



Variational approximations of size-mass energies for k-dimensional currents

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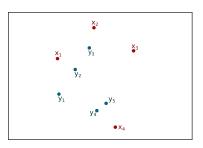
 $\omega_+,\,\omega_-\in\mathcal{P}(\mathbf{R}^n)$ atomic probability measures

- 'Source' measure $\omega_+ = \sum_i a_i \delta_{x_i}$,
- 'Sink' measure $\omega_{-} = \sum_{j} b_{j} \delta_{\mathsf{x}_{j}}$.

Polyhedral transport flux

 $\sigma \in \mathcal{M}(\mathbf{R}^n, \mathbf{R}^n)$ vector measure

$$\sigma = \sum_i \theta_i \tau_i \mathcal{H}^1 \llcorner \Sigma_i$$



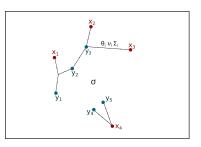
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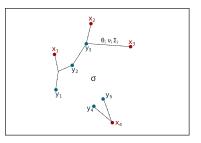
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Constraint

$$\operatorname{div} \sigma = \omega_+ - \omega_- \quad \text{in } \mathcal{D}'(\mathbf{R}^n)$$



Generalization to surfaces

Model for vector measures

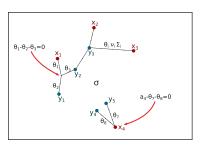
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Cost function

A function $h: \mathbf{R} \to \mathbf{R}^+$ is a transport cost function if it is:

- lower semicontinuous,
- 2. h(0) = 0,
- 3. sub-additive.
- even

Generalization to surfaces

$$h(\theta) = |\theta|^{\alpha}$$
 with $\alpha \in [0, 1)$

$$h(\theta) = \begin{cases} 0, & \text{if } \theta = 0, \\ 1, & \text{otherwise} \end{cases}$$

$$h(\theta) = \min\{\alpha_0 |\theta|, \alpha_1 |\theta| + a\}$$
$$a > 0 \text{ and } 0 < \alpha_1 < \alpha_0$$

$$h(\theta) = \begin{cases} 0, & \text{if } \theta = 0, \\ (1 + \alpha |\theta|), & \text{otherwise} \end{cases}$$

Transport cost function

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A function $h: \mathbf{R} \to \mathbf{R}^+$ is a transport cost function if it is:

- 1. lower semicontinuous,
- 2. h(0) = 0,
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- 4. even.

Examples:

- Branched transport:

Generalization to surfaces

$$h(\theta) = |\theta|^{\alpha}$$
 with $\alpha \in [0,1)$

- 'Steiner' cost:

$$h(heta) = egin{cases} 0, & ext{if } heta = 0, \ 1, & ext{otherwise}. \end{cases}$$

- Urban Planning cost:

$$h(\theta) = \min\{\alpha_0|\theta|, \alpha_1|\theta| + a\}$$

 $a > 0 \text{ and } 0 < \alpha_1 < \alpha_0$

- Affine cost functional:

$$h(heta) = egin{cases} 0, & ext{if } heta = 0, \ (1 + lpha | heta|), & ext{otherwise}. \end{cases}$$

For a function h and polyhedral transport flux we set

$$\mathcal{F}(\sigma) = \sum_{i} h(\theta_{i}) \mathcal{H}^{1}(\Sigma_{i}) \qquad \text{if } \sigma = \sum_{i} \theta_{i} \tau_{i} \mathcal{H}^{1} \sqcup \Sigma_{i}. \tag{1}$$

[White (2000)] If h is a transport cost function then \mathcal{F} extends on $X:=\{\sigma\in\mathcal{M}(\mathbf{R}^n,\mathbf{R}^n):\operatorname{div}\sigma=\omega_+-\omega_-\}$ via

Relaxatio

$$\overline{\mathcal{F}}(\sigma) := \inf \left\{ \liminf_{j \to +\infty} \mathcal{F}(\sigma_j) : \sigma_j \in X \text{ of the form (1) and } \sigma_j \overset{*}{\rightharpoonup} \sigma \right\}.$$

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Rectifiable σ

We will say that σ is rectifiable if $\sigma = (\theta, \tau, \Sigma)$ with

- 1. Σ is \mathcal{H}^1 -rectifiable,
- 2. $\theta \in L^1(\Sigma, \mathcal{H}^1 \sqcup \Sigma)$,
- 3. $\tau: \Sigma \to S^1$ is tangent to Σ , $\mathcal{H}^1 \sqcup \Sigma$ -a.e..

