \mathbf{x}^2 + \mathbf{y}^2 \right)
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The new parameters (m0, m1, m2, m3) can be written in terms of the old ones (x_0, y_0, z_0, a) as

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\begin{array}{ll} \text{In}[149] \coloneqq & \text{Solve} \left[ x_{\theta}^2 + y_{\theta}^2 = = & (\text{m0} - z_{\theta}) \; / \; a \; , \; \text{m0} \right] \\ & \text{Solve} \left[ x_{\theta} = = & \text{m1} \; / \; (-2 \; a) \; , \; \text{m1} \right] \\ & \text{Solve} \left[ y_{\theta} = = & \text{m2} \; / \; (-2 \; a) \; , \; \text{m2} \right] \\ & \text{m3} \; \rightarrow \; a \\ \\ & \text{Out}[149] = \; \left\{ \left\{ \text{m0} \; \rightarrow \; a \; x_{\theta}^2 + a \; y_{\theta}^2 + z_{\theta} \right\} \right\} \\ & \text{Out}[150] = \; \left\{ \left\{ \text{m1} \; \rightarrow \; -2 \; a \; x_{\theta} \right\} \right\} \\ & \text{Out}[151] = \; \left\{ \left\{ \text{m2} \; \rightarrow \; -2 \; a \; y_{\theta} \right\} \right\} \\ & \text{Out}[152] = \; \text{m3} \; \rightarrow \; a \\ \end{array}
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and the old ones can be recovered by substituting:

$$\begin{aligned} & \text{In}[157] \coloneqq \text{Solve} \left[\left\{ x_0^2 + y_0^2 == \left(m0 - z_0 \right) / a, \ x_0 == m1 / \left(-2 \, a \right), \ y_0 == m2 / \left(-2 \, a \right) \right\}, \\ & \left\{ x_0, \ y_0, \ z_0 \right\} \right] \\ & \text{Out}[157] = \left\{ \left\{ x_0 \to -\frac{m1}{2 \, a}, \ y_0 \to -\frac{m2}{2 \, a}, \ z_0 \to -\frac{-4 \, a \, m0 + m1^2 + m2^2}{4 \, a} \right\} \right\} \end{aligned}$$

Carrying out the fit, my best-fit new parameters are:

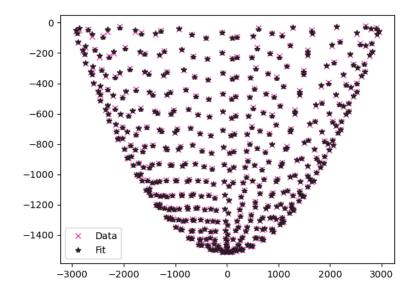
$$m0 = -1512.31182$$

 $m1 = 4.53599028 \times 10^{-4}$
 $m2 = -1.94115589 \times 10^{-2}$
 $m3 = 1.66704455 \times 10^{-4}$.

The old parameters are then given by:

 $x_0 = -1.3604886221970875$ $y_0 = 58.22147608157978$ $z_0 = -1512.8772100367878$ a = 0.00016670445477401347.

Plotting the fit and the real data, I get:



with an RMS error between fit and data equal to 3.7683386487847277.

The covariance matrix $N = (A^T N^{-1} A)^{-1}$ gives the correlated noise $\langle n_i n_j \rangle$. Since we have a = m3, the uncertainty in a is given by $n_3 = \sqrt{\langle n_3 n_3 \rangle}$, where $\langle n_3 n_3 \rangle$ is just the last input of the matrix N. In this way, I get the uncertainty $\delta a = 1.712133743432042 \times 10^{-8}$.

The focal length in the paraboloid is given by

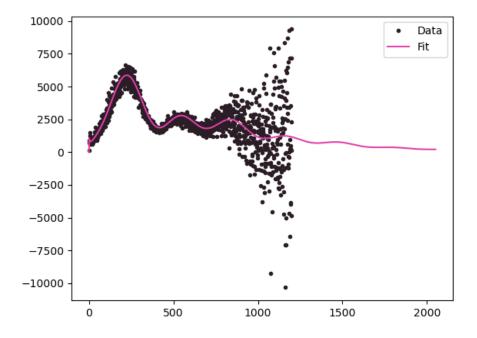
$$f = \frac{1}{4a}$$

and its uncertainty (by error propagation) is

$$\delta f = \left| \frac{\delta a}{4a^2} \right| \, .$$

Substituting values, we get $f = 1.49966 \pm 0.00015$ m.

 ${\bf P2}$ With the given parameters, we get a $\chi^2=1588.2376465828454.$



P3

Using Newton's method. With optical depth fixed at $\tau = 0.05$, the best-fit values for the other parameters are:

$$H_0 = 69.3273685 \pm 2.40207892$$

 $\omega_b h^2 = (2.24913957 \pm 0.0539639860) \times 10^{-2}$
 $\omega_c h^2 = 0.113912236 \pm 0.00522680121$
 $A_s = (2.04250577 \pm 0.0389837370) \times 10^{-9}$
 $n_s = 0.969769787 \pm 0.0135890077$

and the new minimized χ^2 is equal to 1227.935636135719.

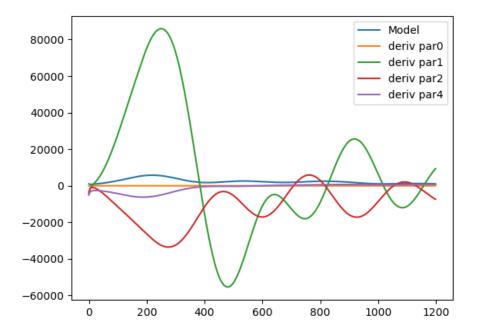


Figure 1: CMB and the derivatives for each of the parameters above, keeping tau constant. The derivative w.r.t. parameter 3 (A_s) was omitted due to its scaling.

