Matthew Lisondra

Research - Robotics & Physics, AI and Computer Vision

matthew.lisondra@torontomu.ca (or @alum.utoronto.ca) (647)-821-8290 Toronto Metropolitan University, EPH Eric Palin Hall mattlisondra.com

Research interests Robotics, Simultaneous Localization and Mapping (SLAM), State Estimation,

Computer Vision, Autonomous Systems, Deep/Reinforcement Learning

Education Toronto Metropolitan University Toronto, ON

MASc Master's in Mechanical Engineering Sep 2022 – Present

(Mechatronics, MEMS and Robotics Engineering)

Supervised by: Profs. Dr. Sajad Saeedi, Dr. Kourosh Zareinia

University of Toronto, St. George Toronto, ON

HBSc Honours Bachelor's in Physics/Mathematics Sep 2017 – June 2021

Collaborated with: Prof. Dr. Dylan Jones

Publications Visual Inertial Odometry using Focal Plane Binary Features (BIT-VIO)

M. Lisondra^{1,*}, J. Kim^{1,*}, R. Murai², K. Zareinia¹, S. Saeedi¹ - In Review

(¹Toronto Metropolitan University, ²Imperial College London)

Submitted The International Conference on Robotics and Automation (ICRA) 2024

Research experience Robotics and Computer Vision Laboratory (RCVL) Toronto, ON

Toronto Metropolitan University by Dr. Sajad Saeedi Sep 2022 – Present Worked on Visual-Inertial Sensor Fusion (VIO and SLAM), Autonomous Driving Algorithms, Focal-Plane Sensor-Processor (FPSP) Chips, Reinforcement

Learning Pose-Graph Optimization (RL-PGO) research

Haptics and Telerobotics Laboratory (HapTel) Toronto, ON

Toronto Metropolitan University by Dr. Kourosh Zareinia Sep 2022 – Present Worked on Image-Based Force Estimation in Medical Applications research

Reviewer (Conference) for ICRA 2024 Fall 2023

International Conference on Robotics and Automation (ICRA) 2024

Reviewer (Conference) for IEEE CCECE 2023 Winter 2023

2023 Canadian Conference On Electrical and Computer Engineering

Reviewer (Conference) for IROS 2023 Winter 2023

IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)

Teaching experience Graduate/Teaching Assistant for MEC411 Winter 2023

Mechanics of Machines at *Toronto Metropolitan University*

Graduate/Teaching Assistant for BME/MEC323 Fall 2022

Statics and Mechanics of Materials at Toronto Metropolitan University

Industry experience

Virtute Innovation Academy

Richmond Hill, ON

Department of Mathematics and Science Instructor

Sep 2023 – Present

Taught online/in-person Physics, Calculus and Computer Science I, II instruction in class sessions of 20-40 students via lecture plans, assignments, exami-

nations

Collaborated with: Dr. Albert Jiang

Academic Horizons

Surrey, BC

Senior Physics and Computer Science Instructor Oct 2021 - Sep 2023 Taught online 1-on-1 teaching sessions with students, Developed individualized, appropriate learning programs, assisted in collecting and maintaining learner records for the purpose of evaluating student progress

Lumist Educational Institution

Toronto, ON

Lead Physics Instructor (+ Computer Science) April 2021 - Oct 2021 Taught online 1st-4th yr. students from UCLA, UC Berkeley, UCSD in class sessions of 40-50 students, delivered instruction in live/recorded/edited lecture video modules

Collaborated with: Profs. Dr. Nathan Murray, Dr. Francisco Guevara Parra

Skills **Coding:** Python, PyTorch, keras, R, C/C++, Java, R, C#, Javascript, HTML, CSS

Technologies: Windows, Linux, NXP MCUs based on Arm Cortex-M cores

Extra-Curriculars Toronto Metropolitan Aerial Vehicles - TMAV Fall 2022

Collaborated on Carbon-Cover, Inverse Kinematics of Robotic Arm Projects

References available on request.