[Xia (1997)] in the case $h = |\cdot|^{\alpha}$ ($\alpha \in [0,1)$), [Brancolini-Wirth (2017)] for general transport cost functions.

Generalized Gilbert-Steiner energy

If $\sigma \in X$ and writes as $\sigma = \sigma^{\perp} + (\theta, \tau, \Sigma)$ then the relaxation writes as

$$\overline{\mathcal{F}}(\sigma) = h'(0)|\sigma^{\perp}| + \int_{\Sigma} h(|\theta|) \; \mathrm{d}\mathcal{H}^1 \quad \text{where} \quad h'(0) = \lim_{t \to 0_+} \frac{h(t)}{t}.$$

Conclusion

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'Branched transportation' type

For two measures $\omega_+, \omega_- \in \mathcal{P}(\Omega)$ approximate:

$$\overline{\sigma} := \operatorname{argmin} \left\{ \overline{\mathcal{F}}(\sigma) : \sigma \in \mathcal{M}(\Omega, \mathbf{R}^n) \text{ and div } \sigma = \omega_+ - \omega_+ \right\}$$

Generalization to surfaces

$$h(\theta) = \begin{cases} 0, & \text{if } \theta = 0, \\ 1, & \text{otherwise.} \end{cases} \qquad \omega_{+} = \delta_{x_{0}}, \quad \omega_{-} = \frac{1}{N} \sum_{1}^{N} \delta_{y_{i}}$$

find $\overline{K} = \operatorname{argmin}\{\mathcal{H}^1(K) : K \text{ compact, connected and } \{x_0, \dots, x_N\} \subset K \subset \mathbb{R}^n\}$

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Motivation: Solutions to this problems are computationally hard to find. For instance: the case

$$h(\theta) = \begin{cases} 0, & \text{if } \theta = 0, \\ 1, & \text{otherwise.} \end{cases}$$
 $\omega_+ = \delta_{x_0}, \quad \omega_- = \frac{1}{N} \sum_1^N \delta_{y_i}$

corresponds to the Steiner Tree Problem:

find $\overline{K} = \operatorname{argmin}\{\mathcal{H}^1(K) : K \text{ compact, connected and } \{x_0, \dots, x_N\} \subset K \subset \mathbf{R}^n\}$ Is NP-hard [Karp (1972)], [Leal do Forte et al. (2016)].

[Modica, Mortola (1977)], [Ambrosio, Tortorelli (1990)], [Bonnivard, Lemenant, Santambrogio (2015)]

- Let $\varepsilon \in (0,1]$ and ρ_{ε} be a convolution kernel
- Relaxed vector measure:

$$\sigma \in L^1(\Omega, \mathbf{R}^n)$$
 and div $\sigma = (\omega_+ - \omega_-) * \rho_{\varepsilon}$ in $\mathcal{D}'(\mathbf{R}^n)$

$$arphi \in W^{1,2}(\Omega), \quad arphi \geq \eta \quad ext{ and } \quad arphi \llcorner \partial \Omega \equiv 1$$

$$\mathcal{F}_{\varepsilon,a}(\sigma,\varphi) := \underbrace{\int_{\Omega} \frac{\varphi |\sigma|^2}{2\,\varepsilon} \,\mathrm{d}x}_{\text{'Constraint'}} + \underbrace{\int_{\Omega} \varepsilon^{p-n+1} |\nabla \varphi|^2 + \frac{(1-\varphi)^2}{\varepsilon^{n-1}} \,\mathrm{d}x}_{\text{'Rescaled Modica-Mortola'}}$$

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[Chambolle, F, Merlet (2017)

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[Chambolle, F. Merlet (2017)]

Results

Theorem [Chambolle, F., Merlet]

If $\eta=a\varepsilon$ with a>0 then $\{\mathcal{F}_{\varepsilon,a}\}$ is equicoercive with respect to the weak-* convergence of measures and the strong L^2 convergence.

