

# Fabio Ferreira | Resume

Georg-Friedrich-Str. 28A – 76131 Karlsruhe – Germany

☎ +49 151 56017041 • ✉ fabioferreira [at] mailbox [dot] org  
in ferreira-fabio • 🌐 ferreirafabio

## Experience

- Machine Learning Lab, University of Freiburg** **Freiburg, Germany**  
*Doctoral Researcher* *Since 2020*  
Research in meta-learning for automated pretraining and finetuning, automated data augmentation, and self-supervised learning. Authored > 10 research papers published at top-tier conferences (four conference papers as first author at ICML and ICLR) and supervised > 10 students. PhD supervisor: Frank Hutter. Thesis: Meta-Learning and Synthetic Data for Automated Pretraining and Finetuning
- Amazon Web Services (AWS) AI** **Seattle, USA**  
*Applied Research Scientist Intern* *11/23–02/24*  
Research in meta-learning models for cost-aware performance prediction of ML algorithms using prior performance data. I developed methods to select and configure well-performing model ensembles under time constraints.
- Interactive Perception and Robot Learning Lab, Stanford University** **Stanford, USA**  
*Visiting Student Researcher* *11/18–06/19*  
Learning neural physics simulators for visual robotic manipulation of rigid objects using relational inductive biases in Graph Neural Networks. Supervisor: Jeannette Bohg.
- Baden-Wuerttemberg Cooperative State University** **Karlsruhe, Germany**  
*Visiting Lecturer* *05/18–08/18*  
Designed and taught a machine learning introductory course for business information system degree students.
- High Performance Humanoid Technologies Lab, KIT** **Karlsruhe, Germany**  
*Research Assistant* *10/17–10/18*  
Research in deep learning for robotic perception and cognition, advice of staff in deep learning and TensorFlow-related questions, Supervisor: Tamim Asfour

## Education

- University of Freiburg** **Freiburg, Germany**  
*PhD in Computer Science* *2020–2025*
- Karlsruhe Institute of Technology** **Karlsruhe, Germany**  
*M. Sc. in Computer Science (GPA: 3.8/4.0, top 15%)* *2016–2019*  
focus: Machine Learning & Robotics, Thesis: Learning Dynamics Models for Rigid Objects from Image Input using Relational Inductive Biases
- Karlsruhe University of Applied Sciences** **Karlsruhe, Germany**  
*B. Sc. in Computer Science (GPA: 3.8/4.0, with distinction, top 5%)* *2013–2016*  
Thesis: Optimal Convolutional Neural Network Architectures for Image Defect Classification
- Advanced Training, Gottlieb–Daimler–Schule 2** **Sindelfingen, Germany**  
*State-Certified CS/EE Technical Engineer, graduated best of class* *2010–2012*
- Apprenticeship, Deutsche Telekom AG** **Sindelfingen, Germany**  
*IT systems engineer* *2006–2009*

## Scholarships

- German Academic Scholarship Foundation scholarship (0.5% acceptance rate) (2015–2019)
- Baden-Württemberg-Stiftung scholarship (2018–2019)
- e-fellows scholarship by Capgemini SE (2017–2018) and TRUMPF Group (2018–2019)

## Software and Language Skills

---

**Programming:** Python, Java, C, C++

**Scientific Tools:** NumPy, SciPy, LaTeX

**Machine Learning:** PyTorch, TensorFlow

**Data Handling:** Pandas, SQL & Co

**DevOps:** Git, GitHub Workflows, TravisCI

**Cloud & HPC:** AWS, Slurm, Docker

**Languages:** English (C2), German (C2), Portuguese (C2)

## Selected Publications

---

### Meta-Learning: Data Augmentation and Synthetic Data.....

#### Beyond Random Augmentations: Pretraining with Hard Views

**Ferreira, F.\***, Rapant\*, I., Franke, J. and Hutter, F. 2025

International Conference on Learning Representations (ICLR) 2025

#### One-shot World Models Using a Transformer Trained on a Synthetic Prior

**F. Ferreira**, M. Schlageter, R. Rajan, A. Biedenkapp and F. Hutter 2024

Workshop on Open-World Agents at NeurIPS 2024

#### Learning Synthetic Environments and Reward Networks for Reinforcement Learning

**F. Ferreira**, T. Nierhoff, A. Sälinger and F. Hutter 2022

International Conference Learning Representations (ICLR) 2022

#### On the Importance of Hyperparameters and Data Augm. for Self-Supervised Learning

D. Wagner, **F. Ferreira**, D. Stoll, R. T. Schirrmeister, S. Müller and F. Hutter 2022

International Conference on Machine Learning (ICML) Pre-Training Workshop 2022

### Meta-Learning for Automated Model Selection and Finetuning.....

#### Quick-Tune: Quickly Learning Which Pretrained Model to Finetune and How

Arango Pineda, S. and **Ferreira, F.** and Kadra, A. and Grabocka, J. and Hutter, F. 2024

International Conference on Learning Representations (ICLR) 2024, oral presentation

#### Quick-Tune-Tool: A Practical Tool for Automatically Finetuning Pretrained Models

I. Rapant, L. Purucker, **F. Ferreira**, S. P. Arango, A. Kadra, J. Grabocka, F. Hutter 2024

International Conference on Automated Machine Learning - Workshop Track 2024

#### Transfer Learning for Finetuning Large Language Models

T. Strangmann, L. Purucker, J. K. H. Franke, I. Rapant, **F. Ferreira** and F. Hutter 2024

NeurIPS Workshop on Adaptive Foundation Models 2024

#### Zero-Shot AutoML with Pretrained Models

**F. Ferreira\***, E. Öztürk\*, H. S. Joma\*, L. Schmidt-Thieme, J. Grabocka, F. Hutter 2022

International Conference on Machine Learning (ICML) 2022, spotlight presentation

#### Winning Solutions and Post-Challenge Analyses of the ChaLearn AutoDL Challenge '19

Liu, Z., Pavao, A., Xu, Z., Escalera, S., **Ferreira, F.**, Guyon, I. and others 2021

IEEE Transactions on Pattern Analysis and Machine Intelligence (TPAMI) 2021

### Robotics.....

#### UniGrasp: Learning a Unified Model to Grasp with N-Fingered Robotic Hands

L. Shao, **F. Ferreira\***, M. Jorda\*, V. Nambiar\*, O. Khatib and J. Bohg et al. 2020

IEEE Robotics and Automation Letters, presented at ICRA 2020

#### Encoding, Recalling, and Predicting Episodic Experiences for Robot Action Execution

**F. Ferreira\***, J Rothfuss\*, Eren. E. Aksoy, Y. Zhou and T Asfour 2018

IEEE Robotics and Automation Letters 2018, presented at IROS 2018

---

\* equal contribution