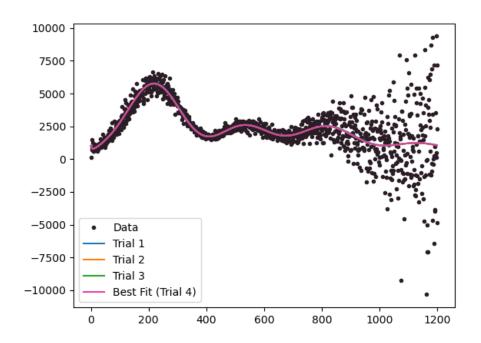


Figure 2: CMB data and 4 fits.

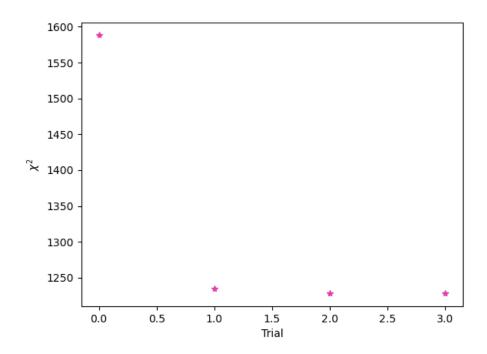


Figure 3: χ^2 for each of the 4 trials.

If I let all parameters float, I get as best-fit values:

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H_0 = 68.8015331 \pm 3.25778331
\omega_b h^2 = (2.23770286 \pm 0.0765761984) \times 10^{-2}
\omega_c h^2 = 0.114822064 \pm 0.00658297176
\tau = 0.0194766363 \pm 0.150860338
A_s = (1.92249969 \pm 0.598622072) \times 10^{-9}
n_s = 0.965829151 \pm 0.0228317247
```

and χ^2 equal to 1235.5552207546873. These errors and χ^2 are worse than the case above, where τ was constant.

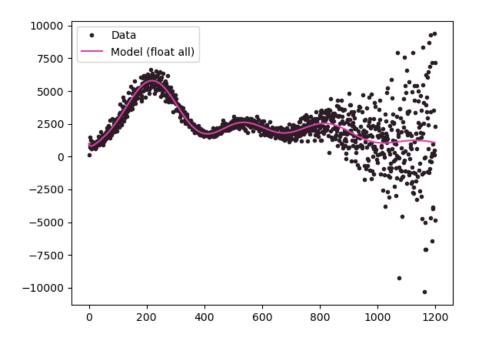


Figure 4: CMB data and fit with all parameters floating.

P4

Using a Markov-chain Monte Carlo with 5000 steps¹, I get the new parameters:

```
H_0 = 70.3112543 \pm 2.62403787

\omega_b h^2 = (2.26686607 \pm 0.0588006489) \times 10^{-2}

\omega_c h^2 = 0.112163971 \pm 0.00519791688

\tau = 0.0810869807 \pm 0.0473308810

A_s = (2.17328497 \pm 0.196466768) \times 10^{-9}

n_s = 0.977929447 \pm 0.0154416237
```

and χ^2 equal to 1233.099189381654. Since we could only accept steps that would give positive τ , the actual number of accepted steps was equal to 1784, giving an acceptance rate of 0.3568. When comparing to the parameters given above for Newton's method floating τ , there is a clear improvement in parameters errors.

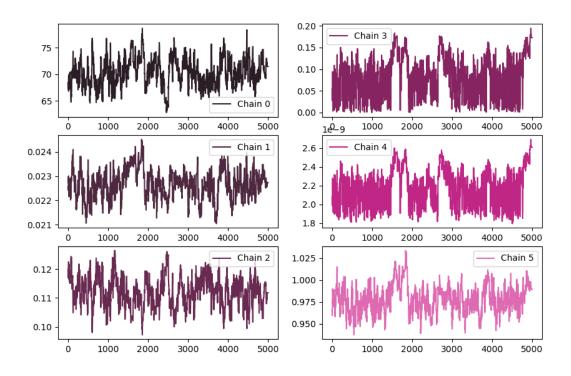


Figure 5: Chains for each parameter.

 $^{^{1}}$ I am doing only 5000 steps and only one chain because I am usin a > 10 years old MacBook, and it took around 18h to run this.

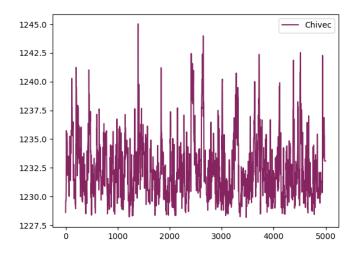


Figure 6: χ^2 evolution during chain.

From the FFTs of the chains (Fig. 7), it seems that the convergence was not very good for this number of steps. Unfortunately I don't have access to a faster computer at this moment.

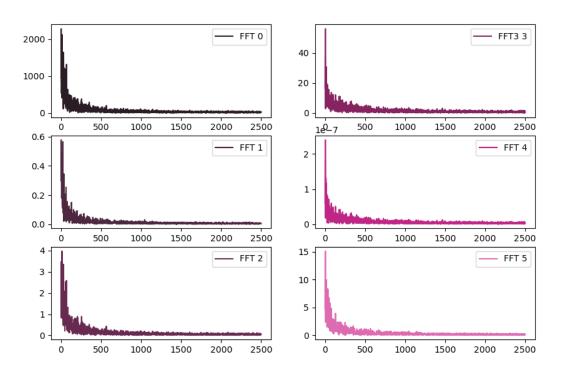


Figure 7: FFTs of chains.