Theorem: Γ – lim inf [Chambolle, F., Merlet]

$$\Gamma - \lim_{\varepsilon \downarrow 0} \mathcal{F}_{\varepsilon,a} = \mathcal{F}_a(\sigma,\varphi)$$

with respect to the product topology. Where

$$\mathcal{F}_{a}(\sigma, \varphi) := egin{cases} \int_{\Sigma} h_{a}(\theta) \; \mathrm{d}\mathcal{H}^{1}, & ext{if } \sigma = \theta au \mathcal{H}^{1} \llcorner \Sigma \; ext{and} \; \varphi \equiv 1 \ +\infty, & ext{otherwise}. \end{cases}$$

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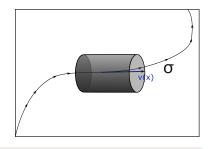
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Reduced dimension problem and cost function h_a

We introduce m, the flux of σ trough an n-1 dimensional hyperplane and study the energy.



For a ball in $B_r(0) \subset \mathbf{R}^d$ we let

$$E_{\varepsilon,a}(\vartheta,u;B_r) := \int_{B_r} \left[\varepsilon^{p-n+1} |\nabla \varphi|^p + \frac{(1-\varphi)^2}{\varepsilon^{n-1}} + \frac{\varphi|m|^2}{\varepsilon} \right] dx$$

$$h_{\varepsilon,a}(\theta,r) = \min \begin{cases} E_{\varepsilon,a}(\vartheta,\varphi;B_r) \\ \varphi \in W^{1,p}(B_r), \varphi \llcorner \partial \mathcal{B}_r = 1 \text{ and } \int_{B_r} \vartheta = \theta. \end{cases}$$

Theorem ([Chambolle, F., Merlet])

For every r

$$\lim_{\varepsilon\downarrow 0}h_{\varepsilon,\mathsf{a}}(\theta,r)=h_{\mathsf{a}}(\theta),$$

is a transport cost function and for $m \neq 0$ we have the following semi-explicit formulation

$$h_{a}(m) = \min_{\hat{r}>0} \left\{ \frac{a m^{2}}{\omega_{n-1} \hat{r}^{n-1}} + \omega_{n-1} \hat{r}^{n-1} + (n-2) \omega_{n-1} q^{n-1}(\hat{r}) \right\}$$

Furthermore $\lim_{a\downarrow 0} h_a^d = c(n, p)$.

In the above ω_{n-1} is the volume of unit (n-1)-dimensional ball. And $q^{n-1}(\hat{r})$ is the transition cost

$$q^{n-1}(\hat{r}) := \left\{ \int_{\hat{r}}^{\infty} t^{n-2} \left[|v'|^p + (1-v)^2 \right] \; \mathrm{d}t \, : \, v(\hat{r}) = 0 \; \mathsf{and} \; \lim_{t \to \infty} v(t) = 1 \right\}$$

GENERALIZATION TO SURFACES

- For 0 < k < n, we consider the space $D_k(\Omega) = \mathcal{D}^k(\Omega)'$,
- $\sigma = \sum_i \theta_i \tau_i \mathcal{H}^k \sqcup \Sigma_i$ where Σ_i is a k-dimensional polyhedra and τ_i is a k-multivector orienting it,
- ullet the constraint is modeled via the boundary operator ∂ ,
- $\mathcal{F}(\sigma) = \sum_{i} h(\theta) \mathcal{H}^{k}(\Sigma_{i})$
- A k-current $\sigma \in \mathcal{D}_k(\Omega)$ is rectifiable, if $\sigma = (\theta, \tau, \Sigma)$ where
 - ullet Σ is an \mathcal{H}^k -rectifiable set,
 - τ is a multivector orienting the tangent plane to $\Sigma \mathcal{H}^k \sqcup \Sigma$ -a.e.,
 - $\theta \in L^1(\mathcal{H}^k \sqcup \Sigma)$.



