

Fabio Ferreira | Resume

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Experience

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| Machine Learning Lab, University of Freiburg <i>Postdoctoral Researcher</i> Research in automated data augmentation and self-supervised learning. Supervisor: Frank Hutter | Freiburg, Germany Since 2025 |
| Machine Learning Lab, University of Freiburg <i>Doctoral Researcher</i> Research in meta-learning for automated pretraining and finetuning, automated data augmentation, and self-supervised learning. Authored > 10 research papers published at top-tier conferences (four conference papers as first author at ICML and ICLR) and supervised > 10 students. PhD supervisor: Frank Hutter. Thesis: Meta-Learning and Synthetic Data for Automated Pretraining and Finetuning | Freiburg, Germany 01/20–06/25 |
| Amazon Web Services (AWS) AI <i>Applied Research Scientist Intern</i> Research in meta-learning models for cost-aware performance prediction of ML algorithms using prior performance data. I developed methods to select and configure well-performing model ensembles under time constraints. | Seattle, USA 11/23–02/24 |
| Interactive Perception and Robot Learning Lab, Stanford University <i>Visiting Student Researcher</i> Learning neural physics simulators for visual robotic manipulation of rigid objects using relational inductive biases in Graph Neural Networks. Supervisor: Jeannette Bohg. | Stanford, USA 11/18–06/19 |
| Baden-Wuerttemberg Cooperative State University <i>Visiting Lecturer</i> Designed and taught a machine learning introductory course for business information system degree students. | Karlsruhe, Germany 05/18–08/18 |
| High Performance Humanoid Technologies Lab, KIT <i>Research Assistant</i> Research in deep learning for robotic perception, advised staff in deep learning, Supervisor: Tamim Asfour | Karlsruhe, Germany 10/17–10/18 |

Education

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| University of Freiburg <i>PhD in Computer Science</i> | Freiburg, Germany 2020–2025 |
| Karlsruhe Institute of Technology <i>M. Sc. in Computer Science (GPA: 3.8/4.0, top 15%)</i> focus: Machine Learning & Robotics, Thesis: Learning Dynamics Models for Rigid Objects from Image Input using Relational Inductive Biases | Karlsruhe, Germany 2016–2019 |
| Karlsruhe University of Applied Sciences <i>B. Sc. in Computer Science (GPA: 3.8/4.0, with distinction, top 5%)</i> Thesis: Optimal Convolutional Neural Network Architectures for Image Defect Classification | Karlsruhe, Germany 2013–2016 |
| Advanced Training, Gottlieb-Daimler-Schule 2 <i>State-Certified CS/EE Technical Engineer, graduated best of class</i> | Sindelfingen, Germany 2010–2012 |
| Apprenticeship, Deutsche Telekom AG <i>IT systems engineer</i> | Sindelfingen, Germany 2006–2009 |

Scholarships

- German Academic Scholarship Foundation scholarship (0.5% acceptance rate) (2015–2019)
- Baden-Württemberg-Stiftung scholarship (2018–2019)
- e-fellows scholarship by Capgemini SE (2017–2018) and TRUMPF Group (2018–2019)

Software and Language Skills

Programming: Python, Java, C, C++

Scientific Tools: NumPy, SciPy, LaTeX

Machine Learning: PyTorch, TensorFlow

Data Handling: Pandas, SQL & Co

DevOps: Git, GitHub Workflows, TravisCI

Cloud & HPC: AWS, Slurm, Docker

Languages: English (C2), German (C2), Portuguese (C2)

Selected Publications

Meta-Learning: Data Augmentation and Synthetic Data.....

Beyond Random Augmentations: Pretraining with Hard Views

Ferreira, F.*, Rapant*, I., Franke, J. and Hutter, F. 2025

International Conference on Learning Representations (ICLR) 2025

One-shot World Models Using a Transformer Trained on a Synthetic Prior

F. Ferreira, M. Schlageter, R. Rajan, A. Biedenkapp and F. Hutter 2024

Workshop on Open-World Agents at NeurIPS 2024

Learning Synthetic Environments and Reward Networks for Reinforcement Learning

F. Ferreira, T. Nierhoff, A. Sälinger and F. Hutter 2022

International Conference Learning Representations (ICLR) 2022

On the Importance of Hyperparameters and Data Augm. for Self-Supervised Learning

D. Wagner, **F. Ferreira**, D. Stoll, R. T. Schirrmeister, S. Müller and F. Hutter 2022

International Conference on Machine Learning (ICML) Pre-Training Workshop 2022

Meta-Learning for Automated Model Selection and Finetuning.....

Quick-Tune: Quickly Learning Which Pretrained Model to Finetune and How

Arango Pineda, S. and **Ferreira, F.** and Kadra, A. and Grabocka, J. and Hutter, F. 2024

International Conference on Learning Representations (ICLR) 2024, oral presentation

Quick-Tune-Tool: A Practical Tool for Automatically Finetuning Pretrained Models

I. Rapant, L. Purucker, **F. Ferreira**, S. P. Arango, A. Kadra, J. Grabocka, F. Hutter 2024

International Conference on Automated Machine Learning - Workshop Track 2024

Transfer Learning for Finetuning Large Language Models

T. Strangmann, L. Purucker, J. K. H. Franke, I. Rapant, **F. Ferreira** and F. Hutter 2024

NeurIPS Workshop on Adaptive Foundation Models 2024

Zero-Shot AutoML with Pretrained Models

F. Ferreira*, E. Öztürk*, H. S. Joma*, L. Schmidt-Thieme, J. Grabocka, F. Hutter 2022

International Conference on Machine Learning (ICML) 2022, spotlight presentation

Winning Solutions and Post-Challenge Analyses of the ChaLearn AutoDL Challenge '19

Liu, Z., Pavao, A., Xu, Z., Escalera, S., **Ferreira, F.**, Guyon, I. and others 2021

IEEE Transactions on Pattern Analysis and Machine Intelligence (TPAMI) 2021

Robotics.....

UniGrasp: Learning a Unified Model to Grasp with N-Fingered Robotic Hands

L. Shao, **F. Ferreira***, M. Jorda*, V. Nambiar*, O. Khatib and J. Bohg et al. 2020

IEEE Robotics and Automation Letters, presented at ICRA 2020

Encoding, Recalling, and Predicting Episodic Experiences for Robot Action Execution

F. Ferreira*, J Rothfuss*, Eren. E. Aksoy, Y. Zhou and T Asfour 2018

IEEE Robotics and Automation Letters 2018, presented at IROS 2018

* equal contribution