# **Hawkeye System** - An Active Vision Algorithm for drones

## Mission:

Develop a gimbal system that detects objects and keeps them centered in the image autonomously to enhance safe indoor drone flight, introducing further sensing techniques such as thermal sensing.

## Steps to the goal:

1. Research (Hardware)
   1. Gimbal search (Roque) 🟢
   2. Camera search (Ferran) 🟡
   3. Connections (Ekaitz) 🟡
2. Research (Software)
   1. Object Tracking Algorithms (Ekaitz) 🟡
   2. Gimbal Control (Roque) 🟡
   3. Control Loops for active vision (Mario) 🟡
   4. Simulation environment (Ferran) 🟡
3. Separate development
   1. YOLO object tracking (Ekaitz & Ferran) 🔘
   2. Gimbal control (Mario & Roque) 🔘
4. Implementation of control loop
5. Test in controlled environment
6. Implementation in drone hardware
   1. YOLO in camera / Raspberry PI 5
   2. Control algorithm in Storm32 / Raspberry PI
7. Final testing
8. Development of further technologies

## GitHub

**CLONE REPOSITORY**

1. Log In to GitHub and check that you are a collaborator
2. Go to desired local folder:

cd path/to/your/project

1. Clone repository:

git clone https://github.com/ferran-artero/Hawkeye\_System

**NAVIGATE TO REPOSITORY**

cd path/to/your/project

\* If you try git status and it says “not a git repository,” you're in the wrong folder

**BRANCHES**

# All possible branches and know where you are

git branch

# Move to a branch

git checkout branch

# Create a branch

git checkout -b new-branch-name

**PULL**

*Option 1*

git pull --all # pulls changes for all tracking branches

*Option 2*

# Fetch all updates (metadata)

git fetch --all

# Then pull specific branches

git pull origin main

git pull origin teammate-branch

git pull origin your-branch

**PUSH**

git push origin branch