With the same relaxation procedure proposed above we can define a functional on the space of currents $\sigma \in \mathcal{D}_k(\Omega)$

Theorem ([Colombo et al. (2017)])

Generalization to surfaces

If $\sigma \in \mathcal{D}_k(\Omega)$ and it is rectifiable, then

$$\overline{\mathcal{F}}(\sigma) = \int_{\Sigma} h(\theta) \, \mathrm{d}\mathcal{H}^k.$$

And

$$\overline{\mathcal{F}}(\sigma) < \infty \implies \sigma \text{ rectifiable } \iff h'(0) < \infty.$$

[White (2000)], [Morgan (1989)], [De pauw Hardt (2003)] size functional.

Plateau type problems

Given a polyhedral normal chain $\sigma_0 \in \mathcal{D}_k(\Omega)$ approach

$$\overline{\sigma} := \operatorname{argmin} \left\{ \overline{\mathcal{F}}(\sigma) : \sigma \in \mathcal{D}_k(\Omega) \text{ and } \partial \sigma = \partial \sigma_0 \right\}.$$

Consider the functional

$$\mathcal{F}^k_{\varepsilon,a}(\sigma,\varphi) := \underbrace{\int_{\Omega} \frac{\varphi |\sigma|^2}{2\,\varepsilon} \,\mathrm{d}x}_{\text{'Constraint'}} + \underbrace{\int_{\Omega} \varepsilon^{p-n+k} |\nabla \varphi|^2 + \frac{(1-\varphi)^2}{\varepsilon^{n-k}} \,\mathrm{d}x}_{\text{'Rescaled Modica-Mortola'}}.$$

Where σ is a smoothed k-current:

$$\sigma \in \mathcal{D}_k(\Omega), \quad \partial \sigma = \partial \sigma_0 * \rho_\varepsilon \quad \sigma \ll \mathcal{L}^1$$

 φ is a phase-field function:

$$\varphi \in W^{1,2}(\Omega), \quad \varphi \geq \eta \quad \text{and} \quad \varphi \sqcup \partial \Omega \equiv 1$$

Ghilardin (2014)

Theorem [Chambolle, F., Merlet]

If $\eta=a\varepsilon$ with a>0 then $\{\mathcal{F}^k_{\varepsilon,a}\}$ is equicoercive with respect to the Flat norm for currents and the strong L^2 convergence.

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with respect to the product topology. Where

$$\mathcal{F}_{\mathsf{a}}^{k}(\sigma,\varphi) := \begin{cases} \int_{\Sigma} h_{\mathsf{a}}^{n-k}(\theta) \; \mathrm{d}\mathcal{H}^{k}, & \text{ if } \sigma = \theta\tau\mathcal{H}^{1} \llcorner \Sigma \text{ and } \varphi \equiv 1 \\ +\infty, & \text{ otherwise.} \end{cases}$$

Theorem ([Chambolle, F., Merlet])

For a = 0 we have

$$h_0^d(\theta) = \begin{cases} c, & \text{if } \theta \neq 0, \\ 0, & \text{otherwise.} \end{cases}$$

Generalization to surfaces

for some c = c(n, k, p) > 0. Furthermore

$$\Gamma \lim_{\mathsf{a}\downarrow 0} \mathcal{F}^k_{\mathsf{a}} = \mathcal{F}^k_0 := \begin{cases} c\mathcal{H}^k(\Sigma), & \textit{if } \varphi = 1 \textit{ a.e. } \sigma = \theta\tau\mathcal{H}^k \llcorner \Sigma \partial \sigma = \partial \sigma_0, \\ +\infty & \textit{otherwise}. \end{cases}$$

Numerics in collaboration with Elie Bretin

Remarks

In the case n=3 and k=2 we may identify the space $\mathcal{D}_2(\Omega)$ with $\mathcal{M}(\Omega, \mathbf{R}^3)$ and the boundary operator corresponds to the curl operator as a distribution.







- A phase-field approximation of the Steiner problem in dimension two (published in Advances in Calculus of Variations),
- Variational approximations of size-mass energies for k-dimensional currents (to appear in ESAIM: cocv).

Thank you for your attention!





Generalization to surfaces