Finding Partite Hypergraphs Efficiently

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Abstract

TODO

1 Introduction

Hypergraph Turán problems study how many edges a k-uniform hypergraph H = (V, E) with n vertices can have without containing a specific subgraph G. The maximal such number is known as the $Turán\ number\ ex(n,G)$. It is known that $ex(n,G) = o\left(\binom{n}{k}\right)$ if and only if G is k-partite, i.e., if its vertex set can be partitioned into k disjoint sets such that each edge contains exactly one vertex from each part. Kővári, Sós, and Turán [17] (for k=2) and Erdős [8] (for any $k \geq 2$) established that

$$ex(n, K(t, ...^k, t)) = \mathcal{O}(n^{k - \frac{1}{t(k-1)}}),$$
 (1)

where $K(t, ...^k, t)$ is the complete balanced k-partite k-graph with k parts of size t. Furthermore, if H is a k-graph with at least $d\binom{n}{k}$ edges for some constant d > 0, then it contains a $K(t, ...^k, t)$ with $t = c_d \log(n)^{1/(k-1)}$.

This result is non-constructive, meaning it guarantees the existence of such a subgraph but does not provide an efficient way to find it. Note that a simple brute-force search for a $K(t, .^k., t)$ would involve checking all $\binom{n}{kt}$ vertex subsets, which is superpolynomial in n for $t = \Theta((\log n)^{1/(k-1)})$. Mubayi and Turán [19] developed a polynomial-time algorithm for the case k = 2, which reaches the stated order of magnitude for the subgraph part size. This paper extends their approach to the general case of k-uniform hypergraphs, reaching analogous results for $k \geq 3$. More concretely, we prove the following.

Theorem 1. There is a deterministic algorithm that, given a k-graph H with n vertices and $m = dn^k$ edges, finds a complete balanced k-partite subgraph K(t, .k., t) in polynomial time, where

$$t = \left\lfloor \left(\frac{\log(n/2^{k-1})}{\log(3/d)} \right)^{\frac{1}{k-1}} \right\rfloor.$$

This value of t matches the order of magnitude from existence proofs. In fact, a probabilistic argument shows that it is the best possible up to a constant factor.

2 Finding a Balanced k-Partite Subgraph

We present a recursive algorithm, Find_Partite, that finds a K(t, ..., t) in a given k-graph H. The core idea is to reduce the uniformity of the problem from k to k-1 in each recursive step.

The algorithm takes a k-graph H as input. It first defines the target part size t, a small set size w, and a threshold edge count s for the recursive call, based on the input graph's parameters

 $(n, d = m/n^k, k)$:

$$t(n,d,k) = \left[\left(\frac{\log(n/2^{k-1})}{\log(3/d)} \right)^{\frac{1}{k-1}} \right]$$
$$w(n,d,k) = \left[\frac{2t(n,d,k)}{d} \right]$$
$$s(n,d,k) = \left[d^{t(n,d,k)} n^{k-1} \right]$$

The main steps are:

- 1. Base Case (k = 1): A 1-graph is just a collection of vertices. Return the set of all vertices that are "edges".
- 2. **Select High-Degree Vertices:** Choose a set $W \subset V$ of w vertices with the highest degrees in H. Let $U = V \setminus W$.
- 3. Find a Dense Link Graph: Iterate through all t-subsets $T \subset W$. For each T, consider the set S of all (k-1)-subsets of U that form a hyperedge with every vertex in T.
- 4. **Recurse:** The pigeonhole principle, formalized by the Kővári–Sós–Turán theorem, guarantees that for at least one choice of T, the resulting set S will be large $(|S| \ge s)$. We form a new (k-1)-graph H'=(U,S) and make a recursive call: Find_Partite(H', k-1).
- 5. Construct Solution: The recursive call returns k-1 parts V_1, \ldots, V_{k-1} of size at least t. By construction, every choice of vertices from these parts forms an edge in H' with T. Thus, $(V_1, \ldots, V_{k-1}, T)$ form the desired $K(t, \cdot, \cdot, t)$ in the original graph H.

The pseudocode is given in Algorithm 1.

Algorithm 1 Finding a balanced partite k-graph

```
1: function FIND_PARTITE(H, k)
 2:
          if k = 1 then
               return (\{x \colon \{x\} \in E(H)\})
 3:
          end if
 4:
          n \leftarrow |V(H)|, \ m \leftarrow |E(H)|, \ d \leftarrow m/n^k
 5:
          t \leftarrow t(n,d,k), w \leftarrow w(n,d,k), s \leftarrow s(n,d,k)
          assert t \geq 2
 7:
 8:
          W \leftarrow \text{a set of } w \text{ vertices with highest degree in } H
         for all T \in {W \choose t} do
S \leftarrow \{ y \in {V \setminus W \choose k-1} : \forall x \in T, \{x\} \cup y \in E(H) \}
 9:
10:
               if |S| \ge s then
11:
                    H' \leftarrow (V \setminus W, S)
                                                                                                           \triangleright H' is a (k-1)-graph
12:
                    (V_1, \ldots, V_{k-1}) \leftarrow \text{FIND\_PARTITE}(H', k-1)
13:
                    return (V_1, \ldots, V_{k-1}, T)
14:
               end if
15:
          end for
17: end function
```

3 Analysis

We briefly sketch the proof of correctness and polynomial runtime for our algorithm. The full, detailed proofs can be found in the first author's master's thesis [?]. We assume $t \geq 2$, which holds if d is not too small (e.g., $d = \Omega(n^{-1/2^{(k-1)}})$).

3.1 Correctness

The correctness of the algorithm hinges on two key lemmas, which we state here without proof.

- 1. There always exists a t-subset $T \subseteq W$ for which the set S of common neighbors satisfies $|S| \geq s$.
- 2. The recursive call Find_Partite(H', k-1) is guaranteed to find parts of size at least t.

The first claim follows from a double-counting argument akin to the proof of the Kővári-Sós-Turán theorem. We define a bipartite graph between the (k-1)-subsets of $V \setminus W$ and the vertices in W. By showing this graph is dense, we can guarantee the existence of a complete bipartite subgraph K(s,t), which corresponds to finding the desired set T and a large corresponding set S

For the second claim, we show that the new hypergraph $H' = (V \setminus W, S)$ is sufficiently dense. Its density d' satisfies $d' \geq d^t$. We then prove that the target part size for the recursive call, t' = t(n - w, d', k - 1), satisfies $t' \geq t$. This ensures that the part sizes do not shrink during recursion. For the base case $k = 2 \rightarrow k = 1$, we show directly that $|S| \geq t$.

3.2 Complexity

The algorithm runs in polynomial time in n. The dominant cost at each recursive level comes from the loop over all t-subsets of W. The number of iterations is $\binom{w}{t}$. Since $w = \lceil 2t/d \rceil$ and $t = \Theta((\log n)^{1/(k-1)})$, the number of iterations can be bounded:

$$\binom{w}{t} \le \left(\frac{ew}{t}\right)^t \le \left(\frac{e(2t/d+1)}{t}\right)^t \approx \left(\frac{3e}{d}\right)^t.$$

Substituting the definition of t, this expression is polynomial in n (e.g., $\mathcal{O}(n^c)$ for some constant c). Inside the loop, constructing the set S and the new hypergraph H' takes polynomial time. Since the recursion depth is fixed at k-1, the total runtime is a nested polynomial, which remains polynomial in n. A detailed analysis shows the complexity is roughly $\mathcal{O}(n^{2k+3})$.

4 Conclusion and Future Work

We have presented a deterministic, polynomial-time algorithm to find a large complete balanced k-partite subgraph in any sufficiently dense k-uniform hypergraph. This provides a constructive counterpart to a classical existence result by Erdős in extremal hypergraph theory.

Several avenues for future research remain open.

- General Blow-ups: Our algorithm finds a blow-up of a single edge, $K(t, \stackrel{k}{\dots}, t)$. Can this framework be adapted to find a t_n -blowup of an arbitrary fixed k-graph G? Existence theorems guarantee such structures, but efficient algorithms are lacking.
- Unbalanced Partite Graphs: The algorithm could be modified to search for unbalanced complete partite graphs $K(t_1, \ldots, t_k)$, where the part sizes may grow at different rates.
- **Optimality:** The bounds on t are asymptotically tight, but the constants can likely be improved with a more refined analysis. For k=2, it is known that in dense graphs one can find a $t=\Theta(\log n)$ blow-up of any bipartite graph. It is an open question if a constructive proof for this stronger result exists for $k \geq 2$.

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